

MATHEMATICS FOR ENGINEERS
PART II

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FOUNDED BY THE LATE WILFRID J. LINEHAM, B.Sc., M.Inst.C.E.

GENERAL EDITOR: JOHN L. BALE

Mathematics for Engineers

PART II

BY

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SECOND EDITION

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FOUNDER'S NOTE

THE DIRECTLY-USEFUL TECHNICAL SERIES requires a few words by way of introduction. Technical books of the past have arranged themselves largely under two sections: the Theoretical and the Practical. Theoretical books have been written more for the training of college students than for the supply of information to men in practice, and have been greatly filled with problems of an academic character. Practical books have often sought the other extreme, omitting the scientific basis upon which all good practice is built, whether discernible or not. The present series is intended to occupy a midway position. The information, the problems and the exercises are to be of a directly-useful character, but must at the same time be wedded to that proper amount of scientific explanation which alone will satisfy the inquiring mind. We shall thus appeal to all technical people throughout the land, either students or those in actual practice.

AUTHOR'S PREFACE

CONCERNING the aim and scope of this work nothing need be added here to the statement made in the Preface to the former volume. It is there asserted that the subject-matter has been so chosen, and, through the examples, so applied to practical problems, that the two volumes "embrace all the mathematical work needed by engineers in their practice, and by students in all branches of engineering science."

As with the first volume, much thought has been given to the elimination of all rules and processes of academic interest only; but the fact of the importance and necessity of logical reasoning has not been overlooked.

With the exception of the chapters on Spherical Trigonometry and Mathematical Probability, this volume is devoted to the study of the Calculus, both Differential and Integral. Whilst it is wise, and even imperative, if this subject is to be presented in an intelligible manner, that much attention should be paid to the graphic interpretation of its rules, care must be taken to ensure that the graphic methods do not become other than auxiliaries. Accordingly the treatment throughout is based upon algebraic principles; but whenever graphic proofs or constructions have been found to amplify or explain the subject, they have been utilised to the fullest extent. Thus from the commencement the connection between the rate of change of a quantity and the slope of a curve is clearly demonstrated: and this correlation of the algebraic and the graphic methods is continued through all the stages of the development of the subject.

The conception of "limiting values," mentioned briefly in Part I, is further discussed in Chapter I, a familiar example from Dynamics being chosen as the illustration: in this chapter, also, two methods of graphic differentiation are given, the second of which, and the less familiar, being the simpler to apply.

The various rules for the differentiation of both algebraic and trigonometric functions are explained in detail in Chapter II; and Chapter III, containing the rules for the differentiation of a function of a function, a product of functions, etc., together with an introduction to partial differentiation, may be regarded as complementary to Chapter II.

From the abstract reasoning required for comprehension of such an idea as that of "limiting values," the practical mind turns with relief to the applications of differentiation found in Chapter IV; the determination of maximum and minimum values making a particularly strong appeal. In view of the importance of this branch of the subject, a very varied selection of practical examples is presented, in the choice of which the method of solution has been a determining factor. In this chapter also the use of Taylor's theorem in cases of interpolation from steam tables is demonstrated.

Chapters V and VI contain the rules required for the integration of functions occurring in engineering theory and practice. The former chapter serves as an introduction to integration, the significance of the symbols \int and dx being explained by reference to a graph; whilst in the latter chapter the various types of integrals, many of them of a somewhat complicated character, are discussed. At this stage also the reduction formulæ are introduced, and mention is made of the Gamma function and its uses.

Instances of the application of the rules of integration are to be found in the processes enumerated in Chapter VII; and special features of this chapter are the determination of the perimeter of the ellipse, the graphic method for fixing the position of the centroid vertical, the drawing of 1st and 2nd moment curves and the evaluation of the moment of inertia of a compound vibrator.

The utility of polar co-ordinates to the electrical engineer is shown by the inclusion of examples on the candle-powers of lamps, and the employment of the Rousseau diagram to find the mean spherical candle-power; and Dr. Fleming's graphic method for determination of root mean square values of currents is here inserted, since it involves polar plotting.

Differential equations occur so frequently that the methods of solution demand most careful study. Chapter IX presents the most common types, and the selection of examples based upon these, both worked and set, emphasises the need for a proper appreciation of the method of solution.

Chapter X, with its applications of the Calculus to problems encountered in the study of Thermodynamics, Strength of Materials,

Applied Mechanics, Applied Electricity and Hydraulics, provides further illustration of the need of a sound knowledge of the subject to the engineer desirous of equipping himself at all points.

The last two chapters contain much of interest to the surveyor, the examples chosen being such as arise in his practice; and particular attention is directed to the investigation relating to the corrections following errors of observation.

The Author greatly deplores the fact that the inspirer of this work, the late Mr. W. J. LINEHAM, B.Sc., M.I.C.E., does not see its completion: to his enthusiasm for his ideals in education, and for his many personal kindnesses to the Author, tribute is here paid. Sincere thanks are also tendered to Messrs. J. L. BALE and C. B. CLAPHAM, B.Sc., for much valuable assistance.

Great care has been taken to produce the book free from errors, but some may remain, notification of which will be esteemed a great favour.

W. N. ROSE.

*Borough Polytechnic Institute,
S.E. 1,
December, 1919.*

NOTE TO SECOND EDITION

In this edition various corrections have been made, a few exercises have been added, and the work on "least squares" has been made more complete by the inclusion of a section relating to the determination of laws.

To those readers who have assisted by offering criticism or by pointing out errors the sincere thanks of the Author are tendered.

December, 1922.

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MATHEMATICS FOR ENGINEERS

PART II

INTRODUCTORY

THE subject-matter of this volume presents greater difficulty than that of Part I. Many of the processes described herein depend upon rules explained and proved in the former volume; and accordingly it is suggested that, before commencing to read this work, special attention should first be paid to Part I, pp. 452-460, 463-467, 469-472, and pp. 273-299; whilst a knowledge of the forms of the curves plotted in Chapter IX should certainly prove of great assistance.

The abbreviations detailed below will be adopted throughout.

→	stands for " approaches."
=	" " " equals" or " is equal to."
+	" " " plus."
-	" " " minus."
×	" " " multiplied by."
÷	" " " divided by."
∴	" " " therefore."
±	" " " plus or minus."
➤	" " " greater than."
➤	" " " less than."
○	" " " circle."
○ce	" " " circumference."
∞	" " " varies as."
∞	" " " infinity."
∠	" " " angle."
△	" " " triangle" or " area of triangle."
4 or 4!	" " " factorial four"; the value being that of the product 1.2.3.4 or 24.
P ₂	" " " the number of permutations of n things taken two at a time."
C ₂	" " " the number of combinations of n things taken two at a time."
n ₃	" " " $n(n-1)(n-2)$.

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	stands for " efficiency."
θ	" " " angle in degrees."
I.H.P.	" " " angle in radians."
B.H.P.	" " " indicated horse-power."
m.p.h.	" " " brake horse-power."
r.p.m.	" " " miles per hour."
r.p.s.	" " " revolutions per minute."
I.V.	" " " revolutions per second."
F. [°]	" " " independent variable."
C. [°]	" " " degrees Fahrenheit."
E.M.F.	" " " degrees Centigrade."
I	" " " electro-motive force."
E	" " " moment of inertia."
S _n	" " " Young's modulus of elasticity."
S _∞	" " " the sum to n terms."
Σ	" " " the sum to infinity (of terms)."
B.T.U.	" " " sum of."
B.Th.U	Board of Trade unit."
μ	British thermal unit."
\sin^{-1}	absolute temperature."
g	coefficient of friction."
cms.	the angle whose sine is x ."
grms.	the base of Napierian logarithms."
$\lim y$	the acceleration due to the force of gravity."
C. of G.	" centimetres."
C. of P.	" grammes."
k	" the limit to which y approaches as x approaches the value a ."
M.V.	" centre of gravity."
R.M.S.	" centre of pressure."
$f'(x)$	" swing radius," or " radius of gyration."
$f''(x)$	" $\sqrt{-1}$."
$\frac{dy}{dx}$	" mean value."
$\int y dx$	" root mean square."
δ	" the first derivative of a function of x ."
D	" the second derivative of a function of x ."
C.P.	" the differential coefficient of y with regard to x ."
M.S.C.P.	" the integral of y with respect to x as the I.V."
ρ	" difference of."
A.M.	" the operation $\frac{d}{dx}$."
	" candle-power."
	" mean spherical candle-power."
	" density."
	" arithmetic mean."

CHAPTER I

INTRODUCTION TO DIFFERENTIATION

THE seventeenth century will ever be remarkable for the number of great mathematicians that it produced, and still more so for the magnitude of the research accomplished by them. In the early part of the century Napier and Briggs had introduced their systems of logarithms, whilst Wallis and others directed their thoughts to the quadrature of curves, which they effected in some instances by expansion into series, although the Binomial Theorem was then unknown to them. In 1665 Newton, in his search for the method of quadrature, evolved what he termed to be a system of "fluxions" or flowing quantities : if x and y , say, were flowing quantities, then he denoted the velocity by which each of these fluents increased by \dot{x} and \dot{y} respectively. By the use of these new forms he was enabled to determine expressions for the tangents of curves, and also for their radii of curvature. At about the same time Leibnitz of Leipsic, also concerned with the same problem, arrived at practically the same system, although he obtained his tangents by determining "differences of numbers." To Leibnitz is due the introduction of the term "differential," and also the differential notation, viz., dx and dy for the differentials of x and y : he also in his expression for the summation of a number of quantities first wrote the symbol \int , his first idea being to employ the word "omnia" or its abbreviation "omn." Thus, if summing a number of quantities like x , he first wrote "omnia x ," which he contracted to "omn. x ," and later he modified this form to $\int x$.

Great controversy raged for some time as to the claims of Newton and Leibnitz to be called the inventor of the system of the "Calculus," which is the generic term for a classified collection of rules; but it is now generally conceded that the discoveries were independent, and were in fact the natural culmination of the research and discoveries of many minds.

The Calculus was further developed by Euler, Bernoulli, Legendre and many others, but until a very recent date it remained merely "a classified collection of rules": its true meaning and the wide field of its application were for long obscured.

Nowadays, however, a knowledge of the Calculus is regarded, particularly by the engineer, as a vital part of his mental equipment: its rules have been so modified as to become no serious tax on the memory, and the true significance of the processes has been presented in so clear a light that the study of the Calculus presents few difficulties even to the ultra-practical engineer.

This revolution of thought has been brought about entirely through the efforts of men who, realising the vast potentialities of the Calculus, have reorganised the teaching of the subject: they have clothed it and made it a live thing.

The Calculus may be divided into two sections, viz., those treating of *differentiation* and *integration* respectively. Differentiation, as the name suggests, is that part of the subject which is concerned with *differences*, or more strictly with the comparison of differences of two quantities. Thus the process of differentiation resolves itself into a calculation of rates of change; but the manner in which the rate of change is determined depends on the form in which the problem is stated. Thus, if the given quantities are expressed by the co-ordinates of a curve, the change of the ordinate compared with the change in the abscissa for any particular value of the abscissa is measured by the slope of the curve at the point considered.

Differentiation is really nothing more nor less than the determination of rates of change or of slopes of curves.

The term "rate of change" does not necessarily imply a "time rate of change," *i.e.*, a rate of change with regard to time, such as the rate at which an electric current is changing per second, or the rate at which energy is being stored per minute; but the change in one quantity may be compared with the change in any other quantity. As an illustration of this fact we may discuss the following example—

The velocity of a moving body was measured at various distances from its starting point and the results were tabulated, thus—

s (distance in feet)

5

v (velocity in feet per sec.)

14

15

To find the values of the "space rate of change of velocity" for the separate space intervals.

Considering the displacement from 0 to 5 ft., the change in the velocity corresponding to this change of position is 14–10, *i.e.*, 4 ft. per sec.

$$\text{Hence} \quad \frac{\text{change of velocity}}{\text{change of position}} = \frac{14-10}{5-0} = \frac{4}{5} = .8$$

or, the change of velocity per one foot change of position = .8 ft. per sec., and rate of change of velocity = .8 ft. per sec. per foot.

Again, if s varies from 0 to 12, the change of $v = 15-10 = 5$; or, the rate of change of velocity (for this period) = $\frac{5}{12}$ ft. per sec. per foot.

Similarly, the rate of change of v , whilst s ranges from 5 to 12,

$$= \frac{15-14}{12-5} = \frac{1}{7} \text{ ft. per sec. per foot.}$$

The rates of change have thus been found by comparing differences. The phrase "change of" occurs frequently in this investigation, and to avoid continually writing it a symbol is adopted in its place. The letter thus introduced is δ (delta), the Greek form of d , the initial letter of the word "difference": it must be regarded on all occasions as an abbreviation, and hence no operation must be performed upon it that could not be performed if the phrase for which δ stands was written in full. In other words, the ordinary rules applying to algebraic quantities, such as multiplication, division, addition or subtraction, would be incorrectly used in conjunction with δ .

Thus, mv (the formula for momentum) means m multiplied by v , or a mass multiplied by a velocity, whilst δv represents "the change of v ," or if v is the symbol for velocity, $\delta v = \text{change of velocity}$.

Again, $\delta t = \text{change of time}$ or change of temperature, as the case may be. Using this notation our previous statements can be written in the shorter forms: thus—

$$(1) \text{ As } s \text{ changes from } 0 \text{ to } 5 \qquad \delta v = 14-10 = 4$$

$$\delta s = 5-0 = 5$$

$$\text{and} \qquad \frac{\delta v}{\delta s} = \frac{4}{5} = .8$$

$$(2) \text{ As } s \text{ changes from } 0 \text{ to } 12 \qquad \delta v = 15-10 = 5$$

$$\delta s = 12-0 = 12$$

$$\text{and} \qquad \frac{\delta v}{\delta s} = \frac{5}{12} = .417$$

MATHEMATICS FOR ENGINEERS

(3) As s changes from 5 to 12

$$\delta v = 15 - 14 = 1$$

$$\delta s = 12 - 5 = 7$$

and $\frac{\delta v}{\delta s} = \frac{1}{7} = .143$

It must be noted that we do not cancel δ from the numerator and denominator of the fraction $\frac{\delta v}{\delta s}$.

The final result in (1), viz., $\frac{\delta v}{\delta s} = .8$, as s changes from 0 to 5, needs further qualification. From the information supplied we cannot say with truth that the change in the velocity for each foot from 0 to 5 ft. is .8 ft. per sec.: all that we know with certainty is that, as s changes from 0 to 5 ft., the *average* rate of change of velocity over this space period is .8 ft. per sec. Supposing the change of velocity to be continuous over the period considered, the value of $\frac{\delta v}{\delta s}$ already obtained would be the *actual* rate of change of velocity at some point or points in the period considered.

It is usual to tabulate the values of the original quantities and their changes, and unless anything is given to the contrary the *average* values of the rate of change are written in the middle of the respective periods.

The table is set out thus—

s	v	δs	δv	$\frac{\delta v}{\delta s}$
0	10	—	—	—
—	—	5	4	$\frac{4}{5} = .8$
5	14	—	—	—
—	—	7	1	$\frac{1}{7} = .143$
12	15	—	—	—

To distinguish in writing between *average* and *actual* rates of change the notation employed is slightly modified, d being used in place of δ ; $\frac{dv}{dt}$ thus representing an *actual* rate of change of velocity, and $\frac{\delta v}{\delta t}$ representing an *average* rate of change of velocity. Once again it must be emphasised that d must be treated strictly in association with the v or t , as the case may be, and dt does not mean $d \times t$, nor does $\frac{dv}{dt}$ give $\frac{v}{t}$.

INTRODUCTION TO DIFFERENTIATION

Another example can now be considered to demonstrate clearly the distinction between an average and an actual rate of change.

For a body falling freely under the influence of gravity the values of the distances covered to the ends of the 1st, 2nd and 3rd seconds of the motion are as in the table—

t (secs.)				
s (feet)	16.1	64.4	144.9	

Find the average velocities during the various intervals of time, and also the actual velocities at the ends of the 1st, 2nd and 3rd seconds respectively.

The average velocities are found in the manner described before, *i.e.*, by the comparison of differences of space and time, and the results are tabulated, thus—

t	s	δs	δt	$v = \frac{\delta s}{\delta t}$
0	0	—	—	—
1	16.1	16.1	1	16.1
2	64.4	48.3	1	48.3
3	144.9	80.5	1	80.5

The average velocities, viz., the values in the last column, are written in the lines between the values of the time to signify that they are the averages for the particular intervals. As also it is known that in this case the velocity is increased at a uniform rate, it is perfectly correct to state that the actual velocities at the ends of .5, 1.5 and 2.5 seconds respectively are given by the average velocities over the three periods and are 16.1, 48.3 and 80.5 ft. per sec.

We have thus found the actual velocities at the half seconds, but not those at the ends of the 1st, 2nd and 3rd seconds. The determination of these velocities introduces a most important process, illustrating well the elements of differentiation, and in consequence the investigation is discussed in great detail.

The student of Dynamics knows that the law connecting space and time, in the case of a falling body, is $s = \frac{1}{2}gt^2 = 16.1t^2$, and

a glance at the table of values of s and t confirms this law; thus, when $t = 2$, $s = 64.4$, which = $16 \cdot 1 \times 2^2$ or $16 \cdot 1 t^2$.

To find the actual velocity at the end of the first second we must calculate the average velocities over small intervals of time in the neighbourhood of 1 sec., and see to what figure these velocities approach as the interval of time is taken smaller and smaller.

$$\text{Thus if } t = 1 \quad s = 16 \cdot 1 \times 1^2 = 16 \cdot 1$$

$$t = 1 \cdot 1 \quad s = 16 \cdot 1 \times 1 \cdot 1^2 = 19 \cdot 481$$

$$\delta s = 19 \cdot 481 - 16 \cdot 1 = 3 \cdot 381 \quad \delta t = 1 \cdot 1 - 1 = .1$$

$$\text{and} \quad (\text{average}) v = \frac{\delta s}{\delta t} = \frac{3 \cdot 381}{.1} = 33 \cdot 81$$

i.e., the average velocity over the interval of time 1 to 1.1 sec. is 33.81 ft. per sec. This value must be somewhere near the velocity at the end of the first second, but it cannot be the absolute value, since even in the short interval of time, viz., .1 sec., the velocity has been increased by a measurable amount. A better approximation will evidently be found if the time interval is narrowed to .01 sec.

$$\text{Then } t = 1 \quad s = 16 \cdot 1$$

$$t = 1 \cdot 01 \quad s = 16 \cdot 1 \times 1 \cdot 01^2 = 16 \cdot 42361$$

$$\delta s = .32361 \quad \delta t = .01$$

$$(\text{average}) v = \frac{\delta s}{\delta t} = \frac{.32361}{.01} = 32 \cdot 361$$

A value still nearer to the true will be obtained if the time interval is made .001 sec. only.

$$t = 1 \quad s = 16 \cdot 1$$

$$t = 1 \cdot 001 \quad s = 16 \cdot 1 \times 1 \cdot 001^2 = 16 \cdot 1322161$$

$$\delta s = .0322161 \quad \delta t = .001$$

$$\text{and} \quad (\text{average}) v = \frac{\delta s}{\delta t} = \frac{.0322161}{.001} = 32 \cdot 2161$$

By taking still smaller intervals of time, more and more nearly correct approximations would be found for the velocity; the values of v all tending to 32.2, and thus we are quite justified in saying that when $t = 1$, $v = 32 \cdot 2$ ft. per sec.

Or, using the language of p. 458 (*Mathematics for Engineers*, Pt. I), we state that the limiting value of v as t approaches 1 is 32.2; a result expressed in the shorter form

(average) $v \rightarrow 32 \cdot 2$ as $\delta t \rightarrow 0$ when $t = 1$
where the symbol \rightarrow means "approaches"

but (average) $v = \frac{\delta s}{\delta t}$, and thus $\frac{\delta s}{\delta t} \rightarrow 32 \cdot 2$ as $\delta t \rightarrow 0$ when $t = 1$

INTRODUCTION TO DIFFERENTIATION

Again, an actual velocity is an average velocity over an extremely small interval of time; or, in other words, an actual velocity is the limiting value of an average velocity, so that—

$$\text{(actual) } v = \lim_{\delta t \rightarrow 0} \text{(average) } v$$

$$\text{i. e., } \frac{ds}{dt} = \lim_{\delta t \rightarrow 0} \frac{\delta s}{\delta t}$$

By similar reasoning it could be proved that the actual velocity at the end of the 2nd second was 64·4 ft. per sec., and at the end of the 3rd second the velocity was 96·6 ft. per sec.

This example may usefully be continued a step further, by calculating the values of the acceleration; this being now possible since the velocities are known.

Tabulating as before—

t	v	δv	δt	$a = \frac{\delta v}{\delta t}$
1	32·2	—	—	—
—	—	32·2	1	32·2
2	64·4	—	—	—
—	—	32·2	1	32·2
3	96·6	—	—	—

and we note that the average acceleration is constant and is thus the actual acceleration.

Our results may now be grouped together in one table, in which some new symbols are introduced, for the following reason. A velocity is the rate of change of displacement, and is found by “differentiating space with regard to time,” and an acceleration is the rate of change of velocity, and hence it is a rate of change of the change of position, and so implies a double differentiation.

Thus whilst $\frac{ds}{dt}$ is called the first *derivative* or *differential coefficient* of s with regard to t , $\frac{dv}{dt}$ is the first derivative of v with regard to t and the second derivative of s with regard to t .

Then $v = \frac{ds}{dt}$ and $a = \frac{dv}{dt} = \frac{d}{dt}\left(\frac{ds}{dt}\right)$, this last form being usually written as $\frac{d^2s}{dt^2}$ (spoken as *d two s, dt squared*); and it denotes that the operation of differentiating has been performed twice upon s .

The complete table of the values of the velocity and the acceleration reads—

s	t	δs	δt	$v = \frac{\delta s}{\delta t}$	$\delta v = \frac{(\delta v)}{\delta t}$	δt	$a = \frac{\delta v}{\delta t} = \frac{\delta^2 s}{\delta t^2}$
0	0	—	—	—	—	—	—
—	—	16.1	1	16.1	—	—	—
16.1	1	—	—	—	32.2	1	32.2
—	—	48.3	1	48.3	—	—	—
64.4	2	—	—	—	32.2	1	32.2
—	—	80.5	1	80.5	—	—	—
144.9	3	—	—	—	—	—	—

The next example refers to a similar case, but is treated from the graphical aspect.

Example 1.—Experiments made with the rolling of a ball down an inclined plane gave the following results—

t (secs.)	.	0			3
—	—	—	—	—	—
s (cms.)	.	0	20	80	180

Draw curves giving the space, velocity and acceleration respectively at any time during the period 0 to 3 secs.

By plotting the given values, s vertically and t horizontally, the "space-time" curve or "displacement" curve is obtained; the curve being a parabola (Fig. 1).

Select any two points P and Q on the curve, not too far apart, and draw the chord PQ , the vertical QN and the horizontal PN .

Then the slope of the chord $PQ = \frac{QN}{PN}$.

Now PN may be written as δt since it represents a small addition to the value of t at P : also $QN = \delta s$,

so that— slope of chord $PQ = \frac{\delta s}{\delta t}$

but $\frac{\delta s}{\delta t} =$ average velocity between the times OM and OR , hence the average velocity is measured by the slope of a chord. Now let Q approach P , then the chord PQ tends more and more to lie along the tangent at P , and by taking Q extremely close to P the chord PQ and the tangent at P are practically indistinguishable

the one from the other; whilst in the limit the two lines coincide. Then since the slope of the chord PQ gives the value of $\frac{\delta s}{\delta t}$, and the limiting value of $\frac{\delta s}{\delta t}$ is $\frac{ds}{dt}$, it follows that the slope of the tangent expresses $\frac{ds}{dt}$; but the slope of a curve at any point is measured

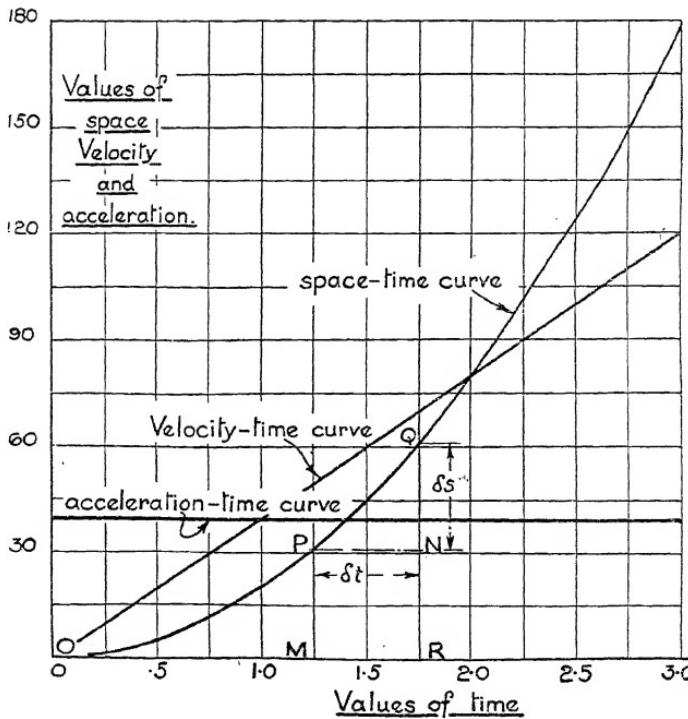


FIG. I.

by the slope of its tangent at that point, and hence we have evolved the most important principle, viz., that differentiation is the determination of the slopes of curves.

[Incidentally it may be remarked that here is a good illustration of the work on limiting values; for the slope of a curve, or of the tangent to the curve, is the limiting value of the slope of the chord, *i.e.*, the value found when the extremities of the chord coincide; and this value does not take the indeterminate form $\frac{0}{0}$, as might at first sight be supposed, but is a definite figure.]

Thus the slope of the tangent at any point on the space-time curve measures the actual rate of change of the space with regard to time at that particular instant; or, in other words, the actual velocity at that instant. Hence by drawing tangents to the space-time curve at various points and calculating the slopes, a set of values of the velocity is obtained: these values are then plotted to a base of time and a new curve is drawn, which gives by its ordinate the value of the velocity at any time and is known as the "velocity-time" curve.

Since this curve is obtained by the calculation of slopes, or rates of change, it is designated a *derived* or *slope* curve; the original curve, viz., the space-time curve, being termed the *primitive*.

In the case under notice the velocity-time curve is a sloping straight line, and in consequence its slope is constant, having the value 40. Hence the derived curve, which is the acceleration-time curve, is a horizontal line, to which the ordinate is 40. There are thus the three curves, viz., the primitive or space-time curve, the *first derived* curve or the velocity-time curve, and the *second derived* curve or the acceleration-time curve.

Graphic Differentiation.—The accurate construction of slope curves is a most tedious business, for the process already described necessitates the drawing of a great number of tangents, the calculations of their respective slopes and the plotting of these values. There are, however, two modes of graphic differentiation, both of which give results very nearly correct provided that reasonable care is taken over their use.

Method 1 (see Fig. 2).—Divide the base into small elements, the lengths of the elements not being necessarily alike, but being so chosen that the parts of the curve joining the tops of the consecutive ordinates drawn through the points of section of the base are, as nearly as possible, straight lines. Thus, when the slope of the primitive is changing rapidly, the ordinates must be close together; and when the curve is straight for a good length, the ordinates may be placed well apart. Choose a pole P, to the left of some vertical OA, the distance OP being made a round number of units, according to the horizontal scale. Erect the mid-ordinates for all the strips.

Through P draw PA parallel to ab , the first portion of the curve, and draw the horizontal Ac to meet the mid-ordinate of the first strip in c. Then dc measures, to some scale, the slope of the chord ab , and therefore the slope of the tangent to the primitive

curve at m , or the average slope of the primitive from a to b , with reasonable accuracy.

Continue the process by drawing PM parallel to bl and Ms horizontal to meet the mid-ordinate of the second strip in s : then cs is a portion of the slope or derived curve.

Repeat the operations for all the strips and draw the smooth curve through the points c, s , etc.: then this curve is the curve of slopes.

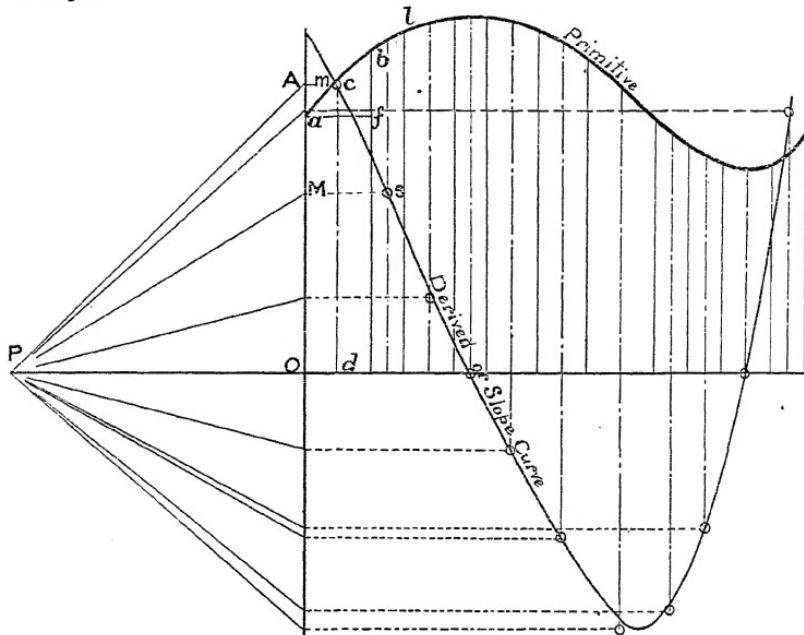


FIG. 2.—Graphic Differentiation, Method 1.

Indicate a scale of slope along a convenient vertical axis and the diagram is complete: the scale of slope being the old vertical scale divided by the polar distance expressed in terms of the horizontal units.

E. g., if the original vertical scale is $1'' = 40$ ft. lbs. and the horizontal scale is $1'' = 10$ ft.: then, if the polar distance p is taken as $2''$, i. e., as 20 horizontal units,

the new vertical scale, or scale of slope, is $1'' = \frac{40 \text{ ft. lbs.}}{20 \text{ ft.}} = 2 \text{ lbs.}$

Proof of the construction.—

The slope of the primitive curve at m = slope of curve ab

$$= \frac{bf}{af} = \frac{OA}{\rho} = \frac{cd}{\rho}$$

or, the ordinate dc , measured to the old scale, = $p \times$ the slope of the curve at m .

If, then, the original vertical scale is divided by p the ordinate dc , measured to the new scale, = slope of the curve at m .

The great disadvantage of this method is that parallels have to be drawn to very small lengths of line and a slight error in the setting of the set square may quite easily be magnified in the drawing of the parallel. Hence, for accuracy, extreme care in draughtsmanship is necessary.

It should be observed that this method of graphic differentiation is the converse of the method of graphic integration described in

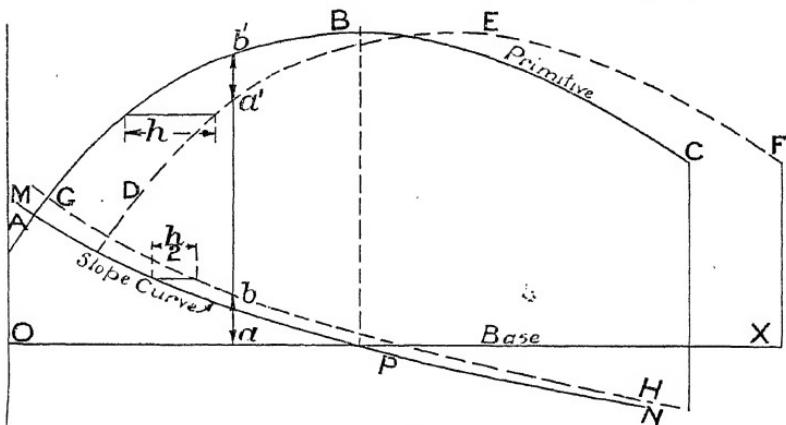


FIG. 3.—Graphic Differentiation, Method 2.

Chapter VII (Part I), and referred to in greater detail in Chapter V of the present volume.

Method 2.—Let ABC (Fig. 3) be the primitive curve.

Shift the curve ABC forward to the right a horizontal distance sufficiently large to give a well-defined difference between the curves DEF and ABC; but the horizontal distance, denoted by h , must not be great. From the straight line base OX set up ordinates which give the differences between the ordinates of the curves ABC and DEF, the latter curve being treated as the base: thus $ab = a'b'$. Join the tops of the ordinates so obtained to give the new curve GbH , and shift the curve GbH to the left a horizontal distance $= \frac{h}{2}$, this operation giving the curve MPN, which is the true slope or derived curve of the primitive ABC. Complete the diagram by adding a scale of slope, which is the old vertical scale divided by h (expressed in horizontal units).

This method can be still further simplified by the use of tracing paper, thus: Place the tracing paper over the diagram and trace the curve ABC upon it; move the tracing paper very carefully forward the requisite amount, viz., $\frac{h}{2}$, and with the dividers take the various differences between the curves, such as $a'b'$. Step off these differences from OX as base, but along ordinates $\frac{h}{2}$ units removed to the left of those on which the differences were actually measured: then draw the curve through the points and this is the slope curve.

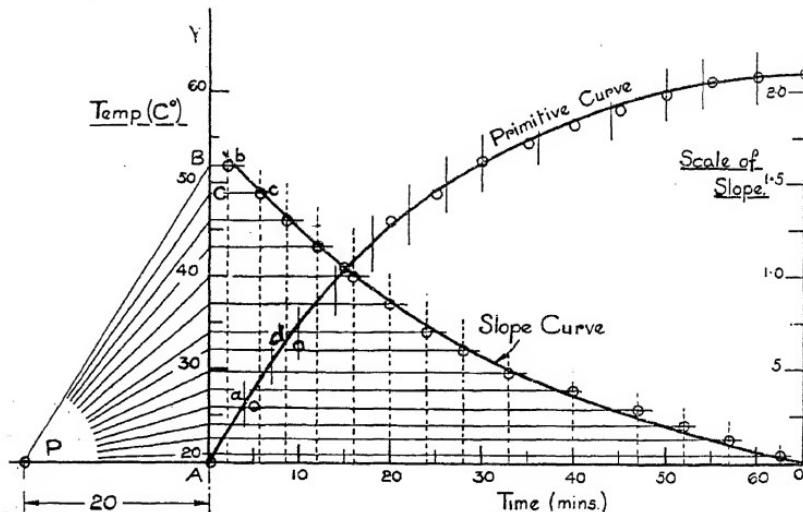


FIG. 3a.—Variation of Temperature of Motor Field Coils.

Examples on the use of these two methods now follow.

Example 2.—The temperature of the field coils of a motor was measured at various times during the passage of a strong current, with the following results—

Time (mins.) . .	0	5	10	15	20	25	30	35	40	45	50	55	60	65
Temperature (C. $^{\circ}$)	20	26	32.5	41	46	49	52.5	54.5	56.5	58	59.5	61	61.7	62

Draw a curve to represent this variation of temperature, and a curve to show the rate at which the temperature is rising at any instant during the period of 65 mins.

The values of the temperature when plotted to a base of time give the primitive curve in Fig. 3a.

To draw the slope curve we first divide the base in such a way that the portions of the curve between consecutive ordinates have the same inclination for the whole of their lengths, *i.e.*, the elements of the curve are approximately straight lines. Thus, in the figure, there is no appreciable change of slope between A and a , or a and d . There is no need to draw the ordinates through the points of section for their full lengths, since the intersections with the primitive curve are all that is required. Next a pole P is chosen, 20 horizontal units to the left of A, and through P the line PB is drawn parallel to the portion of the curve Az. A horizontal Bb cuts the mid-ordinate of the first strip at b , and b is a point on the slope or derived curve. The process is repeated for the second strip, PC being drawn parallel to ad and Cc drawn horizontal to meet the mid-ordinate of the second strip in c , which is thus a second point on the slope curve. A smooth curve through points such as b and c is the slope curve, giving by its ordinates the rate of increase of the temperature; and it will be observed that the rate of increase is diminished until at the end of 65 mins. the rate of change of temperature is zero, thus indicating that at the end of 65 mins. the losses due to radiation just begin to balance the heating effect of the current.

Since the polar distance = 20 units, the scale of slope

$$= \frac{\text{original vertical scale}}{20};$$

and in the figure the original vertical scale is $1'' = 20$ units; hence the scale of slope is $1'' = 1$ unit; and this scale is indicated to the right of the diagram.

Example 3.—Plot the curve $y = x^2$, x ranging from 0 to 3, and use Method 2 to obtain the derived curve.

The values for the ordinates of the primitive curve $y = x^2$ are as in the table—

x	0
y	0
	1
	4

and the plotting of these gives the curve OAB in Fig. 4.

Choosing h as .5 horizontal unit, the curve is first shifted forward this amount, and the curve CG results. The vertical differences between these two curves are measured, CG being regarded as the base curve, and are then set off from the axis of x as the base. Thus when $x = 3$, the ordinate of the curve OAB is 9 units, and that of CG is 6.25 so that the difference is 2.75, and this is the ordinate of the curve MN. By shifting the curve MN to the left by a distance = $\frac{5}{2}$, *i.e.*, .25 horizontal unit, the true slope curve ODE is obtained: this is a straight

line, as would be expected since the primitive curve is a "square" parabola.

As regards the scale of slope, the new vertical scale

$$= \frac{\text{old vertical scale}}{h}$$

and since $h = .5$, the new vertical scale, or scale of slope, which is used when measuring ordinates of the curve ODE, is twice the original vertical scale.

The derived curve supplies much information about the primitive. Thus, when the ordinate of the derived curve is zero, *i.e.*, when the derived curve touches or cuts the horizontal axis, the

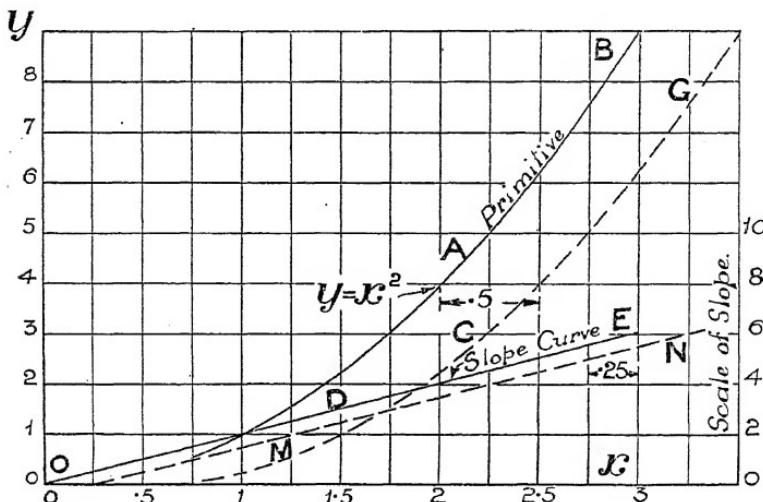


FIG. 4.—Graphic Differentiation.

slope of the primitive is zero; but if the slope is zero the curve must be horizontal, since it neither rises nor falls, and this is the case at a turning point, either maximum or minimum. Hence turning points on the primitive curve are at once indicated by zero ordinates of the slope curve.

Again, a positive ordinate of the derived curve implies a positive slope of the primitive, and thus indicates that in the neighbourhood considered the ordinate increases with increase of abscissa. Also a large ordinate of the slope curve indicates rapid change of ordinate of the primitive with regard to the abscissa.

This last fact suggests another and a more important one. By a careful examination of the primitive curve we see what is *actually*

happening, whilst the slope curve carries us further and tells us what is *likely to happen*. In fact, the rate at which a quantity is changing is very often of far greater importance than the actual value of the quantity; and as illustrations of this statement the following examples present the case clearly.

Example 4.—The following table gives the values of the displacement of a 21 knot battleship and the weight of the offensive and defensive factors, viz., armament, armour and protection. From these figures

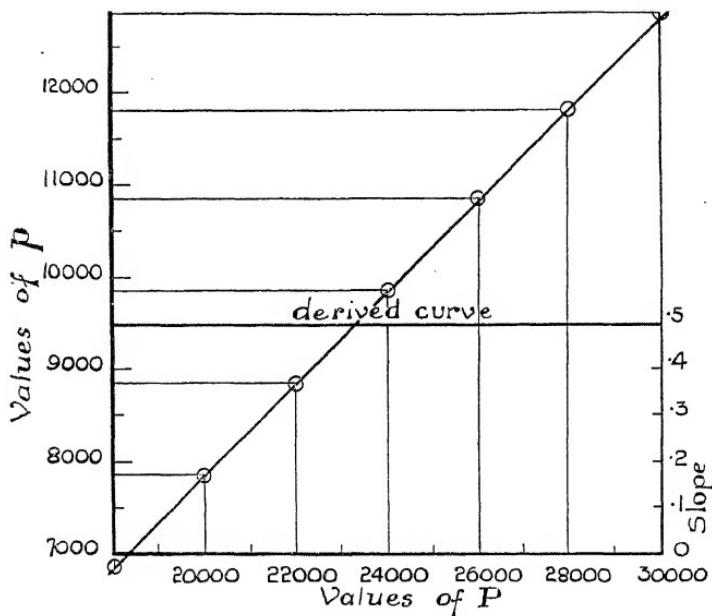


FIG. 5.—Displacement and Armament of Battleship.

calculate values of Q (ratio of armament, etc., to displacement) and q (rate of increase of armament, etc., with regard to displacement).

Find also the values of $\frac{q}{Q}$.

Displacement P tons	18000	20000	22000	24000	26000	28000	30000
Armament, etc., p tons	6880	7850	8830	9820	10810	11820	12845

The values of Q are found by direct division and are—

P	18000	20000	22000	24000	26000	28000	30000
Q	.383	.392	.401	.409	.416	.422	.428

Values of q , i.e., $\frac{dp}{dP}$, may be found by (a) construction of a slope curve, or (b) tabulating differences.

(a) *By construction of a slope curve.*—Plotting p along the vertical axis and P along the horizontal axis (see Fig. 5), we find that the points lie very nearly on a straight line. Hence the slope curve is a horizontal line, whose ordinate everywhere is the slope of the original line. By actual measurement the slope is found to be .498 and thus the average value for $\frac{dp}{dP}$ over the range considered, is .498. This average value of the rate of change does not, however, give as much information for our immediate purpose as the separate rates of change considered over the various small increases in the displacement.

(b) *By tabulation of differences*, as in previous examples—

P	p	δp	δP	$q = \frac{\delta p}{\delta P}$
18000	6880	—	—	
—	—	970	2000	.485
20000	7850	—	—	—
—	—	980	2000	.490
22000	8830	—	—	—
—	—	990	2000	.495
24000	9820	—	—	—
—	—	990	2000	.495
26000	10810	—	—	—
—	—	1010	2000	.505
28000	11820	—	—	—
—	—	1025	2000	.5125
30000	12845	—	—	

Now $\frac{\delta p}{\delta P}$ = rate of increase of armament compared with displacement; as the displacement increases it is seen from the table of values that this ratio increases, and the questions then arise: "Does this increase coincide with an increase or a decrease in the values of Q , and if with one of these, what is the relation between the two changes?"

By tabulating the corresponding values of q and Q and calculating the values of $\frac{q}{Q}$, we obtain the following table (the values of Q at 19000, 21000, etc., being found from a separate plotting not shown here)—

P	19000	21000	23000	25000	27000	29000
$\frac{P}{Q}$.485	.490	.495	.495	.505	.5125
Q	.387	.396	.405	.412	.419	.426
$\frac{q}{Q}$	1.253	1.236	1.223	1.202	1.203	1.204

It will be seen by examination of this table that the fraction $\frac{q}{Q}$ decreases as ships are made larger: in other words, while the armament increases with the displacement, the increase is not so great as it should be for the size of the ship, since the weight of the necessary engines, etc., is greater in proportion to the weight of armament and protection for the larger than for the smaller ships.

Thus, other things being equal, beyond a certain point it is better to rely on a greater number of smaller ships than a few very large ones.

Example 5.—Friend gives the following figures as the results of tests on iron plates exposed to the action of air and water. The original plates weighed about 2.5 to 3 grms.

Plot these figures and obtain the rate curves for the two cases, these curves being a measure of the corrosion: comment on the results.

Time in days . . .	2	7	13	19	26	32	37
In the light: loss of weight in grms. . .	.0048	.031	.0645	.08	.093	.126	—
In the dark: loss of weight in grms. . .	.0032	.0208	.037	.058	.0674	.0816	.0916

The two sets of values are plotted in Fig. 6, the respective curves being LLL for the plates exposed in the light, and DDD for those left in the dark. The effect of the action of light is very apparent from an examination of these curves. Next, the slope curves for the two cases are drawn, Method 2 being employed, but the intermediate steps are not shown. The curve *lll* is the slope curve for LLL, and *ddd* that for the curve DDD.

It will be observed that in both cases the rate of loss is great at the commencement, but decreases to a minimum value after 20 days exposure in the case of the curve *lll*, and after 25 days in the case of the curve *ddd*.

After these turning points have been reached the rate quickens,

the effect being very marked for the plates exposed to the light; and for these conditions the slope curve *III* suggests that the corrosive action is a very serious matter, since it appears that the rate of loss must steadily increase.

A further extremely good illustration of the value of slope curves is found in connection with the cooling curves of metals. In the early days of the research in this branch of science, the cooling curve alone was plotted, viz., temperatures plotted to a base of

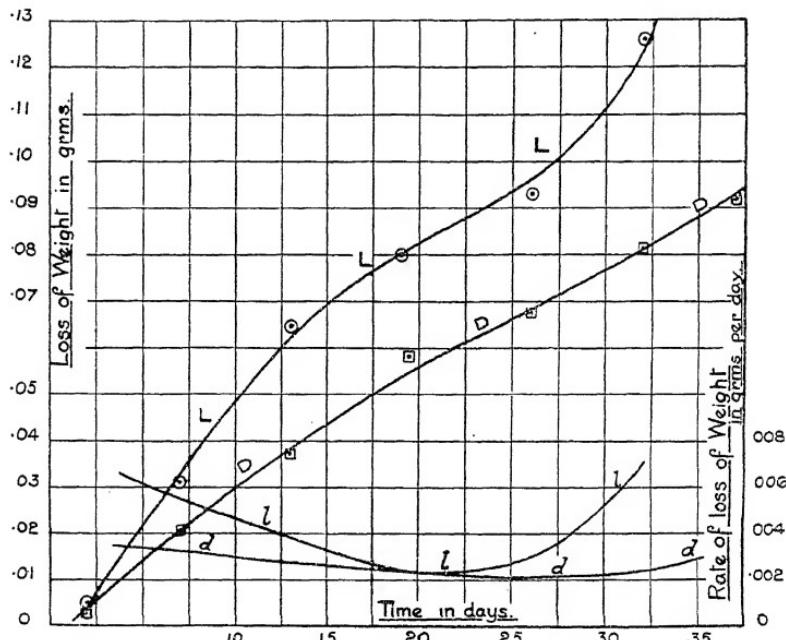


FIG. 6.—Tests on Corrosion of Iron Plate.

time. Later investigations, however, have shown that three other curves are necessary, viz., an inverse rate curve, a difference curve and a derived differential curve; the co-ordinates for the respective curves being—

- (a) Temperature (θ)—time (t) curve; t horizontal and θ vertical.
- (b) Inverse rate curve: $\frac{dt}{d\theta}$ horizontal and θ vertical. To obtain this curve from curve (a), the slopes must be very carefully calculated, and it must be remembered that these slopes are the measures of the inclinations to the vertical axis and not to the horizontal, i.e., are values of $\frac{dt}{d\theta}$ and not $\frac{d\theta}{dt}$.

(c) 0 vertical and $0 - \theta_1$ horizontal : $0 - \theta_1$ being the difference of temperature between the sample and a neutral body cooling under identical conditions.

(d) 0 vertical and $\frac{d(\theta - \theta_1)}{dt}$ horizontal : this curve thus being the inverse rate curve of curve (c).

Exercises 1.—On Rates of Change and Derived Curves

1. What do the fractions $\frac{\delta s}{\delta t}$ and $\frac{ds}{dt}$ actually represent (s being a displacement, and t a time)? Take some figures to illustrate your answer.

2. Further explain the meanings of $\frac{\delta s}{\delta t}$ and $\frac{ds}{dt}$ by reference to a graph.

3. When an armature revolves in a magnetic field the E.M.F. produced depends on the rate at which the lines of force are being cut. Express this statement in a very brief form.

4. For a non-steady electric current the voltage V is equal to the resistance R multiplied by the current C plus the self-inductance L multiplied by the time rate at which the current is changing. Express this in the form of an equation.

5. At a certain instant a body is 45.3 cms. distant from a fixed point. 2.14 seconds afterwards it is 21.7 cms. from this point. Find the average velocity during this movement. At what instant would your result probably measure the actual velocity?

6. At 3 ft. from one end of a beam the bending moment is 5 tons ft. At 3' 2 $\frac{1}{2}$ " from the same end it is 5.07 tons ft. If the shear is measured by the rate of change of bending moment, what is the average shearing force in this neighbourhood?

7. Tabulate the values of q , i.e., $\frac{\delta p}{\delta P}$ for the following case, the figures referring to a battleship of 23 knots.

P	18000	20000	22000	24000	26000	28000	30000	32000
p	6170	7080	8000	8930	9890	10855	11820	12810

8. Tabulate the values of $\frac{q}{Q}$ for the case of a battleship of 25 knots from the following—

P | 18000 | 20000 | 22000 | 24000 | 26000 | 28000 | 30000 | 32000

5210 6050 6910 7790 8660 9550 10460 11370

$$q = \frac{\delta p}{\delta P} \text{ and } Q = \frac{p}{P}.$$

9. Tabulate the values of the velocity and the acceleration for the following case—

Space (feet) 1 2.4 4.4 6 7.6 11.2 15.6 20.4

Time (secs.) .6 .7 .8 I 1.4

10. Plot the space-time curve for the figures given in Question 9 and by graphic differentiation obtain the velocity-time and the acceleration-time curves.

11. Plot the curve $y = \cdot5x^3$ from $x = -2$ to $x = +4$ and also its derived curve. What is the ordinate of the latter when $x = 1.94$?

12. Given the following figures for the mean temperatures of the year (the average for 50 years), draw a curve for the rate of change of temperature and determine at what seasons of the year it is most rapid in either direction.

Time (intervals of $\frac{1}{3}$ month)	o	1	2	3	4	5	6	7	8	9	10	11
Temperature	38.6	37.9	38.4	39.8	38.5	39.5	40.3	40.7	41.5	45.5	45.5	48.5
	12	13	14	15	16	17	18	19	20	21	22	23
	49.3	52	55	57.2	58.4	60.5	61.4	62.5	62.9	62.2	62.5	61.1
	59.8	58.2	55.8	53.2	51.4	49.8	48.5	47.2	46.0	44.8	43.5	42.2
	40.6	39.8	38.8	37.8	36.8	35.8	34.8	33.8	32.8	31.8	30.8	29.8
	28	29	30	31	32	33	34	35	36			
	54.2	51	48.8	46.8	43.5	42.1	40.6	39.8	38.8	38.6		

13. s is the displacement from a fixed point of a tramcar, in time t secs. Draw the space-time, velocity-time and acceleration-time curves.

t	0	1			5	6	7		9	10
s	0	4	11	21	34	50	91	116	144	175

The scales must be clearly indicated.

14. The table gives the temperature of a body at time t secs. after it has been left to cool. Plot the given values and thence by differentiation obtain the rate of cooling curve. What conclusions do you draw from your final curve?

15. The following figures give the bending moment at various points along a beam supported at both ends and loaded uniformly. Draw the bending moment curve, and by graphic differentiation obtain the shear and load curves. Indicate clearly the scales and write down the value of the load per foot run.

Distance from one end (ft.) . . . }	8 10 12 14 16 18 20
-------------------------------------	---------------------------------

Bending moment } (tons ft.) . . . }	0 3.5 6.3 8.4 9.6 10 9.6 8.4 6.3 3.5
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16. By taking values of θ in the neighbourhood of 15° find the actual rate of change of $\sin \theta$ with regard to θ (θ being expressed in radians). Compare your result with the value of $\cos 15^\circ$. In what general way could the result be expressed?

17. If the shear at various points in the length of a beam is as in the table, draw the load curve (*i.e.*, the derived curve) and write down the loading at $3\frac{1}{2}$ ft. from the left-hand end.

Distance from left-hand end (ft.)

Shearing force (tons)	·3	·1.5	2.1
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18. An E.M.F. wave is given by the equation

$$E = 150 \sin 314t + 50 \sin 942t.$$

Derive graphically the wave form of the current which the E.M.F. will send through a condenser of 20 microfarads capacity, assuming the condenser loss to be negligible.

Given that $C = K \frac{dE}{dt}$, where C is current and K is capacity.

19. If momentum is given by the product of mass into velocity, and force is defined as the time rate of change of momentum, show that force is expressed by the product of mass into acceleration.

20. The following are the approximate speeds of a locomotive on a run over a not very level road. Plot these figures and thence obtain a curve showing the acceleration at any time during the run.

Time (in mins. and secs.)	1.0 2.15 6.15 9.22 11.45 14.26 16.35 20.52 23.10
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Speed (miles per hour)	10 18.2 22.8 25.5 28 29.2 28.6 26.1
------------------------	---

21. Taking the following figures referring to CO_2 for use in a refrigerating machine, draw the rate curve and find the value of $\frac{dp}{dt}$ when $t=18^\circ \text{ F.}$

$t^\circ \text{ F. . . }$	-5 0 5 10 15 20 25 30 35 40
$p \text{ lbs. per sq. in. . . }$	285 310 335 363 392 423 456 491 528 567

22. The weight of a sample of cast iron was measured after various heatings with the following results; the gain in weight being due to the external gases in the muffle.

Number of heats . . .	o		25		26				
Weight . . .	146.88	146.94	147.04	147.54	148.02	148.11	148.27	148.36	148.46
					27	30	35	39	45
					148.61	149.18	150.49	152.36	156.44

Plot a curve to represent this table of values, and from it construct the rate curve.

23. The figures in the table are the readings of the temperature of a sample of steel at various times during its cooling. Plot these values to a time base, and thence draw the "inverse rate" curve, *i.e.*, the curve in which values of $\frac{dt}{d\theta}$ are plotted horizontally and the temperatures along the vertical axis.

Time in secs. (t) . . .	75	90	105	120	135	150	165	180	195	210	225
Temperature in C. $^{\circ}$ (θ)	850	848	844.7	842	839.5	838.5	838.2	838.1	838	837.9	837.5
	240	255	270	285	292.5	300	315	330	345	360	367.5
	836	833	829	825	823.3	822.2	821.7	821.5	821.3	821.1	819

CHAPTER II

DIFFERENTIATION OF FUNCTIONS

Differentiation of ax^n .—It has been shown in Chapter I how to compare the changes in two quantities with one another, and thus to determine the rate at which one is changing with regard to the other at any particular instant, for cases in which sets of values of the two variables have been stated. In a great number of instances, however, the two quantities are connected by an equation, indicating that the one depends upon the other, or, in other words, one is a *function* of the other. Thus if $y = 5x^3$, y has a definite value for each value given to x , and this fact is expressed in the shorter form $y = f(x)$. Again, if $z = 17x^2y - 4xy^3 + 5 \log y$, where both x and y vary, z depends for its values on those given to both x and y , and $z = f(x, y)$.

To differentiate a function it is not necessary to calculate values of x and y and then to treat them as was done to the given sets of values in the previous chapter. This would occasion a great waste of time and would not give absolutely accurate results. Rules can be developed entirely from first principles which permit the differentiation of functions without any recourse to tables of values or to a graph.

We now proceed to develop the first of the rules for the differentiation of functions; and we shall approach the general case, viz., that of $y = ax^n$, by first considering the simple case of $y = x^3$. Our problem is thus to find the rate at which y changes with regard to x , the two variables (y the dependent and x the independent variable or I.V.) being connected by the equation $y = x^3$.

The rate of change of y with regard to x is given by the value of $\frac{dy}{dx}$, and this is sometimes written as Dy when it is clearly understood that differentiation is with regard to x : the *operator* D having many important properties, as will be seen later in the book. If y is expressed as $f(x)$, then $\frac{dy}{dx}$ is often written $\frac{df(x)}{dx}$ or $f'(x)$.

$\frac{dy}{dx}$, Dy , $\frac{df(x)}{dx}$ or $f'(x)$ is called the *derivative* or *differential coefficient* of y with respect to x ; and the full significance of the latter of these terms is shown in Chapter III.

We wish to find a rule giving the actual rate of change of y with regard to x , y being $= x^3$, the rule to be true for all values of x . As in the earlier work, the actual rate of change must be determined as the limiting value of the average rate of change.

Let x be altered by an amount δx so that the new value of $x = x + \delta x$; then y , which depends upon x , must change to a new value $y + \delta y$, and since the relation between y and x is $y = x^3$ for all values of x —

$$(\text{new value of } y) = (\text{new value of } x)^3$$

$$\text{or } y + \delta y = (x + \delta x)^3 = x^3 + 3x^2 \cdot \delta x + 3x \cdot (\delta x)^2 + (\delta x)^3 \quad (1)$$

$$\text{but } y = x^3 \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (2)$$

Hence, by subtraction of (2) from (1)—

$$y + \delta y - y = 3x^2 \cdot \delta x + 3x \cdot (\delta x)^2 + (\delta x)^3$$

$$\text{and } \delta y = 3x^2 \cdot \delta x + 3x \cdot (\delta x)^2 + (\delta x)^3.$$

Divide through by δx , and—

$$\frac{\delta y}{\delta x} = 3x^2 + 3x \cdot \delta x + (\delta x)^2.$$

Thus an *average* value for the rate of change over a small interval δx has been found; and to deduce the *actual* rate of change the interval δx must be reduced indefinitely.

$$\text{Let } \delta x = .001; \text{ then } \frac{\delta y}{\delta x} = 3x^2 + (3x \times .001) + .000001$$

$$= 3x^2 + .003x + .000001$$

whilst if $\delta x = .00001$ —

$$\frac{\delta y}{\delta x} = 3x^2 + .00003x + .0000000001 \quad . \quad (3)$$

Evidently, by still further reducing δx the 2nd and 3rd terms of (3) can be made practically negligible in comparison with the 1st term.

Then, in the limit, the right-hand side becomes $3x^2$,

$$\text{and thus— } \frac{dy}{dx} = \lim_{\delta x \rightarrow 0} \frac{\delta y}{\delta x} = 3x^2.$$

$$\text{or } \frac{dx^3}{dx} = 3x^2.$$

This relation can be interpreted graphically in the following manner : If the curve $y = x^3$ be plotted, and if also its slope curve be drawn by either of the methods of Chapter I, then the equation to the latter curve is found to be $y = 3x^2$.

The two curves are plotted in Fig. 7.

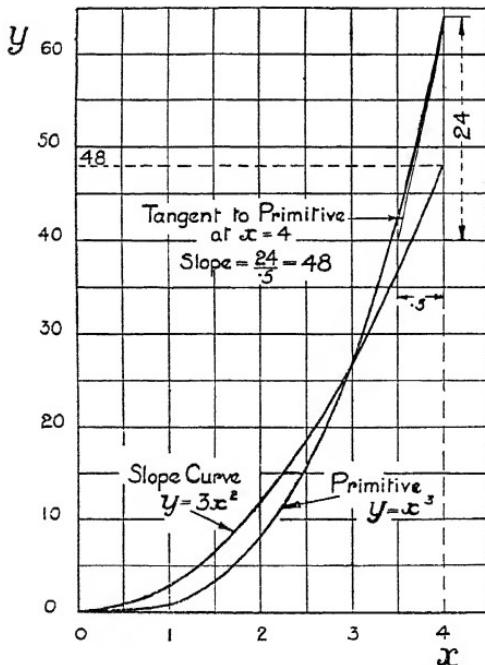


FIG. 7.—Primitive and Slope Curves.

Example 1.—Find the slope of the curve $y = x^3$ when $x = 4$.

$$\text{The slope of the curve} = \frac{dy}{dx} = \frac{dx^3}{dx} = 3x^2$$

$$\text{and if } x = 4 \quad \frac{dy}{dx} = 3 \times 4^2 = 48.$$

Meaning that, in the neighbourhood of $x = 4$, the ordinate of the curve $y = x^3$ is changing 48 times as fast as the abscissa ; this fact being illustrated by Fig. 7.

Working along the same lines, it would be found that $\frac{dx^4}{dx} = 4x^3$, and $\frac{dx^5}{dx} = 5x^4$ (the reader is advised to test these results for himself).

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Re-stating these relations in a modified form—

$$\frac{dx^3}{dx} = 3x^2 = 3x^{3-1}$$

$$\frac{dx^4}{dx} = 4x^3 = 4x^{4-1}$$

$$\frac{dx^5}{dx} = 5x^4 = 5x^{5-1}$$

We note that in all these cases the results take the form—

$$\frac{dx^n}{dx} = nx^{n-1}.$$

Thus the three cases considered suggest a general rule, but it would be unwise to accept this as the true rule without the more rigid proof, which can now be given.

Proof of the rule—

$$\frac{dx^n}{dx} = nx^{n-1}.$$

Let $y = x^n$, this relation being true for all values of x . . . (1)

If x is increased to $x + \delta x$, y takes a new value $y + \delta y$, and from (1) it is seen that—

$$y + \delta y = (x + \delta x)^n.$$

Expand $(x + \delta x)^n$ by the Binomial Theorem (see p. 463, Part I). Then—

$$\begin{aligned} y + \delta y &= x^n + nx^{n-1}\delta x + \frac{n(n-1)}{1_2}x^{n-2}(\delta x)^2 \\ &\quad + \frac{n(n-1)(n-2)}{1_3}x^{n-3}(\delta x)^3 + \dots (\delta x)^n. \end{aligned} \quad (2)$$

Subtract (1) from (2), and—

$$\delta y = nx^{n-1}\delta x + \frac{n(n-1)}{1_2}x^{n-2}(\delta x)^2 + \frac{n(n-1)(n-2)}{1_3}x^{n-3}(\delta x)^3 + \dots (\delta x)^n$$

Divide by δx —

$$\frac{\delta y}{\delta x} = nx^{n-1} + \frac{n(n-1)}{1_2}x^{n-2}(\delta x) + \frac{n(n-1)(n-2)}{1_3}x^{n-3}(\delta x)^2 + \text{terms}$$

containing products of $(\delta x)^3$ and higher powers of (δx) .

Let δx be continually decreased, and then, since δx is a factor of the second and all succeeding terms, the values of these terms can be made as small as we please by sufficiently diminishing δx .

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Thus in the limit— $\frac{\delta y}{\delta x} \rightarrow nx^{n-1}$

$$\text{or } \frac{dy}{dx} = \lim_{\Delta x \rightarrow 0} \frac{\delta y}{\delta x} = nx^{n-1}$$

Hence the first rule for differentiation of functions is established, viz.—

$$\frac{dx^n}{dx} = nx^{n-1}$$

i.e., differentiation lowers the power of the I.V. by one, but the new power of x must be multiplied by the original exponent.

The reason for the multiplication by the n can be readily seen, for the bigger the value of n the steeper is the primitive curve and therefore the greater the change of y for unit change of x . The n actually determines the slope of the primitive (cf. Part I, p. 340), and it must therefore be an important factor in the result of differentiation, since that operation gives the equation of the slope curve.

To make the rule perfectly general, allowance must be made for the presence of the constant multiplier a in ax^n .

It will be agreed that if the curve $y = x^3$ had been plotted, the curve $y = 4x^3$ would be the same curve modified by simply multiplying the vertical scale by 4. Hence, in the measurement of the slope, the vertical increases would be four times as great for the curve $y = 4x^3$ as for the curve $y = x^3$, provided that the same horizontal increments were considered.

Now the slope of the curve $y = x^3$ is given by the equation—

$$\frac{dy}{dx} = 3x^2$$

so that the slope of the curve $y = 4x^3$ is given by—

$$\frac{dy}{dx} = 4 \times 3x^2 = 12x^2.$$

In other words, the constant multiplier 4 remains a multiplier throughout differentiation. This being true for any constant factor—

$$\frac{d}{dx} ax^n = nax^{n-1}$$

Accordingly, a constant factor before differentiation remains as such after differentiation.

We can approach the differentiation of a multinomial expression

by discussing the simple case $y = 5x^2 + 17$ (a binomial, or two-term expression). The curves $y = 5x^2$ and $y = 5x^2 + 17$ are seen plotted in Fig. 8, and an examination shows that the latter curve is the former moved vertically an amount equal to 17 vertical units, *i.e.*, the two curves have the same form or shape and consequently their slopes at corresponding points are alike. Thus if a tangent is drawn to each curve at the point for which $x = 2.5$, the slope of each tangent is measured as $\frac{25}{1}$, *i.e.*, 25; and consequently the diagram informs us that the term 17 makes no difference to the slope.

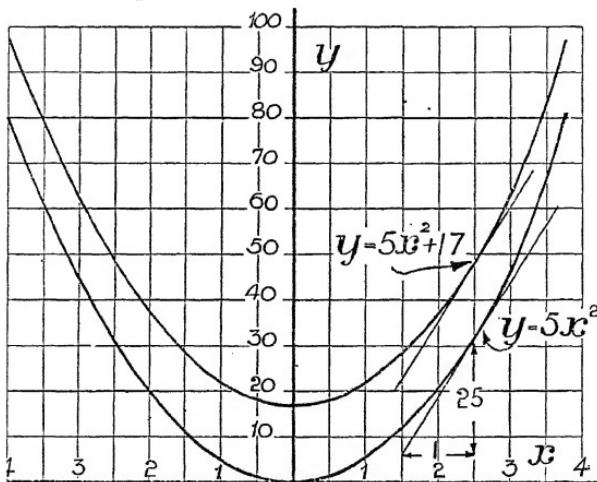


FIG. 8.

$$\text{Thus—} \quad \frac{d}{dx} 5x^2 = \frac{d}{dx} (5x^2 + 17).$$

Now, by differentiating $5x^2 + 17$ term by term, we have—

$$\begin{aligned} \frac{d}{dx} (5x^2 + 17) &= \frac{d}{dx} 5x^2 + \frac{d}{dx} 17 = \frac{d}{dx} 5x^2 + 0 \\ &= \frac{d}{dx} 5x^2 \end{aligned}$$

since 17 is a constant and does not in any way depend upon x , and therefore its rate of change must be zero.

It is seen that in this simple example it is a perfectly logical procedure to differentiate term by term and then add the results; and the method could be equally well applied to all many-term expressions.

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Hence $\frac{d}{dx}(ax^n + bx^{n-1} + cx^{n-2} + \dots + d) = nax^{n-1} + b(n-1)x^{n-2} + c(n-2)x^{n-3} + \dots$
 and $\frac{d}{dx}(ax^n + b) = nax^{n-1}.$

To apply these rules to various numerical examples :—

Example 2.—Differentiate with respect to x the function—

$$9x^{1.6} + 4 + 2x^{-5}.$$

$$\begin{aligned}\frac{d}{dx}(9x^{1.6} + 4 + 2x^{-5}) &= \frac{d}{dx}9x^{1.6} + \frac{d}{dx}4 + \frac{d}{dx}2x^{-5} \\ &= (9 \times 1.6x^{0.6}) + 0 + (2 \times -5x^{-6}) \\ &= 14.4x^{0.6} + x^{-6} \quad \text{or} \quad 14.4x^{0.6} + \frac{-}{\sqrt{x}}.\end{aligned}$$

Example 3.—If $y = .8 \times \sqrt{\frac{1}{x^3}}$, find the value of $\frac{dy}{dx}$

$$y = .8 \times \sqrt{\frac{1}{x^3}} = .8 \times \frac{1}{x^{1.5}} = .8x^{-\frac{3}{2}} \quad \text{or} \quad .8x^{-1.5}$$

so that in comparison with the standard form—

$$a = .8 \text{ and } n = -1.5.$$

Then—

$$\frac{dy}{dx} = -1.5 \times .8x^{-1.5-1} = -1.2x^{-2.5} \quad \text{or} \quad -\frac{1.2}{x^{2.5}}$$

Example 4.—If $\rho v^{1.41} = C$, the equation representing the adiabatic expansion of air, find $\frac{dp}{dv}$.

In this example we have to differentiate p with regard to v , and before this can be done p must be expressed in terms of v .

$$\text{Now } \rho v^{1.41} = C, \text{ so that } p = \frac{C}{v^{1.41}} = Cv^{-1.41}.$$

$$\text{Hence } \frac{dp}{dv} = \frac{d}{dv}Cv^{-1.41} = C \times -1.41v^{-2.41} = -1.41Cv^{-2.4}$$

and this result can be put into terms of p and v only, if for C we write its value $\rho v^{1.41}$.

$$\text{Thus } \frac{dp}{dv} = -1.41 \times \rho v^{1.41} \times v^{-2.41} = -1.41\rho v^{-1} = -\frac{1.41\rho}{v}.$$

Example 5.—The formula giving the electrical resistance of a length of wire at temperature t° C. is—

$$R_t = R_0(1 + \alpha t)$$

where R_0 = Resistance at 0° C. Find the increase of resistance per 1° C. rise of temperature per ohm of initial resistance, and hence state a meaning for α .

The question may be approached from two standpoints; viz.—

(a) Working from first principles.

$$\begin{aligned} R_t &= R_0(1 + \alpha t) = R_0 + R_0\alpha t \\ R_t - R_0 &= R_0\alpha t \end{aligned}$$

$$\text{i.e., increase in resistance for } t^{\circ} \text{ C.} = R_0\alpha t$$

$$\text{, , , , } 1^{\circ} \text{ C.} = \frac{R_0\alpha t}{t} = R_0\alpha$$

but this is the resistance increase for initial resistance R_0 , hence increase in resistance per 1° C. per ohm initial resistance = $\frac{R_0\alpha}{R_0} = \alpha$.

(b) By differentiation.

$$\text{Rate of change of } R_t \text{ with regard to } t = \frac{dR_t}{dt}$$

$$= \frac{d}{dt}(R_0 + R_0\alpha t)$$

$$= 0 + R_0\alpha = R_0\alpha$$

and consequently the rate of change of resistance per 1° C. per 1 ohm initial resistance = α .

The symbol α is thus the "temperature coefficient," its numerical value for pure metals being .0038.

Example 6.—Find the value of $\frac{d}{ds}\left(4s^4 - \frac{3}{s^2} + 6s^{\frac{1}{5}} - 1 \cdot 8^4\right)$.

Write the expression as $4s^4 - 3s^{-2} + 6s^{\frac{1}{5}} - 1 \cdot 8^4$.

Then—

$$\begin{aligned} \frac{d}{ds}\left(4s^4 - 3s^{-2} + 6s^{\frac{1}{5}} - 1 \cdot 8^4\right) &= 4 \times 4s^3 - (3 \times -2s^{-3}) + (6 \times \cdot 5s^{-\frac{4}{5}}) - 0 \\ &= 16s^3 + 6s^{-3} + 3s^{-\frac{4}{5}} \\ &= 16s^3 + \frac{6}{s^3} + \frac{3}{\sqrt[5]{s}} \end{aligned}$$

Example 7.—If $x = a^{n-1} (1 - a^{-n})^{n-1}$, a formula referring to the flow of a gas through an orifice, find an expression for $\frac{dx}{da}$.

As it stands $a^{n-1} (1 - a^{-n})^{n-1}$ is a product of functions of the I.V. (in this case a), and it cannot therefore be differentiated with our D

present knowledge. We may simplify, however, by removing the brackets, and then—

$$\begin{aligned}x &= a^n - a^{\frac{n-1}{n}} \cdot a = a^n - a^{\frac{n+1}{n}} \\ \frac{dx}{da} &= \frac{d}{da} \left(a^{\frac{2}{n}} - a^{\frac{n+1}{n}} \right) \\ &= \frac{2}{n} \times a^{\frac{2}{n}-1} - \frac{n+1}{n} a^{\frac{n+1}{n}-1} \\ &= {}^2 a^{\frac{2-n}{n}} - \frac{n+1}{n} a^{\frac{1}{n}} \\ &= \frac{1}{n} \left(2a^{\frac{-n}{n}} - (n+1)a^{\frac{1}{n}} \right).\end{aligned}$$

Example 8.—Determine the value of

$$\frac{d}{dm} \left(\frac{17m^{7.5} + 45m^{9.56} + 11 + 2.4m^{4.32}}{5m^{4.32}} \right).$$

To avoid the quotient of functions of m , divide each term by $5m^{4.32}$, then the expression $= \frac{17m^{7.5}}{5m^{4.32}} + \frac{45m^{9.56}}{5m^{4.32}} + \frac{11}{5m^{4.32}} + \frac{2.4m^{4.32}}{5m^{4.32}}$

$$\begin{aligned}&= 3.4m^{3.57} + 0.9m^{5.54} + 2.2m^{-4.32} + .48 \\ \text{and } \frac{d}{dm} (\text{expression}) &= (3.4 \times -3.57m^{-4.57}) - (0.9 \times 5.54m^{4.54}) \\ &\quad + (2.2 \times -4.32m^{-5.32}) + 0 \\ &= -12.14m^{-4.57} - 4.99m^{4.54} - 9.50m^{-5.32} \\ &= -\left(\frac{12.14}{m^{4.57}} + 4.99m^{4.54} + \frac{9.5}{m^{5.32}} \right).\end{aligned}$$

Proof of the construction for the slope curve given on p. 14.

Let us deal first with the particular case in which the equation of the primitive curve is $y = x^2$.

Referring to Fig. 4, the equation of the curve OAB is $y = x^2$, and the equation of the curve CG is $y_1 = (x - h)^2 = x^2 + h^2 - 2xh$.

Hence the difference between the ordinates of the curves OAB and CG, the latter being regarded as the base curve—

$$\begin{aligned}&= x^2 - x^2 - h^2 + 2xh \\ &= 2xh - h^2\end{aligned}$$

so that the equation of the curve MN is—

$$v_s = 2xh - h^2.$$

Now the curve ODE is the curve MN shifted back a distance of $\frac{h}{2}$ horizontal units, and hence its equation is $y_3 = 2\left(x + \frac{h}{2}\right)h$

since for x we must now write $(x + \frac{h}{2})$.

Thus the equation of curve ODE is—

$$y_3 = 2xh$$

or

$$\frac{y_3}{h} = 2x$$

i.e., if Y be written for $\frac{y_3}{h}$, $Y = 2x$

or the equation of the curve ODE is that of the slope curve of the curve $y = x^2$ provided that the ordinates are read to a certain scale; this scale being the original vertical scale divided by h expressed in horizontal units.

Hence the curve ODE is the slope curve of the curve OAB.

Before discussing the general case, let us take the case of the primitive with equation $y = x^3$.

If the curve be shifted forward an amount $= h$, the equation of the new curve is—

$$y_1 = (x - h)^3$$

and the equation of the curve giving the differences of the ordinates is—

$$\begin{aligned} y_2 = y - y_1 &= x^3 - (x - h)^3 = x^3 - x^3 + 3x^2h - 3xh^2 + h^3 \\ &= 3x^2h - 3xh^2 + h^3. \end{aligned}$$

By shifting this curve $\frac{h}{2}$ units to the left we change its equation, by writing $\left(x + \frac{h}{2}\right)$ in place of x , into the form—

$$\begin{aligned} y_3 &= 3\left(x + \frac{h}{2}\right)^2h - 3\left(x + \frac{h}{2}\right)h^2 + h^3 \\ &= 3x^2h + \frac{3h^3}{4} + 3h^2x - 3xh^2 - \frac{3h^3}{2} + h^3 \\ &= 3x^2h + \frac{h^3}{4} \end{aligned}$$

Dividing by h —

$$y_3 = 3x^2 + \frac{h^2}{4}$$

or $Y = 3x^2 + \frac{h^2}{4}$

Now if h is taken sufficiently small, $\frac{h^2}{4}$ is negligible in comparison with $3x^2$, and we thus have the equation of the curve $Y = 3x^2$, which is the slope curve of the curve $y = x^3$; but the ordinates must be measured to the old vertical scale divided by h .

We may now consider the case of the primitive $y = x^n$. Adopting the notation of the previous illustrations—

$$\begin{aligned}y_1 &= (x-h)^n \\y_2 = y - y_1 &= x^n - (x-h)^n = \left(x^n - nx^{n-1}h + \frac{n(n-1)}{2}x^{n-2}h^2 \right) \\&\quad - nx^{n-1}h + \frac{n(n-1)}{2}x^{n-2}h^2 + \dots\end{aligned}$$

Write $\left(x + \frac{h}{2}\right)$ in place of x , and then— .

$$\begin{aligned}y_3 &= n\left(x + \frac{h}{2}\right)^{n-1}h - \frac{n(n-1)}{2}\left(x + \frac{h}{2}\right)^{n-2}h^2 + \dots \\ \frac{y_3}{h} &= \left[nx^{n-1} + \frac{n(n-1)}{2}x^{n-2}h + \frac{n(n-1)(n-2)}{8}x^{n-3}h^2 + \dots \right. \\ &\quad \left. - \frac{n(n-1)}{2}x^{n-2}h - \frac{n(n-1)(n-2)}{4}x^{n-3}h^2 - \dots \right] \\ &= nx^{n-1} + \text{terms containing } h \text{ as a factor.}\end{aligned}$$

Hence if h is made very small—

$$Y \text{ or } \frac{y_3}{h} = nx^{n-1}.$$

Exercises 2.—On Differentiation of Powers of the I.V.

1. Find from first principles the differential coefficient of x^4 .

2. Find the slope of the curve $y = \frac{8}{x^3}$ when $x = 5$

(a) By actual measurement and (b) by differentiation.

3. The sensitiveness of a governor is measured by the change of height corresponding to the change of speed expressed as a fraction of the speed. Thus if h and v represent respectively the height and speed, the sensitiveness = $dh \div \frac{dv}{v}$. If the height is inversely proportional to the square of the velocity, find an expression for the sensitiveness.

Differentiate with respect to x the functions in Exs. 4 to 15.

4. $3x^9$. 5. $\frac{15}{x^5}$. 6. $81 \cdot 5x^{-23}$. 7. $19x^{1.72}$. 8. $\frac{.215}{4x^{-1.18}}$.

9. $\frac{8x^{4.13}}{2.94x^{-7.55}}$

10. $5^9 \sqrt{x^{-2}}$

11. $\left(\frac{4x^{-2}}{7x^{\frac{3}{5}}}\right)^{\frac{1}{2}}$

12. $15x^{1.42}$

13. $15x^3 - 16x^{2.8} - \frac{14}{2x^3} + 87.$

14. $9y^{8.17}$

15. $\frac{8a^2b^{1.75}}{7. \sqrt[3]{27x^{1.5}}}$

16. Find the value of $\frac{dp}{dv}$ when $pv^{1.3} = 570$ and $v = 28.1$.

✓ 17. Find the value of $\frac{d}{dv} \left(\frac{1.17v^9 - 2v^8 - 3v^{.72} + v^{-.04} + 24}{8v^{4.16}} \right)$.

✓ 18. If $E = -15 + 14T - 0.068T^2$, find the rate of change of E with regard to T when T has the value 240.

✓ 19. Calculate the value of $\frac{dH}{dv}$ from $\frac{dH}{dv} = \frac{1}{\gamma-1} \left\{ v \frac{dp}{dv} + \gamma p \right\}$ when $pv^{1.3} = C$ and $\gamma = 1.4$.

20. Find the rate of discharge ($\frac{dm}{dt}$) of air through an orifice from a tank (the pressure being 55 lbs./ $\square^{\prime \prime}$) from the following data—

$$\begin{aligned} 144pV &= mRT \\ R &= 53.2, V = 47.7, T = 548. \end{aligned}$$

Time (secs.) (t)	0	60	135	255	315
Pressure (lbs. per sq. in.) (p)	63	45	30	15	10

Hint.—Plot p against t and find $\frac{dp}{dt}$ when $p = 55$.

21. If P = load displacement of a ship,

p = weight of offensive and defensive factors.

Then $P = aP + bP^{\frac{2}{3}} + p$.

Find the rate of increase of armament and protection in relation to increase of displacement.

✓ 22. If $M = \frac{w(l-x)^2y}{2l} \left(1 + \frac{y}{l} \right) - \frac{w(y-x)^2}{2l}$, find $\frac{dM}{dx}$. y and l being constants.

✓ 23. If $M = \frac{Wy}{2l^2} (l^2 - 4y^2)$, find the value of y that makes $\frac{dM}{dy} = 0$.

24. If $S = \frac{w}{2} \left\{ \frac{(x+ny)^2 - x^2}{l} - \frac{x^2}{y} \right\}$, find the value of $\frac{dS}{dx}$.

25. Find the value of h which makes $\frac{dD}{dh} = 0$ when—

$$D = \frac{f_c + f_t}{2Eh} \left(\frac{l^2}{4} + \frac{ld}{4} + \frac{lh^2}{d} \right).$$

[h is the height of a Warren girder; and the value found will be the height for maximum stiffness.]

26. If $p = \frac{2B}{r^3} - A$ and $q = \frac{B}{r^3} + A$, find the value of $r \frac{dp}{dr}$ in terms of p and q . (This question refers to the stresses in a thick spherical shell, p being the radial pressure, and q the hoop tension.)

✓ 27. In a certain vapour the relation between the absolute temperature τ and the absolute pressure p is given by the equation $\tau = 140p + 465$, and the latent heat L is given by $L = 1431 - .5\tau$. Find the volume, in cu. ft., of 1 lb. of the vapour when at a pressure of 51 lbs. per sq. in. absolute, from—

$$V = 0.02 = \frac{JL}{144\tau} \cdot \frac{d\tau}{dp} \quad (J = 778).$$

28. For a rolling uniform load of length r on a beam of length l , the bending moment M at a point is given by—

$$M = \frac{wry}{l} \left(l - y + x - \frac{r}{2} \right) - \frac{wx^2}{2}.$$

If y is a constant, find an expression for the shear (*i. e.*, the rate of change of bending moment).

29. Given that ρ = electrical resistance in microhms per cu. cm.
and x = percentage of aluminium in the steel,
then $\rho = 12 + 12x - 3x^2$ for steel with low carbon content.

Find the rate of increase of ρ with increase of aluminium when $x = 4$.

✓ 30. The equation giving the form taken by a trolley wire is—

$$y = \frac{x^2}{2000} - \frac{x^2}{1760}$$

and the radius of curvature = $\frac{I}{\frac{d^2y}{dx^2}}$

Find the value of the radius of curvature.

Good examples of the great advantage obtained by utilising the rules of differentiation already proved are furnished by the two following examples, which have reference to loaded beams.

Example 9.—Prove that the shearing force at any point in a beam is given by the rate of change of the bending moment at that point.

Consider two sections of the beam δx apart (see Fig. 9). The shear at a section being defined as the sum of all the force to the right of that section, let the shear at $b = S$, and let the shear at $a = S + \delta S$. Also let the moment of all the forces to the right of b (*i. e.*, the bending moment at b) = M , and let the bending moment at $a = M + \delta M$.

Taking moments about C—

$$\begin{aligned} M + \delta M &= M + (S + \delta S) \frac{\delta x}{2} + S(\delta x) \\ &= M + S \cdot \delta x + \frac{\delta S \cdot \delta x}{2} \end{aligned}$$

or

$$\delta M = S \delta x + \frac{\delta S \cdot \delta x}{2}$$

$$\text{Dividing by } \delta x, \quad \frac{\delta M}{\delta x} = S + \frac{\delta S}{2}$$

and when δx is diminished indefinitely, δS becomes negligible

$$\text{and} \quad \frac{dM}{dx} = S.$$

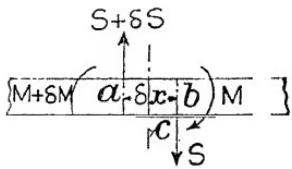


FIG. 9.
Examples on Loaded Beams.

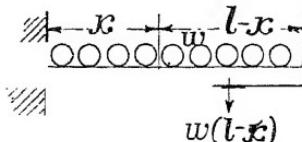


FIG. 10.

The last example should be considered in conjunction with the following :—

Example 10.—For a beam of length l , fixed at one end and loaded uniformly with w tons per foot run, the deflection y at distance x from the fixed end is given by the formula—

$$y = \frac{w}{24EI} (6l^2x^2 - 4lx^3 + x^4)$$

E being the Young's Modulus of the material of the beam, and I being the moment of inertia of the beam section.

Find the values of $\frac{dy}{dx}$, $\frac{d^2y}{dx^2}$, $\frac{d^3y}{dx^3}$ and $\frac{d^4y}{dx^4}$.

$$y = \frac{w}{24EI} (6l^2x^2 - 4lx^3 + x^4)$$

$$\begin{aligned} \text{Differentiating, } \frac{dy}{dx} &= \frac{w}{24EI} ((6l^2 \times 2x) - (4l \times 3x^2) + 4x^3) \\ &= \frac{w}{24EI} (12l^2x - 12lx^2 + 4x^3) \\ &= \underline{\underline{\frac{w}{6EI} (3l^2x - 3lx^2 + x^3)}}. \end{aligned}$$

$$\begin{aligned} \text{Differentiating again, } \frac{d^2y}{dx^2} &= \frac{d}{dx} \left(\frac{w}{6EI} (3l^2x - 3lx^2 + x^3) \right) \\ &= \frac{w}{6EI} (3l^2 - 6lx + 3x^2) \\ &= \underline{\underline{\frac{w}{2EI} (l^2 - 2lx + x^2)}}. \end{aligned}$$

$$\text{or, } \frac{w}{2EI} (l-x)$$

$$\begin{aligned}\text{Differentiating again, } \frac{d^3y}{dx^3} &= \frac{d}{dx} \left(\frac{d^2y}{dx^2} \right) = \frac{d}{dx} \left[\frac{w}{2EI} (l^2 - 2lx + x^2) \right] \\ &\quad \cdot \frac{w}{2EI} (0 - 2l + 2x) \\ &= \frac{w}{EI} (x - l).\end{aligned}$$

Carrying the differentiation one stage further—

$$\begin{aligned}\frac{d^4y}{dx^4} &= \frac{d}{dx} \left(\frac{d^3y}{dx^3} \right) = \frac{d}{dx} \left[\frac{w}{EI} (x - l) \right] \\ &= \frac{w}{EI} (1 - 0) = \underline{\underline{\frac{w}{EI}}}.\end{aligned}$$

Physical meanings may now be found for these various derivatives. Referring to Fig. 10, consider a section of the beam distant x from the fixed end. To the right of this section there is a length of beam $l-x$ loaded with w tons per foot, so that the total load or total downward force on this length is $w(l-x)$; and since this load is evenly distributed, it may be all supposed to be concentrated at distance $\frac{l-x}{2}$ from the section.

Now the bending moment at the section

$$\begin{aligned}&= \text{moment of all the force to the right of the section} \\ &= \text{force} \times \text{distance} = w(l-x) \times \left(\frac{l-x}{2} \right) = \frac{w}{2}(l-x)^2.\end{aligned}$$

Comparing this result with the value found for $\frac{d^2y}{dx^2}$, we notice that the two are alike except for the presence of the constants E and I : thus $\frac{d^2y}{dx^2}$ must be a measure of the bending moment.

Actually the rule connecting M , the bending moment, and $\frac{d^2y}{dx^2}$ is—

$$\frac{M}{I} = E \frac{d^2y}{dx^2} \quad \text{or} \quad M = EI \frac{d^2y}{dx^2}$$

the proof of this rule being given in a later chapter.

Again, we have proved in the previous example that the shear is given by the rate of change of bending moment: thus—

$$\begin{aligned}S &= \frac{dM}{dx} = \frac{d}{dx} \left(EI \frac{d^2y}{dx^2} \right) = EI \frac{d^3y}{dx^3} \\ &= EI \times \frac{w}{EI} (x - l) \\ &= w(x - l)\end{aligned}$$

a result agreeing with our statement that the shear at a section is the sum of all the loads to the right of the section. [The reason for the minus sign, viz., $(x-l)$, being written where $(l-x)$ might be expected need not be discussed at this stage.]

Continuing the investigation—

$$\frac{d^4y}{dx^4} = \frac{w}{EI}$$

$$\text{or } EI \frac{d^4y}{dx^4} = w$$

but w is the loading on the beam and—

$$EI \frac{d^4y}{dx^4} = \frac{d}{dx} \left(EI \frac{d^3y}{dx^3} \right) = \frac{dS}{dx}$$

so that the loading is measured by the rate of change of the shear.

If now the deflected form is set out, by constructing successive slope curves we obtain, respectively, the slope curve of the deflected form, the bending moment curve, the shear curve and finally the curve of loads.

Example 11.—The work done in the expansion of gas in gas turbines is given by—

$$W = \frac{n}{n-1} P_1 V_0 \frac{T_1}{T_0} \left(1 - r^{-\frac{n-1}{n}} \right)$$

where r is the ratio of expansion.

Compare governing by expansion control with governing by alteration of the initial temperature, from the point of view of efficiency.

Deal first with the expansion control, i.e., regard T_1 as constant and r as variable. Then the rate at which the work is increased with respect to r is $\frac{dW}{dr}$.

$$\begin{aligned} \text{Now } \frac{dW}{dr} &= \frac{d}{dr} \left[\frac{n}{n-1} P_1 V_0 \frac{T_1}{T_0} \left(1 - r^{-\frac{n-1}{n}} \right)^{-1} \right] \\ &= \frac{n}{n-1} P_1 V_0 \frac{T_1}{T_0} \left(0 - \frac{n-1}{n} r^{-\frac{n-1}{n}-1} \right) \\ &= \frac{P_1 V_0 T_1}{T_0 r^{\frac{1}{n}}} \times \frac{n-1}{n} r^{-\frac{1}{n}} \end{aligned}$$

Now regard r as constant, but T_1 as variable.

$$\text{Then}— \quad \frac{dW}{dT_1} = \frac{n}{n-1} \frac{P_1 V_0}{T_0} \left(1 - r^{\frac{n-1}{n}} \right)$$

and, expressing the two results in the form of a ratio—

$$\begin{aligned} \frac{dW}{dr} : \frac{dW}{dT_1} &= \frac{P_1 V_0 T_1}{T_0 r^n} : \frac{(n-1) T_0}{n P_1 V_0 \left(1 - r^{\frac{n-1}{n}} \right)} \\ &= \frac{(1-n) T_1}{n r^n \left(1 - r^{\frac{n-1}{n}} \right)} \end{aligned}$$

Lengths of Sub-tangents and Sub-normals of Curves.—The projection of the tangent to a curve on to the axis of x is known as the *sub-tangent*, *i.e.*, the distance “sub” or “under” the tangent. The projection of the normal on the x axis is called the *sub-normal*.

The slope of a curve at any point, measured by the slope of its tangent at that point, is given by the value of $\frac{dy}{dx}$ there, or if α = inclination of the tangent to the x axis—

$$\tan \alpha = \frac{dy}{dx}$$

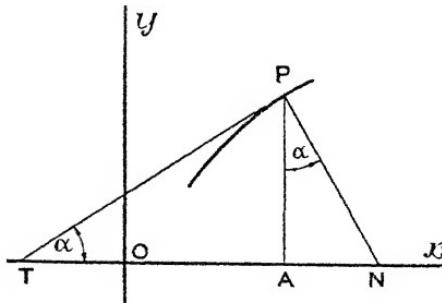


FIG. II.—Sub-tangent and Sub-normal.

In Fig. II—

$$\frac{PA}{AT} = \tan \alpha = \frac{dy}{dx}$$

$$\therefore \quad AT = PA \frac{dx}{dy}$$

But— $AT = \text{sub-tangent}$ and $PA = y$

and hence the length of the sub-tangent $= y \frac{dx}{dy}$

Again— $\angle APN = \alpha$, since $\angle TPN =$ a right angle

$$\tan \angle APN = \frac{AN}{PA} = \frac{\text{sub-normal}}{y}$$

$$\text{i.e.,} \quad \tan \alpha = \frac{\text{sub-normal}}{y}$$

$$\text{or} \quad \text{sub-normal} = y \times \tan \alpha = y \frac{dy}{dx}$$

To find the length of the tangent PT—

$$\begin{aligned} (PT)^2 &= (PA)^2 + (AT)^2 \\ &= y^2 + y^2 \left(\frac{dx}{dy} \right)^2 \\ &= y^2 \left[1 + \left(\frac{dx}{dy} \right)^2 \right] \end{aligned}$$

and

$$PT = y \sqrt{1 + \left(\frac{dx}{dy} \right)^2}$$

$$\text{In like manner—} \quad PN = y \sqrt{1 + \left(\frac{dy}{dx} \right)^2}$$

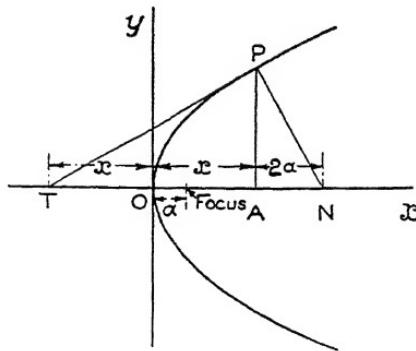


FIG. 12.

Example 12.—Find the lengths of the sub-tangent and the sub-normal of the parabola $y^2 = 4ax$ (Fig. 12).

$$4ax \quad \text{and} \quad y = 2\sqrt{a} \cdot x^{\frac{1}{2}}$$

$$\text{then} \quad \frac{dy}{dx} = 2\sqrt{a} \cdot \frac{1}{2}x^{-\frac{1}{2}} \quad \text{or} \quad \frac{\sqrt{a}}{\sqrt{x}}$$

$$\text{Then length of sub-tangent} = y \frac{dx}{dy}$$

$$= y \times \frac{\sqrt{x}}{\sqrt{a}} = 2\sqrt{a} \sqrt{x} \times \frac{\sqrt{x}}{\sqrt{a}}$$

This result illustrates an important property of the parabola and one useful in the drawing of tangents. For $AT = 2x = 2 \times AO$, and hence to draw the tangent at any point P, drop PA perpendicular to the axis, set off OT = OA and join TP.

$$\begin{aligned}\text{The length of the sub-normal } AN &= y \frac{dy}{dx} \\ &= y \times \frac{\sqrt{a}}{\sqrt{x}} = \frac{2\sqrt{a}\sqrt{x}\sqrt{a}}{\sqrt{x}} \\ &= \underline{\underline{2a}}.\end{aligned}$$

i.e., the length of the sub-normal is independent of the position of P, provided that the sub-normal is measured on the axis of the parabola.

Example 13.—Find the lengths of the sub-tangent and the sub-normal of the parabola— $y = 15x^2 - 2x - 9$ when $x = -2$ and also when $x = 3$.

The axis of this parabola is vertical, and consequently the sub-normal, which is measured along the x axis when given by the value of $y \frac{dy}{dx}$, is not constant.

$$\text{Now } y = 15x^2 - 2x - 9$$

$$\text{and } \frac{dy}{dx} = 30x - 2.$$

$$\text{Hence sub-tangent } = y \frac{dx}{dy} = \frac{15x^2 - 2x - 9}{30x - 2}$$

$$\text{and sub-normal } = y \frac{dy}{dx} = (15x^2 - 2x -$$

Thus when $x = -2$

$$\text{sub-tangent} = \frac{60 + 4 - 9}{-60 - 2} = -\frac{55}{62} \text{ units.}$$

$$\text{sub-normal} = (60 + 4 - 9)(-62) = -3410 \text{ units.}$$

When $x = 3$

$$\text{sub-tangent} = \left(\frac{135 - 6 - 9}{88} \right) = \frac{120}{88} = \frac{15}{11} \text{ units.}$$

$$\text{sub-normal} = 120 \times 88 = 10560 \text{ units.}$$

Example 14.—A shaft 24 ft. long between the bearings weighs 2 cwt. per foot run, and supports a flywheel which weighs $3\frac{1}{2}$ tons at a distance of 3 ft. from the right-hand bearing. Find at what point the maximum bending moment occurs and state the maximum bending moment.

Regarding the shaft as a simply supported beam AB (see Fig. 13), we may draw the bending moment diagrams for the respective systems

of loading, viz., ADB for the distributed load, being the weight of the shaft, and ACB for the concentrated load.

The total distributed load is wl , i.e., $24 \times 1 = 24$ tons, giving equal reactions of 12 tons at A and B; and the bending moment diagram is a parabola with vertex at D, the maximum ordinate DF being $\frac{wl^2}{8}$, i.e., $\frac{12 \times 24^2}{8}$ or 72 tons ft. If for convenience in the later working the axes of x and y are as shown in the figure, the equation to this parabola is $y^2 = 4ax$; or taking the value of y as FB and that of x as DF, $12^2 = 4a \times 7.2$, from which $4a = 20$ and $y^2 = 20x$.

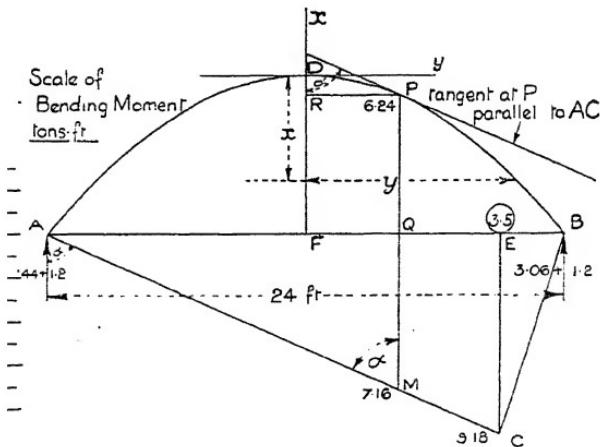


FIG. 13.

The load of 3·5 tons produces reactions of $\frac{21}{24} \times 3\cdot5$ tons at B, and $\frac{3}{24} \times 3\cdot5$ tons at A, i.e., $R_B = 3\cdot06$ and $R_A = \cdot44$ tons: thus the bending moment at E is $3\cdot06 \times 3 = 9\cdot18$ tons ft.

Since the total bending moment is obtained by adding the ordinates of the diagram ADB to the corresponding ordinates of ACB, the maximum bending moment will be determined when the tangent to the parabola is parallel to AC, and the position satisfying this condition can readily be found by differentiation. Thus—

The equation of the curve ADB is $y^2 = 20x$ or $y = 4.47x^{1/2}$, and the slope of the curve is given by the value of $\frac{dy}{dx}$.

$$\text{Now if } y = 4.47x^{\frac{1}{2}}, \quad \frac{dy}{dx} = 4.47 \times \frac{1}{2}x^{-\frac{1}{2}}$$

$$i. e., \quad \tan \alpha = \frac{4.47}{2x^{\frac{1}{2}}}$$

Referring to the figure ACB, $\tan \alpha = \frac{AQ}{QM} = \frac{21}{9.18}$

and thus—

$$\frac{4.47}{2x^2} = \frac{21}{9.18}$$

or

$$x^2 = \frac{4.47 \times 9.18}{42}$$

i.e.,

$$(DR)^{\frac{1}{2}} = \frac{4.47 \times 9.18}{42}$$

$$\text{Again, } (PR)^2 = 20 \times DR, \text{ and thus } PR = \sqrt{20 \times 4.47 \times 9.18} \\ = 4.37 \text{ ft.}$$

Thus the maximum bending moment occurs at a distance of $12 - 4.37$, i.e., 7.63 ft. from the right-hand bearing.

To find the maximum bending moment—

$$DR = \frac{(4.47 \times 9.18)^2}{42} = .956$$

$$PQ = DF - DR = 7.2 - .96 = 6.24 \text{ tons ft.}$$

$$\text{Also— } \frac{QM}{EC} = \frac{16.37}{21} \times 9.18 = 7.16 \text{ tons ft.}$$

$$\text{Hence the maximum bending moment} = 7.16 + 6.24 = \underline{13.4 \text{ tons ft.}}$$

Exercises 3.—On the Lengths of the Sub-tangent and Sub-normal : also Beam Problems.

1. Find the lengths of the sub-normal and sub-tangent of the curve $5y = 4x^3$ at the point for which $x = 3$.

2. If $y = \frac{gx^2}{2V^2}$, $V = 117$, and $g = 32.2$, find the value of x that makes the slope of the curve 1 in 17.4.

3. A parabolic arched rib has a span of 50 ft. and a rise of 8 ft. Find the equation of the tangent of the slope of the rib. What is the slope of the tangent at the end?

4. Find the equation of the tangent to the curve $p = \frac{450}{v^{1.2}}$ at the point for which $v = 5$.

In Exercises 5 to 7, y is a deflection and x a distance along the beam. Find, in each case, expressions for the Bending Moment, Shearing Force and Load. The beam is of uniform section throughout, and of span l .

5. The beam is supported at both ends, and loaded with W at the centre.

$$y = \frac{W}{2EI} \left(\frac{l x^2}{4} - \frac{x^3}{6} \right) \quad \{x \text{ is the distance from the centre}\}.$$

6. The beam is supported at both ends, and loaded continuously with w per ft. run.

$$y = \frac{w}{2EI} \left(\frac{l^2 x^2}{8} - \frac{x^4}{12} \right) \quad \{x \text{ is the distance from the centre}\}.$$

7. A cantilever loaded with W at the free end.

$$y = \frac{W(lx^2)}{EI_2} - \quad \{x \text{ is the distance from the fixed end}\}.$$

8. Find the lengths of the projections on the y axis of the tangent and the normal of the parabola, $x^2 = 10b^2y + 4c$, x having the value $9a$.

9. Prove that the sub-normal (along the axis of the parabola) of the parabola $x^2 = 6y$ is constant and find the value of this constant.

- ✓ 10. If $EI \frac{dy}{dx} = \frac{wlx^2}{l^2} - \frac{wx^3}{l^2} - \frac{Px^2}{l^2} + C$ and $C = \frac{Pl^2}{l^2} - \frac{P}{l^2}$, find the value of $\frac{d^2y}{dx^2}$

Differentiation of Exponential Functions.—The rule for differentiation already given applies only to functions involving the I.V. (usually the x) raised to some power. A method must now be found for the differentiation of exponential functions, viz., those in which the I.V. appears as exponent; such as e^{5x} or 4^x .

When concerned with the plotting of the curve $y = e^x$ (see Part I, p. 352) mention was made of the fact that, if tangents are drawn to the curve at various points, the slopes of these tangents are equal to the ordinates to the primitive curve at the points at which the tangents touch the curve. Thus the slope curve of the curve $y = e^x$ lies along the primitive, and—

$$\frac{de^x}{dx} = e^x$$

or the rate of change of the function is equal to the value of the function itself.

We may establish the result algebraically thus—

$$e^x = 1 + x + \frac{x^2}{1 \cdot 2} + \frac{x^3}{1 \cdot 2 \cdot 3} + \frac{x^4}{1 \cdot 2 \cdot 3 \cdot 4} + \dots$$

Assuming that a series composed of an unlimited number of terms can be differentiated term by term and the results added to give the true derivative (this being true for all the cases with which we shall deal), then by differentiation—

$$\begin{aligned} \frac{de^x}{dx} &= 0 + 1 + \frac{2x}{2} + \frac{3x^2}{6} + \frac{4x^3}{24} \\ &= 1 + x + \frac{x^2}{2} + \frac{x^3}{6} + \dots \\ &= e^x. \end{aligned}$$

Another respect in which the function e^x is unique may be

noted : the sub-tangent $= y \frac{dx}{dy} = e^x \times \frac{1}{e^x} = 1$, i.e., the sub-tangent is constant and equal to unity.

The curve $y = e^x$ may be usefully employed as a gauge or template for testing slopes of lines; the curve being drawn on tracing-paper and moved over the line to be tested until the curve and line have the same direction, and the ordinate of the curve being then read, any necessary change of scales being afterwards made.

The work may now be carried a stage further, so that the rule for the differentiation of e^{bx} may be found.

Referring to Part I, p. 354, we note that if the curve $y = e^x$ be plotted, then this curve represents also the equation $y = e^{bx}$ if the numbers marked along the horizontal scale used for the curve $y = e^x$ are divided by b . If, then, the slope of the construction curve, i.e., that having the equation $y = e^x$, is measured, we can obtain from it the slope of the curve $y = e^{bx}$ by multiplying the slope by b , since vertical distances are unaltered, whilst horizontal distances in the case of $y = e^{bx}$ are $\frac{1}{b} \times$ corresponding horizontal distances for $y = e^x$.

Hence the slope of the curve $y = e^{bx}$ is $b \times$ slope of curve $y = e^x$

$$\text{or---} \quad \frac{de^{bx}}{dx} = be^{bx}$$

It should be noticed that the power of the function remains the same after differentiation, but the multiplier of the I.V. becomes after differentiation a multiplier of the function. This latter rule must be remembered throughout differentiation, viz., **any multiplier or divisor of the I.V. in the function to be differentiated must become a multiplier or divisor of the function after differentiation.**

From e^{bx} we can proceed to ae^{bx} , the result from the differentiation of which is given by—

$$\frac{dae^{bx}}{dx} = abe^{bx}$$

Example 15.—If $y = 5e^{-\frac{1}{6}x}$, find the value of $\frac{dy}{dx}$

$$\frac{dy}{dx} = \frac{d}{dx} 5e^{-\frac{1}{6}x} = 5 \times -\frac{1}{6}e^{-\frac{1}{6}x}$$

$$\therefore -\frac{5}{6}e^{-\frac{1}{6}x}.$$

Referring to the last example, note that the power of e is exactly the same after differentiation as before: the factor $-\frac{1}{6}$ multiplies the I.V. in the original function, and therefore it occurs as a constant multiplier after differentiation; also the constant factor 5 remains throughout differentiation.

Example 16.—If $C = C_0 e^{-\frac{Rt}{L}}$, where C and C_0 are electrical currents, R is the resistance of a circuit, L is the self-inductance of the circuit and t is a time, find the time-rate of change of C .

This example illustrates the importance of the rate of change as compared with the change itself; for it demonstrates the fact that for an inductive circuit the change of current is often extremely rapid and consequently dangerous.

$$\begin{aligned}\text{Time rate of change of } C &= \frac{dC}{dt} = \frac{d}{dt} C_0 e^{-\frac{Rt}{L}} \\ &= C_0 \times -\frac{R}{L} e^{-\frac{Rt}{L}} \\ &= -\frac{R}{L} C_0 e^{-\frac{Rt}{L}}\end{aligned}$$

i.e., the rate of decrease of the current when the impressed E.M.F. is removed is proportional to the current at the instant the circuit is broken.

To better illustrate the example, take the case for which the current at the instant of removal of the E.M.F. is 14.5 amps., the resistance of the circuit is 6.4 ohms, and its self-inductance .006 henry. Then the rate of change of the current $= -\frac{6.4}{.006} \times 14.5 = -15470$ amps. per second, whereas the actual current is only 14.5 amps.

The expressions e^x and e^{bx} are particular forms of the more general exponential function a^x ; to differentiate which we may proceed by either of two methods:—

(a) *Working from first principles.* In Part I, p. 470, the expansion for a^x is given, viz.—

$$a^x = 1 + x \log a + \frac{(x \log a)^2}{[2]} + \frac{(x \log a)^3}{[3]} + \dots$$

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$$\begin{aligned}
 \log a + (\log a)^2 x + (\log a)^3 \frac{x^2}{2} + \dots \\
 \log a + (x \log a)^2 + (x \log a)^3 + \dots \\
 = \log a \times a^x \\
 i.e. = a^x \cdot \log a.
 \end{aligned}$$

the result for the differentiation of e^{bx}

Let— $a^x = e^{bx}$
 $a = e^b$, and therefore $\log_e a = b$.

Then— $\frac{d}{dx} a^x = \frac{d}{dx} e^{bx} = b e^{bx} = \log_e a \times e^{bx}$
 $= \log_e a \times a^x$
 or $a^x \log a$

thus— $\frac{da^x}{dx} = a^x \cdot \log a.$

Example 17.—Find the value of $\frac{d4^x}{dx}$

In this case $a = 4$ and $\log_e 4 = 1.3863$.

Hence $\frac{d4^x}{dx} = 1.3863 \times 4^x.$

Note carefully that this result cannot be simplified by combining 1.3863 with 4 and writing the result as 5.5452^x , which is quite incorrect. The 4 alone is raised to the x power, and 1.3863 is not raised to this power.

Example 18.—Find the value of $\frac{d^2}{ds^2}(3.6)^s$.

Here $a = 3.6$ and $\log 3.6 = 1.2809$.

Thus $\frac{d}{ds}(3.6)^s = \log 3.6 \times (3.6)^s = 1.2809 \times (3.6)^s.$

Then—

$$\begin{aligned}
 \frac{d^2}{ds^2}(3.6)^s &= \frac{d}{ds} \left(\frac{d}{ds}(3.6)^s \right) = \frac{d}{ds} [1.2809 \times (3.6)^s] \\
 &= 1.2809 \times \frac{d}{ds}(3.6)^s = 1.2809 \times 1.2809 \times (3.6)^s \\
 &= 1.64(3.6)^s.
 \end{aligned}$$

Example 19.—Given that $s = 4e^{5t} + 7e^{-5t}$, find the value of $\frac{d^2s}{dt^2} - 25s$.

$$\begin{aligned}s &= 4e^{5t} + 7e^{-5t} \\ \frac{ds}{dt} &= (4 \times 5e^{5t}) + (7 \times -5e^{-5t}) \\ &= 20e^{5t} - 35e^{-5t}. \\ \text{Again---} \quad \frac{d^2s}{dt^2} &= 100e^{5t} + 175e^{-5t} \\ \therefore \frac{d^2s}{dt^2} - 25s &= 100e^{5t} + 175e^{-5t} - 100e^{5t} - 175e^{-5t} = 0.\end{aligned}$$

Differentiation of $\log x$.—The rule for the differentiation of logarithmic functions can be derived either from the expansion of $\log_e(1+x)$ into a series, or by assuming the result for the differentiation of e^x . Considering these methods in turn—

(a) *Working from first principles.* Let $y = \log x$, i. e., $\log_e x$. Then if x be increased to become $x+\delta x$, y takes a new value $y+\delta y$, and $y+\delta y = \log(x+\delta x)$.

$$\text{Now } \log(x+\delta x) = \log x\left(1 + \frac{\delta x}{x}\right) = \log x + \log\left(1 + \frac{\delta x}{x}\right),$$

therefore—

$$(y+\delta y) - y = \log x + \log\left(1 + \frac{\delta x}{x}\right) - \log x$$

$$\text{i. e., } \delta y = \log\left(1 + \frac{\delta x}{x}\right)$$

Also $\log\left(1 + \frac{\delta x}{x}\right)$ can be expanded into a series of the form

$$\log(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots \text{ (see Part I, p. 470)}$$

so that—

$$\log\left(1 + \frac{\delta x}{x}\right) = \left(\frac{\delta x}{x}\right) - \frac{1}{2}\left(\frac{\delta x}{x}\right)^2 + \frac{1}{3}\left(\frac{\delta x}{x}\right)^3 - \frac{1}{4}\left(\frac{\delta x}{x}\right)^4 + \dots$$

$$\therefore \delta y = \left(\frac{\delta x}{x}\right) - \frac{1}{2}\left(\frac{\delta x}{x}\right)^2 + \frac{1}{3}\left(\frac{\delta x}{x}\right)^3 - \frac{1}{4}\left(\frac{\delta x}{x}\right)^4 + \dots$$

Dividing all through by δx —

$$\frac{\delta y}{\delta x} = \frac{1}{x} - \frac{\delta x}{2x^2} + \frac{(\delta x)^2}{3x^3} - \frac{(\delta x)^3}{4x^4} + \dots$$

By sufficiently diminishing the value of δx we may make the

second and succeeding terms as small as we please, and evide the limiting value of the series is $\frac{I}{x}$

$$\text{i. e.,} \quad \frac{dy}{dx} = \prod_{\delta x \rightarrow 0} \frac{\delta y}{\delta x} = \frac{I}{x}$$

Hence—

$$\frac{d \log_e x}{dx} = 1$$

$$(b) \text{ Assuming the result—} \quad \frac{d e^x}{dx} = e^x$$

$$\text{Let—} \quad y = \log_e x, \quad \text{so that} \quad x = e^y$$

$$\text{and} \quad \frac{dx}{dy} = \frac{de^y}{dy} = e^y.$$

Now $\frac{\delta y}{\delta x} = \frac{I}{\frac{\delta x}{\delta y}}$ and consequently by considering the limit values of these fractions

$$\frac{dy}{dx} = \frac{I}{\frac{dx}{dy}} = \frac{I}{e^y}$$

We wish to find $\frac{dy}{dx}$ and we have already obtained an express for $\frac{dx}{dy}$.

$$\text{Hence} \quad \frac{dy}{dx} = \frac{I}{\frac{dx}{dy}} = \frac{I}{e^y} = \frac{I}{x}$$

$$\text{or} \quad \frac{d \log_e x}{dx} = \frac{I}{x}$$

This result can be amplified to embrace the more general for thus—

$$\frac{d}{dx} \log_e (Ax + B) = \frac{I}{Ax + B}$$

for, in accordance with the rule given on p. 48, the A wh multiplies the I.V. in the original function must appear as multiplier after differentiation.

All these rules apply to functions involving natural logs, 1

they can be modified to meet the cases in which common logs occur; for — $\log_{10} x = .4343 \log_e x$

$$\text{and hence } \frac{d \log_{10} x}{dx} = .4343 \frac{d \log_e x}{dx} = \frac{.4343}{x}$$

$$\text{and } \frac{d}{dx} \log_{10} (Ax+B) = \frac{.4343A}{Ax+B}$$

It should be observed that in all these logarithmic functions the I.V. is raised to the first power only: if the I.V. is raised to a power higher than the first, other rules, which are given later, must be employed.

Example 20.—If $y = \log_e 7x$, find $\frac{dy}{dx}$.

$$\frac{dy}{dx} = \frac{d}{dx} \log_e 7x = \frac{7}{7x} = \frac{1}{x}$$

$$\text{or alternatively } \log_e 7x = \log_e 7 + \log_e x$$

$$\begin{aligned} \text{and thus } \frac{d}{dx} \log_e 7x &= \frac{d}{dx} \log_e 7 + \frac{d}{dx} \log_e x \\ &= 0 + \frac{1}{x} = \frac{1}{x} \end{aligned}$$

Example 21.—Differentiate with regard to t the expression $\log_{10} (5t-14)$ and find the numerical value of the derivative when $t = 3.2$.

$$\frac{d}{dt} \log_{10} (5t-14) = \frac{.4343 \times 5}{5t-14} = \frac{2.1715}{5t-14}$$

When $t = 3.2$

$$\frac{d}{dt} \log_{10} (5t-14) = \frac{2.1715}{16-14} = 1.0858.$$

We may check this result approximately by taking values of t 3.19 and 3.21 and calculating the value of $\frac{\delta \log_{10} (5t-14)}{\delta t}$.

Thus—

When $t = 3.19$, $\log_{10} (5t-14) = \log_{10} (15.95-14) = \log_{10} 1.95 = .2900$
when $t = 3.21$, $\log_{10} (5t-14) = \log_{10} (16.05-14) = \log_{10} 2.05 = .3118$

so that

$$\delta \log_{10} (5t-14) = .3118 - .2900 = .0218$$

$$\text{while } \delta t = 3.21 - 3.19 = .02$$

$$\text{and } \frac{\delta}{\delta t} \log_{10} (5t-14) = \frac{.0218}{.02} = 1.09.$$

Differentiation of the Hyperbolic Functions, $\sinh x$ and $\cosh x$.—Expressing the hyperbolic functions in terms of exponential functions—

$$\sinh x = \frac{e^x - e^{-x}}{2}$$

$$\text{and} \quad \cosh x = \frac{e^x + e^{-x}}{2}$$

Thus to differentiate $\sinh x$ we may differentiate $\frac{e^x - e^{-x}}{2}$

$$\text{Hence-} \quad \frac{d \sinh x}{dx} = \frac{d}{dx} \left(\frac{e^x - e^{-x}}{2} \right) = \frac{1}{2}(e^x + e^{-x}) \\ = \cosh x$$

$$\text{also} \quad \frac{d}{dx} \cosh x = \frac{d}{dx} \left(\frac{e^x + e^{-x}}{2} \right) = \frac{1}{2}(e^x - e^{-x}) \\ = \sinh x.$$

Example 22.—Find the inclination to the horizontal of a cable weighing $\frac{1}{2}$ lb. per ft. and stretched to a tension of 30 lbs. weight, at the end of its span of 50 ft.

The equation to the form taken by the cable is—

$$y = \frac{c}{2}(e^{\frac{x}{c}} + e^{-\frac{x}{c}}) = c \cosh \frac{x}{c}$$

$$\text{where } c = \frac{\text{horizontal tension}}{\text{weight per foot}} = \frac{30}{.5} = 60.$$

We require the slope of the curve when $x = 25$, this being given by the value of $\frac{dy}{dx}$ there.

$$\frac{dy}{dx} = \frac{d}{dx} c \cosh \frac{x}{60} = c \times \frac{1}{60} \sinh \frac{x}{60} = \sinh \frac{x}{60}$$

$$\text{When } x = 25 \quad \frac{dy}{dx} = \sinh \frac{25}{60} = \sinh .4167 = .4167$$

$$= \frac{1.517 - .659}{2}$$

$$= .429.$$

This value is that of the tangent of the angle of inclination to the horizontal; which is thus $\tan^{-1} .429$ or $23^\circ 13'$.

Exercises 4.—On the Differentiation of a^x , $\log x$ and the Hyperbolic Functions.

Differentiate with respect to x the functions in Nos. 1 to 20.

1. e^{-5x} .
2. $1 \cdot 5e^{4 \cdot 1x}$.
3. $\frac{27}{e^{3x}}$.
4. $4 \cdot 15^x$.
5. $8 \cdot 72^{2x}$.
6. $e^{9x} + 5e^{-7x}$.
7. $2x^e$.
8. 14×2^x .
9. $41e^{-25x} + \frac{19}{e^{16x}} + e^{-414} + 17$.
10. $3 \cdot 14e^{5 \cdot 1x} - 5x^{0 \cdot 45} + 3 \cdot 1^3x + b$.
11. $\frac{10e^{-4x}}{5e^{2x}} \times \frac{3e^{7 \cdot 2x}}{2e^{-4 \cdot 6x}}$.
12. $\log 7x$.
13. $3 \log(4 - 5x)$.
14. $10 \log_{10} 8x$.
15. $c \log(4xa + 5b)$.
16. $9e^{-2x} - \log 2x + \frac{5 \cdot 71}{x^{43}}$.
17. $\log 2x(3x - 4 \cdot 7)$.
18. $\log \frac{(5x+4)(3x-2)}{(7-4x)}$.
19. $(ex)^3 + 4 \cosh 2x - 1 \cdot 7 \log_{10} 2 \cdot 3x$.
20. $\log 3x^2 + 5x^{-7} - 1 \cdot 8(1 \cdot 8x) + 12$.
21. If $y = A_1e^{-3x} + A_2e^{-4x}$, find the value of $\frac{d^2y}{dx^2} + 7\frac{dy}{dx} + 12y$.
22. Find $\frac{d}{dv} \log(3 - 4v)$ when $v = 1 \cdot 7$. Check your result approximately by taking as values of v 1.65 and 1.75.
23. Determine the value of $\frac{d}{du} 71 \log(18 - 0.4u)$.
24. Write down the value of $\frac{d}{dt} \log_{10} 18t$.
25. If $T = 50e^{2\theta}$, find the rate of change of T compared with change in θ .
26. If $C = C_0 \left(1 - e^{-\frac{Rt}{L}}\right)$, C and C_0 being electrical currents, R the resistance of a circuit and L its self-inductance, find the rate at which the current C is changing, t being the time.
27. Given that $v = 2 \cdot 03 \log_{10} (7 - 1 \cdot 8u)$, find $\frac{dv}{du}$.
28. Evaluate $\frac{d}{dx} 5 \cosh \frac{x}{4}$ and also $\frac{d}{dy} p \sinh \frac{y}{q}$.
29. An electromotive force E is given by—

$$E = A \cosh \sqrt{lr} \cdot x + B \sinh \sqrt{lr} \cdot x$$
.
 Find the value of $\frac{d^2E}{dx^2}$ in terms of E .
30. If $W = 144(p_1(1 + \log r) - rp_b)$, find the value of r that makes $\frac{dW}{dr} = 0$; W being the work done in the expansion of steam from pressure p_1 through a ratio of expansion r .
31. Find the value of $\frac{dy}{dx} + ay$ if $y = \frac{b}{a} - \frac{A}{a}e^{-ax}$.

✓ 32. If $y = Ae^{2x} + Be^{3x} + Ce^{-4x}$, find the value of—

$$\frac{d^3y}{dx^3} - \frac{d^2y}{dx^2} - 14\frac{dy}{dx} + 24y.$$

✓ 33. Evaluate $\frac{d^2V}{dx^2} - \frac{Vr_1}{r_2}$ when $V = A_1e^{\sqrt{\frac{r_1}{r_2}}x} + A_2e^{-\sqrt{\frac{r_1}{r_2}}x}$

34. Nernst gives the following rule connecting the pressure p of a refrigerant (such as Carbon Dioxide or Ammonia) and its absolute temperature τ —

$$p = A + B \log \tau + C\tau + \frac{D}{\tau}$$

where A, B, C and D are constants. Find an expression for $\frac{dp}{d\tau}$.

Differentiation of the Trigonometric Functions.—Before proceeding to establish the rules for the differentiation of $\sin x$ and $\cos x$, it is well to remind ourselves of two trigonometric relations which are necessary for the proofs of these rules, viz.—

(a) When the angle is small, its sine may be replaced by the angle itself expressed in radians, i. e.—

$$\lim_{\theta \rightarrow 0} \frac{\sin \theta}{\theta} = 1 \quad (\text{cf. Part I, p. 458}).$$

$$(b) \sin A - \sin B = 2 \cos \left(\frac{A+B}{2} \right) \sin \left(\frac{A-B}{2} \right) \quad (\text{cf. Part I, p. 285}).$$

To find $\frac{d}{dx} \sin x$ we proceed as in former cases; thus—

$$\text{Let } y = \sin x \quad \text{and } y + \delta y = \sin(x + \delta x)$$

$$\begin{aligned} \text{then } \delta y &= y + \delta y - y = \sin(x + \delta x) - \sin x \\ &= 2 \cos \left(\frac{2x + \delta x}{2} \right) \sin \left(\frac{\delta x}{2} \right) \end{aligned}$$

Dividing through by δx —

$$\frac{\delta y}{\delta x} : \frac{2 \cos \left(\frac{2x + \delta x}{2} \right) \sin \left(\frac{\delta x}{2} \right)}{\delta x}$$

$$\frac{\cos \left(\frac{2x + \delta x}{2} \right) \sin \left(\frac{\delta x}{2} \right)}{\frac{\delta x}{2}}$$

$$= \cos \left(\frac{2x + \delta x}{2} \right) \times \left(\frac{\sin \frac{\delta x}{2}}{\frac{\delta x}{2}} \right)$$

The limiting value of $\frac{\delta y}{\delta x}$ is $\frac{dy}{dx}$, and that of the right-hand side is $\cos x$, since $\cos(x + \frac{\delta x}{2})$ approaches more and more nearly to $\cos x$ as δx is made smaller and smaller, and the limiting value of $\sin \frac{\delta x}{2}$, or, as we might write it, $\frac{\sin \theta}{\theta}$, is 1.

$$\text{Hence } \frac{d \sin x}{dx} \text{ or } \frac{dy}{dx} = \lim_{\delta x \rightarrow 0} \frac{\delta y}{\delta x} = \cos x$$

$$\frac{d \sin x}{dx} = \cos x.$$

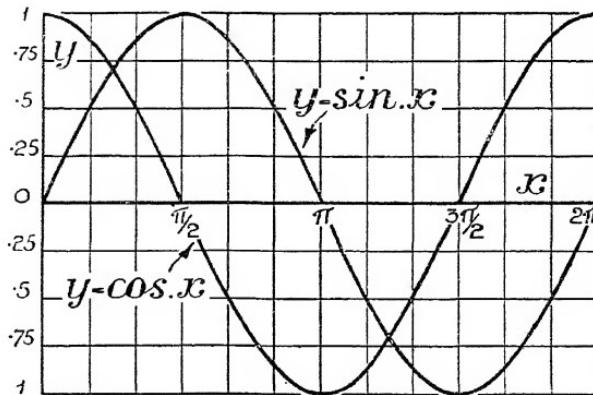


FIG. 14.—Curves of $y = \sin x$ and $y = \cos x$.

By similar reasoning the derivative of $\cos x$ may be obtained; its value being given by—

$$\frac{d \cos x}{dx} = -\sin x$$

The graphs of the sine and cosine curves assist towards the full appreciation of these results. In Fig. 14 the two curves are plotted, and it is noted that the cosine curve is simply the sine curve shifted backwards along the horizontal axis: thus the slope curve and the primitive have exactly the same shape. This condition also holds for the primitive curve $y = e^{bx}$, and so suggests that there must be some connection between these various natural functions; and further reference to this subject is made later in the book.

Much trouble is caused by the presence of the minus sign in the relation $\frac{d \cos x}{dx} = -\sin x$, it being rather difficult to remember whether the minus sign occurs when differentiating $\sin x$ or $\cos x$. A mental picture of the curves, or the curves themselves, may be used as an aid in this respect. The cosine and sine curves differ in phase by $\frac{1}{4}$ period (see Fig. 14), but are otherwise identical. Treating $y = \sin x$ as the primitive: when x is small, $\sin x$ and x are very nearly alike, and thus the slope of the curve here is 1; as x increases from 0 to $\frac{\pi}{2}$ the slope of the curve continually diminishes until at $x = \frac{\pi}{2}$ the slope of the curve is zero. Now the ordinate of the cosine curve when $x = 0$ is unity, and it diminishes until at $x = \frac{\pi}{2}$ it is zero. From $x = \frac{\pi}{2}$ to $x = \pi$ the slope of the sine curve is negative, but increases *numerically* to -1, this being the value when $x = \pi$; and it may be observed that the ordinates of the cosine curve give these changes exactly, both as regards magnitude and sign. Thus the cosine curve is the slope curve of the sine curve:

Now regard the cosine curve as the primitive. At $x = 0$ the curve is horizontal and the slope = 0; from $x = 0$ to $x = \frac{\pi}{2}$ the slope increases *numerically*, but is negative, reaching its maximum negative value, viz., -1, at $x = \frac{\pi}{2}$; but the ordinates of the sine curve are all positive from $x = 0$ to $x = \frac{\pi}{2}$, so that although these ordinates give the slope of the curve as regards magnitude, they give the wrong sign. In other words, the sine curve must be folded over the axis of x to be the slope curve of the cosine curve, *i.e.*, the curve $y = -\sin x$ is the slope curve of the curve $y = \cos x$.

To summarise, we can say that the derived curve for the sine curve or for the cosine curve is the curve itself shifted back along the axis a horizontal distance equal to one-quarter of the period.

Thus we can say at once that the slope curve of the curve $y = \sin(x+b)$ is the curve $y = \cos(x+b)$, since the curve $y = \sin(x+b)$ is the simple sine curve shifted along the horizontal axis an amount given by the value of b , the amplitude and period being unaltered.

$$\text{Thus— } \frac{d}{dx} \sin(x+b) = \cos(x+b)$$

and, in like manner—

$$\frac{d}{dx} \cos(x+b) = -\sin(x+b).$$

Again, $\frac{d}{dx} \sin(5x+6) = 5 \cos(5x+6)$, since 5 multiplies the I.V. in the original function.

Then in general—

$$\frac{d}{dx} A \sin(Bx+C) = AB \cos(Bx+C)$$

$$\frac{d}{dx} A \cos(Bx+C) = -AB \sin(Bx+C).$$

To differentiate $\tan x$ with regard to x .

Let $y = \tan x$ and $(y+\delta y)$ then $= \tan(x+\delta x)$

$$\begin{aligned}\delta y &= y + \delta y - y = \tan(x + \delta x) - \tan x \\ &= \frac{\sin(x + \delta x)}{\cos(x + \delta x)} - \frac{\sin x}{\cos x} \\ &= \frac{\sin(x + \delta x) \cos x - \cos(x + \delta x) \sin x}{\cos(x + \delta x) \cos x} \\ &= \frac{\sin[(x + \delta x) - x]}{\cos(x + \delta x) \cos x} \\ &\quad \frac{\sin \delta x}{\cos(x + \delta x) \cos x}\end{aligned}$$

Dividing through by δx —

$$\frac{\delta y}{\delta x} = \frac{\sin \delta x}{\delta x} \times \frac{1}{\cos(x + \delta x) \cos x}$$

Now as δx approaches zero, $\frac{\sin \delta x}{\delta x}$ approaches 1 and $(x + \delta x)$ approaches x .

$$\text{Hence— } \frac{dy}{dx} = \lim_{\delta x \rightarrow 0} \frac{\delta y}{\delta x} = 1 \times \frac{1}{\cos x \cos x} = \frac{1}{\cos^2 x} = \sec^2 x.$$

$$\frac{d}{dx} \tan x = \sec^2 x$$

In like manner it can be proved that—

$$\frac{d \cot x}{dx} = - \operatorname{cosec}^2 x$$

$$\frac{d \sec x}{dx} = \frac{\sin x}{\cos^2 x}$$

and

$$\frac{d \operatorname{cosec} x}{dx} = - \frac{\cos x}{\sin^2 x}$$

To generalise

$$\frac{d}{dx} A \tan (Bx+C) = AB \sec^2 (Bx+C)$$

$$\frac{d}{dx} A \cot (Bx+C) = - AB \operatorname{cosec}^2 (Bx+C)$$

$$\frac{d}{dx} A \operatorname{cosec} (Bx+C) = - \frac{AB \cos (Bx+C)}{\sin^2 (Bx+C)}$$

$$\frac{d}{dx} A \sec (Bx+C) = \frac{AB \sin (Bx+C)}{\cos^2 (Bx+C)}.$$

Example 23.—Find the slope of the curve representing the equation $s = 5 \cdot 2 \sin (40t - 2 \cdot 4)$ when $t = 0 \cdot 07$.

The slope of the curve—

$$\begin{aligned} \frac{ds}{dt} &= \frac{d}{dt} 5 \cdot 2 \sin (40t - 2 \cdot 4) = 5 \cdot 2 \times 40 \cos (40t - 2 \cdot 4) \\ &= 208 \cos (40t - 2 \cdot 4). \end{aligned}$$

Hence when—

$$\begin{aligned} t = 0 \cdot 07, \text{ the slope} &= 208 \cos (2 \cdot 8 - 2 \cdot 4) = 208 \cos 0 \cdot 4 \text{ (radian)} \\ &= 208 \cos 22 \cdot 9^\circ \\ &= \underline{192}. \end{aligned}$$

Example 24.—Differentiate, with regard to z , the function $9 \cdot 4 \cot (7 - 5z)$.

$$\begin{aligned} \frac{d}{dz} 9 \cdot 4 \cot (7 - 5z) &= 9 \cdot 4 \times -5 \times -\operatorname{cosec}^2 (7 - 5z) \\ &= \underline{47 \operatorname{cosec}^2 (7 - 5z)}. \end{aligned}$$

Simple Harmonic Motion.—We can now make a more strict examination of simple harmonic motion. Suppose a crank of length r (see Fig. 15), starting from the position OX, rotates at a constant angular velocity ω in a right-handed direction. Let it have reached the position OA after t seconds have elapsed from the start; then the angle passed through in this interval of time $= \text{AOM} = \omega t$, since the angular distance covered in 1 sec. $= \omega$ radians and the angular distance in t seconds $= \omega t$ radians.

Considering the displacement along the horizontal axis, the displacement in time $t = s = OM$

$$= AO \cos AOM = r \cos \omega t.$$

$$\text{Then the velocity } = \frac{ds}{dt} = -r \times \omega \sin \omega t = -\omega r \sin \omega t$$

$$\text{and the acceleration } = \frac{dv}{dt} = -\omega r \times \omega \times \cos \omega t = -\omega^2 r \cos \omega t \\ = -\omega^2 s$$

i.e., the acceleration is proportional to the displacement, but is directed towards the centre: thus, when the displacement from the centre increases, the acceleration towards the centre increases. When the displacement is greatest, the acceleration is greatest: e.g., if the crank is in the position OX, the acceleration has its maximum value $\omega^2 r$ and is directed towards the centre, just destroying the outward velocity, which at X is zero. At O the acceleration $= -\omega^2 \times 0 = 0$, or the velocity is here a maximum.

An initial lag or lead of the crank does not affect the truth of the foregoing connection between acceleration and displacement. The equation of the motion is now $s = r \cos (\omega t \pm c)$, where c is the angle of lag or lead, and the differentiation to find the velocity and the acceleration is as before.

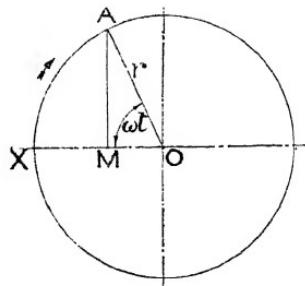


FIG. 15.

Example 25.—If $s = 5 \sin 4t - 12 \cos 4t$, show that this is the equation of a S.H.M. and find the angular velocity.

$$s = 5 \sin 4t - 12 \cos 4t.$$

$$\text{Then } v = \frac{ds}{dt} = (5 \times 4 \cos 4t) - (12 \times 4 \times -\sin 4t). \\ = 20 \cos 4t + 48 \sin 4t$$

$$\text{and } a = \frac{dv}{dt} = (20 \times 4 \times -\sin 4t) + (48 \times 4 \cos 4t) \\ = -80 \sin 4t + 192 \cos 4t \\ = -16(5 \sin 4t - 12 \cos 4t) = -16s$$

i.e., the acceleration is proportional to the displacement.

Now, in S.H.M., the acceleration $= -\omega^2 s$.

$$\therefore \omega^2 = 16, \text{i.e., } \omega = \text{angular velocity} \\ = 4 \text{ radians per sec.}$$

This last question might be treated rather differently by first expressing $5 \sin 4t - 12 \cos 4t$ in the form $M \sin(4t + c)$ (see Part I, p. 276) and then differentiating. This method indicates that a S.H.M. may be composed of two simple harmonic motions differing in phase and amplitude.

Exercises 5.—On the Differentiation of Trigonometric Functions.

Differentiate with respect to x the functions in Nos. 1 to 16.

1. $\sin(4 - 5.3x)$.
2. $3.2 \cos 5.1x$.
3. $.16 \tan(3x + 9)$.
4. $2.15 \sin$
5. $8 \cot 5x$.
6. $43.15 \sec(0.05 - 117x)$.
7. $bc \cos(d - gx)$.
8. $4 \cos 5x - 7 \sin(2x - 5)$.
9. $\sin 5.2x \cos 3.6x$.
10. $2.17 \cos 4.5x \cos 1.7x$.
11. $9.04 \sin(px + c) \sin(qx - c)$.
12. $5 \sin^2 x$.
13. $.065 \cos^2 3x$.
14. $\cos^2(7x - 1.5) + \sin^2(7x - 1.5)$.
- ✓ 15. $3x^{1.72} - 5.14 \log(3x - 4.1) + 1.4 \sin(4.31 - 19.5x) + 24.93x$.
16. $7.05 \sin 0.015x - 2.3 \cos(6.1 - 23x) + 1.85 \tan(4x - 0.07)$.

17. x , the displacement of a valve from its central position, is given approximately by $x = -1.2 \cos \omega t - 1.8 \sin \omega t$, where ω = angular velocity of crank shaft (making 300 r.p.m.) and t is time in seconds from dead centre position.

Find expressions for the velocity and acceleration of the valve.

18. If $s = 4.2 \sin(2.1 - 1.7t) - 3.15 \cos(2.1 - 1.7t)$, s being a displacement and t a time, find an expression for the acceleration in terms of s . What kind of motion does this equation represent?

19. The current in a circuit is varying according to the law $C = 3.16 \sin(2\pi ft - 3.06)$. At what rate is the current changing when $t = 0.07$, the frequency f being 60?

20. If the deflected form of a strut is a sine curve, what will be the form of the bending moment curve?

21. If y = deflection of a rod at a distance x from the end, the end load applied being F —

$$y = \frac{\frac{Bl}{8} \cos \frac{\pi x}{l}}{\frac{EI\pi^2}{l^2} - F}$$

Find the value of $EI \frac{d^2y}{dx^2} + Fy + \frac{Bl}{8} \cos \frac{\pi x}{l}$; y and x being the only variables.

22. The primary E.M.F. of a certain transformer was given by the expression—

$$E = 1500 \sin pt + 100 \sin 3pt - 42 \cos pt + 28 \cos 3pt.$$

Find the rate at which the E.M.F. varied.

23. A displacement s is given by $s = \sin 12t - \frac{12}{13} \sin 13t$. Show that the acceleration = $25 \sin 12t - 169s$.

CHAPTER III

ADDITIONAL RULES OF DIFFERENTIATION

Differentiation of a Function of a Function.—Whilst the expression $e^{\sin 4x}$ is essentially a function of x , it can also be spoken of as a function of $\sin 4x$, which in turn is a function of x ; and thus it is observed that $e^{\sin 4x}$ is a function of a function of x . This fact will be seen more clearly, perhaps, if u is written in place of $\sin 4x$: thus $e^{\sin 4x} = e^u$, which is a function of u , which, again, is a function of x , since $u = \sin 4x$.

To differentiate a function of a function the following rule is employed—

$$\frac{dy}{dx} = \frac{dy}{du} \times \frac{du}{dx}$$

and this rule is easily proved.

Let y be a function of u , and let u be a function of x : then y is a function of a function of x . Now increase x by a small amount δx ; then since u depends on x , it takes a new value $u + \delta u$, and also the new value of y becomes $y + \delta y$. Since these changes are measurable quantities, although small, the ordinary rules of arithmetic can be applied, so that—

$$\frac{\delta y}{\delta x} = \frac{\delta y}{\delta u} \times \frac{\delta u}{\delta x}$$

When δx approaches zero these fractions approach the limiting values $\frac{dy}{dx}$, $\frac{dy}{du}$ and $\frac{du}{dx}$ respectively; and thus in the limit—

$$\frac{dy}{dx} = \frac{dy}{du} \times \frac{du}{dx}$$

In like manner, if y is a function of u , u a function of w , and w a function of x , it can be proved that—

$$\frac{dy}{dx} = \frac{dy}{du} \times \frac{du}{dw} \times \frac{dw}{dx}$$

It will be observed that on the right-hand side of the equation we have dy as the first numerator and dx as the last denominator (these giving in conjunction the left-hand side of the equation); and we may regard the other numerators and denominators as neutralising one another. The simple arithmetic analogy may help to impress the rule upon the memory: thus—

$$\frac{4}{5} = \frac{4}{5^1} \times \frac{5^1}{7 \cdot 6} \times \frac{7^6}{5}.$$

Example 1.—If $y = e^{\sin 4x}$, find the value of $\frac{dy}{dx}$.

Let $u = \sin 4x$, so that $\frac{du}{dx} = 4 \cos 4x$ and $y = e^u$.

Since y is now a function of u , we can differentiate it with regard to u , whereas it is impossible to differentiate with regard to x directly.

$$y = e^u \text{ and } \frac{dy}{dx} = \frac{de^u}{du} = e^u = e^{\sin 4x}.$$

Then, since

$$\frac{dy}{dx} = \frac{dy}{du} \times \frac{du}{dx}$$

$$\begin{aligned} \frac{dy}{dx} &= e^{\sin 4x} \times 4 \cos 4x \\ &= 4 \cos 4x \times e^{\sin 4x}. \end{aligned}$$

Example 2.—Find the value of $\frac{d}{dx} \log (\cos 2x)^3$.

Let $v = (\cos 2x)^3$ and $u = \cos 2x$; and thus $y = \log_e v$ and $v = u^3$

$$\begin{aligned} \text{Then } \frac{dy}{dx} &= \frac{dy}{dv} \times \frac{dv}{du} \times \frac{du}{dx} & \frac{du}{dx} &= -2 \sin 2x \\ &= \frac{d \log v}{dv} \times \frac{du^3}{du} \times \frac{d \cos 2x}{dx} & v &= u^3 \\ &= \frac{1}{v} \times 3u^2 \times -2 \sin 2x & \frac{dv}{du} &= 3u^2 \\ &= \frac{-6 \sin 2x \times (\cos 2x)^2}{(\cos 2x)^3} = \frac{-6 \sin 2x}{\cos 2x} \\ &= -6 \tan 2x. \end{aligned}$$

Example 3.—The radius of a sphere is being decreased at the rate of 0.02 in. per min. At what rate is (a) the surface, (b) the weight, varying, when the radius is 15 ins. and the material weighs 3 lb. per cu. in.?

If r = radius, then $\frac{dr}{dt}$ = rate of change of the radius, and is in this case equal to -0.02 .

(a) The surface = $4\pi r^2$, and thus the rate of change of surface

$$\begin{aligned} &= \frac{dS}{dt} \\ &= \frac{d}{dt}(4\pi r^2) \\ &= 4\pi \cdot \frac{dr^2}{dt} \\ &= 4\pi \cdot \frac{dr^2}{dr} \times \frac{dr}{dt} \\ &= 4\pi \times 2r \times \frac{dr}{dt} \\ &= 8\pi r \times -0.02. \end{aligned}$$

Hence when $r = 15$, $\frac{dS}{dt} = 8\pi \times 15 \times -0.02 = -7.53$, i.e., the surface is being diminished at the rate of 7.53 sq. ins. per min.

(b) The volume = $\frac{4}{3}\pi r^3$

so that the rate of change of volume = $\frac{dV}{dt} = \frac{d}{dt}\left(\frac{4}{3}\pi r^3\right)$

and the rate of change of the weight = $\frac{dW}{dt} = \frac{d}{dt}\left(\frac{4}{3} \times 3\pi r^3\right)$

$$\begin{aligned} \frac{dW}{dt} &= \frac{d}{dt}(4\pi r^3) = 4\pi \cdot \frac{dr^3}{dt} = 4\pi \times \frac{dr^3}{dr} \times \frac{dr}{dt} \\ &\quad \cdot 4\pi \times 3r^2 \times \frac{dr}{dt} \\ &= 4\pi \times 3r^2 \times -0.02. \end{aligned}$$

When $r = 15$, $\frac{dW}{dt} = 4\pi \times 3 \times 225 \times -0.02 = -16.93$

or the weight is decreasing at the rate of 16.93 lbs. per min.

Example 4.—Find expressions for the velocity and acceleration of the piston of a horizontal steam engine when the crank makes n revolutions per second.

In each turn the angle swept out = 2π radians.

Hence in 1 second $2\pi n$ radians are swept out, i.e., the angular velocity = $2\pi n$; and this is the rate of change of angle, so that $\frac{d\theta}{dt} = 2\pi n$.

From Fig. 16 $CD = l \sin \alpha$

and $CD = r \sin \beta$

Thus $l \sin \alpha = r \sin \beta$

or $\sin \theta = \frac{r}{l} \sin \alpha$, and $\sin \alpha = \frac{l}{r} \sin \beta$

$$\text{Again, } \cos \alpha = \sqrt{1 - \sin^2 \alpha} \\ = \sqrt{1 - \sin^2 \theta} = \left(1 - \frac{r^2}{l^2}\right) \sin^2$$

If the connecting rod is long compared with the crank, $\frac{r}{l}$ is small and $\frac{r^2}{l^2}$ still smaller, so that our method of approximation can be applied to the expansion of the bracket, *i.e.*—

$$\cos \alpha = 1 - \frac{1}{2} \frac{r^2}{l^2} \sin^2 \theta, \text{ very nearly.}$$

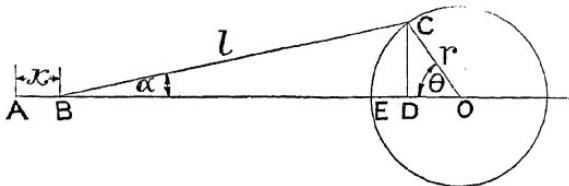


FIG. 16.—Velocity and Acceleration of Piston.

$$\begin{aligned} \text{Let } AB &= \text{displacement of the piston from its in-dead-centre position} \\ &= x = AE + OE - BO = l + r - BD - DO \\ &= l + r - l \cos \alpha - r \cos \theta \\ &= l + r - l \left(1 - \frac{r^2}{2l^2} \sin^2\right) \\ &= r + \frac{r^2}{2l} \sin^2 \theta - r \cos \theta \\ &= r + \frac{r^2}{2l} \left(\frac{1 - \cos 2\theta}{2}\right) - r \cos \theta \\ &= r + \frac{r^2 - r^2 \cos 2\theta}{4l} - r \cos \theta. \end{aligned}$$

$$\text{Now the velocity of the piston} = \frac{dx}{dt} = \frac{d}{dt} \left\{ r + \frac{r^2 - r^2 \cos 2\theta}{4l} - r \cos \theta \right\}$$

We cannot differentiate this expression directly, so we write—

$$\frac{dx}{dt} = \frac{dx}{d\theta} \times \frac{d\theta}{dt}.$$

$$\begin{aligned} \text{Hence } \frac{dx}{dt} &= \frac{d}{d\theta} \left\{ r + \frac{r^2 - r^2 \cos 2\theta}{4l} - r \cos \theta \right\} \times \frac{d\theta}{dt} \\ &= \left\{ 0 + 0 - \left(\frac{r^2}{4l} \times -2 \sin 2\theta\right) - (r \times -\sin \theta) \right\} \times 2\pi n \\ &= 2\pi nr \left\{ \frac{r \sin 2\theta}{2l} + \sin \theta \right\}. \end{aligned}$$

$$\text{or if } \frac{r}{v} = m$$

$$v = \frac{dx}{dt} = 2\pi nr \left\{ \frac{\sin 2\theta}{2m} + \sin \theta \right\}$$

$$\begin{aligned} \text{Also the acceleration } &= \frac{dv}{dt} = \frac{dv}{d\theta} \times \frac{d\theta}{dt} = \frac{d}{d\theta} \cdot 2\pi nr \left\{ \frac{\sin 2\theta}{2m} + \sin \theta \right\} \times \frac{d\theta}{dt} \\ &= 2\pi nr \left\{ \frac{\cos 2\theta}{m} + \cos \theta \right\} \times 2\pi n \\ &= 4\pi^2 n^2 r \left\{ \cos \theta + \frac{\cos 2\theta}{m} \right\} \end{aligned}$$

Example 5.—Water is flowing into a large tank at the rate of 200 gallons per min. The reservoir is in the form of a frustum of a pyramid, the length of the top being 40 ft. and width 28 ft., and the corresponding dimensions of the base being 20 ft. and 14 ft.; the depth is 12 ft. (see Fig. 17). At what rate is the level of the water rising when the depth of water is 4 ft.?

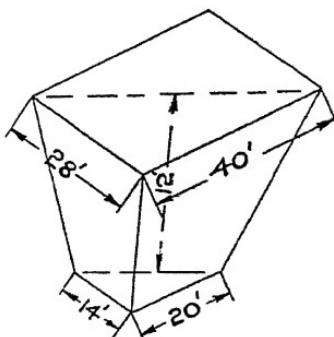


FIG. 17.

In 12 ft. the length decreases by 20 ft., and therefore in 8 ft. the length decreases by $\frac{20 \times 8}{12}$, i. e., $13\frac{1}{3}$ ft., so that the length when the water is 4 ft. deep is $40 - 13\frac{1}{3} = 26\frac{2}{3}$ ft.

Similarly,

$$\text{i. e., the breadth} = 28 - (\frac{2}{3} \times 14) = 18\frac{2}{3} \text{ ft.}$$

$$\text{the area of surface} = 26\frac{2}{3} \times 18\frac{2}{3} = 498 \text{ sq. ft.}$$

$$\begin{aligned} \text{200 gals. per min.} &= \frac{200}{6.24} \text{ cu. ft. per min.} \\ &= 32.1 \text{ cu. ft. per min.} \end{aligned}$$

$$\text{i. e., the rate of change of volume} = \frac{dV}{dt} = 32.1.$$

$$\text{Now } \frac{dV}{dt} = \frac{d}{dt} \cdot Ah, \text{ where } A = \text{area of surface}$$

and h = depth of water,

$$= A \frac{dh}{dt} \quad \left\{ \text{since for the short interval of time considered the area of the surface may be considered constant.} \right\}$$

$$\text{Hence the rate of change of level} = \frac{dh}{dt} = \frac{dV}{dt} \times \frac{1}{A}$$

$$\begin{aligned} &= \frac{32.1 \times 1}{498} = .0644 \text{ ft. per min.} \\ &= .773 \text{ in. per min.} \end{aligned}$$

Example 6.—If a curve of velocity be plotted to a base of space, prove that the sub-normal of this curve represents the acceleration.

The sub-normal of a curve : $y \frac{dy}{dx}$ (see p. 43).

In this case, since v is plotted along the vertical axis and s along the horizontal axis—

$$\begin{aligned}\text{the sub-normal} &: v \frac{dv}{ds} \\ &= v \cdot \frac{dv}{dt} \times \frac{dt}{ds} \\ &= v \times a \times \frac{1}{s} \\ &= a\end{aligned}$$

$$\left. \begin{aligned}\text{for } \frac{dv}{dt} &= \text{rate of change of velocity} = a \\ \text{and } \frac{ds}{dt} &= \text{rate of change of position}.\end{aligned}\right\}$$

As a further example of this rule, consider the case of motion due to gravity; in this instance $v^2 = 2gs$, i.e., the velocity space curve is a parabola. Hence we know that the sub-normal must be a constant, i.e., the acceleration must be constant.

$$\text{The sub-normal} = v \frac{dv}{ds}$$

$$\text{Now } \frac{dv^2}{ds} = \frac{u}{ds} \cdot 2gs = 2g \cdot \frac{ds}{ds} = 2g$$

$$\text{but } \frac{dv^2}{ds} : \frac{dv^2}{dv} \cdot \frac{dv}{ds} : 2v \frac{dv}{ds}$$

$$2v \frac{dv}{ds} = 2g$$

$$\text{or } v \frac{dv}{ds} = g$$

i.e., the sub-normal or the acceleration = g .

Exercises 6.—On the Differentiation of a Function of a Function.

$$\text{Find 1. } \frac{d}{dx} e^{\sin 2x}. \quad 2. \frac{u}{dv} \log v^2. \quad 3. \frac{u}{dt} 2 \cos^2 t.$$

$$4. \frac{a}{dx} 8 \sin x^3. \quad 5. \frac{d}{dx} 3 \cdot 14 \tan(5x^2 + 7x - 2) \quad 6. \frac{d}{dx} a^{\sin 3x}.$$

$$7. \frac{d}{dx} e^{x^{1.85}}. \quad 8. \frac{d}{dx} \log_{10}(3 + 7x - 9x^3). \quad \checkmark 9. \frac{d}{ds} \cos(\log s^5).$$

$$\text{and 10. } \frac{d}{dx} \log \tan \frac{x}{2}.$$

- ✓ 11. In the consideration of the theory of Hooke's coupling it is required to find an expression for $\frac{\omega_B}{\omega_A}$, i.e., a ratio of angular velocities.

If $\omega_B = \frac{d\phi}{dt}$, $\omega_A = \frac{d\theta}{dt}$ and $\tan \phi = \frac{\tan \theta}{\cos \alpha}$, find an expression for ω_B in terms of the ratios of θ , ϕ and α .

12. Find an expression for the slope of the cycloid at any point. The equation of the cycloid is $x = a(\theta + \sin \theta)$
 $y = a(1 - \cos \theta)$

the co-ordinates x and y being measured as indicated in Fig. 18.

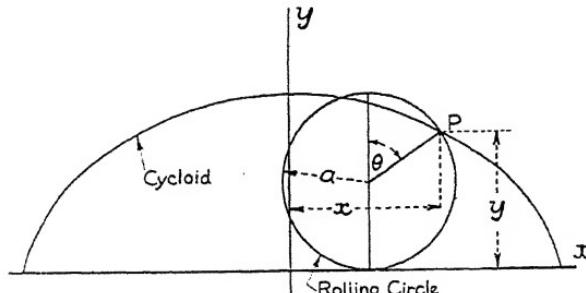


FIG. 18.

- ✓ 13. Assuming that the loss of head due to turbulent flow of water in a pipe is expressed by $h = C(AV^2 + BV^{\frac{5}{2}})$, where V = mean velocity of flow in ft. per sec.; show that the slope of the curve in which $\log h$ and $\log V$ are plotted with rectangular co-ordinates is given by—

$$\frac{d \log h}{d \log V} = \frac{2V^{\frac{1}{2}} + \frac{3B}{2A}}{V^{\frac{1}{2}} + \frac{B}{A}}$$

14. If $3x^2 + 8xy + 5y^2 = 1$

show that $\frac{dy}{dx^2} = (4x + 5y)^3$

- ✓ 15. A vessel in the form of a right circular cone whose height is 7 ft. and diameter of its base 6 ft., placed with its axis vertical and vertex downwards, is being filled with water at the rate of 10 cu. ft. per min.; find the velocity with which the surface is rising (a) when the depth of the water is 4 ft. and (b) when 60 cu. ft. have been poured in.

- ✓ 16. If $\frac{1}{1-E} = (r)^{\frac{R}{K}}$, prove that $\frac{dE}{dK} = -\frac{R}{K^2} \left(\frac{1}{r}\right)^K \log r$.

17. If $x^3 - 6x^2y - 6xy^2 + y^3 = \text{constant}$, prove that—

$$\frac{dy}{dx} = \frac{x^2 - 4xy - 2y^2}{2x^2 - y^2 + 4xy}$$

✓ 18. A ring weight is being turned in a lathe. It is required to find the weight removed by taking a cut of depth $\frac{1}{200}$ ". The material is cast iron (.26 lb. per cu. in.), the outside diameter of the ring is 3.26" and the length is 2.5". Find the weight removed.

Find also a general expression for the weight removed for a cut of depth $\frac{1}{200}$ " at any diameter.

19. Find the value of $\frac{d}{dt} \left[\log \tan \frac{\pi t}{2} + 15t^3 \right]$.

20. If $P = \frac{F^2 l}{2EA}$, and $\frac{dF}{dW} = u$, find $\frac{dP}{dW}$. (This question has reference to stresses in redundant frames.)

21. Find the angle which the tangent to the ellipse $\frac{x^2}{4} + \frac{y^2}{9} = 2$ at the point $x = 2$, $y = -3$, makes with the axis of x .

22. Find the slope of the curve $4x^2 + 4y^2 = 25$ at the point $x = 2$, $y = -\frac{3}{2}$, giving the angle correct to the nearest minute.

23. If force can be defined as the space-rate of change of kinetic energy, and kinetic energy $= \frac{wv^2}{2g}$, prove that force $= \frac{wa}{g}$.

24. If $x = 8 \log(12t^3 - 74)$, find the value of $\frac{dx}{dt}$.

Differentiation of a Product of Functions of x .—It has already been seen that to differentiate the sum of a number of terms we differentiate the terms separately and add the results. We might therefore be led to suppose that the differentiation of a product might be effected by a somewhat similar plan, viz., by multiplication together of the derivatives of the separate factors. This is, however, not the correct procedure; thus—

$$\frac{a}{dx} (\log x \times x^2) \text{ does not equal } \frac{d}{dx} \log x \times \frac{dx^2}{dx}, \text{ i. e., } \frac{1}{x} \times 2x \text{ or } 2.$$

The true rule is expressed in the following manner: If u and v are both functions of x , and $y = uv$, i. e., their product—

$$\frac{dy}{dx} = \frac{d}{dx}(uv) = v \frac{du}{dx} + u \frac{dv}{dx}$$

Proof.—Let x increase by an amount δx ; then since both u and v are dependent on x , u changes to a new value $u + \delta u$ and v becomes $v + \delta v$.

Now $y = uv$, and hence the new value of y , which can be written $y + \delta y$, is given by—

$$y + \delta y = (u + \delta u)(v + \delta v)$$

but

$$y = uv$$

whence by subtraction—

$$\begin{aligned}\delta y &= y + \delta y - y = (u + \delta u)(v + \delta v) - uv \\&= uv + u\delta v + v\delta u + \delta u \cdot \delta v - uv \\&= u\delta v + v\delta u + \delta u \cdot \delta v.\end{aligned}$$

Dividing through by δx —

$$\frac{\delta y}{\delta x} = u \frac{\delta v}{\delta x} + v \frac{\delta u}{\delta x} + \delta u \cdot \frac{\delta v}{\delta x}$$

As δx is decreased without limit, $\frac{\delta y}{\delta x}$, $\frac{\delta v}{\delta x}$ and $\frac{\delta u}{\delta x}$ approach the values $\frac{dy}{dx}$, $\frac{dv}{dx}$ and $\frac{du}{dx}$ respectively, and the term $\delta u \cdot \frac{\delta v}{\delta x}$ becomes negligible; so that in the limit—

$$\frac{dy}{dx} = v \frac{du}{dx} + u \frac{dv}{dx}$$

The rule may be extended to apply to the case of a product of more than two functions of x . Thus if u , v and w are each functions of x —

$$\begin{aligned}\frac{d(uvw)}{dx} &= \frac{d(wV)}{dx}, \text{ where } V \text{ is written for } uv \\&= w \frac{dV}{dx} + V \frac{dw}{dx} \\&= w \frac{d(uv)}{dx} + uv \frac{dw}{dx} \\&= w \left(v \frac{du}{dx} + u \frac{dv}{dx} \right) + uv \frac{dw}{dx}\end{aligned}$$

and thus—

$$\frac{d(uvw)}{dx} = wv \frac{du}{dx} + wu \frac{dv}{dx} + uv \frac{dw}{dx}$$

Example 7.—Find $\frac{dy}{dx}$ when $y = x^2 \cdot \log x$.

Let— $u = x^2$ so that $\frac{du}{dx} = 2x$

and let $v = \log x$ so that $\frac{dv}{dx} = \frac{1}{x}$.

Then $\frac{d(uv)}{dx} = v \frac{du}{dx} + u \frac{dv}{dx} = (\log x \times 2x) + \left(x^2 \cdot \frac{1}{x}\right)$
 $= \underline{x(1+2 \log x)}.$

MATHEMATICS FOR ENGINEERS

Example 8.—Find the value of $\frac{d}{dt}[5e^{-7t} \cdot \sin(6t-4)]$

$$\text{Let } u = 5e^{-7t} \quad \text{so that } \frac{du}{dt} = 5 \times -7e^{-7t} = -35e^{-7t}$$

$$\text{and let } v = \sin(6t-4) \quad \text{so that } \frac{dv}{dt} = 6 \cos(6t-4).$$

$$\begin{aligned}\text{Then } -\frac{d}{dt}(uv) &= v \cdot \frac{du}{dt} + u \cdot \frac{dv}{dt} \\ &= [\sin(6t-4) \times -35e^{-7t}] + [5e^{-7t} \times 6 \cos(6t-4)] \\ &= \underline{\underline{5e^{-7t}[6 \cos(6t-4) - 7 \sin(6t-4)]}}.\end{aligned}$$

Example 9.—If $2q + \frac{1}{x} \frac{d}{dx}(px^2) = 0$, show that $2q = -2p - x \frac{dp}{dx}$
 p being a function of x . This example has reference to thick spherical shells.

If p is a function of x , px^2 is of the form uv , where $u = p$ and $v = x^2$.

$$\text{Hence } -\frac{d}{dx} \cdot px^2 = x^2 \frac{dp}{dx} + p \frac{d}{dx}(x^2) = x^2 \frac{dp}{dx} + 2xp.$$

$$\text{Hence } 2q + \frac{1}{x} \frac{d}{dx} \cdot px^2 = 2q + x \frac{dp}{dx} + 2p$$

$$\text{i. e., } 0 = 2q + x \frac{dp}{dx} + 2p$$

$$\text{or } 2q = -2p - x \frac{dp}{dx}.$$

Example 10.—Find the value of $\frac{d}{dx} 9x^4 \sin(3x-7) \log(1-5x)$.

$$\text{Let } u = x^4, \quad v = \sin(3x-7) \quad \text{and} \quad w = \log(1-5x)$$

$$\text{then } \frac{du}{dx} = 4x^3, \quad \frac{dv}{dx} = 3 \cos(3x-7) \quad \text{and} \quad \frac{dw}{dx} = \frac{-5}{1-5x} = \frac{5}{5x-1}$$

$$\frac{d}{dx} 9x^4 \sin(3x-7) \log(1-5x) = 9 \frac{d}{dx}(uvw)$$

$$= 9 \left[uv \frac{du}{dx} + wu \frac{dv}{dx} + uw \frac{dw}{dx} \right]$$

$$\begin{aligned}&= 9 \left[\log(1-5x) \sin(3x-7) 4x^3 + \{\log(1-5x)x^4 \times 3 \cos(3x-7)\} \right. \\&\quad \left. + x^4 \sin(3x-7) \frac{5}{5x-1} \right]\end{aligned}$$

$$\begin{aligned}&= 9x^3 \left[4 \sin(3x-7) \log(1-5x) + 3x \cos(3x-7) \log(1-5x) \right. \\&\quad \left. + \frac{5x \sin(3x-7)}{5x-1} \right].\end{aligned}$$

Exercises 7.—On the Differentiation of a Product.

Differentiate, with respect to x , the functions in Nos. 1 to 12.

1. $x^2 \sin 3x$.
2. $\log 5x \times 2x^{3.4}$.
3. $e^{9x} \log_{10} 9x$.
4. $4x^{-5} \cdot \tan(3.1 - 2.07x)$.
5. $\cos 3.2x \cos(1.95x + 4)$.
6. $\cos(5 - 3x) \tan 2x$.
7. $8x^{1.6} \cos(3 + 8x) + 16x^{1.6}$.
8. $9 \log x^3 \cdot 5^{3x}$.
9. $e^x \log x$.
10. $\frac{5}{4} e^{4x} \left\{ x^2 - \frac{x}{2} + \frac{1}{8} \right\}$.
11. $6e^{5x+2}(5x+2)^2$.
12. $7.2 \tan \frac{x}{8} \log x^7$.

- ✓ 13. If $y = Ae^{3x} \cos \left(\frac{2x}{3} + B \right)$, find the value of—

$$\frac{d^2y}{dx^2} - 6 \frac{dy}{dx} + \frac{85}{9}y.$$

- ✓ 14. Find the value of $\frac{d}{dt} e^{-5t} \cosh(-5t)$.

- ✓ 15. $y = (A + Bx)e^{-1x}$; find the value of $\frac{d^2y}{dx^2} + 8 \frac{dy}{dx} + 16y$.

- ✓ 16. If $V = 250 \sin(7t - 116)$, $A = 7.2 \sin 7t$ and $W = VA$, find the value of $\frac{dW}{dt}$.

17. Differentiate with respect to t the function $15t^2 \sin(4 - 8t)$.

18. Find the value of $\frac{d}{dt}(4t^{3.7} \cos 3t)$.

Differentiation of a Quotient.—If u and v are both functions of x , and $y = \frac{u}{v}$, then—

$$\frac{dy}{dx} = \frac{v \frac{du}{dx} - u \frac{dv}{dx}}{v^2}$$

Proof.

(a) *From first principles.*—Let $y = \frac{u}{v}$: then a change δx in x causes changes of δy in y , δu in u , and δv in v , so that the new value of $y = y + \delta y = \frac{u + \delta u}{v + \delta v}$.

$$\text{Then } \delta y = y + \delta y - y = \frac{u + \delta u}{v + \delta v} - \frac{u}{v} = \frac{uv + v\delta u - uv - u\delta v}{v(v + \delta v)} \\ = \frac{v\delta u - u\delta v}{v(v + \delta v)}$$

and, dividing through by δx —

$$\frac{\delta y}{\delta x} = \frac{1}{v(v + \delta v)} \left\{ v \cdot \frac{\delta u}{\delta x} - u \cdot \frac{\delta v}{\delta x} \right\}.$$

When δx becomes very small, $\frac{\delta y}{\delta x}$, $\frac{\delta u}{\delta x}$ and $\frac{\delta v}{\delta x}$ approach the values $\frac{dy}{dx}$, $\frac{du}{dx}$ and $\frac{dv}{dx}$ respectively, whilst $v + \delta v$ becomes indistinguishable from v .

Hence in the limit $\frac{dy}{dx} = \frac{1}{v \times v} \left(v \cdot \frac{du}{dx} - u \cdot \frac{dv}{dx} \right)$

$$= v \frac{du}{dx} - u \frac{dv}{dx}$$

(b) Using the rules for a product and a function of a function.

$$y = \frac{u}{v} = uv^{-1}$$

$$\begin{aligned} \text{Then } \frac{dy}{dx} &= \frac{u}{dx} \cdot (uv^{-1}) = v^{-1} \frac{du}{dx} + u \cdot \frac{dv^{-1}}{dx} \\ &= \left(\frac{1}{v} \frac{du}{dx} \right) + \left(u \cdot \frac{dv^{-1}}{dv} \times \frac{dv}{dx} \right) \\ &= \left(\frac{1}{v} \cdot \frac{du}{dx} \right) + \left(u \times -v^{-2} \times \frac{dv}{dx} \right) \\ &= v \frac{du}{dx} - u \frac{dv}{dx} \end{aligned}$$

Example 11.—Differentiate, with regard to s , the expression—

$$\frac{4s^3 + 7s}{5 \cos(3s+4)}.$$

$$\text{Let } u = 4s^3 + 7s, \quad \text{then } \frac{du}{ds} = 12s^2 + 7,$$

$$\text{and let } v = 5 \cos(3s+4), \text{ then } \frac{dv}{ds} = -15 \sin(3s+4).$$

$$\begin{aligned} \text{Then } \frac{d}{ds} \cdot \left(\frac{u}{v} \right) &= \frac{v \frac{du}{ds} - u \frac{dv}{ds}}{v^2} \\ &= \frac{[5 \cos(3s+4) \times (12s^2 + 7)] - [(4s^3 + 7s) \times -15 \sin(3s+4)]}{25 \cos^2(3s+4)} \\ &= \frac{(12s^2 + 7)[\cos(3s+4)] + (4s^3 + 21s)[\sin(3s+4)]}{5 \cos^2(3s+4)} \end{aligned}$$

Example 12.—If $y = 9^{4x} \times \frac{1}{\log 7x}$, find the value of $\frac{dy}{dx}$.

$$\text{Let } u = 9^{4x}, \text{ then } \frac{du}{dx} = 4 \times 9^{4x} \log_e 9 = 4 \times 2.1972 \times 9^{4x} \\ = 8.789 \times 9^4$$

$$\text{and let } v = \log 7x, \text{ then } \frac{dv}{dx} = \frac{7}{7x} = \frac{1}{x}.$$

$$\text{Hence } \frac{dy}{dx} = \frac{d(u)}{dx} \cdot \frac{v}{v} = \frac{\frac{du}{dx} - u \frac{dv}{dx}}{v \frac{dv}{dx}}$$

$$= \frac{(8.789 \times 9^4) - (9^{4x} \times \frac{1}{x})}{(\log 7x)^2}$$

$$= \frac{9^{4x} \{(8.789 \times \log 7x) - 1\}}{x (\log 7x)^2}$$

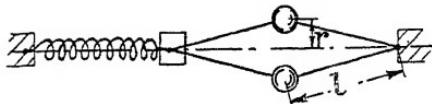


FIG. 19.—Spring loaded Governor.

Example 13.—For a spring loaded governor (see Fig. 19)—

$$\omega^2 = \frac{g \{T + 2Q(l - \sqrt{l^2 - r^2})\}}{W \sqrt{l^2 - r^2}}$$

where Q = force to elongate the spring 1 unit, T = tension in spring, W = weight of 1 ball, ω = angular velocity, r = radius of path of balls, l = length of each of the 4 arms.

If $W = 3$, $g = 32.2$ and $\frac{d\omega}{dr} = 80$ when $\omega = 26$, $r = .25$ and $l = 1$, find T and Q .

As there are two unknowns, we must form two equations. By simple substitution—

$$(26)^2 = \frac{32.2 \{T + 2Q(1 - \sqrt{1 - .0625})\}}{3 \sqrt{1 - .0625}} \quad \frac{\sqrt{1 - .0625}}{=.968}$$

whence $T + .064Q = 60.96 \dots \dots \dots \quad (1)$

We are told that $\frac{d\omega}{dr}$ must equal 80.

$$\text{Now } \frac{d\omega^2}{dr} = \frac{d\omega^2}{d\omega} \times \frac{d\omega}{dr} = 2\omega \frac{d\omega}{dr} \quad \dots \dots \dots$$

$$\text{Also } \frac{d}{dr} \frac{g \{T + 2Q(l - \sqrt{l^2 - r^2})\}}{W \sqrt{l^2 - r^2}} = \frac{d(u)}{dr} \cdot \frac{v}{v}$$

$$\text{where } u = g \{T + 2Q(l - \sqrt{l^2 - r^2})\} \\ \text{and } v = W \sqrt{l^2 - r^2}$$

Thus to determine $\frac{du}{dr}$ and $\frac{dv}{dr}$ it is first necessary to find the value of $\frac{d\sqrt{l^2-r^2}}{dr}$: to do this let $l^2-r^2 = y$

$$\text{so that } \frac{dy}{dr} = -2r$$

$$\begin{aligned}\text{then } \frac{d}{dr} \sqrt{l^2-r^2} &= \frac{dy^{\frac{1}{2}}}{dr} = \frac{dy^{\frac{1}{2}}}{dy} \times \frac{dy}{dr} \\ &= \frac{1}{2}y^{-\frac{1}{2}} \times -2r \\ &= -\frac{r}{\sqrt{l^2-r^2}}\end{aligned}$$

$$\text{Thus } \frac{du}{dr} = g\left(0+0+\frac{2Qr}{\sqrt{l^2-r^2}}\right) = \frac{2gQr}{\sqrt{l^2-r^2}}$$

$$\text{and } \frac{dv}{dr} = -\frac{Wr}{\sqrt{l^2-r^2}}$$

$$\begin{aligned}\text{Then } \frac{d}{dr} \frac{u}{v} &= \frac{v \frac{du}{dr} - u \frac{dv}{dr}}{v^2} \\ &= \frac{W \sqrt{l^2-r^2} \times \frac{2gQr}{\sqrt{l^2-r^2}} + g[T+2Q(l-\sqrt{l^2-r^2})]W_r}{W^2(l^2-r^2)} \quad (3)\end{aligned}$$

Thus, differentiating both sides of the original equation with respect to r , we have from (2) and (3)—

$$2\omega \frac{d\omega}{dr} = gr \left\{ \frac{2Q + \frac{I}{\sqrt{l^2-r^2}} - \frac{1}{2}[T+2Q(l-\sqrt{l^2-r^2})]}{l^2-r^2} \right\}$$

Substituting the numerical values—

$$\begin{aligned}2 \times 26 \times 80 &= \frac{32 \cdot 2 \times 25}{3 \times 9375} \left\{ 2Q + \frac{I}{.968} [T + .064Q] \right\} \\ \frac{52 \times 80 \times 3 \times 9375 \times .968}{32 \cdot 2 \times 25} &= 1.936Q + T + .064Q = 2Q + T\end{aligned}$$

$$\begin{aligned}\text{whence } 1407 &= 2Q + T \\ \text{but from (1) } 60.96 &= .064Q + T \\ \text{and therefore } Q &= 695.3 \\ \text{and } T &= 16.4\end{aligned}$$

Differentiation of Inverse Trigonometric Functions.—

Since inverse trigonometric functions occur frequently in the study of the Integral Calculus, it is necessary to demonstrate the rules for their differentiation; and in view of their importance in the later stages of the work, the results now to be deduced should be carefully studied.

The meaning of an inverse trigonometric function has already been explained (see Part I, p. 297), so that a reminder only is

needed here. Thus $\sin^{-1} x$ is an inverse trigonometric function, and it is such a function that if $y = \sin^{-1} x$, then $\sin y = x$.

To differentiate $\sin^{-1} x$ with regard to x .

Let $y = \sin^{-1} x$ so that, from definition, $\sin y = x$

$$\text{then } \frac{d \sin y}{dx} = \frac{dx}{dx} = 1$$

$$\text{but } \frac{d \sin y}{dx} = \frac{d \sin y}{dy} \times \frac{dy}{dx}$$

$$\text{and hence } 1 = \cos y \times \frac{dy}{dx}$$

$$\text{or } \frac{dy}{dx} : \cos y = \sqrt{1 - \sin^2 y} = \sqrt{1 - x^2}$$

$$\frac{d}{dx} \sin^{-1} x = \frac{1}{\sqrt{1-x^2}}$$

$$\text{Similarly— } \frac{d}{dx} \cos^{-1} x = -\frac{1}{\sqrt{1-x^2}}$$

(y being supposed to vary between 0 and $\frac{\pi}{2}$).

Example 14.—Find the value of $\frac{d}{dx} \tan^{-1} \frac{x}{a}$.

$$\text{Let } y = \tan^{-1} \frac{x}{a}, \text{ i.e., } \tan y = \frac{x}{a}$$

$$\text{and } \sec^2 y = 1 + \tan^2 y = 1 + \frac{x^2}{a^2}$$

$$\frac{a^2 + x^2}{a^2}$$

$$\text{Now } \frac{d \tan y}{dx} = \frac{d}{dx} \left(\frac{x}{a} \right) = \frac{1}{a}$$

$$\text{but } \frac{d \tan y}{dx} = \frac{d \tan y}{dy} \times \frac{dy}{dx}$$

$$\text{Hence } \frac{1}{a} = \sec^2 y \times \frac{dy}{dx}$$

$$\text{or } \frac{dy}{dx} = a \frac{1}{\sec^2 y} = \frac{1}{a} \times \frac{a^2}{a^2 + x^2}$$

$$\frac{a^2}{a^2 + x^2}$$

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Example 15.—Find the value of $\frac{d}{dx} \cosh^{-1} \frac{x}{a}$.

Let $v = \cosh^{-1}$

$$\text{then } \cosh y = a$$

$$\text{So that } \frac{d \cosh y}{dx} = \frac{d}{dx} \left(\frac{x}{a} \right)$$

$$\text{but } \frac{d \cosh y}{dx} = \frac{d \cosh y}{dy} \times \frac{dy}{dx}$$

$$\text{hence } \frac{1}{a} = \sinh y \times \frac{dy}{dx}$$

$$\text{Now } \cosh^2 y - \sinh^2 y = 1$$

$$\text{whence } \sinh^2 y = \cosh^2 y - 1 = \frac{x^2}{a^2} - 1 \\ = \frac{x^2 - a^2}{a^2}$$

and

$$\sinh y = \pm \frac{1}{a} \sqrt{x^2 - a^2}$$

Then, substituting this value for $\sinh y$ in (1)—

$$\frac{1}{a} = \pm \frac{1}{a} \sqrt{x^2 - a^2} \times \frac{dy}{dx}$$

or

$$\frac{dy}{dx} = \frac{1}{\sqrt{x^2 - a^2}}$$

$$\text{i.e., } \frac{d}{dx} \cosh^{-1} \frac{x}{a} = \pm \frac{1}{\sqrt{x^2 - a^2}}$$

Exercises 8.—On the Differentiation of a Quotient and the Differentiation of Inverse Functions.

Differentiate with respect to x the functions in Nos. 1 to 12.

1. $\frac{5x^3}{x+2}$.

2. $\frac{\log(2-7x)}{\cos(2-7x)}$.

3. $5 \sin^{-1} \frac{4x}{7}$.

4. $\cos^{-1} \frac{bx}{3a}$.

5. $\frac{5^{2-2x}}{x^2}$.

6. $\cosh \frac{1-8x}{4^{1-8}}$.

7. $\frac{1}{\sqrt{6}} \tan^{-1} \frac{x+3}{\sqrt{6}}$.

8. $\frac{7 \cos^{-1} 3x}{\sqrt{1-9x^2}}$.

9. $\frac{wb(a-x)x}{2(b-x \cot B)}$.

10. $a^2(a^2+x^2)^{\frac{1}{2}}$.

✓ 11. $\frac{l^3 - 6l^2x + 12lx^2 - 7x^3}{3l^4 - 4x}$ (an expression occurring in the solution of a beam problem).

12. $\frac{e^{\sin(1.2x+1.7)}}{\log(8x^2-7x+3)}.$

13. Assuming the results for $\frac{d}{dx} \cosh x$ and $\frac{d}{dx} \sinh x$, find the value of $\frac{d}{dx} \tanh x$.

Nos. 14 and 15 refer to the flow of water through circular pipes; v being the velocity of flow, Q the quantity flowing, and θ being the angle at the centre subtended by the wetted perimeter.

14. If $v = 13.1 \left(1 - \frac{\sin \theta}{\theta}\right)^{\frac{1}{2}}$ find $\frac{dv}{d\theta}$.

15. Given that $Q = 132.4 \frac{(\theta - \sin \theta)^{\frac{3}{2}}}{\theta^{\frac{1}{2}}}$ find $\frac{dQ}{d\theta}$.

16. Differentiate, with respect to y , the expression—

$$\log\left(\frac{1+y}{1-y}\right)^{\frac{1}{2}} - \frac{1}{2} \tan^{-1} y.$$

17. If v (a velocity) = $r\omega (\sin \theta + \frac{\sin 2\theta}{2\sqrt{m^2 - \sin^2 \theta}})$ and $\frac{d\theta}{dt} =$ find the acceleration $(\frac{dv}{dt})$; find also the acceleration when θ is very small.

18. If $\sin \phi =$ and $\frac{d\theta}{dt} = \omega$, find the angular velocity $(\frac{d\phi}{dt})$ of a connecting-rod and also the angular acceleration $(\frac{d^2\phi}{dt^2})$.

19. Given that $x = \frac{w \tan^2 \theta + q}{(\phi - q) \tan \theta}$ find $\frac{dx}{d\theta}$ and hence the value of $\tan \theta$ that makes $\frac{dx}{d\theta} = 0$.

20. Find the value of $\frac{dM}{dx}$ when $M = \frac{wx(l-x)(l-2x)}{2(3l-2x)}$. M is a bending moment, l is the length of a beam and x is a portion of that length.

21. Differentiate, with respect to t , the quotient $\frac{5 \log(5t-8)}{t^3}$.

Partial Differentiation.—When dealing with the equation $PV = C\tau$ in connection with the theory of heat engines, we know that C alone is a constant, P, V and τ being variables. If one of these variables has a definite value, the individual values of the others are not thereby determined; e.g., assuming that C and τ are known, then so also is the product PV, but not the individual values of P and V. If, now, the value of one of these is fixed, say of P, then the value of V can be calculated: therefore V depends on both P and τ , and any change in V may be due to a change in either or both of the other variables. To find the change in the value of V consequent on changes in values of P and τ ,

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the change in V due to the change in P (assuming that τ is kept constant) is added to the change in V due to the change in τ (P being kept constant). Rates of change found according to this plan are spoken of as *partial* rates of change, or more usually *partial derivatives*, and the process of determining them is known as *partial differentiation*.

When only two variables occur, a plane curve may be plotted to depict the connection between them, but for three variables a surface is needed. The three co-ordinate axes will be mutually at

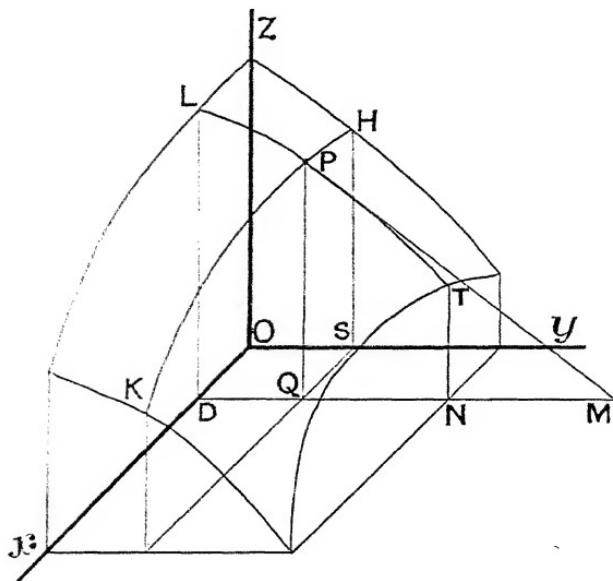


FIG. 20.

right angles, two in the plane of the paper, and the other at right angles to it. If x , y and z are the variables, we can say that z is a function of x and y , or, in the abbreviated form $z = f(x, y)$.

$$\begin{aligned} \text{Similarly---} \\ \text{and} \end{aligned} \quad \begin{aligned} x &= f(y, z) \\ y &= f(x, z). \end{aligned}$$

Dealing with the first of these forms, and assuming the axes of x and y to be horizontal (Fig. 20), let us examine, from the aspect of the graph, the significance of this form. Giving any value to x , we know the distance of the point in front of or behind the paper: the value of y determines the distance to the right or left of the axis of z , i.e., the vertical on which the point lies is

determined and the actual height up this vertical is fixed by the value of z . If z is kept constant whilst values of x and y are chosen, a number of points are found all lying on a horizontal plane, and if all such points are joined we have what is known as a contour line. Therefore, if one of the quantities is constant our work is confined to one plane; but we have already seen that when dealing with a plane, the rate of change of one quantity with regard to another is measured by the slope of a curve, hence we can ascribe a meaning to a partial derivative.

To illustrate by reference to a diagram (Fig. 20).

The point P on the surface is fixed by its co-ordinates x , y and z , or SQ, OS and QP.

If x is kept constant, the point must lie on the plane LTND. The slope of the curve LPT, as given by the tangent of the angle PMN, must measure the rate of change of z with regard to y when x is constant; and this is what we have termed the partial derivative of z with regard to y . This partial derivative may be expressed by $\frac{\partial z}{\partial y}$, or, more conveniently, by $(\frac{dz}{dy})_x$, and if there is no possibility of ambiguity as to the quantity kept constant the suffix x may be dispensed with.

$$\therefore \left(\frac{dz}{dy} \right) = -\tan \angle PMN \quad (\text{the slope being negative, since } z \text{ decreases as } y \text{ increases}).$$

Similarly, the slope of the curve KPH

$$= \left(\frac{dz}{dx} \right).$$

If the variables are connected by an equation, the partial derivatives can be obtained by the use of the ordinary rules of differentiation.

Example 16.—Given that $z = 5x^2y - 2x^3y^2 + 20e^{xy}$.

Find— $\left(\frac{dz}{dx} \right)$, $\left(\frac{dz}{dy} \right)$, $\left(\frac{d^2z}{dx^2} \right)$ and $\left(\frac{d^2z}{dy^2} \right)$.

To find $\left(\frac{dz}{dx} \right)$, i.e., to find the rate of change of z with regard to x when y is constant, differentiate in the ordinary way, but treating y as a constant.

Thus—
$$\begin{aligned} \left(\frac{dz}{dx} \right) &= (5y \times 2x) - (2y^2 \times 3x^2) + 20ye^{xy} \\ &= \underline{10xy - 6x^2y^2 + 20ye^{xy}} \end{aligned}$$

and
$$\begin{aligned} \left(\frac{d^2z}{dx^2} \right) &= (10y \times 1) - (6y^2 \times 2x) + (20y \times ye^{xy}) \\ &= \underline{10y - 12xy^2 + 20y^2e^{xy}} \end{aligned}$$

To find $\left(\frac{d^2z}{dy^2}\right)$ and $\left(\frac{d^2z}{dx^2}\right)$ x must be kept constant.

$$z = 5x^2y - 2x^3y^2 + 20e^{xy}$$

$$\begin{aligned} \text{then } \left(\frac{d^2z}{dy^2}\right) &= (5x^2 \times 1) - (2x^3 \times 2y) + 20x \cdot e^{xy} \\ &= \underline{\underline{5x^2 - 4x^3y + 20xe^{xy}}} \end{aligned}$$

$$\begin{aligned} \text{and } \left(\frac{d^2z}{dx^2}\right) &= 0 - (4x^3 \times 1) + (20x \times x \cdot e^{xy}) \\ &= \underline{\underline{x^2e^{xy} - 4x^3}}. \end{aligned}$$

Example 17.—If $z = 6 \log xy - 18x^5y^2$, find the values of $\left(\frac{d^2z}{dx^2}\right)$, and $\left(\frac{d^2z}{dy \cdot dx}\right)$, and state the conclusion to be drawn from the results.

To find $\left(\frac{d^2z}{dx \cdot dy}\right)$ we must first find the value of $\left(\frac{dz}{dy}\right)$, x being regarded as a constant: then if Y be written for this expression the value of $\left(\frac{dY}{dx}\right)$ must next be determined, y being treated as a constant, and this is the value of $\left(\frac{d^2z}{dx \cdot dy}\right)$.

$$\text{Now } \left(\frac{dz}{dy}\right) = \frac{6 \times x}{xy} - 18x^5 \times 2y = \frac{6}{y} - 36x^5y = Y, \text{ say.}$$

Differentiating this expression with regard to x , y being regarded as a constant—

$$\left(\frac{dY}{dx}\right) = 0 - 180x^4y$$

$$\text{or } \left(\frac{d^2z}{dx \cdot dy}\right) = -180x^4$$

$$\text{Now } \left(\frac{dz}{dx}\right) : \left(\frac{6 \times y}{xy}\right) - (18y^2 \times 5x^4) = \frac{6}{x} - 90y^2x^4$$

$$\text{and } \left(\frac{d}{dy}\right) \left(\frac{dz}{dx}\right) \text{ or } \left(\frac{d^2z}{dy \cdot dx}\right) = 0 - (90x^4 \times 2y) = -180x^4y,$$

$$\text{i.e., } \left(\frac{d^2z}{dx \cdot dy}\right) = \left(\frac{d^2z}{dy \cdot dx}\right).$$

Hence the order of differentiation does not affect the result.

Total Differential.—If y is a function of x , then $y = f(x)$ and $\frac{dy}{dx} = \frac{d}{dx}f(x)$ or $f'(x)$,

$$\text{i.e., } dy = f'(x)dx.$$

dy and dx are spoken of as *differentials*, and $f'(x)$ is the coefficient of the differential dx ; hence we see the reason for the term *differential coefficient*.

If z is a function of x and y , i. e., $z = f(x, y)$, the total differential dz is obtained from the partial differentials dx and dy by the use of the following rule—

$$dz = \left(\frac{dz}{dx} \right) dx + \left(\frac{dz}{dy} \right) dy.$$

The reason for this is more clearly seen if we work from the fundamental idea of rates of change, and introduce the actually measurable quantities like δz , δx and δy .

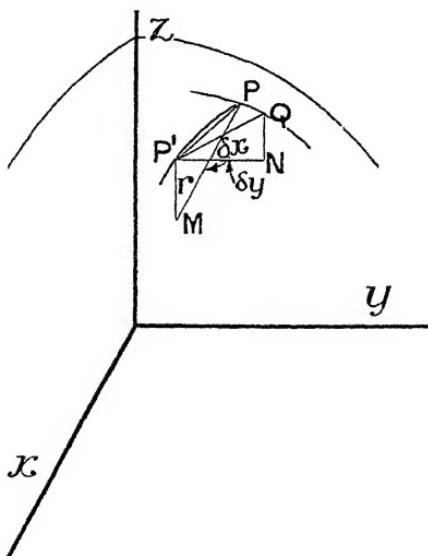


FIG. 21.

Thus—

$$\delta z = \left(\frac{dz}{dx} \right) \delta x + \left(\frac{dz}{dy} \right) \delta y.$$

or total change in z = change in z due to the change in x + change in z due to the change in y .

The change in z due to the change in x must be measured by the product of the change in x multiplied by the rate at which z is changing with regard to x ; and this fact can be better illustrated by reference to a diagram (Fig. 21).

Let P be a point (x, y, z) on a surface, and let P move to a new position Q near to P . The change of position is made up of—

- (a) A movement δx to P' on the surface (y being kept constant).
- (b) A movement δy to Q on the surface (x being kept constant).

In (a) z increases by MP'
 and $MP' = PM \times \tan \angle MPP'$
 $= \delta x \times \text{mean value of } \left(\frac{dz}{dx} \right)$

In (b) the change in $z = NQ$
 $= \delta y \times \text{mean value of } \left(\frac{dz}{dy} \right).$

If P , P' and Q are taken extremely close to one another, the mean or average slopes become the actual slopes and
 the total change in $z = \delta z$

$$= MP' + NQ = \delta x \left(\frac{dz}{dx} \right) + \delta y \left(\frac{dz}{dy} \right).$$

Example 18.—If Kinetic Energy $= K = \frac{mv^2}{2g}$, find the change in the energy as m changes from 49 to 49.5 and v from 1600 to 1590.

From the above rule, the change in $K = \delta K$

$$= \delta m \left(\frac{dK}{dm} \right) + \delta v \left(\frac{dK}{dv} \right).$$

Now

$$\delta m = 49.5 - 49 = .5$$

and

$$\delta v = 1590 - 1600 = -10.$$

Also $\left(\frac{dK}{dm} \right)$ (*i.e.*, v being constant) $= \frac{d}{dm} \left(\frac{v^2}{2g} \times m \right) = \frac{v^2}{2g} \times 1$

and $\left(\frac{dK}{dv} \right)$ (m being constant) $= \frac{d}{dv} \left(\frac{m}{2g} \times v^2 \right) = \frac{m}{2g} \times 2v.$

$$\delta K = .5 \times \frac{v^2}{2g} + (-10) \times 2 \frac{vm}{2g}.$$

$$= .5 \times \frac{1600^2}{64.4} - \frac{20 \times 1600 \times 49}{64.4}$$

$$= 19880 - 24380 = \underline{-4500 \text{ units.}}$$

Example 19.—A quantity of water Q is measured by

$$Q = C \frac{D^2}{4} \sqrt{2gH}.$$

If r_1 = the probable error of D , a diameter, r_2 = the probable error of H , a head, and R = the probable error of Q ,

$$R = \sqrt{r_1^2 \left(\frac{dQ}{dD} \right)^2 + r_2^2 \left(\frac{dQ}{dH} \right)^2}$$

where $\left(\frac{dQ}{dD} \right)$ and $\left(\frac{dQ}{dH} \right)$ are partial derivatives.

Find an expression for R .

$$\begin{aligned} \left(\frac{dQ}{dD} \right)_H &= \frac{d}{dD} \left(C \times \frac{\pi}{4} \sqrt{2gH} \cdot D^2 \right) \\ &= 2D \times C \times \frac{\pi}{4} \sqrt{2gH}. \end{aligned}$$

Also—
$$\left(\frac{dQ}{dH}\right)_D = \frac{d}{dH} \left(C \times \frac{\pi}{4} D^2 \sqrt{2g} \cdot H^4 \right)$$

$$= \frac{I}{2H^4} \times \frac{\pi CD^2}{4} \sqrt{2g}$$

Hence—
$$R = \sqrt{\frac{r_1^2 C^2 D^2 \pi^2 \times 2g H}{4} + \frac{r_2^2 \times \pi^2 C^2 D^4 \times 2g}{64H}}$$

$$= C \cdot \frac{\pi}{4} D^2 \cdot \sqrt{2gH} \cdot \sqrt{\frac{r_1^2}{D^2} + \frac{r_2^2}{4H^2}}$$

$$= Q \sqrt{4 \left(\frac{r_1}{D}\right)^2 + \frac{I}{4} \left(\frac{r_2}{H}\right)^2}.$$

or
$$\frac{R}{Q} = \sqrt{4 \left(\frac{r_1}{D}\right)^2 + \frac{I}{4} \left(\frac{r_2}{H}\right)^2}$$

i.e., if the probable error of D is 3% and that of H is 1%
that of $Q = \sqrt{4 \cdot (0.03)^2 + \frac{1}{4} \cdot (0.01)^2}$
 $= 0.602$, i.e., is about 6%.

Logarithmic Differentiation.—Occasionally it is necessary to differentiate an expression which can be resolved into a number of factors; and in such a case, to avoid repeated applications of the rules for the differentiation of products and quotients, we may first take logs throughout, and then differentiate, making use of the rule for the differentiation of a function of a function. By the judicious use of this artifice much labour can often be saved.

Example 20.—Find the value of $\frac{d}{dx} \left\{ \frac{(3x-4)(4x+7)}{(2x-9)} \right\}$.

Let— $y = \frac{(3x-4)(4x+7)}{(2x-9)}$

then $\log y = \log (3x-4) + \log (4x+7) - \log (2x-9)$.

Differentiating with regard to x —

$$\frac{d \log y}{dx} = \frac{3}{(3x-4)} + \frac{4}{(4x+7)} - \frac{2}{(2x-9)}$$

but $\frac{d \log y}{dx} = \frac{d \log y}{dy} \times \frac{dy}{dx} = \frac{1}{y} \cdot \frac{dy}{dx}$

so that $\frac{1}{y} \cdot \frac{dy}{dx} = \frac{3}{(3x-4)} + \frac{4}{(4x+7)} - \frac{2}{(2x-9)}$

or $\frac{dy}{dx} = \frac{(3x-4)(4x+7)}{(2x-9)} \times$

$$\frac{24x^2 - 66x - 189 + 24x^2 + 144 - 140x - 24x^2 - 10x + 56}{(3x-4)(4x+7)(2x-9)}$$

$$= \frac{24x^2 - 216x + 11}{(2x-9)^2}.$$

As an exercise, the reader should work this according to the following plan. Write $y = \frac{12x^2 + 5x - 28}{(2x-9)}$, and then use the rule for the differentiation of a quotient.

It is with examples in which powers of factors occur that this method is most useful.

Example 21.—Find $\frac{dy}{dx}$ when $y = \frac{(7x+2)^3(x-1)}{(2x-5)^2}$.

Taking logs throughout—

$$\log y = 3 \log (7x+2) + \log (x-1) - 2 \log (2x-5)$$

Then—

$$\begin{aligned} \frac{d \log y}{dy} &= \frac{3 \times 7}{(7x+2)} + \frac{1}{(x-1)} - \frac{2 \times 2}{(2x-5)} \\ &= \frac{42x^2 + 105 - 147x + 14x^2 - 3x - 10 - 28x^2 + 20x + 8}{(7x+2)(x-1)(2x-5)} \\ &= \frac{28x^2 - 158x + 103}{(7x+2)(x-1)(2x-5)} \\ \therefore \frac{1}{y} \cdot \frac{dy}{dx} &= \frac{28x^2 - 158x + 103}{(7x+2)(x-1)(2x-5)} \\ \text{i.e., } \frac{dy}{dx} &= \frac{(7x+2)^3(x-1)}{(2x-5)^2} \times \frac{28x^2 - 158x + 103}{(7x+2)(x-1)(2x-5)} \\ &= \frac{(7x+2)^2(28x^2 - 158x + 103)}{(2x-5)^3}. \end{aligned}$$

Exercises 9.—On Partial Differentiation and Logarithmic Differentiation.

1. In measuring the sides of a rectangle, the probable errors in the sides were r_1 and r_2 . If A = area and a and b are the sides, find the probable error R in A .

Given that— $R = \sqrt{r_1^2 \left(\frac{dA}{da} \right)^2 + r_2^2 \left(\frac{dA}{db} \right)^2}$

the derivatives being partial.

2. If $z = 3 \cdot 26x^5 e^{2y}$, find $\left(\frac{dz}{dx} \right)$ and $\left(\frac{d^2z}{dx^2} \right)$.

3. If $s = t^{5.2} - pt^2 + \log(5p-3) \times e^{4t}$, find $\left(\frac{ds}{dp} \right)_t$ and $\left(\frac{ds}{dt} \right)_p$.

4. If $v = (4-u)^2(3+8u)^3$, find $\frac{dv}{du}$.

5. If $y = \frac{(1+x)^n}{(1-x)^n}$, show that $\frac{dy}{dx} = \frac{2ny}{1-x^2}$.

6. If $y = 8x(1.7 + 2x)^4$, find $\frac{dy}{dx}$.
- ✓ 7. Differentiate, with respect to x , $\frac{x+3}{(x^2+6x+5)^2}$
8. Find the rate of discharge $\frac{dm}{dt}$ of air from a closed reservoir when $m = \frac{pv}{cr}$, m , p , v and r all being variables.
9. If $x = r \cos \theta$, $y = r \sin \theta$, and u is a function of both x and y , prove that—

$$\left(\frac{\partial u}{\partial x}\right)_y = \cos \theta \left(\frac{\partial u}{\partial r}\right)_\theta - \frac{1}{r} \sin \theta \left(\frac{\partial u}{\partial \theta}\right)_r$$

$$\text{and } \left(\frac{\partial u}{\partial y}\right)_x = \sin \theta \left(\frac{\partial u}{\partial r}\right)_\theta + \frac{1}{r} \cos \theta \left(\frac{\partial u}{\partial \theta}\right)_r.$$

CHAPTER IV

APPLICATIONS OF DIFFERENTIATION

HAVING developed the rules for the differentiation of the various functions, algebraic and trigonometric, we are now in a position to apply these rules to the solution of practical problems. By far the most important and interesting direction in which differentiation proves of great service is in the solution of problems concerned with maximum and minimum values; and with these problems we shall now deal.

Maximum and Minimum Values.—Numerous cases present themselves, both in engineering theory and practice, in which the value of one quantity is to be found such that another quantity, which depends on the first, has a maximum or minimum value when the first has the determined value.

E. g., suppose it is desired to arrange a number of electric cells in such a way that the greatest possible current is obtained from them. Knowing the voltage and internal resistance of each cell and the external resistance through which the current is to be passed, it is possible by simple differentiation to determine the relation that must exist between the external resistance and the total internal resistance in order that the maximum current flows.

Again, it might be necessary to find the least cost of a hydraulic installation to transmit a certain horse-power. Here a number of quantities are concerned, such as diameter of piping, price of power, length of pipe line, etc., any one of which might be treated as the main variable. By expressing all the conditions in terms of this one variable and proceeding according to the plan now to be demonstrated, the problem would become one easy of solution.

A graphic method for the solution of such problems has already been treated very fully (see Part I, pp. 183 *et seq.*). This method, though direct and perfectly general in its application, is somewhat laborious, and unless the graphs are drawn to a large scale in the neighbourhood of the turning points, the results obtained are usually good approximations only. In consequence of these failings

of the graphic treatment, the algebraic method is introduced, but it should be remembered that its application is not so universal as that of the solution by plotting.

The theory of the algebraic method can be simply explained in the following manner :—

The slope of a curve measures the rate of change of the ordinate with regard to the abscissa ; and hence, when the slope of the

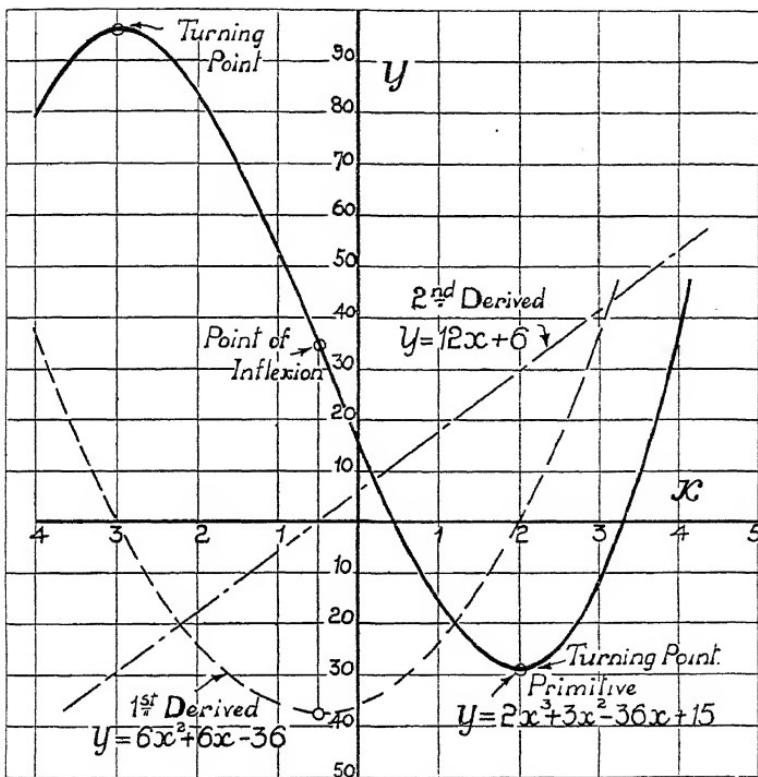


FIG. 22.—Maximum and Minimum Values.

curve is zero, the rate of change of the function is zero, and the function must have a turning value, which must be either a maximum or a minimum. But it has already been pointed out that the slope of a curve is otherwise defined as the derivative or the differential coefficient of the function ; therefore the function has a turning value whenever its derivative is zero.

Hence, to find maximum or minimum values of a function we must first determine the derivative of the function, and then find

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the value or values of the I.V. which make the derivative zero; the actual maximum or minimum values of the function being found by the substitution of the particular values of the I.V. in the expression for the function.

The rule, stated in a concise form, is : To find the value of the I.V. which makes the function a maximum or minimum, differentiate the function, equate to zero and solve the resulting equation.

The full merit of the method will be best appreciated by the discussion of a somewhat academic problem before proceeding to some of a more practical nature.

Example 1.—Find the values of x which give to the function $y = 2x^3 + 3x^2 - 36x + 15$ maximum or minimum values. Find also the value of x at the point of inflexion of the curve.

This question may be treated from two points of view, viz.—

(a) From the graphical aspect.

We first plot the primitive curve $y = 2x^3 + 3x^2 - 36x + 15$ (see Fig. 22), the table of values for which is :—

x^3	$2x^3 + 3x^2 - 36x + 15$
-4	16
-3	9
-2	4
-1	1
0	0
1	1
2	4
3	9
4	16
5	25
	125
	-128 + 48 + 144 + 15
	-54 + 27 + 108 + 15
	-16 + 12 + 72 + 15
	-2 + 3 + 36 + 15
	0 + 0 - 0 + 15
	2 + 3 - 36 + 15
	16 + 12 - 72 + 15
	54 + 27 - 108 + 15
	128 + 48 - 144 + 15
	250 + 75 - 180 + 15
	160

This curve has two turns and two turns only, and consequently y has two turning values, one being a maximum and one a minimum. By successive graphic differentiation the first and second derived curves may be drawn, these being shown on the diagram.

Now for values of x less than -3 the slope of the primitive curve is positive, as is demonstrated by the fact that the ordinates of the first derived curve are positive. At $x = -3$ the primitive curve is horizontal and the first derived curve crosses the x -axis; and since the ordinates of the first derived curve give the values of $\frac{dy}{dx}$, we see that when the primitive curve has a turning value, the value of $\frac{dy}{dx} = 0$. For values of x between -3 and $+2$ the slope of the primitive is negative; when $x = +2$ the slope is zero, and from that

point the slope is positive. Thus y has turning values when $x = -3$ and when $x = +2$; these values being a maximum at $x = -3$ and a minimum at $x = +2$ as observed from the curve.

This investigation proves of service when we proceed to treat the question from the algebraic aspect; in fact, for complete understanding the two methods must be interwoven.

(b) *From the algebraic point of view.*

$$\text{Let} \quad y = 2x^3 + 3x^2 - 36x + 15$$

$$\begin{aligned}\text{then} \quad \frac{dy}{dx} &= 6x^2 + 6x - 36 \\ &= 6(x^2 + x - 6).\end{aligned}$$

Now in order that y may have turning values we have seen that it is necessary that $\frac{dy}{dx} = 0$.

$$\begin{aligned}\text{But} \quad \frac{dy}{dx} &= 0 \text{ if } 6(x^2 + x - 6) = 0 \\ \text{i. e.,} \quad &\text{if } 6(x+3)(x-2) = 0 \\ \text{i. e.,} \quad &\text{if } x = -3 \text{ or } 2\end{aligned}$$

and hence y has turning values when $x = -3$ and $x = +2$. We do not yet, however, know the character of these turning values, so that our object must now be to devise a simple method enabling us to discriminate between values of x giving maximum and minimum values to y .

An obvious, but slow, method is as follows: Let us take a value of x slightly less than -3 , say -3.1 ; then the calculated value of y is 95.85. Next, taking a value of x rather bigger than -3 , say -2.9 , the value of y is found to be 95.85. Therefore, as x increases from -3.1 to -3 and thence to -2.9 , y has the values 95.85, 96, and 95.85 respectively. Thus the value of y must be a maximum at $x = -3$, since its values on either side are both less than its value when $x = -3$. In like manner it can be shown that when $x = +2$, y has a minimum value.

The arithmetical work necessary in this method can, however, be dispensed with by the use of a more mathematical process, now to be described.

Referring to the first derived curve, the equation of which is $y = 6x^2 + 6x - 36$, we note that as x increases from -4 to -3 the ordinate of the derived curve decreases from 36 to 0; from $x = -3$ to $x = -0.5$ the ordinate is negative but increasing numerically, *i. e.*, in the neighbourhood of $x = -3$ the slope of the second derived curve, which is the slope curve of the first derived curve, is negative (for the ordinate decreases as the abscissa or the I.V. increases). But the slope of the first derived

curve, and thus the ordinate of the second derived curve, must be expressed by $\frac{d^2y}{dx^2}$, so that we conclude that in the neighbourhood of a maximum value of the original function the second derivative of it is a negative quantity.

In the same way we see that in the neighbourhood of a minimum value of the function, its second derivative is a positive quantity. Hence a more direct method of discrimination between the turning values presents itself : Having found the values of the I.V. causing turning values of the original function, substitute these values in turn in the expression for the second derivative of the function ; if the result is a negative, then the particular value of the I.V. considered is that giving a maximum value of the function and vice-versa.

This rule may be expressed in the following brief fashion :—

Let $y = f(x)$ and let the values of x that make $\frac{df}{dx}(x) = 0$ be x_1 and x_2 .

Find the value of $\frac{d^2y}{dx^2}$ or $f''(x)$, as it may be written, and in this expression substitute in turn the values x_1 and x_2 in place of x : the values thus obtained are those of $f''(x_1)$ and $f''(x_2)$ respectively. Then if $f''(x_1)$, say, is negative, y has a maximum value when $x = x_1$; and if $f''(x_1)$ is positive, y has a minimum value when $x = x_1$.

Applying to our present example :—

$$\begin{aligned}y &= 2x^3 + 3x^2 - 36x + 15 \\f'(x) &= \frac{dy}{dx} = 6x^2 + 6x - 36 \\f''(x) &= \frac{d^2y}{dx^2} = 12x + 6.\end{aligned}$$

When $x = -3$ the value of $\frac{d^2y}{dx^2}$ is $12(-3) + 6$, i.e., $f''(-3) = -30$; and since $f''(-3)$ is a negative quantity, y is a maximum when $x = -3$.

Similarly, $f''(+2) = 12(2) + 6 = +30$

and hence y is a minimum when $x = +2$.

Referring to the second derived curve, i.e., the curve $y = 12x + 6$, we note that its ordinate is negative for all values of x less than -5 and positive for all values of x greater than -5 , the curve crossing the axis of x when $x = -5$. This indicates that when $x = -5$ the first derived curve has a turning value ; but the first

derived curve is the curve of the gradients of the primitive curve, and hence when $x = -\cdot 5$ the gradient of the primitive must have a turning value, which may be either a maximum or a minimum. In other words, if we had placed a straight edge to be tangential in all positions to the primitive curve, it would rotate in a right-handed direction until $x = -\cdot 5$ was reached, after which the rotation would be in the reverse direction. A point on the curve at which the gradient ceases to rotate in the one direction and commences to rotate in the opposite direction is called a *point of inflexion* of the curve. Thus points of inflexion or contra-flexure occur when $\frac{d^2y}{dx^2} = 0$.

A useful illustration of the necessity for determining points of contra-flexure is furnished by cases of fixed beams. We have

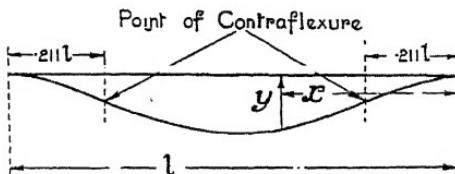


FIG. 23.

already seen that the bending moment at any section is proportional to the value of $\frac{d^2y}{dx^2}$ there; hence there must be points of contra-flexure when the bending moment is zero.

Example 2.—Find the positions of the points of contra-flexure of a beam fixed at its ends and uniformly loaded with w units per foot; the deflected form having the equation—

$$y = \frac{1}{EI} \left(\frac{wlr^3}{12} - \frac{wl^2x^2}{24} - \frac{wx^4}{24} \right).$$

We may regard this question from either the graphic aspect or the physical. According to the former we see that it is necessary to determine the points of inflexion, and therefore to find values of x for which $\frac{d^2y}{dx^2}$ is zero.

Reasoning from the physical basis we arrive at the same result, by way of the following argument: the bending moment, which is expressed by $EI \frac{d^2y}{dx^2}$, changes sign, as is indicated by the change in the curvature of the beam (see Fig. 23), and therefore at two points the bending moment must be zero, since the variation in it is uniform

and continuous; but the bending moment is zero when $\frac{d^2y}{dx^2}$ is zero, since $M = EI \cdot \frac{d^2y}{dx^2}$.

$$\text{Now } y = \frac{w}{EI} \left(\frac{lx^3}{12} - \frac{l^2x^2}{24} - \frac{x^4}{24} \right),$$

$$\text{hence } \frac{dy}{dx} = \frac{w}{EI} \left[\left(\frac{l}{12} \times 3x^2 \right) - \left(\frac{l^2}{24} \times 2x \right) - \frac{4x^3}{24} \right] \\ = \frac{w}{EI} \left(\frac{lx^2}{4} - \frac{l^2x}{12} - \frac{x^3}{6} \right)$$

$$\text{and } \frac{d^2y}{dx^2} = \frac{w}{EI} \left[\left(\frac{l}{4} \times 2x \right) - \left(\frac{l^2}{12} \times 1 \right) - \frac{3x^2}{6} \right] \\ = \frac{w}{EI} \left(\frac{lx}{2} - \frac{l^2}{12} - \frac{x^2}{2} \right)$$

$$\text{Now the bending moment } M = EI \cdot \frac{d^2y}{dx^2} = w \left(\frac{lx}{2} - \frac{l^2}{12} - \frac{x^2}{2} \right)$$

$$\text{and } M = 0 \text{ if } \frac{lx}{2} - \frac{l^2}{12} - \frac{x^2}{2} = 0, \text{ i.e. if } 6lx - l^2 - 6x^2 = 0,$$

$$\text{i.e., } 6x^2 - 6lx + l^2 = 0$$

$$\text{or } x = \frac{6l \pm \sqrt{36l^2 - 24l^2}}{12} \\ = \frac{l}{12} (6 \pm 3.46) \\ = \underline{.789l \text{ or } .211l}.$$

Hence the points of inflexion occur at points distant $.211l$ of the length from the ends.

Example 3.—A line, 5 ins. long, is to be divided into two parts such that the square of the length of one part together with four times the cube of the length of the other is a minimum. Find the position of the point of section.

Let x ins. = the length of one part, then $5-x$ = length of the other part.

Then $(5-x)^2 + 4x^3$ is to be a minimum.

$$\text{Let } y = (5-x)^2 + 4x^3 \\ = 25 + x^2 - 10x + 4x^3.$$

$$\text{Then } \frac{dy}{dx} = 2x - 10 + 12x^2 \\ = 2(6x^2 + x - 5) \\ = 2(6x - 5)(x + 1).$$

Hence $\frac{dy}{dx} = 0$ if $x = \frac{5}{6}$ or -1 (the latter root implying external cutting).

To test for the nature of the turning value—

$$\frac{dy}{dx} = 12x^2 + 2x - 10$$

and $\frac{d^2y}{dx^2} = 24x + 2.$

When $x = \frac{5}{6}$

$$\frac{d^2y}{dx^2} = \left(\frac{24 \times 5}{6}\right) + 2 = \text{a positive quantity.}$$

Therefore y is a minimum when $x = \frac{5}{6}$ and the required point of section is $\underline{\frac{5}{6}}$ in. from one end.

Example 4.—If s = detrimental surface of an aeroplane

S = area of planes

K = lifting efficiency

then f , the "fineness," is obtained from the formula $f^2 = \frac{KS}{.08s}$.

Also the thrust required for sustentation $= C \left(i + \frac{1}{f^2 i^2} \right)$, where C is a constant and i is the angle of incidence of the plane (expressed in radians).

Taking $S = 25s$ and $K = .4$, find the angle of incidence for the case in which the least thrust is required.

$$f^2 = \frac{KS}{.08s} = \frac{.4 \times 25}{.08} = 125.$$

The thrust $T = C \left(i + \frac{1}{f^2 i^2} \right)$ and since i is the only variable in this expression, we must differentiate with regard to it.

Thus $\frac{dT}{di} = C \left(1 - \frac{1}{f^2 i^2} \right)$

and $\frac{dT}{di} = 0$ if $\left(1 - \frac{1}{f^2 i^2} \right) = 0$

i. e., $\text{if } i^2 = \frac{1}{f^2} = \frac{1}{125}.$

Thus $i = .0895$

or the thrust required is either a maximum or minimum when the angle of incidence is $.0895$ radian.

To test whether this turning value is a maximum or a minimum, let us find the second derivative—

$$\frac{dT}{di} = C \left(1 - \frac{1}{f^2 i^2} \right)$$

$$\frac{d^2T}{di^2} = C \left(0 + \frac{2}{f^2 i^3} \right).$$

When $i = .0895$, $\frac{d^2T}{di^2}$ must be positive, and hence T has its minimum value when $i = \underline{.0895}$.

Example 5.—Find the dimensions of the greatest cylinder that can be inscribed in a right circular cone of height 6 ins. and base 10 ins. diameter.

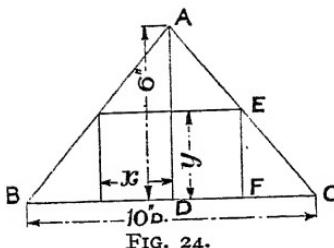


FIG. 24.

Assume that the radius of the base of the cylinder = x ins. (Fig. 24)
and the height of the cylinder = y ins.

Then the volume = $V = \pi x^2 y$.

We must, then, obtain an expression for y in terms of x before differentiating with regard to x .

From the figure, by similar triangles, taking the triangles ADC and EFC—

$$\frac{6}{5} = \frac{y}{5-x}$$

$$\text{or } y = \frac{6}{5}(5-x)$$

$$\text{Hence } V = \pi x^2 \times \frac{6}{5}(5-x) = \frac{6\pi}{5}(5x^2 - x^3)$$

$$\text{and } \frac{dV}{dx} = \frac{6\pi}{5}(10x - 3x^2)$$

$$\text{Thus } \frac{dV}{dx} = 0 \text{ if } x(10 - 3x) = 0$$

i. e., if $x = 0$ (giving the cylinder of zero volume)

or if $10 = 3x$, i. e., $x = \underline{\underline{3\frac{1}{3}}}$ ins.

$$\text{Then } y = \frac{6}{5}(5 - 3\frac{1}{3}) : 2 \text{ ins.}$$

$$\text{and the volume of the greatest cylinder} = \pi \times \left(\frac{10}{3}\right)^2 \times 2 = \underline{\underline{69.8}}$$
 cu. ins.

Example 6.—The total running cost in pounds sterling per hour of a certain ship being given by—

$$C = 4.5 + \frac{v^3}{2100}$$

where v = speed in knots, find for what speed the total cost for a journey is a minimum.

The total cost for the journey depends on—

- (a) The cost per hour; and
- (b) The number of hours taken over the journey.

Item (b) depends inversely on the speed, so that if the journey were 2000 nautical miles the time taken would be $\frac{2000}{v}$ hours; or, in general, the number of hours = $\frac{K}{v}$.

Then the total cost for a journey of K nautical miles

$$\begin{aligned} C_t &= \frac{K}{v} \times \left(4.5 + \frac{v^3}{2100} \right) \\ &= K \left(4.5v^{-1} + \frac{v^3}{2100} \right) \end{aligned}$$

Differentiating with regard to the variable v

$$\begin{aligned} \frac{dC_t}{dv} &= K \left[(4.5 \times -1 \times v^{-2}) + \frac{2v}{2100} \right] \\ &= K \left(-\frac{4.5}{v^2} + \frac{2v}{2100} \right) \end{aligned}$$

Then $\frac{dC_t}{dv} = 0$ if $-\frac{4.5}{v^2} + \frac{2v}{2100} = 0$

i.e., if $\frac{2v}{2100} = \frac{4.5}{v^2}$

or $v^3 = 4.5 \times 2100 = 4725$

hence $v = 16.78$ knots.

Example 7.—A water main is supplied by water under a head of 60 ft. The loss of head due to pipe friction, for a given length, is proportional to the velocity squared. Find the head lost in friction when the horse-power transmitted by the main is a maximum.

If v = velocity of flow, then—

Head lost = Kv^2 , where K is some constant,
i.e., the effective head = $60 - Kv^2 = H_e$.

$$\begin{aligned} \text{H.P. transmitted} &= \frac{\text{Quantity (in lbs. per min.)} \times \text{effective head (in feet)}}{33000} \\ &= \frac{\text{area (in sq. ft.)} \times \text{velocity (ft. per min.)} \times 62.4 \times H_e}{33000} \\ &= CvH_e, \text{ where } C \text{ is some constant} \\ &= Cv(60 - Kv^2) \\ &= C(60v - Kv^3) \end{aligned}$$

Then $\frac{d}{dv} (\text{H.P.}) = C(60 - 3Kv^2)$

= $C(60 - 180 + 3H_e)$

or $\frac{d}{dv} (\text{H.P.}) = 0$ when $3H_e = 120$

i.e., $H_e = 40$.

In general, then, the maximum horse-power is transmitted when the head lost is one-third of the head supplied, i.e., the maximum efficiency is $\frac{2}{3}$ or 66.7%.

Example 8.—The stiffness of a beam is proportional to the breadth and the cube of the depth of the section. Find the dimensions of the stiffest beam that can be cut from a cylindrical log 4 ins. in diameter.

From hypothesis

$$S \propto bd^3$$

$$S = Kbd^3.$$

Both breadth and depth will vary, but they depend on each other; and from Fig. 25 we see that $b^2 = 16 - d^2$. Hence we can substitute for b its value in terms of d and then differentiate with regard to d ; accordingly—

$$S = Kd^3 \sqrt{16 - d^2}.$$

As it stands this would be a rather cumbersome expression to differentiate, and we therefore employ a method which is often of great assistance. Since we are dealing with positive quantities throughout, S^2 will be a maximum when S is a maximum,* and hence we square both sides before differentiating.

FIG. 25.

$$\text{Thus } S^2 = K^2 d^6 (16 - d^2) = K^2 (16d^6 - d^8)$$

$$\text{and } \frac{dS^2}{d.d} = K^2 (96d^5 - 8d^7) = 8d^5(12 - d^2)$$

$$\text{Hence } \frac{dS^2}{d.d} = 0 \text{ if } d^5 = 0, \text{ i.e., } d = 0 \text{ (giving zero stiffness)}$$

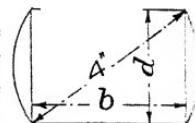
$$\text{or if } d^2 = 12$$

$$\text{i.e., } d = \underline{3.464} \text{ ins.}$$

$$\text{Hence } b = \sqrt{16 - 12} = 2 \text{ ins.}$$

* If we were dealing with negative quantities it would be incorrect to say that the quantity itself had a maximum value when its square was a maximum, for suppose the values of the quantity y in the neighbourhood of its maximum value were $-13, -12, -11, -10, -11, -12$, etc., corresponding values of y^2 would be $+169, +144, +121, +100, +121, +144$, so that if $y = -10$ (its maximum value) when $x = 4$, say, then $y^2 = 100$ when $x = 4$, and therefore a minimum value of y^2 occurs when $x = 4$, and not a maximum.

Example 9.—Find the shape of the rectangular channel of given sectional area A which will permit the greatest flow of water; being given that $Q = Av$, $v = c\sqrt{mi}$, m = hydraulic mean depth = $\frac{\text{area}}{\text{wetted perimeter}}$ and i is the hydraulic gradient; Q being the quantity flowing.



Let the breadth of the section be b and the depth d ; then, by hypothesis—

$$bd = A, \text{ whence } b = \frac{A}{d}.$$

$$m = \frac{\text{area}}{\text{wetted perimeter}} = \frac{A}{b+2d} \text{ and therefore } v = c\sqrt{i}\sqrt{\frac{A}{b+2d}} \\ = c\sqrt{Ai} \cdot \frac{1}{\sqrt{b+2d}}$$

Hence—

$$Q = Av = Ac\sqrt{Ai} \cdot \frac{1}{\sqrt{b+2d}}$$

$$= K \cdot \frac{1}{\sqrt{b+2d}} \text{ where } K = Ac\sqrt{Ai}$$

Q will be a maximum when Q^2 is a maximum, hence we shall find the value of b for which Q^2 is a maximum.

$$Q^2 = K^2 \frac{1}{b+2d} = K^2 \cdot \frac{1}{b + \frac{2A}{b}}$$

Also Q^2 is a maximum when the denominator of this fraction is a minimum.

Let this denominator be denoted by D —

$$\text{then } \frac{dD}{db} = \frac{d}{db} \left(b + \frac{2A}{b} \right) = 1 - \frac{2A}{b^2}$$

$$\text{and } \frac{dD}{db} = 0 \text{ if } 1 = \frac{2A}{b^2}, \text{ i.e., if } b = \sqrt{2A}.$$

$$\text{Now } d = \frac{A}{b} = \frac{A}{\sqrt{2A}} = \sqrt{\frac{A}{2}}.$$

∴ the dimensions would be—

$$\text{depth} = \sqrt{\frac{A}{2}} \text{ and breadth} = \sqrt{2A}.$$

Example 10.—For a certain steam engine the expression for W , the brake energy per cu. ft. of steam, was found in terms of r , the ratio of expansion, as follows—

$$W = \frac{\frac{120}{r}(1+\log r)-27}{\frac{.00833}{r}+.000903}$$

Find the value of r that makes W a maximum.

Before proceeding to differentiate, we can put the expression in a somewhat simpler form.

Thus—

$$W = \frac{120(1+\log r)-27r}{.00833+.000903r}$$

and W is a quotient $= \frac{u}{v}$ where $u = 120(1+\log r)$

so that

$$\frac{du}{dr} = \frac{120}{r} - 27$$

and

$$v = .00833 + .000903r$$

so that

$$\frac{dv}{dr} = .000903.$$

Hence $\frac{dW}{dr} = v \frac{du}{dr} - u \frac{dv}{dr}$

$$\frac{.00833 + .000903r}{\left(\frac{120}{r} - 27 \right) - [120(1 + \log r) - 27r] \cdot 0.000903}{\left(.00833 + .000903r \right)^2}$$

Now $\frac{dW}{dr} = 0$ if the numerator of the right-hand side = 0

$$\text{i.e., if } \left(\frac{.00833 \times 120}{r} \right) - (27 \times .00833) + (120 \times .000903) - (27 \times .000903r) - (120 \times .000903) - (120 \times .000903 \log r) + (27 \times .000903r) = 0$$

$$\text{i.e., if } \frac{I}{r} - .225 - .1084 \log r = 0.$$

This equation must be solved by plotting, the intersection of the curves $y_1 = .1084 \log r$ and $y_2 = \frac{I}{r} - .225$ being found; the value of r here being 2.93.

Hence—

$$r = \underline{2.93}.$$

Example 11.—The value of a secondary electric current was given by the formula—

$$y = \frac{I}{2} \left(e^{-\frac{Rt}{L+M}} - e^{-\frac{Rt}{L-M}} \right)$$

where L = inductance of primary circuit

R = resistance of primary circuit

M = coefficient of mutual inductance

I = steady current.

Find for what value of t , y has a maximum value.

$$y = \frac{I}{2} \left(e^{-\frac{Rt}{L+M}} - e^{-\frac{Rt}{L-M}} \right)$$

$$\text{Then } \frac{dy}{dt} = \frac{I}{2} \left(-\frac{R}{L+M} e^{-\frac{Rt}{L+M}} + \frac{R}{L-M} e^{-\frac{Rt}{L-M}} \right)$$

$$\text{and } \frac{dy}{dt} = 0 \text{ if } \frac{R}{L-M} e^{-\frac{Rt}{L-M}} = \frac{R}{L+M} e^{-\frac{Rt}{L+M}}$$

Transposing the factors—

$$e^{-\frac{Rt}{L-M}} + \frac{Rt}{L+M} = \frac{L-M}{L+M}$$

$$e^{\frac{Rt(L-M-L-M)}{L^2-M^2}} = \frac{L-M}{L+M}$$

$$e^{-\frac{2MRt}{L^2-M^2}} = \frac{L-M}{L+M}$$

$$e^{\frac{2MRt}{L^2-M^2}} = \frac{L+M}{L-M}$$

or

In order to find an expression for t , this equation must be changed to a log form, thus—

$$\log \left(\frac{L+M}{L-M} \right) = \frac{2MRt}{L^2 - M^2}$$

or
$$t = \frac{L^2 - M^2}{2MR} \log \left(\frac{L+M}{L-M} \right).$$

If three variables are concerned, say x , y and z , the relation between them being expressed by the equation $z = f(x, y)$, then in order to find the values of x and y for turning values of z , it is necessary to determine where the plane tangential to the surface is horizontal.

The algebraic problem is to find the values of x and y that satisfy simultaneously the equations $\left(\frac{dx}{dz} \right) = 0$ and $\left(\frac{dy}{dz} \right) = 0$, these derivatives being partial.

Example 12.—The electric time constant of a cylindrical coil of wire (*i. e.*, the time in which the current through the coil falls from its full value to a value equal to $\cdot 632$ of this) can be expressed approximately by $K = \frac{mxyz}{ax+by+cz}$ where z is the axial length of the coil, y is the difference between the external and internal radii and x is the mean radius; a , b and c representing constants. If the volume of the coil is fixed, find the values of x and y which make the time constant as great as possible.

The volume V of the coil = cross section \times length

$$\text{i. e., } V = 2\pi x \times y \times z \text{ and } z = \frac{V}{2\pi xy}$$

$$K = m \left\{ \frac{xyz}{ax+by+cz} \right\} \text{ and is a maximum}$$

when $\frac{ax+by+cz}{xyz}$ or $\frac{a}{yz} + \frac{b}{xz} + \frac{c}{xy}$ is a minimum.

Let

$$\begin{aligned} p &= \frac{a}{yz} + \frac{b}{xz} + \frac{c}{xy} \\ &= \frac{a \times 2\pi xy}{yV} + \frac{b \times 2\pi xy}{xV} + \frac{c}{xy} \\ &= \frac{2\pi xy a}{yV} + \frac{2\pi xy b}{xV} + \frac{c}{xy}. \end{aligned}$$

$$\text{Now } \left(\frac{dp}{dx} \right) (\text{i. e., with } y \text{ constant}) = \frac{\frac{2\pi a}{V} + \left(\frac{c}{y} \times -\frac{1}{x^2} \right)}{\frac{2\pi a}{V} - \frac{c}{x^2 y}}$$

Similarly $\left(\frac{dp}{dy}\right)_x = \frac{2\pi b}{V} - \frac{c}{xy^2}$

Both $\left(\frac{dp}{dx}\right)$ and $\left(\frac{dp}{dy}\right)$ must be equated to zero,

so that $\frac{2\pi a}{V} = \frac{c}{x^2 y}$

i.e., $x^2 y = \frac{cV}{2\pi a}$

and $\frac{2\pi b}{V} = \frac{c}{xy^2}$

i.e., $xy^2 = \frac{cV}{2\pi b}$

(2)

To solve for x and y .

From (2)— $\frac{cV}{2\pi b y^2}$

Substituting in (1)—

$$\frac{c^2 V^2 y}{4\pi^2 b^2 y^4} = \frac{cV}{2\pi a}$$

whence $y^3 = \frac{cVa}{2\pi b^2}$

or $y = \sqrt[3]{\frac{cVa}{2\pi b^2}}$

also $x = \sqrt[3]{\frac{cbV}{2\pi a^2}}$

Exercises 10.—On Maximum and Minimum Values.

- If $M = 15x - 0.1x^2$, find the value of x that makes M a maximum.
- Find the value of x that makes M a maximum if $M = 3.42x - 1x^2$.
M is a bending moment and x is a length; find x in terms of l . M shall be a maximum, and find also the maximum value of M.

$$M = \frac{wx}{2} (l-x).$$

- As for No. 3, but taking—

$$M = \frac{Wx}{3} \left(1 - \frac{x^2}{l^2} \right)$$

- The work done by a series motor in time t is given by—

$$W = \frac{et(E-e)}{R}$$

where

e = back E.M.F.

E = supply pressure

R = resistance of armature.

The electrical efficiency is $\frac{e}{E}$. Find the efficiency when the motor so runs that the greatest rate of doing useful work is reached.

In Nos. 6 to 8 find values of x which give turning values to y , stating the nature of these turning values.

6. $y = 4x^2 + 18x - 41.$ 7. $y = 5x - 9x^2 + 18.$
8. $y = x^3 + 6x^2 - 15x + 51$ (find also the value of x at the point of inflexion).
9. Sixteen electric cells, each of internal resistance 1 ohm and giving each 1 volt, are connected up in mixed circuit through a resistance of 4 ohms. Find the arrangement for the greatest current [say $\frac{16}{x}$ rows with x cells in each row].
10. If 40 sq. ft. of sheet metal are to be used in the construction of an open tank with square base, find the dimensions so that the capacity of the tank is a maximum.
11. Given that $W = 4C^2 + \frac{74}{C}$, find a value of C that gives a turning value of W , and state the nature of this turning value.
12. M (a bending moment) = $W \frac{(l-x)}{l} (x+y) - Wy$. For what value of x is M a maximum? { W, l and y are constants.}
13. The cost C (in pounds sterling per mile) of an electric cable can be expressed by—
- $$C = \frac{157}{x} + 636x$$
- where x is the cross section in sq. ins.
- Find the cross section for which the cost is the minimum, and find also the minimum cost.
14. A window has the form of a rectangle together with a semi-circle on one of its sides as diameter, and the perimeter is 30 ft. Find the dimensions so that the greatest amount of light may be admitted.
15. C , the cost per hour of a ship, in pounds, is given by—
- $$C = 3.2 + \frac{s^3}{2200}$$
- where s = speed in knots.
- Find the value of s which makes the cost of a journey of 3000 nautical miles a minimum.
- At speed 10% greater and less than this compare the total cost with its minimum value.
16. An isolated load W rolls over a suspension bridge stiffened with pin-jointed girders. When the load is at A , distant x from the centre, the bending moment at this section = $M_A = \frac{Wx}{2l^2} (l^2 - 4x^2)$. For what value of x is M_A a maximum?
17. A riveted steel tank of circular section open at the top has to be constructed to contain 5000 gals. of water. Find the dimensions so that the least possible amount of steel plate is required.
18. A canister having a square base is cut out of 128 sq. ins. of tin, the depth of the lid being 1 in. Find the dimensions in order that the contents of the canister may be as large as possible.
19. The stiffness of a beam of rectangular section is proportional to the breadth and the cube of the depth. Find the ratio of the sides of the stiffest beam of rectangular section with a given perimeter.

20. A load uniformly distributed over a length r rolls across a beam of length l , and the bending moment M due to this loading at a point is given by—

$$M = \frac{wry}{l} \left\{ l - y + x - \frac{r}{2} \right\} - \frac{wx^2}{2}$$

For what value of x is M a maximum?

21. Find the value of V (a velocity) that makes R (a resistance) a maximum when—

$$R = \frac{V^2}{54} - \frac{3(V - 12)}{V + 12}.$$

22. If $L = \sqrt{r^2 - x^2} - \frac{1}{r}(r^2 - x^2)$, find the value of x that makes L a maximum.

23. A jet of water, moving with velocity v , impinges on a plate moving in the direction of the jet with velocity u . The efficiency $\eta = \frac{2u(v-u)^2}{v^3}$. Find values of u for maximum and minimum efficiency, and find also the maximum efficiency.

24. If $\eta = \frac{2u(v-u)}{v^2}$, find the value of u for maximum value of η .

25. Given that $Q = K\mu T_1 (\cos \theta - \sin \theta)$, find values of θ between 0° and 360° that make Q a maximum, treating K , μ and T_1 as constants.

26. A cylinder of a petrol engine is of diameter d and length l . Find the value of the ratio $\frac{d}{l}$ which makes $\frac{\text{area of exposed surface}}{\text{capacity}}$ a minimum. The volume must be treated as a constant.

27. If the exposed surface of a petrol engine cylinder is given by—

$$S = 2\pi r^2 + 2\pi rl + 2r^2, \quad l \text{ being the length and } r \text{ the radius,}$$

find the value of the ratio $\frac{l}{r}$ that makes the ratio $\frac{\text{exposed surface}}{\text{capacity}}$ a minimum. The volume must be treated as a constant.

28. Given that $y = \frac{K^2 - 5.2K + 60.2}{K^2 + 9}$, find values of K for turning values of y .

29. If $M = \frac{wR^2}{2} \left(\frac{1}{4} - \sin^2 \theta \right) - .934wR^2 \left(\cos \theta - \sqrt{\frac{3}{2}} \right)$, for what values

of θ is M a maximum? [M is the bending moment at a section of a circular arched rib loaded with a uniform load w per foot of span, and R is the radius of the arch.]

30. An open channel with side slopes at 45° is to have a cross section of 120 sq. ft. Determine the dimensions for the best section (*i.e.*, the section having the smallest perimeter for a given area).

31. If $M = \frac{w(2xl - 3x^2)^2}{8(l^2 - 2x^2)}$, find the value of x which makes M , a bending moment, a maximum. The final equation should be solved by plotting, a value being assumed for l .

32. In connection with retaining walls the following equation occurs—

$$P = \frac{\rho h^2}{72} \cdot \frac{1 - \mu \tan \theta}{1 - \mu^2 + 2\mu \cot \theta}.$$

Find an expression, giving the value of θ (in terms of $\tan \theta$), that makes P a maximum. (μ , ρ and h are constants.)

33. Assuming that the H.P. of an engine can be expressed by the relation—

$$H = C(fnl^3 - K\rho n^3 l^5)$$

where C is a constant, l = stroke, ρ = pressure in piston rod due to the pressure on the piston, ρ = average density of the material of the engine, K = constant depending upon the mode of distribution of the mass of the engine parts, n = R.P.M., and f = safe stress in the material, find an expression for l giving the maximum H.P. for engines of different sizes.

34. Find the turning point of the probability curve—

$$y = \frac{1}{h\sqrt{\pi}} e^{-\frac{x^2}{h^2}}$$

and also the points of inflexion.

35. In a two-stage compressor, neglecting clearances, if P_1 and V_1 are the initial pressure and volume of the L.P. cylinder, P_2 the pressure in the intercooler, and P_3 the discharge pressure of the H.P. cylinder, the total work for the two cylinders is given by—

$$W = \frac{n}{n-1} P_1 V_1 \left[\left(\frac{P_2}{P_1} \right)^{\frac{n-1}{n}} + \left(\frac{P_3}{P_2} \right)^{\frac{n-1}{n}} - 2 \right].$$

For what value of P_2 is W a minimum, P_1 , V_2 , P_3 and n being regarded as constants?

36. Find the height h of a Warren girder to give the maximum stiffness, the stiffness being given by the expression—

$$\frac{f_c + f_t}{2Eh} \left(l^2 + \frac{l^2}{4} + \frac{lh^2}{d} \right)$$

d being the length of one bay and l the span, whilst f_c , f_t and E are constants for the material.

37. The efficiency of a reaction wheel may be expressed by—

$$\eta = \frac{2(n-1)}{(1+K)n^2 - 1}$$

For what value of n has η its maximum value?

38. The weight W of steam passing through an orifice, from pressure P_1 to pressure P_2 , is given by—

$$W = A_2 \sqrt{2g} \frac{P_1}{v_1} \cdot \frac{n}{n-1} \left\{ \left(\frac{P_2}{P_1} \right)^{\frac{2}{n}} - \left(\frac{P_2}{P_1} \right)^{\frac{n+1}{n}} \right\}$$

If $n = 1.135$, find the value of $\frac{P_2}{P_1}$ for which W is a maximum.

39. Find the height of the greatest cylinder that can be inscribed in the frustum of a paraboloid of revolution cut off by a plane perpendicular to the axis and distant 6 units from the origin. The paraboloid is generated by the revolution about the axis of x of the parabola $y^2 = 5x$.

40. If $M = W \left\{ x - \frac{(x+y)}{l} \right\}$, where y and l are constants, find the value of x that makes M a maximum.

41. If T , t and T_f are the tight, slack and centrifugal tensions respectively in a belt passing round a pulley, and v = speed of the belt in feet per sec., then—

$$\text{H.P. transmitted} = \frac{v(T-t)}{550}.$$

Being given that $T_f = \frac{wv^2}{g}$, the maximum permissible tension in the belt = $T_m = T + T_f$, μ = coefficient of friction between belt and pulley, θ = angle of lap of belt in radians, and $\frac{T}{t} = e^{\mu\theta}$, find the value of T_f in terms of T_m so that the maximum H.P. is transmitted.

42. If $y = 3x^4 + 2x^3 - 78x^2 - 240x + 54$, find the values of x which give turning values to y , stating the nature of these turning values; and find also the values of x at the points of inflexion.

43. The radial stress in a rotating disc

$$= \rho_x \\ = \frac{w\omega^2}{8gn} (3m+1) \left(R_1^2 + R_2^2 - \frac{R_1^2 R_2^2}{x^2} - x^2 \right)$$

in which expression x is the only variable.

Find the value of x which gives to ρ_x its maximum value, and state this value of ρ_x .

44. A pipe of length l and diameter D has at one end a nozzle of diameter d through which water is discharged from a reservoir, the level of the water in which is maintained at a constant head h above the centre of the nozzle. Find the diameter of the nozzle so that the kinetic energy of the jet may be a maximum; the kinetic energy being expressed by—

$$\frac{\pi}{4} d^2 \left(\frac{2gD^5 h}{D^5 + 4fd^4} \right)^{\frac{3}{2}}$$

[Hint.—If K = kinetic energy, write—

$$K = \frac{\rho\pi}{4} \left(\frac{2gD^5 h d^{\frac{5}{2}}}{D^5 + 4fd^4} \right)^{\frac{3}{2}}$$

and find the value of d for the maximum value of $K^{\frac{3}{2}}$.]

45. Prove that the cuboid of greatest volume which can be inscribed in a sphere of radius a is a cube of side $577a$.

46. The velocity of the piston of a reciprocating engine can be expressed by—

$$2\pi nr \left(\frac{\sin 2\theta}{2m} + \sin \theta \right)$$

where θ is the inclination of the crank to the line of stroke.

If $m = \frac{\text{connecting-rod length}}{\text{length of crank}} = 8$, find the values of θ between 0° and 360° that make the velocity a maximum.

Calculation of Small Corrections.—Differentiation finds another application in the calculation of small corrections.

Thus an experiment might be carried out, certain readings being taken, and results deduced from these readings; then if there is a possibility of some slight error in the readings and it is required to find the consequent error in the calculated result, we may proceed to find that error in the manner now to be explained.

Suppose we have two quantities A and B connected with one another by a formula $A = KB$; then if the value of B is slightly inaccurate the error in A will depend on this error in B, and also on the rate at which A changes with regard to B. E.g., if A changes three times as fast as B and the error in B is $\cdot 1\%$, then the consequent error in A must be $3 \times \cdot 1$ or $\cdot 3\%$.

We might also look upon this question from a different point of view. Suppose that a reading, instead of being x , as it should have been, was slightly larger, say $x + \delta x$, i.e., the measured value of x would be represented by OB and not OA (Fig. 26), then the error is δx or $\frac{\delta x}{x} \times 100\%$. This error causes an error in the value of y , so that the calculated value of y is BQ and not AP, i.e., the error is δy .

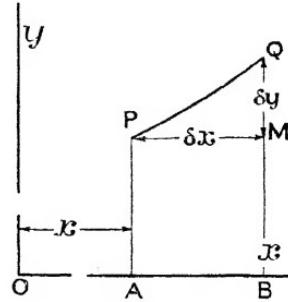


FIG. 26.

To compare these errors we proceed as follows : $\frac{\delta y}{\delta x} = \text{the slope}$ of the chord PQ, and if δx is very small (as it should be, for otherwise the experiment would be repeated), then this would also be the slope of the tangent at both P and Q, or, approximately—

$$\frac{\delta y}{\delta x} = \frac{dy}{dx}$$

$$\text{i.e., } \delta y = \frac{dy}{dx} \times \delta x$$

or, error in y = rate at which y changes with regard to x \times error in x .

Example 13.—In the measurement of the diameter of a shaft, of which the actual diameter was 4 ins., an error of 2% was made; what was the consequent error in the weight?

Here—

$$W = \frac{\pi}{4} d^2 l \rho, \text{ where } \rho \text{ is the density}$$

$$= Kd^2, \quad \text{where } K = \frac{\pi}{4} l \rho.$$

Now the error in the diameter $= \delta d = \frac{2}{100} \times 4 = .08 \text{ in.}$

also

$$\frac{d.W}{d.d} = \frac{d.Kd^2}{d.d} = 2Kd$$

$$\delta W = 2Kd \times .08$$

$$\text{or the percentage error} = \frac{\delta W}{W} \times 100 = \frac{2Kd \times .08}{Kd^2} \times 100$$

$$= \frac{.16}{d} \times 100$$

$$= \underline{\frac{.16}{4}} = 4\%.$$

Example 14.—If some torsion experiments are being made on shafts varying in diameter from 1 in. to 5 ins.; then, allowing a maximum error of 5% in the measurement of the diameters, what is the range of the errors in the stress? Given that $T = \frac{\pi}{16} f d^3$.

$$\text{The stress } f = \frac{16T}{\pi} \times \frac{1}{d^3}$$

$$\text{hence } \frac{df}{d.d} = \frac{16T}{\pi} \times \left(-\frac{3}{d^4} \right) = -\frac{48T}{\pi d^4}.$$

Now the error in the diameter $= \delta d$ is 5%.

$$\text{i.e., } \delta d = \frac{.5}{100} \times d.$$

$$\text{Hence the error in } f = \frac{df}{d.d} \times \delta d = -\frac{48T}{\pi d^4} \times \frac{.5d}{100}$$

i.e., the percentage error in f —

$$= 100 \times \frac{\delta f}{f} = 100 \times -\frac{48T}{\pi d^4} \times \frac{.5d}{100} \times \frac{\pi d^3}{16T}$$

$$= -3.$$

Thus the smallest error = $.03 \times \text{smallest stress}$ }.
 and the largest error = $.03 \times \text{largest stress}$ }.

If the error in the measurement of the diameter is on the high side, then the stress, as calculated, will be too low.

Expansion of Functions in Series. Theorems of Taylor and Maclaurin.—Many of the simpler functions, such as $\log_e(1+x)$, $\sin x$, $\cos x$, etc., can be expressed as the sums of series. These functions can be expressed in terms of these series by the use of a theorem known as Maclaurin's.

Let $f(x)$ stand for the function of x considered, and let $f(x) = a+bx+cx^2+dx^3+\dots$, to be true for all values of x ,

$$\begin{aligned} \text{i.e., } f(0) &= a+(b\times 0)+(c\times 0^2)+(d\times 0^3)+\dots \\ &= a. \end{aligned}$$

We assume that the differentiation of the right-hand side term by term gives the derivative of $f(x)$.

Differentiate both sides with regard to x .

Then— $\frac{df(x)}{dx}$ or $f'(x) = b+2cx+3dx^2+\dots$

This must be true for all values of x ; thus, let $x=0$

then— $f'(x)$ when $x=0$ or $f'(0)=b$

$f'(0)$ implying that $f'(x)$ or $\frac{df(x)}{dx}$ is first found and then the value 0 substituted for x throughout.

Differentiating again, $\frac{d^2f(x)}{dx^2}$ or $f''(x) = 2c+6dx+\dots$

and

$$f''(0) = 2c$$

i.e.,

$$c = \frac{f''(0)}{2}.$$

Similarly, $f'''(x) = 6d+\text{terms containing } x \text{ and higher powers of } x,$

whence

$$f'''(0) = 6d \quad \text{or} \quad 1.2.3.d.$$

∴

$$d = \frac{f'''(0)}{1.2.3} \quad \text{or} \quad \underline{\underline{|3|}}$$

Accordingly we may write the expansions—

$$f(x) = f(0)+f'(0)x+\frac{f''(0)x^2}{\underline{\underline{|2|}}}+\frac{f'''(0)x^3}{\underline{\underline{|3|}}}+\dots$$

This is *Maclaurin's Theorem*. By a similar investigation we might obtain Taylor's Theorem, which may be regarded as a more general expression of the foregoing.

Taylor's Theorem. In this the expansion is of $f(x+h)$ and not $f(x)$; thus—

$$f(x+h) = f(h)+xf'(h)+\frac{x^2}{\underline{\underline{|2|}}}f''(h)+\frac{x^3}{\underline{\underline{|3|}}}f'''(h)+\dots$$

or, as it is sometimes written, to give an expansion for $f(x)$ —

$$f(x) = f(h)+(x-h)f'(h)+\frac{(x-h)^2}{\underline{\underline{|2|}}}f''(h)+\frac{(x-h)^3}{\underline{\underline{|3|}}}f'''(h)+\dots$$

If in either of these two expansions we make $h = 0$, then Maclaurin's series results.

We may now utilise these theorems to obtain series of great importance.

Example 15.—To find a series for $\cos x$.

$$\begin{array}{ll} \text{Let} & f(x) = \cos x \\ \text{then} & f(0) = \cos 0 = 1. \end{array}$$

$$\text{Also } f'(x), \text{ i.e., } \frac{d \cos x}{dx} = -\sin x \\ \text{so that } f'(0) = -\sin 0 = 0.$$

$$\text{Again } f''(x) = \frac{d}{dx}(-\sin x) = -\cos x$$

so that $f'''(0) = -\cos 0 = -1$

$$\text{and } f'''(x) = \frac{d}{dx} (-\cos x) = \sin x$$

so that $f'''(0) = \sin 0 = 0$.

$$\text{Now } f(x) = f(0) + f'(0)x + \frac{f''(0)x^2}{2} + \dots$$

$$\text{Therefore } \cos x = 1 - \frac{x^2}{12} + \frac{x^4}{144}$$

Example 16.—To find a series for $\log_e(1+x)$.

$$\text{Let } f(x) = \log_e(1+x) \text{ then } f'(x) = \frac{1}{1+x}$$

then $f(0) = \log 1 = 0$.

$$\text{Now } f'(x) = \frac{d \log(x)}{dx} = \frac{1}{x}$$

$$\text{so that } f'(0) = \frac{I}{I} = 1$$

$$f''(x) = \frac{d}{dx} \left(\frac{1}{1+x} \right) = -\frac{1}{(1+x)^2}$$

$$\text{so that } f''(0) = \frac{-1}{1} = -1$$

$$\text{and } f'''(x) = \frac{d}{dx} \left(\frac{-1}{(1+x)^2} \right) = \frac{2}{(1+x)^3}$$

so that $f'''(0) = \frac{2}{1} = 2$.

$$\text{Hence } (1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \dots$$

(Compare with the series found by an entirely different method in Part I, p. 470.)

Example 17.—Prove that $e^{jx} = \cos x + j \sin x$, where $j = \sqrt{-1}$. This equation is of great importance, since it links up the exponential and the trigonometric functions.

To find a series for $\sin x$.

$$\begin{array}{lll} \text{Let } & f(x) = \sin x & \text{then } \\ & f'(x) = \cos x & f'(0) = \cos 0 = 1 \\ & f''(x) = -\sin x & f''(0) = -\sin 0 = 0 \\ & f'''(x) = -\cos x & f'''(0) = -\cos 0 = -1. \end{array}$$

$$\text{Hence } \sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots$$

$$\text{and } j \sin x = j \left(x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots \right)$$

To find a series for e^{jx} .

$$\begin{array}{lll} \text{Let } & f(x) = e^{jx} & f(0) = e^0 = 1 \\ & f'(x) = je^{jx} & f'(0) = je^0 = j = \sqrt{-1} \\ & f''(x) = j^2e^{jx} & f''(0) = j^2e^0 = j^2 = -1 \\ & f'''(x) = j^3e^{jx} & f'''(0) = j^3e^0 = j^3 = -\sqrt{-1}. \end{array}$$

$$\text{Hence } e^{jx} = 1 + jx + \frac{j^2x^2}{2!} + \frac{j^3x^3}{3!} \dots$$

Now $\cos x + j \sin x$ (the series for $\cos x$ having been found
Example 15).

$$\begin{aligned} &= (1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots + j \left(x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots \right)) \\ &= 1 + jx - \frac{x^2}{2!} + \frac{jx^3}{3!} + \frac{x^4}{4!} - \dots \\ &= 1 + jx + \frac{j^2x^2}{2!} + \frac{j^3x^3}{3!} + \frac{j^4x^4}{4!} + \dots \quad \left. \begin{array}{l} \text{For } j^2 = -1 \\ j^3 = -\sqrt{-1} \\ j^4 = +1, \text{ etc.} \end{array} \right\} \\ &= e^{jx}. \end{aligned}$$

Use might be made of Taylor's Theorem to determine a more correct solution to an equation when an approximate solution is known; for, taking the first two terms of the expansion only—

$$f(x+h) \doteq f(h) + xf'(h)$$

or interchanging x and h , as a matter of convenience, then—

$$f(h+x) = f(x) + hf'(x).$$

If h is small compared with x , the assumption that two terms of the series may be taken to represent the expansion is very nearly true.

Suppose that a rough approximation for the root has been found (by trial and error); denote this by x . Let the true solution be $x+h$; then by substitution in the above equation the value of h can be found, and thence that of $x+h$.

As an illustration, consider the following case: A rough test gives 2·4 as a solution of the equation $x^4 - 1\cdot5x^3 + 3\cdot7x = 21\cdot554$.

It is required to find a solution more correct.

Here $x = 2\cdot4$ and $f(x) = x^4 - 1\cdot5x^3 + 3\cdot7x - 21\cdot554$

$$\text{so that } f(2\cdot4) = 33\cdot17 - 20\cdot73 + 8\cdot88 - 21\cdot554 = -234.$$

If the correct value of h is found, then $f(x+h)$ must = 0.

$$\text{Hence— } f(x+h) = f(x) + hf'(x)$$

$$\text{i.e., } 0 = -234 + hf'(2\cdot4).$$

$$\text{[Now— } f(x) = x^4 - 1\cdot5x^3 + 3\cdot7x - 21\cdot554$$

$$\therefore f'(x) = 4x^3 - 4\cdot5x^2 + 3\cdot7$$

$$\text{so that } f'(2\cdot4) = 55\cdot30 - 25\cdot92 + 3\cdot7 = 33\cdot08.]$$

$$\text{Hence } 0 = -234 + (h \times 33\cdot08)$$

$$\text{or } h = \frac{-234}{33\cdot08} = .0071.$$

Hence a more correct approximation is $2\cdot4 + .0071$

i.e., $x = 2\cdot407$ is the solution of the equation.

This method may thus be usefully employed in lieu of the graphic method when extremely accurate results are desired.

The following example illustrates the process of interpolation necessary in many cases where the tables of values supplied are not sufficiently detailed for the purpose in hand; and in view of the importance of the method, every step in the argument should be thoroughly understood.

Example 18.—It is desired to use some steam tables giving the pressures for each 10° difference of temperature, to obtain the accurate value of $\frac{dp}{dt}$ when $t = 132^\circ$ C. The figures in the line commencing with $t = 130^\circ$ C. (the nearest to 132°) are as follows:—

t	p	$\frac{dp}{dt}$	$\frac{d^2p}{dt^2}$	$\frac{d^3p}{dt^3}$	$\frac{d^4p}{dt^4}$
130	2025.717	60.5995	1.47051	.026392	.0002738

Calculate, very exactly, the value of $\frac{dp}{dt}$ when $t = 132^\circ$ C.

Taylor's theorem may here be usefully employed, using the form—

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2!}f''(x) + \frac{h^3}{3!}f'''(x) + \frac{h^4}{4!}f''''(x) + \dots$$

Let $f(x) = \frac{dp}{dt}$ when $t = 130$

and $f(x+h) = \frac{dp}{dt}$ when $t = 132$, so that $h = 2$

Then $f'(x) = \frac{d}{dt} \left(\frac{dp}{dt} \right) = \frac{d^2 p}{dt^2}$ and $f''(x) = \frac{d^3 p}{dt^3}$, etc., t having the value 130.

Thus the expansion may be re-written as—

$$\left(\frac{dp}{dt} \right)_{132} = \left(\frac{dp}{dt} \right)_{130} + 2 \left(\frac{d^2 p}{dt^2} \right)_{130} + \frac{2^2}{2!} \left(\frac{d^3 p}{dt^3} \right)_{130} + \frac{2^3}{3!} \left(\frac{d^4 p}{dt^4} \right)_{130}$$

and substituting the values from the table—

$$\left. \frac{dp}{dt} \right|_{132} = 60.5995 + (2 \times 1.47051) + (2 \times 0.026392) + \left(\frac{4}{3} \times 0.0002738 \right)$$

Exercises 11.—On the Calculation of Small Corrections and Expansion in Series.

1. If $R = R_0(1+at+bt^2)$ when R_0 (the resistance of a conductor at 0° C.) is 1.6, a (the temperature-resistance coefficient of the material) = .00388 and b = .000000587, find the error in R (the resistance at temperature t° C.) if t is measured as 101 instead of 100.

2. The quantity Q of water flowing over a notch is given by $Q = \frac{8}{15} \times 64 \times \sqrt{2g} \cdot H^{\frac{3}{2}}$, where H is the head at the notch. What is the percentage error in Q caused by measuring H as .198 instead of .2?

3. If $y = 4x^{1.76}$, $y = 17.3$ when $x = 2.3$. What will be the change in y consequent on a change of x to 2.302?

4. A rough approximation gives $x = -2.44$ as a solution of the equation $10^{\frac{2x}{3}} = 16 + 4x - x^2$. Find a more correct root.

5. Determine the value of x to satisfy the equation $x^{1.5} - 3 \sin x = 3$, having given that it is in the neighbourhood of 2.67.

6. The height h of a Porter governor is expressed by—

$$h = \frac{W+w+f}{w} \cdot \frac{g}{n^2}$$

where n is the number of revolutions per minute. If $W = 100$, $w = 2$ and $f = 10$, find the change in the height due to a change in the speed from 200 to 197 r.p.m.

7. In calculating the co-ordinates of a station in a survey it was thought that there was a possibility of an error of 3 minutes (*i. e.*, $\frac{1}{2}$ either way) in the reading of the bearing. If the bearing of a line was read as $7^\circ 12'$ and the length of the line was 2 chains 74 links,

find the possible errors in the co-ordinates of the distant end of the line. [Co-ordinates are length $\times \cos(\text{bearing})$ and length $\times \sin(\text{bearing})$.]

8. Find by the methods of this chapter a series for a^x .
9. Using the figures given in Example 18, p. 112, calculate very exactly the pressure p at 133°C .
10. The equation $d^3 + 65d - 5 = 0$ occurred when finding the sag of a cable. A rough plotting gives the solution to be in the neighbourhood of 5 : find a more exact root.

CHAPTER V

INTEGRATION

HAVING discussed the section of the Calculus which treats of differentiation, we can now proceed to the study of the process of integration, this having a far more extensive application, and being, without doubt, far more difficult to comprehend.

As with the differentiation, it is impossible fully to appreciate this branch of the subject unless much careful thought is given to the fundamental principles; and accordingly the introduction to the Integral Calculus is here treated at great length, but in a manner which, it is hoped, will commend itself.

Meaning of Integration.—The terms *integer* and *integral* convey the idea of totality; an integer being, as we know, a whole number, and thus the sum of its constituent parts or fractions. The process of *integration* in the same way implies a summation or a totalling, whereas that of differentiation is the determination of rates of change or the comparison of small differences. Differentiation suggests subtraction or differencing, whilst integration suggests addition; differentiation deals with rates of change, integration with the results of the total change; differentiation involves the determination of slopes of curves, and integration the determination of areas of figures. Integration is, in fact, the converse to differentiation, and being therefore a *converse* operation is essentially more difficult to perform. [As instances of this statement contrast the squaring a quantity with the extraction of a square root, or the removal of brackets with factorisation.]

A converse operation is rather more vague as concerns the results than a direct; for when performing a direct operation one result only is obtainable, but the results of a converse operation may be many, as we shall find, for example, when dealing with indefinite integrals.

To illustrate the connection between differentiation and integration, consider the familiar case of velocity and acceleration. Suppose values of v and t are given, as in the table :—

t	$\cdot 1$	$\cdot 15$	$\cdot 20$	$\cdot 25$	$\cdot 30$
v	28.4	29.7	30.5	33.4	36.5
Then	δv	1.3	.8	2.9	3.1
	δt	.05	.05	.05	.05
	$a = \frac{\delta v}{\delta t}$	26	16	58	62

The accelerations are here found by comparing differences of velocity with differences of time.

Regard the question from the other point of view : assume that these accelerations are given and we wish to determine the total change in the velocity in the given period of time. The total change must be given by the sum of the changes in the small periods of time; in the first period of .05 sec. the average acceleration was 26, i.e., the velocity was being increased at the rate of 26 units per sec. each sec.; and therefore the change in the velocity in .05 sec. = $26 \times .05$ units per sec.
 $= 1.3$ units per sec.

In the successive periods the changes in velocity are .8, 2.9 and 3.1 respectively.

Hence the total change in the velocity over the period .2 sec. = $1.3 + .8 + 2.9 + 3.1 = 8.1$ units per sec., or if the initial velocity was 28.4, the final velocity was $28.4 + 8.1 = 36.5$. Note that the acceleration is given by the fraction $\frac{\delta v}{\delta t}$, whilst a small change in the velocity is of the nature $a\delta t$, or the total change of velocity = sum of all small changes = $\Sigma a\delta t$.

We can thus find integrals by working through the processes of differentiation, but in the reverse order. If a function, expressed in terms of symbols, has to be integrated, it is an advantage to transform the rules for differentiation into forms more readily applicable; the method, however, being entirely algebraic.

If numerical values alone are given, the integration resolves itself into a determination of an area.

Hence—

Considered from an *algebraic standpoint*—

Differentiation implies the calculation of rates of change;

Integration implies the summation of small quantities.

From the *graphic standpoint*—

Differentiation is concerned with the measurement of slopes of curves;

Integration is concerned with the measurement of areas under curves.

Just as special symbols are used to denote the processes of differentiation, so also there are special symbols for expressing the processes of integrations.

Regarding an integral as an area, it must be of two dimensions, a length and a breadth; and we have seen in an earlier chapter (Part I, Chap. VII) that in order to ascertain an area correctly its base must be divided up into small elements, the smaller the better, these elements not necessarily being of the same length, but all being small. Thus, to find the area ABCD (Fig. 27) we can suppose it divided up into small strips, as EFGH, then find the area of each of these and add the results. The portion EH of the curve is very nearly straight, so that EFGH is a trapezoid, and hence its area = mean height \times width. Now its mean height, FE and GH are practically the same, so that any one of them can be denoted by y ; also the width FG of the strip is a small element of the base, *i.e.*, is δx .

Hence, the area of the strip EFGH = $y \times \delta x$, and the total area between the curve, the bounding ordinates and the axis of x must equal the sum of all products like $y\delta x$, or, as it might be expressed—

$$\text{Area} = \Sigma y\delta x \text{ (approximately).}$$

However small the width of the strips are made, this sum only gives the area approximately, but as δx is diminished the result approaches the true more and more closely.

Therefore, bearing in mind our previous work on limits, we can say that the limiting value of $\Sigma y\delta x$ must give the area exactly. To this limiting value of the sum different forms of symbols are

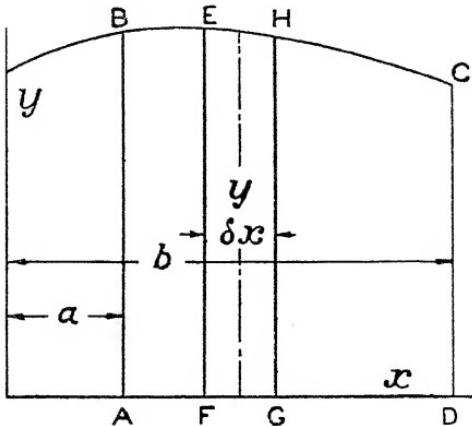


FIG. 27.

attached, the Σ and δ being replaced by the English forms \int and d respectively, so that the area between the curve and the axis of $x = \int y dx$. There is no limit placed to this area in any horizontal direction, so that the area is not defined by the given formula.

Hence $\int y dx$ is spoken of as an *indefinite integral*.

The x is again the I.V., and the size of the area will depend on the values given to it. Suppose that when $y = AB$, $x = a$, and when $y = CD$, $x = b$; then the range of x is from a to b if it is the area ABCD that is considered. Accordingly we can state that the area ABCD = $\int y dx$, the value of this integral being found between $x = a$ and $x = b$, or, as it is written for brevity, $\int_{x=a}^{x=b} y dx$, or, more shortly still, $\int_a^b y dx$, it being clearly understood that the limits a and b apply to the I.V., i.e., that quantity directly associated with the "d."

It is evident that ABCD is a definite area, having one value only, and thus $\int_a^b y dx$ is termed a *definite integral*.

The most convenient method for determining areas (provided that a planimeter is not handy) is undoubtedly the "sum curve" method treated in Part I, Chap. VII; the great virtue of it being that the growth of the area is seen, and that either any portion or the whole of the area of the figure can be readily found by reading a particular ordinate.

In view of the great usefulness of the process of integration by graphic means, the method is here explained in detail, following exactly the plan adopted in Part I, Chap. VII.

Graphic Integration is a means of summing an area with the aid of tee and set square, by a combination of the principles of the "addition of strips" and "similar figures." An area in Fig. 28 is bounded by a curve $a'b'z'$, a base line az and two vertical ordinates aa' and zz' . The base is first divided in such a way that the widths of the strips are taken to suit the changes of curvature between a' and z' , and are therefore not necessarily equal; and mid-ordinates (shown dotted) are erected for every division. Next the tops of the mid-ordinates are projected horizontally on to a vertical line, as BB' . A *pole* P is now chosen to the left of that vertical; its distance from it, called the polar distance p , being a round number of horizontal units. The pole is next joined to each of the projections in turn and parallels are drawn across the

corresponding strips so that a continuous curve results, known as the **Sum Curve**. Thus am parallel to PB' is drawn from a across the first strip; mn parallel to PC' is drawn from m across the second strip, and so on.

The ordinate to the sum curve through any point in the base gives the area under the original or *primitive* curve from a up to the point considered.

Referring to Fig. 28—

$$\text{Area of strip } abb'a' = ab \times AB$$

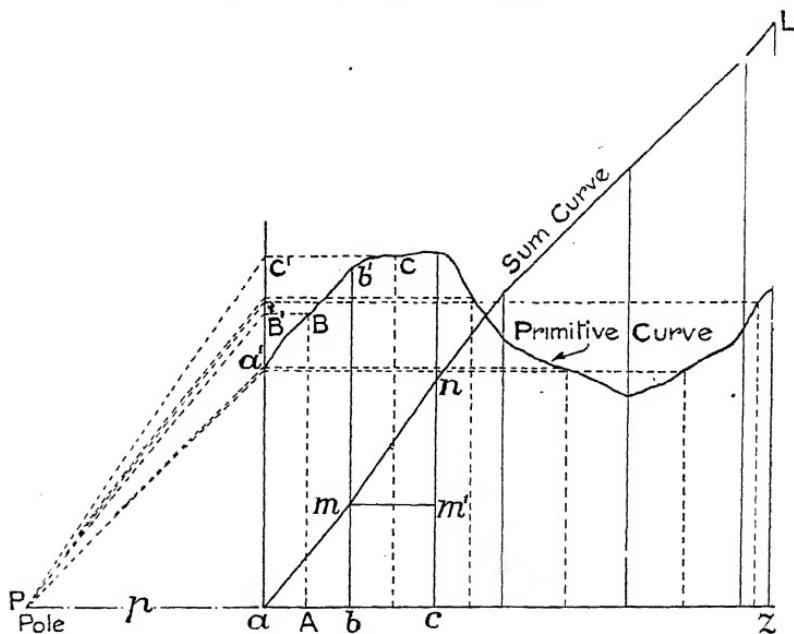


FIG. 28.—Graphic Integration.

but, by similar figures—

$$\frac{B'a \text{ or } BA}{p} = \frac{bm}{ab}$$

$$\text{whence } AB \times ab = p \times bm$$

$$\text{i.e., } bm = \frac{\text{area of strip}}{p} \quad \text{or} \quad \text{area of strip} = p \times bm$$

i.e., bm measures the area of the first strip to a particular scale, which depends entirely on the value of p .

$$\text{In the same way } nm' = \frac{\text{area of second strip}}{p}$$

and by the construction nm' and bm are added, so that—

$$cn = \frac{\text{area of 1st and 2nd strips}}{p}$$

or— area of 1st and 2nd strips = $p \times cn$

Thus, summing for the whole area—

$$\text{Area of } aa'z'z = p \times zL$$

Thus the scale of area is the old vertical scale multiplied by the polar distance; and accordingly the polar distance should be selected in terms of a number convenient for multiplication.

E. g., if the original scales are—

$$\begin{aligned} 1'' &= 40 \text{ units vertically} \\ \text{and} \quad 1'' &= 25 \text{ units horizontally} \end{aligned}$$

and the polar distance is taken as $2''$, i. e., 50 horizontal units; then the new vertical scale—

$$\begin{aligned} &= \text{old vertical scale} \times \text{polar distance} \\ &= 40 \times 50 = 2000 \text{ units per inch.} \end{aligned}$$

If the original scales are given and a *particular scale* is desired for the sum curve, then the polar distance must be *calculated* as follows—

$$\text{Polar distance in horizontal units} = \frac{\text{new vertical scale}}{\text{old vertical scale}}$$

E. g., if the primitive curve is a “velocity-time” curve plotted to the scales, $1'' = 5$ ft. per sec. (vertically) and $1'' = 1$ sec. (horizontally), and the scale of the sum curve, which is a “displacement-time” curve, is required to be $1'' = 2.5$ ft., then—

$$\text{Polar distance (in horizontal units)} = \frac{2.5}{5} = .5$$

and since $1'' = 1$ unit along the horizontal, the polar distance must be made 5”.

Integration is not limited to the determination of areas only; true, an integral may be regarded as an area, but if the ordinate does not represent a mere length, but, say, an area of cross section, the value of the integral will in such cases measure the volume of the solid.

Our standard form throughout will be for the area of the figure as plotted on the paper, viz., $\int y dx$, where y is an ordinate and dx an element of the base, but y and x may represent many different quantities.

Thus, suppose a curve is plotted to represent the expansion of

a gas; if, as is usual, pressures are plotted vertically and volumes horizontally, the ordinate is p and an element of the base is δv ; hence the area under the curve = $\int_{v_1}^{v_2} p \, dv$ (if the initial and final volumes are v_1 and v_2 respectively), and since this is of the nature pressure \times volume, i. e., $\frac{lbs}{(ft)^2} \times (ft)^3$ or ft. lbs., the area must represent the work done in the expansion.

To illustrate such a case:—

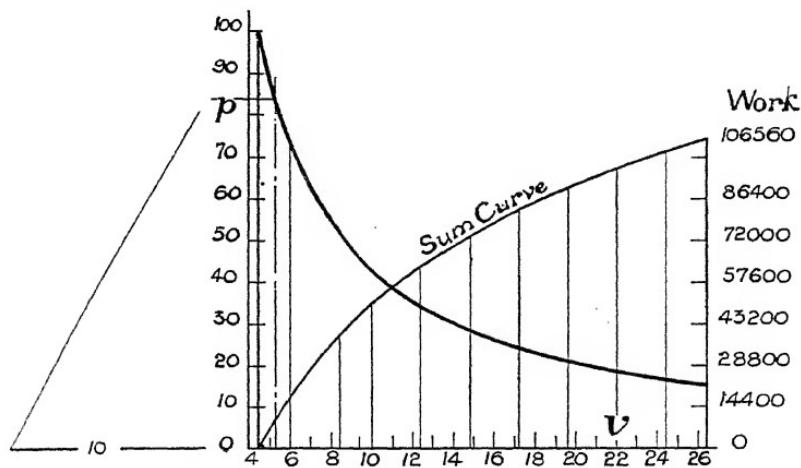


FIG. 29.—Expansion of Steam.

Example 1.—It is required to find the work done in the expansion of 1 lb. of dry saturated steam from pressure 100 lbs. per sq. in. to pressure 15 lbs. per sq. in.

From the steam tables the following corresponding values of p and v are found:—

v (cu. ft. per lb.)	4.44	5.48	7.16	10.50	13.72	20	26.4
p (lbs. per sq. in.)	100	80	60	40	30	20	15

By plotting these values, p vertically, the expansion curve is obtained (Fig. 29); this being the primitive curve.

Selecting a polar distance equivalent to 10 horizontal units, we proceed to construct the sum curve, the last ordinate of which measures to a certain scale the work done in the expansion. Now the new vertical scale = old vertical \times 10, since the polar distance = 10; and also we must multiply by 144, since the pressures are expressed

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in lbs. per sq. in. and must be converted to lbs. per sq. ft., so that the work done may be measured in ft. lbs.

According to this modified scale the last ordinate is read off as 106560; thus the work done = 106560 ft. lbs.

or, as it would be written in more mathematical language—

$$\int_{44}^{264} pdv = 106560.$$

Example 2.—The diameters of a tapering stone column, 20 ft. long at 6 equidistant places were measured as 2.52, 2.06, 1.54, 1.15, .81 and .58 ft. respectively.

Find its weight at 140 lbs. per cu. ft.

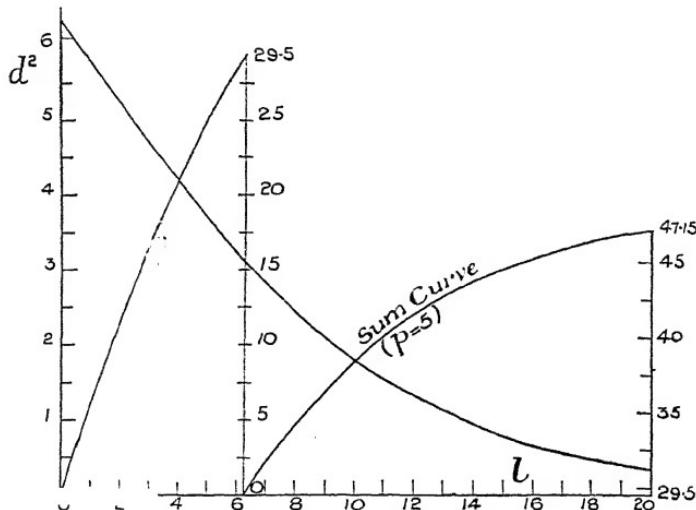


FIG. 30.—Problem on Stone Column.

The volume will be obtained by plotting the areas against the length and summing. Now the area of any section = $\frac{\pi}{4}d^2$, and the total volume will be the sum of the volumes of the small elements into which the solid may be supposed to be divided.

$$\text{Thus the volume } = \int_0^{20} Adl = \int_0^{20} \frac{\pi}{4} d^2 dl.$$

$$\text{and the weight } = 140 \int_0^{20} \frac{\pi}{4} d^2 dl.$$

Since $\frac{\pi}{4}$ is a constant multiplier, it can be omitted until the end, for its effect is simply to alter the final scale; hence a constant factor before integration remains so after.

$$\text{Hence the weight } = \frac{140 \times \pi}{4} \int_0^{20} d^2 dl = 110 \int_0^{20} d^2 dl.$$

The integral will be of the standard form if for d^2 we write y and if for l we write x , so that we see that ordinates must represent d^2 and abscissæ lengths, and hence the table for plotting reads :—

	12	16	20
y or d^2	6.35	4.24	2.37

$\int_0^{20} d^2 \cdot dl$

	1.32	.64	.336
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Plotting these values and thence constructing the sum curve (see Fig. 30), we find the last ordinate to be 47.15, and this is the value of $\int_0^{20} d^2 \cdot dl$.

$$\text{Weight} = 110 \int_0^{20} d^2 \cdot dl = 110 \times 47.15 = \underline{\underline{5187 \text{ lbs.}}}$$

Application of Integration to "Beam" Problems.—At an earlier stage (see p. 38) it has been demonstrated that the shear at any point in the length of a beam loaded in any way whatever is given by the rate of change of the bending moment in the neighbourhood considered, this being the *space rate* of change. Conversely, then, the bending moment must be found by summatting the shearing force; and hence, if the shear curve is given, its sum curve is the curve of bending moment.

In the majority of problems the system of loading is given, from which the curve of loads can be drawn. Then, since the shear at any section is the sum of all the forces to the right or left of that section, the sum curve of the load curve must be the shear curve; continuing the process, the sum curve of the shear curve, *i. e.*, the second sum curve from the load curve as primitive, is the curve of bending moment and the fourth sum curve is the deflected form.

Expressing these results or statements in the notation of the calculus; L, S and M being the respective abbreviations for loading, shear and bending moment—

$$\begin{aligned} S &= \int L dx \\ M &= \int S dx = \int (\int L dx) dx = \iint L(dx)^2 \\ [\iint L(dx)^2 \text{ being termed a } &\text{double integral}] \end{aligned}$$

and the deflection $y = \iint M(dx)^2$ or $\iiint L(dx)^4$.

If the loading is not uniform, but continuous, the summation must be performed graphically. [The link polygon method largely used obviates half these curves, *e. g.*, the link polygon for the loads gives at once the curve of bending moment.]

Example 3.—The loading on a beam, 24 ft. long, simply supported at its ends varies continuously, as shown in the table. Draw diagrams of shearing force and bending moment, stating clearly the maximum values of the shearing force and the bending moment.

Distance from one end (ft.)	0	4	7	10	12	14	17	20	24
Load in tons per ft.	.44	.58	.86	1.06	1.1	1.06	.86	.58	.44

The curve of loads is first plotted, as in Fig. 31.

By sum-curving this curve, we obtain the curve of shearing force, although no measurements can be made to it until account has been taken of the support reactions.

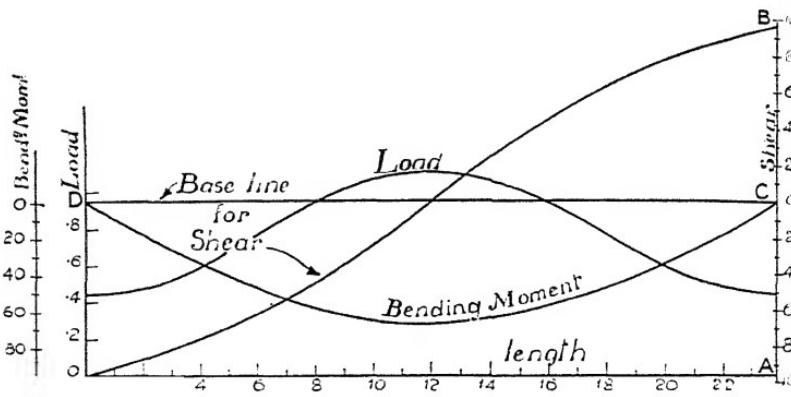


FIG. 31.—Problem on Loaded Beam.

To find the reactions at the ends : We know that these must be equal, since the loading is symmetrical, each reaction being one-half of the total load. Now the last ordinate AB of the sum curve of the load curve is 19; thus the reactions are each 9·5. Bisecting AB, or, in other words, marking off a length AC to represent the reaction at A, we draw a horizontal, and this is the true base line for the curve of shear; any ordinate to the curve of shear from this base giving the shear at the point in the length of the beam through which the ordinate is drawn.

We observe that the shear changes sign and is zero at the centre of the beam; we can conclude from this that the bending moment must have its maximum value at the centre, since shear = rate of change of bending moment, and if the shear is zero, the bending moment must have a turning value.

By sum-curving the shear curve from CD as base, the resulting curve is that of bending moment.

It is well carefully to consider the scales, for it is with these that difficulties often arise.

The scales given here apply to the original drawing, of which Fig. 31 is a reproduction somewhat under half full size.

For the length 1 in. = 2·5 ft.

For loads 1 in. = ·4 ton per ft.

Polar distance for the first sum curve, i.e., the curve of shear—
= 4 ins. = $4 \times 2\cdot5$, or 10 horizontal units.

Hence the scale of shear = $\cdot4 \times 10$, or 4 tons to 1 in.

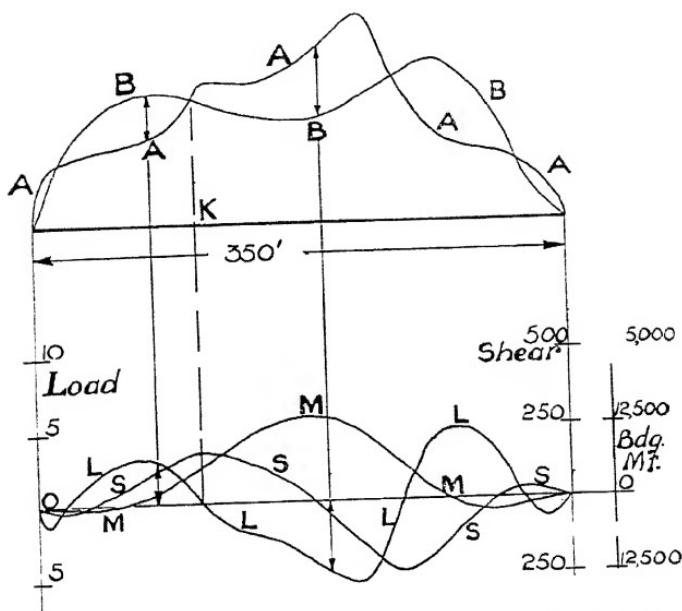


FIG. 32.—Shearing Force and Bending Moment on Ship's Hull.

Polar distance for the second sum curve = 4 ins. = 10 horizontal units.

Hence the scale of bending moment = $4 \times 10 = 40$
or 1 in. (vertically) = 40 tons. ft.

Reading according to these scales—

The maximum shear = 9·5 tons }
and the maximum bending moment = 68 tons. ft. }

Example 4.—In Fig. 32 AAA is the curve of weights or load distribution, and BBB the curve of buoyancy or upward water thrust

for a ship whose length is 350 ft., the scale of loads being indicated on the diagram.

Draw diagrams of shearing force and bending moment on the hull of the vessel and measure the maximum values of these quantities.

It is first necessary to construct the curve of loads to a straight line base, and to do this the differences between the curves AAA and BBB are set off from a horizontal, taken in our case below the original base line.

In this way the curve of loads LLL is obtained, the scale being shown to the left of the diagram.

By sum-curving this curve, the curve of shear SSS is obtained; the polar distance (not shown on the diagram) being taken as 50 horizontal units, so that the scale for the shear is 50 times the scale for the loads.

Sum-curving the curve SSS, the curve MMM, that of bending moment, is obtained (again the polar distance is 50 horizontal units).

Sections such as K, where the upward thrust of the water balances the downward force due to the weights, are spoken of as water-borne.

Reading our maximum values according to the proper scales, we find them to be—

$$\begin{aligned} \text{Maximum shear} &= \underline{\underline{246 \text{ tons}}} \\ \text{Maximum bending moment} &= \underline{\underline{14,300 \text{ tons ft.}}} \end{aligned} \quad \}$$

It should be noted that the last ordinate of both the shear curve and the curve of bending moment is zero; these results we should expect since the areas under the curves AAA and BBB must be equal, so that the shear at the end must be zero, and also the moments of these areas must be alike.

[In practice the maximum bending moment is found by such a formula as—

$$\text{Maximum bending moment} = \frac{\text{Weight} \times \text{length}}{\text{Constant}}$$

the constant for small boats being between 30 and 40, and for larger between 25 and 30.]

The Coradi Integrigraph.—A brief description of the Integrigraph, an instrument devised to draw mechanically the sum curve, can usefully be inserted at this stage.

It consists essentially of a carriage running on four milled wheels A (Fig. 33), a slotted arm C carrying the tracer B which is moved along the primitive curve, and the arm D which carries the pencil E which draws the sum curve.

As B is moved along the primitive curve, the slotted arm C slides about the pins G and P, thus altering its inclination to the horizontal. A parallel link motion ensures the movement of E parallel to the instantaneous position of C, the sharp-edged wheel F assisting in guiding the tracer bracket.

The principle of the instrument is not difficult to understand, and can be explained in a very few words.

The pole is at P, and the tops of the mid-ordinates are projected to the vertical through G by the horizontals like BG; parallels are then drawn to PG by the pencil E, the motion being continuous.

The polar distance can be varied as desired, by altering the position of the bracket carrying the pin P along the horizontal

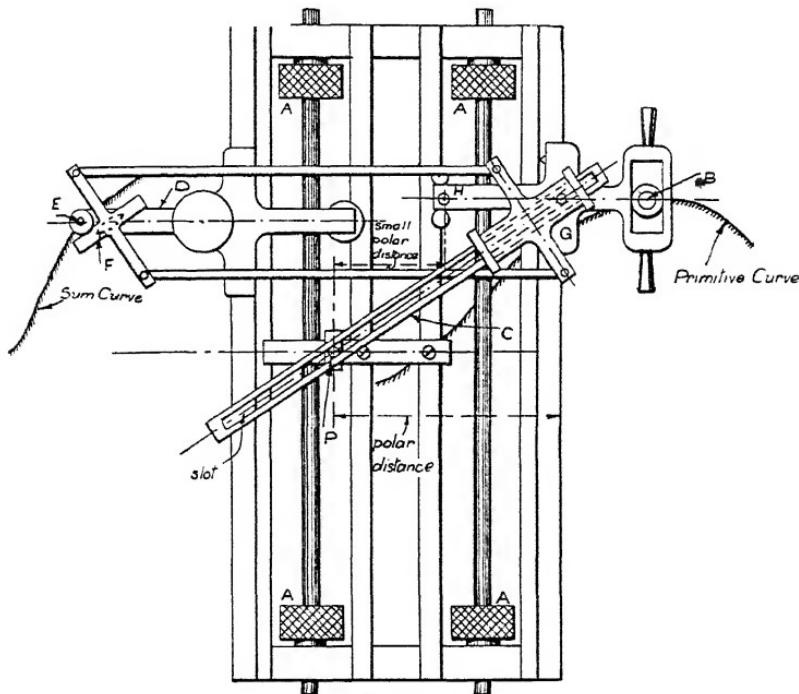


FIG. 33.

arm; and if an extremely small polar distance is found to be advisable, the pin H may be utilised instead of G.

Rules for Integration of Simpler Functions.—Since integration is the reverse of differentiation, many functions can be integrated by reversing the order of the steps in differentiation.

Integration of powers of x .—The first rule given in the work on differentiation of functions was—

$$\frac{d}{dx} x^n = nx^{n-1}.$$

To change into the integration form, we transpose $\frac{d}{dx}$: the "d" on the one side becomes \int on the other side, to indicate the change *differencing to summing*, and the "dx" occurs on the top line of the other side of the equation.

Thus—

$$x^n = \int nx^{n-1} dx$$

$$\text{or } \int x^{n-1} dx = \frac{1}{n} x^n + C$$

the reason for the presence of the constant term C being explained later.

It is a trifle simpler to write n in place of $n-1$, and therefore $n+1$ in place of n , so that—

$$\int x^n dx = \frac{1}{n+1} x^{n+1} + C.$$

Whereas, when *differentiating* a power of the I.V., the power was reduced by 1 in the process of differentiation; when *integrating*, the power is increased by 1.

E.g.,

$$\frac{d}{dx} x^5 = 5x^4$$

whereas

$$\int x^5 dx = \frac{1}{6} x^6 + C.$$

A special case occurs for which the above rule does not apply: for, let $n = -1$, then $\int x^{-1} dx$ should, according to the rule just given, be $\frac{1}{0} x^0$, but to this fraction no definite meaning can be assigned.

We know that

$$\frac{d}{dx} \log x = \frac{1}{x} = x^{-1}$$

$$\therefore \int x^{-1} dx = \log x + C$$

or, as it is sometimes written—

$$\int \frac{dx}{x} = \log x + C.$$

A constant multiplier before integration remains as such after;

$$\text{thus } \int ax^n dx = \frac{a}{n+1} x^{n+1} + C.$$

Also an expression composed of terms can be integrated term by term, and the results added.

Thus, $\int (ax^n + b) dx$ can be written—

$$\begin{aligned} & \int ax^n dx + \int b dx \\ \text{i. e., } & \int ax^n dx + \int bx^0 dx \quad \text{for } x^0 = 1 \end{aligned}$$

$$\text{its value being } \frac{a}{n+1}x^{n+1} + bx - C.$$

Note.—Differentiation of a constant term gives zero, but the integration gives that constant multiplied by the I.V.

The reason for this will be apparent if we consider the statements from the graphical standpoint. The curve representing the equation $y = b$ is a horizontal straight line, and therefore the slope is zero (*i. e.*, $\frac{dy}{dx} = 0$); but the area under the curve = the area of a rectangle = base \times height = $x \times b$ (*i. e.*, $\int b dx = bx$).

Exponential Functions.—We have already proved that $\frac{de^x}{dx} = e^x$ (see p. 47); then by transposition of d and dx to the other side of the equation we obtain the statement $e^x = \frac{1}{d}e^x dx$,

and since $\frac{1}{d}$ corresponds to \int we may write this as $\int e^x dx = e^x + C$.

Thus if we either differentiate e^x or integrate it we arrive at the same result; and e^x is the only function for which the differential coefficient and also the integral are the same as the function itself.

Carrying this work a step further, let us consider the integration of e^{bx} , and hence a^x :

$$\text{Now } \frac{d}{dx} ae^{bx} = abe^{bx} \quad \therefore \int ae^{bx} dx = \frac{a}{b}e^{bx} + C.$$

To avoid confusion as to the placing of a and b we must reason in the following manner: The a is a constant multiplier of the whole function, and therefore remains so after integration; the b multiplies the I.V. only; and thus differentiation would cause it to multiply the result, whereas after integration it becomes a divisor. Great attention should be paid to the application of this rule, for unless care is exercised mistakes are very apt to creep in.

Example 5.—Find the value of $\frac{d}{dt}(15t^4 - 7t^9 + 83)$ and also of $\int \left(60t^3 - \frac{6 \cdot 3}{t^1}\right) dt$.

Differentiating the first expression—

$$\begin{aligned}\frac{d}{dt}(15t^4 - 7t^3 + 83) \\ &= 60t^3 - 6 \cdot 3t^2 + 0.\end{aligned}$$

Integrating the second given expression—

$$\begin{aligned}\int(60t^3 - \frac{6 \cdot 3}{t^1}) dt &= \int 60t^3 dt - \int 6 \cdot 3t^{-1} dt \\ &= \frac{60 \times t^4}{4} - \frac{6 \cdot 3}{-1+1} t^{-1+1} + C \\ &= 15t^4 - 7t^2 + C.\end{aligned}$$

Notice that although a function has been differentiated and the derivative integrated, the final expression is not exactly the same as the original, the constant term being represented only by C , where C may have any value. Further reference will be made to this point on p. 137.

Example 6.—If $\int p v^{1.32} = C$, find the value of $\int p dv$.

To express p in terms of v —

$$\begin{aligned}p &= \frac{C}{v^{1.32}} = Cv^{-1.32} \\ \int pdv &= \int Cv^{-1.32} \cdot dv = C \int v^{-1.32} dv \\ &= C \times \frac{1}{-1.32+1} v^{-1.32+1} + K \\ &= -\frac{C}{1.32} v^{-0.32} + K.\end{aligned}$$

(K being any constant)

This result can be written in a slightly different form, if for C we write its value $\int p v^{1.32}$; then—

$$\begin{aligned}\int pdv &= -\frac{\int p v^{1.32} \times v^{-0.32}}{1.32} + K \\ -\frac{pdv}{1.32} &= -3.125 \int p v + K.\end{aligned}$$

Example 7.—Find $\int pdv$ when $p v = C$.

In this case— $p = Cv^{-1}$

$$\begin{aligned}\therefore \int pdv &= \int_v^C dv = C \int_v^1 dv = C \log v + K \\ &= \underline{p v \log v + K}.\end{aligned}$$

Example 8.—Find the value of $\int 17e^{2x} dx$.

$$\int 17e^{2x} dx = 17 \times \frac{1}{2} e^{2x} + C = \underline{8.5e^{2x} + C}.$$

Note that 17 is a constant multiplier throughout; 2 multiplies the I.V. and therefore appears as a divisor after integration; also the power of e remains exactly the same.

Example 9.—Find the value of $\int(40e^{5v} + v^{5.4})dv$.

$$\begin{aligned}\int(40e^{5v} + v^{5.4})dv &= \int 40e^{5v}dv + \int v^{5.4}dv \text{ (separating the terms)} \\ &= \left(40 \times \frac{1}{5}e^{5v}\right) + \frac{1}{6.4}v^{6.4} + C \\ &= \underline{8e^{5v} + 1.56v^{6.4} + C}.\end{aligned}$$

Example 10.—Find an expression for $\int a^x dx$, and apply the result to determine the value of $\int 12 \times 5^{4x} dx$.

From our previous work we know that—

$$\frac{d}{dx}a^x = a^x \cdot \log a.$$

$$\int a^x dx = \frac{1}{\log a} \cdot a^x + C.$$

$$\begin{aligned}\text{Hence } \int 12 \times 5^{4x} dx &= \left(12 \times \frac{1}{4} \times \frac{1}{\log 5} \times 5^{4x}\right) + C \\ &= 1.609 \times 5^{4x} + C \quad (\log_e 5 = 1.609) \\ &= \underline{1.864 \times 5^{4x} + C}.\end{aligned}$$

Note.—It would be quite incorrect to multiply 1.864 by 5 and express the result as 9.32^{4x}.

Alternatively, the result might have been arrived at in the following manner—

$$\begin{aligned}\int 12 \times 5^{4x} dx &= 12 \int (5^4)^x dx \\ &= 12 \times \frac{1}{\log 625} \times (5^4)^x + C \\ &= \frac{12}{6.44} \times 5^{4x} + C \quad (\log 625 = 6.44) \\ &= \underline{1.864 \times 5^{4x} + C}.\end{aligned}$$

Exercises 12.—On Graphic Integration.

1. The acceleration of a slider at various times is given in the table. By graphic integration obtain the velocity and displacement curves to a time base, indicating clearly your scales.

Time	0	.008	.016	.028	.036	.044	.048	.06
------	---	------	------	------	------	------	------	-----

Acceleration	0	75	87.5	87.5	87.5	87.5	83	0
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.068	.072	.084	.10	.108	.12
78	85	87.5	87.5	83	0

2. An acceleration diagram on a time base has an area of 4·7 sq. ins. The base of the diagram is 2·5 ins. and represents 25 secs. The acceleration scale is 1 in. = 3 ft. per sec.². If the velocity at the beginning is 11 ft. per sec., find the velocity in ft. per sec. at the end of the 25 secs.

3. A rectangular barge is loaded symmetrically in still water. The curve of loading is a triangle with apex at the centre, and the curve of buoyancy is a rectangle. Draw diagrams of shearing force and bending moment on the barge.

4. The curves of loads for a ship 350 ft. long is as given in the table. Plot this, and by graphic integration obtain the curves of shearing force and bending moment.

Distance from one end (ft.)	0	7	10	35	56	84	102
load (tons per foot)	0	·3	0	-2·6	-3·1	-2·3	0
	112	133	161	196	210	237	260
	1·6	2·3	3·15	5·2	5·7	0	-4·5
							-4·95
						0	·9
							0

5. The table gives the values of the pressure and volume for the complete theoretical diagram for a triple expansion engine.

<i>v</i>	0	1	2	4	6	8	10	12
<i>p</i>	240	240	120	60	40	30	24	20

Find the initial pressure in each cylinder in order that the work done per cycle may be the same for each.

(Hint.—Divide the last ordinate of the sum curve into three equal parts, draw horizontals through these points of section to meet the sum curve, and from these points of contact erect perpendiculars to cut the expansion line.)

6. A body weighing 3000 lbs. was lifted vertically by a rope, there being a damped spring balance to indicate the pulling force *F* lbs. of the rope. When the body had been lifted *x* ft. from its position of rest, the pulling force was automatically registered as follows :—

<i>x</i>	0	20	40	65	75	95	110	140
<i>F</i>	8000	7950	7850	7500	7400	6800	6400	4000

Find the work done on the body when it has risen 80 ft. How much of this is potential energy and how much is kinetic energy?

Find also the work done when it has risen 140 ft.

7. The current from a battery was measured at various times, with the following results:—

Time (hours) . .	0	1	3	6	9	10	12	14	15
Current (amperes)	25	28	37	39·5	32	29	24	25·3	27

If its capacity is measured by $\int Cdt$, find the capacity in ampere hours.

8. The following are the approximate speeds of a locomotive on a run over a not very level road. Draw a curve showing the distance run up to any time.

Time (mins. and secs.)	2.15	6.15	9.22	11.45	14.26	16.35	20.52
Speed (miles per hr.)	10	18·2	22·8	25·5	28	29·2	28·6

9. The load curve at a large central station can be constructed from the following data:—

Time (hours) .	1	2	3	4	5	6	7	7·5	10	11
Load (1000 amperes)	3·5	1	1·2	1	6·4	14	17	17·8	16·4	11·3

12	1	2	3	4	5	5·5	6	7	8	9	10	11	12
7·8	8	7·6	8·7	12·5	19	23·3	21	12·4	11	10·5	9·6	9	6

Find the total number of ampere hours supplied in the 24 hours.

10. The velocity of a three-phase electric train, with rheostatic control, at various times, was found as in the table:—

Time (secs.) . . .	0	26·6	66·6	80·1	99
Velocity (ft. per sec.) .	0	40	40	37·3	0

Draw the space-time curve and find the total distance covered in the 99 seconds.

On the Integration of the Powers of x and of the Exponential Functions.

11. What is the significance of the symbols \int and $\frac{d}{dx}$ in the expression $\int x^2 dx$?

Integrate, with respect to x , the functions in Examples 12 to 27

12. $4x^{1.62}$. 13. $70 \cdot 15$. 14. $\frac{3}{x^3}$. 15. $\frac{x^2}{x^{n+1}}$. 16. e^{-7x} .

17. $x^9 - \frac{10}{x} + 14$. 18. $\frac{3 \cdot 47}{x^{-0.4}} - 5x$. 19. $4x^e + \frac{1}{4} e^x$.

20. $12e^{9x-5}$.

21. $\frac{15 \cdot 7}{e^{1 \cdot 2-2 \cdot 4x}}$.

22. $17e^{1 \cdot 4}$.

23. $\frac{b(x^5)^4}{cx^{1 \cdot 59}}$

24. $2 \cdot 54x^{-16} - 8 \cdot 2x^{-1} + \frac{7 \cdot 04}{e^{2 \cdot 6x}} + 1 \cdot 13$.

25. $\frac{82e^{2x} \times e^{-5x}}{(7e^{2 \cdot 4x})^3}$.

26. $(e^3)^{-17x} - x^{-23} + \frac{5 \cdot 03x^2}{e^{-y}}$.

27. $94x^{-18} \cos \theta - \frac{1 \cdot 76x^0}{e^{14-8x}}$.

Find the values of the following—

28. $\int v^5 dv$. 29. $\int \frac{du}{u^4}$. 30. $\int 35 dt$. 31. $\int e^{5s-4} ds$.

32. $\int pdv$ when $pv^{1 \cdot 17} = C$. 33. $\int 14 \times 2^s ds$.

34. $\int (4x^{-2} + 5x + 17x^3 - 8) dx$. 35. $\int 3 \cdot 1^t dt$. 36. $\int \frac{dp}{e^{\beta p}}$.

37. $\int (e^{4t} + e^{-5t} - e) dt$. 38. $\iint 32 \cdot 2(dt)^2$. 39. $2 \cdot 1 \iint x^{-5}(dx)^2$.

40. Solve the equation $\frac{dp}{dv} = -n \frac{p}{v}$.

41. In connection with the flow of air through a nozzle, if x is the distance outwards from the nozzle and v is the velocity there, $v \propto \frac{1}{\sqrt{x}}$.

Also δA (an element of area of flow) = $K\delta x \sqrt{x}$. The added momentum for the small element considered = $\delta M = v\delta A$. Show that M , the total increment to the momentum, can be written $C - \frac{D}{\sqrt{x}}$ where C and D are constants.

Trigonometric Functions.—We have previously seen that the derived curve of either the sine curve or the cosine curve is the primitive curve itself transferred *back* a horizontal distance of one-quarter of the period. Conversely, then, we may state that the sum curve of either the sine or the cosine curve is the curve itself moved *forward* for a distance corresponding to one-quarter of the period. In other words, integration does not alter the form of the curve. Taking the case of the sine curve as the primitive, we see, on reference to Fig. 34, that if this curve is shifted forward for one-quarter period the resulting curve is the cosine curve inverted; or expressing in algebraic language, whilst the equation of the primitive curve is $y = \sin x$, that of the sum or integral curve is $y = -\cos x$. Thus, $\int \sin x dx = -\cos x$. In like manner it could be shown that $\int \cos x dx = \sin x$. For emphasis, the differentiation and the integration of sine x and cosine x are repeated here—

$$\frac{d}{dx} \sin x = \cos x$$

$$\int \sin x dx = -\cos x + C$$

$$\frac{d}{dx} \cos x = -\sin x$$

$$\int \cos x dx = \sin x + C$$

Note.—When differentiating the cosine the minus sign appears in the result; when integrating the sine the minus sign appears; it is important to get a good grip of these statements, and the consideration of them from the graphic aspect is a great help in this respect.

To extend the foregoing rules—

$$\int \cos x dx = \sin x + C$$

$$\therefore \int \cos(ax+b) dx = \frac{1}{a} \sin(ax+b) + C$$

$$\int \sin x dx = -\cos x + C$$

$$\therefore \int \sin(ax+b) dx = -\frac{1}{a} \cos(ax+b) + C.$$

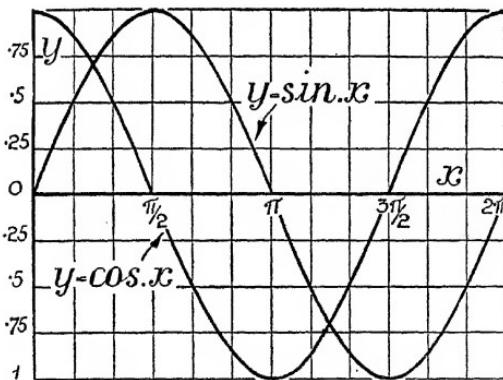


FIG. 34.

Thus the angle remains the same after integration just as it would after differentiation, but the constant multiplier a of the I.V. becomes a divisor.

To integrate $\sec^2 x$ with regard to x we call to mind the differentiation of $\tan x$, viz., $\frac{d}{dx} \tan x = \sec^2 x$. Accordingly

$$\int \sec^2 x dx = \tan x + C.$$

Extending this to apply to the more general case—

$$\int \sec^2(ax+b) dx = \frac{1}{a} \tan(ax+b) + C$$

In like manner—

$$\int \operatorname{cosec}^2(ax+b) dx = -\frac{1}{a} \cot(ax+b) + C.$$

Other two standard integrals are added here, the derivation of which will be considered in the next chapter.

$$\int \tan x \, dx = -\log \cos x + C$$

$$\int \cot x \, dx = \log \sin x + C.$$

To verify these we might work from the right-hand side and differentiate. Dealing with the former—

$$\begin{aligned} \frac{d}{dx}(-\log \cos x) &= -\frac{d}{dx} \log u && \text{if } u = \cos x \\ &\quad -\frac{d \log u}{du} \times \frac{du}{dx} && \text{whence} \\ &= -\frac{1}{u} \times -\sin x && \frac{du}{dx} = -\sin x \\ &\quad \frac{\sin x}{\cos x} = \tan x \\ \therefore \quad \int \tan x \, dx &= -\log \cos x + C. \end{aligned}$$

Example 11.—Find the value of $\int (5 - \sin 4t) dt$.

$$\begin{aligned} \int (5 - \sin 4t) dt &= \int 5 dt - \int \sin 4t dt \\ &= 5t - \left(\frac{1}{4} \times -\cos 4t \right) + C \\ &= 5t + \frac{1}{4} \cos 4t + C. \end{aligned}$$

Example 12.—Evaluate $\int \sin (5 - 4t) dt$.

$$\int \sin (5 - 4t) dt = -\frac{1}{4} \times -\cos (5 - 4t) + C = \frac{1}{4} \cos (5 - 4t) + C.$$

Example 13.—If a force P is given by $P = 36.4 \sin (100s - 62)$, find the value of $\int P ds$.

$$\begin{aligned} \int P ds &= \int 36.4 \sin (100s - 62) ds = \frac{36.4}{100} \times -\cos (100s - 62) + C \\ &= -364 \cos (100s - 62) + C. \end{aligned}$$

Example 14.—Find the value of

$$\int [7.2s^4 - \frac{3}{s} + \frac{15s^{1.7}}{s^9} + 12 \cos (4 - 3s)] ds.$$

The expression $E = 7.2s^4 - 3s^{-1} + 15s^{1.7} + 12 \cos (4 - 3s)$

$$\begin{aligned} \therefore \int E ds &= \left(7.2 \times \frac{1}{5}s^5 \right) - 3 \log s + \frac{15}{1.8}s^{1.8} + \left(12 \times -\frac{1}{3} \sin (4 - 3s) \right) + C \\ &= 1.44s^5 - 3 \log s + 8.33s^{1.8} - 4 \sin (4 - 3s) + C. \end{aligned}$$

Example 15.—If $R = 11 \sec^2(3 - 4.7v)$, find $\int R dv$.

$$\begin{aligned}\int R dv &= \int 11 \sec^2(3 - 4.7v) dv = \frac{11}{-4.7} \tan(3 - 4.7v) + C \\ &= -2.343 \tan(3 - 4.7v) + C.\end{aligned}$$

Exercises 13.—On Integration of Trigonometric Functions.

Integrate, with respect to x , the functions in Nos. 1 to 10.

1. $3 \sin 4x$. 2. $-5.18 \cos(3 - 3x)$. 3. $7 \sec^2(3 - \frac{1}{7}x)$.

4. $x^{-0.12} - 1.4 \cos(0.5 - 1.17x)$. 5. $e^{5.4x} + 5 \sin(b + ax)$.

6. $9.45 \sin 8t$. 7. $-3.08 \sin 2(2.16x - 4.5)$.

8. $9e^{.7x} + \frac{3.47}{x^5} - 1.83 \tan x$.

9. $4.27 \sin\left(\frac{3x - 2.5}{7}\right) - 2 \cos 9x - 4x^{1.74} + 3^{2x+5}$.

10. $2 \sin^2 x - 2.91 \sin\left(\frac{\pi}{4} - 3.7x\right) + 2 \cos^2 x - 14.2 \operatorname{cosec}^2 \frac{3\pi x}{5}$.

11. The acceleration of a moving body is given by the equation—
 $a = -49 \sin(7t - .26)$.

Find expressions for the velocity and the space, the latter being in terms of the acceleration.

12. If $\frac{d^2x}{dt^2} = 4\pi^2 n^2 r (\cos \theta + \frac{\cos 2\theta}{m})$, find the values of $\frac{dx}{dt}$ and x . (x is a displacement of the piston in a steam-engine mechanism.)

13. Find the value of $\int [5^{2p} + \cos(3.7 - 7.2p)] dp$.

14. If $v = 117 \sin 6t - 29.4 \cos 6t$, find the value of $\int v dt$.

Indefinite and Definite Integrals.—The integrals already given, although correct, are not complete. If an integral is to denote an area some boundaries must be known; and nothing was said about the limits to be ascribed to x (or s , as the case might be) in the foregoing, so that we were in reality dealing with indefinite areas or integrals. To indicate that a portion of the area may be dispensed with in certain cases (when the boundaries are stated) a constant C is introduced on the R.H.S. of the equation,

i.e., $\int x^3 dx$ would be written $\frac{x^4}{4} + C$.

As soon as the integral, and therefore the area, is made definite it will be observed that C vanishes.

If $\int x^3 dx$ is to equal $\frac{1}{4}x^4 + C$, $\frac{d}{dx}\left(\frac{1}{4}x^4 + C\right)$ should equal x^3 ; and this is the case for—

$$\frac{d}{dx}\left(\frac{1}{4}x^4 + C\right) = \frac{d}{dx}\frac{1}{4}x^4 + \frac{d}{dx}C = x^3 + 0 = x^3$$

(C being independent of x).

Cf. Example 5, p. 129; the constant in that case being 83.

It is therefore advisable to add the constant in all examples on integration; in many practical examples the determination of the value of the constant is an important feature, and therefore its omission would invalidate the results obtained.

In the list of a few of the simpler standard integrals collected together here for purposes of reference and by way of revision the constant is denoted by C.

$\int(ax^n + b)dx$	$= \frac{x^{n+1}}{n+1} + bx + C$
$\int ax^n dx$	$= \frac{a}{n+1}x^{n+1} + C$
$\int bdx$	$= bx + C$
$\int \frac{dx}{x}$	$= \log x + C$
$\int \frac{dx}{ax+b}$	$= \frac{1}{a} \log (ax+b) + C$
$\int ae^{bx} dx$	$= \frac{a}{b}e^{bx} + C$
$\int e^x dx$	$= e^x + C$
$\int a^x dx$	$= \frac{1}{\log a} \times a^x + C$
$\int \sin(ax+b)dx$	$= -\frac{1}{a} \cos(ax+b) + C$
$\int \sin x dx$	$= -\cos x + C$
$\int \cos(ax+b)dx$	$= \frac{1}{a} \sin(ax+b) + C$
$\int \cos x dx$	$= \sin x + C$
$\int \sec^2(ax+b)dx$	$= \frac{1}{a} \tan(ax+b) + C$
$\int \sec^2 x dx$	$= \tan x + C$
$\int \operatorname{cosec}^2(ax+b)dx$	$= -\frac{1}{a} \cot(ax+b) + C$

$$\begin{aligned}
 \int \operatorname{cosec}^2 x dx &= -\cot x + C \\
 \int \tan(ax+b) dx &= -\frac{1}{a} \log \cos(ax+b) + C \\
 \int \tan x dx &= -\log(\cos x) + C \\
 \int \cot(ax+b) dx &= \frac{1}{a} \log \sin(ax+b) + C \\
 \int \cot x dx &= \log(\sin x) + C.
 \end{aligned}$$

Method of Determining the Values of Definite Integrals.

—We may regard the area of a closed figure as the difference between two areas, viz., all the area to the left, say, of one boundary, minus all the area to the left of the other parallel boundary.

Hence to find the value of a definite integral, the value of the integral must be found when the I.V. has its higher limiting value, and from this must be subtracted its value when the lower limiting value is substituted for the I.V.

$\int x^2 dx = \frac{1}{3}x^3 + C$ is an indefinite integral, but if to C we give a definite value, it becomes definite and unique.

Thus $\int_2^4 x^2 dx$ is a definite integral, because the limits to be applied to x are indicated.

To evaluate it—

We know that

$$\int x^2 dx = \frac{1}{3}x^3 + C.$$

The value of this integral when $x = 4$ is $\frac{64}{3} + C$

and the value of this integral when $x = 2$ is $\frac{8}{3} + C$

the constant being the same in the two cases.

$$\text{The difference} = \left(\frac{64}{3} + C\right) - \left(\frac{8}{3} + C\right) = \frac{56}{3}$$

$$\int_2^4 x^2 dx = \frac{56}{3} = 18\frac{2}{3}$$

meaning that if the curve $y = x^2$ were plotted, and the area between the curve, the x axis and the ordinates through $x = 2$ and $x = 4$ found, its value would be $18\frac{2}{3}$ sq. units.

It will be noticed that C vanishes, and hence when dealing with definite integrals it is usual to omit it altogether.

For brevity, $\int_2^4 x^2 dx$ is written $\left(\frac{x^3}{3}\right)_2^4$, which on expansion reads—

$$\left(\frac{4^3}{3} - \frac{2^3}{3}\right), \text{ i.e., } \frac{56}{3}.$$

Example 16.—Find the value of the definite integral $\int_{-1}^{-4} e^{3x} dx$.

$$\begin{aligned}\int_{-1}^{-4} e^{3x} dx &= \left(\frac{4}{3} e^{3x}\right)_{-1}^{-4} = \frac{4}{3} (e^{3x})_{-1}^{-4} \\&= \frac{4}{3} (e^{3 \times -4} - e^{3 \times -1}) \\&= \frac{4}{3} (e^{12} - e^3) \\&= \frac{4}{3} (3.3201 - 1.3499) \\&= \underline{\underline{2.625}}.\end{aligned}$$

Example 17.—Evaluate the definite integral

$$\int_{\pi}^{\frac{\pi}{2}} (5 \cos 4x + 7) dx$$

$$\begin{aligned}\int_0^{\frac{\pi}{2}} (5 \cos 4x + 7) dx &= \left(\frac{5}{4} \sin 4x + 7x\right)_0^{\frac{\pi}{2}} \\&= \left(\frac{5}{4} \sin \frac{4\pi}{2} + \frac{7\pi}{2} - \frac{5}{4} \sin 4 \times 0 - 7 \times 0\right) \\&= \left(0 + \frac{7\pi}{2} - 0 - 0\right)\end{aligned}$$

Example 18.—Find the value of

$$\frac{\int_2^4 5x^5 dx}{\int_2^4 5x^3 dx}.$$

The expression

$$\begin{aligned}&\frac{5 \int_2^4 x^5 dx}{5 \int_2^4 x^3 dx} = \frac{\left(\frac{x^6}{6}\right)_2^4}{\left(\frac{x^4}{4}\right)_2^4} \\&= \frac{\frac{1}{6} (4^6 - 2^6)}{\frac{1}{4} (4^4 - 2^4)} = 11.2.\end{aligned}$$

Notice that no cancelling takes place, beyond that concerning the constant multiplier 5, until the values (4 and 2) have been substituted in place of x . In other words, it would be quite wrong to say—

$$\frac{\left(\frac{6}{x^4}\right)^4}{\left(\frac{x^4}{4}\right)_2} = \left(\frac{2}{3}x^8\right)_2^4 = \frac{2}{3}(12) = 8$$

Example 19.—The total range of an aeroplane in miles can be obtained from the expression $-\int_1^q \frac{m}{q} dq$ where m = pound-miles per lb. of petrol, and $q = \frac{\text{loading at any time}}{\text{initial loading}}$.

Taking $q = .6$ and $m = 4000$, find the total range.

$$\begin{aligned} -\int_1^q \frac{m}{q} dq &= -m \int_1^q \frac{dq}{q} = -m (\log q)_1^q \\ &= -m (\log q - \log 1) \\ &= -m \log q. \end{aligned}$$

Now if $q = .6$, $\log q = 1.4892 = -.5108$.

Hence the range = $4000 \times .5108 = \underline{\underline{2043 \text{ miles}}}$.

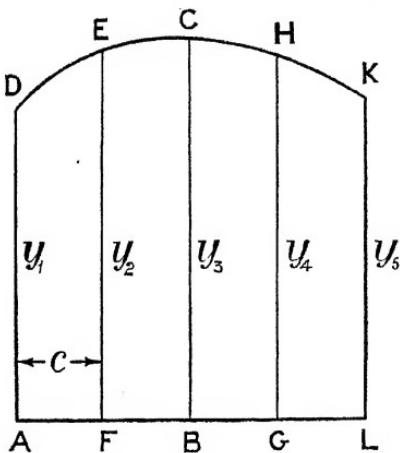


FIG. 35.—Proof of Simpson's Rule.

Proof of Simpson's Rule for the Determination of Areas of Irregular Curved Figures.—This rule, given on p. 310 of Part I, states that—

$$\text{Area} = \frac{\text{length of one division of the base}}{3} \left[\begin{array}{l} \text{first + last ordinate +} \\ 4 \sum \text{even ordinates +} \\ 2 \sum \text{odd ordinates.} \end{array} \right]$$

It is now possible to give the proof of this rule.

Let us deal with a portion of the full area to be measured, such as ABCD in Fig. 35. Let the base AB = $2c$.

Let the equation of the curve DEC be $y = A + Bx + Cx^2$, so that DEC is a portion of some parabola.

We can assume that the origin is at F, and therefore the abscissae of D, E and C are $-c$, 0 and $+c$ respectively.

$$\text{Hence } AD = y_1 = A + B(-c) + C(-c)^2 = A - Bc + Cc^2$$

$$FE = y_2 = A + B(0) + C(0)^2 = A$$

$$BC = y_3 = A + B(c) + C(c)^2 = A + Bc + Cc^2.$$

$$\text{Now the area } ABCD = \int_{-c}^{+c} y dx$$

$$= \int_{-c}^{+c} (A + Bx + Cx^2) dx$$

$$= \left[Ax + \frac{Bx^2}{2} + \frac{Cx^3}{3} \right]_{-c}^{+c}$$

$$= Ac + \frac{Bc^2}{2} + \frac{Cc^3}{3} + Ac - \frac{Bc^2}{2} - \frac{Cc^3}{3}$$

$$= 2Ac + \frac{2Cc^3}{3}$$

$$= \frac{c}{3} \{6A + 2Cc^2\}$$

$$= \frac{c}{3} \{A - Bc + Cc^2 + 4A + A + Bc + Cc^2\}$$

$$= \frac{c}{3} \{y_1 + 4y_2 + y_3\}$$

Imagine now another strip of total width $2c$ added to the right of BC; the double width being chosen, since there must be an even number of divisions of the base.

Then if GH = y_4 and LK = y_5

$$\text{Area of BLKC} = \frac{c}{3} \{y_3 + 4y_4 + y_5\}.$$

$$\text{or area of ALKD} = \frac{c}{3} \{y_1 + 4y_2 + y_3 + y_3 + 4y_4 + y_5\}$$

$$= \frac{c}{3} \{y_1 + y_5 + 4(y_2 + y_4) + 2(y_3)\}.$$

If a strip of width = $2c$ is added to the right—

$$\text{Area} = \frac{c}{3} \{y_1 + y_7 + 4(y_2 + y_4 + y_6) + 2(y_3 + y_5)\}.$$

Or, in general—

$$\text{Area} = \frac{c}{3} \{ \text{first} + \text{last} + 4 \sum \text{even} + 2 \sum \text{odd} \}.$$

Exercises 14.—On the Evaluation of Definite Integrals.

Find the values of the definite integrals in Nos. 1 to 7.

1. $\int_{1.02}^{1.16} x^3 dx.$

2. $\int_{1.7}^{2.4} \frac{dv}{v}.$

3. $\int_{-2}^{+55} e^{4s} ds.$

4. $\int_0^3 5 \cdot 1 \sin 2\theta d\theta.$

5. $\int_{-3}^{-46} 2t^{1.7} dt.$

6. $\int_{2.3}^{2.7} 5 \cdot 2^{4.1x} dx.$

7. $\int_1^3 x^{1.74} dx$
 $\int_3^8 x^{.44} dx$

8. The change in entropy of a gas as the absolute temperature changes from 643 to 775 is given by $\int_{643}^{775} 85 \frac{d\tau}{\tau}$. Find this change.

9. If $H = \frac{2I}{\rho} \int_0^{\frac{\pi}{2}} \sin \theta d\theta$, find the value of H.

10. The average useful flux density (for a 3-phase motor)

$$= B = \frac{I}{\pi r} \int_{\frac{\pi}{12}}^{\frac{5\pi}{12}} I \sin \theta d\theta. \text{ Find } B \text{ in terms of } B_{max}.$$

11. Express $\sin at \cos bt$ as the sum of two terms and integrate with regard to t. If a is $\frac{2\pi}{T}$ and b is 3a, what is the value of the integral between the limits 0 and T?

12. If $v_1 r_1^2 \int_{R_1}^{R_2} \frac{dr}{r^3}$, find h.

13. Given that $EI \frac{d^2y}{dx^2} = \frac{wlx}{2} - \frac{wx^2}{2} - Px$. Also that $\frac{dy}{dx} = 0$ when $x = l$, and $y = 0$ when $x = 0$ and also when $x = l$; find the value of P and an expression for y.

14. If $M = \frac{wx^2}{2}$, $I = E \frac{d^2y}{dx^2}$, $\frac{dy}{dx} = 0$ and also $y = 0$ when $x = l$, find an expression for y.

15. Given that $M = \frac{w}{2} \left(\frac{l^2}{4} - x^2 \right) - K$, $\frac{M}{IE} = \frac{d^2y}{dx^2}$. Also $\frac{dy}{dx} = 0$ when $x = \frac{l}{2}$, and $y = 0$ when $x = \pm \frac{l}{2}$; find an expression for y. (The case of a fixed beam uniformly loaded.)

16. Find the value of $\int_0^l (lx - x^2)^2 dx$.

17. Evaluate $3 \int_{-2l}^l x(l^2 - 2lx + x^2) dx$, an integral occurring in a beam problem.

18. If $Q = \int_0^h q dx$ and $q = \frac{1 - \sin \phi}{1 + \sin \phi} wx$, find Q , the total horizontal thrust on a retaining wall of height h , w being the weight of 1 cu. ft. of earth, and ϕ the angle of repose of the earth.

19. Find the area between the positive portion of the curve $y = 3x - 4x^2 + 11$ and the axis of x , and compare with the area of the surrounding rectangle.

20. Evaluate $\int_{4.6}^{15.8} p dv$ when $p v^{1.37} = 594$.

21. If $\frac{d^2y}{dx^2} = 6x^{1.4} - \frac{5}{x^2}$; $\frac{dy}{dx} = 10.5$ when $x = 1$, and $y = 14$ when $x = 2$, find an expression for y in terms of x .

22. Evaluate $\int_{1.47}^{2.31} \frac{4}{13 - 5x} dx$.

23. Find the value of n , given by the relation $n = \int_0^l \frac{Neax dx}{l}$.

24. The total centrifugal force on a ring $= \int_{R_2}^{R_1} \frac{2\pi w V_1^2 r^2 dr}{R_1^2}$; find an expression for the force.

25. The area of a bending moment diagram in a certain case was given by $-\int_0^l \left(\frac{1}{2}al - \frac{a^3}{2l} \right) da$; find the value of this area.

26. H, the horizontal thrust on a parabolic arch,

$$= \frac{5wl^2}{8r} \int_0^{\frac{l}{2}} (x^2 - 2x^3 + x^4) dx.$$

Find an expression for H.

27. The work done by an engine working on the Rankine cycle with steam kept saturated $= \int_{\tau_2}^{\tau_1} \frac{L}{\tau} d\tau$.

Find the work done if the temperature limits are 620° F. and 800° F. (both absolute), and $L = 1437 - 7\tau$.

28. Evaluate $\int_1^{2.4} [e^{-5s} - \sin(2s - 7)] ds$.

29. Find the value of n , the frequency of transverse vibrations of a beam simply supported at its ends and uniformly loaded with w tons per foot run, when the equation of the deflected form is—

$$y = \frac{w}{24EI} (x^4 - 2lx^3 + l^3x)$$

and

$$\frac{\int_0^l y dx}{\int_0^l y^2 dx}$$

30. From Dieterici's experiments we have the following relations—

If s = specific volume of liquid ammonia
and c = specific heat of liquid ammonia

then for temperatures above 32° F.—

$$c = 1.118 + 0.001156(t - 32)$$

and

$$s = \int_0^t c dt.$$

Find s when $t = 45^{\circ}$ F.

31. If $Q = \frac{\pi dtp}{8l\mu} \int_0^s (s^2 - x^2) dx$, Q being the leakage of fluid past a well-fitting plug, find its value.

32. The total ampere conductors per pole due to the three windings in a railway motor = $\frac{3}{2}C\sqrt{2} \int_0^{l/2h} A_1 \sin \frac{\pi x}{l} dx$.

Evaluate this integral.

33. For a viscous fluid flowing through a narrow cylindrical tube of radius r , the quantity Q is given by the formula—

$$Q = \int_0^a \frac{\pi f(a^2 - r^2) r dr}{2\mu}$$

where μ is the coefficient of viscosity.

Find the value of Q .

34. If $u = \frac{4\pi l}{10} \left[\int_x^{x_1} \frac{dx}{\pi x} + \frac{y}{2x} \right]$ find its value.

35. Find the area between the curve $y = 2x^3 - 11x^2 - 21x + 90$, the axis of x , and the ordinates through $x = -3$ and $x = 7$.

Evaluate $Q = \frac{8B}{H} \int_0^H (H-h) h^{\frac{1}{3}} dh$ when $B = 1.5$ and $H = .6$.

CHAPTER VI

FURTHER METHODS OF INTEGRATION

By the use of the rules enumerated in the previous chapter it is possible to perform any integration by a graphic method and the integration of the simpler functions by algebraic processes. Whilst the graphic integration is of universal application, it at times involves much preliminary arithmetical work, which it is tedious to perform, so that it is very frequently the better plan to resort to a somewhat more difficult, though shorter, algebraic method. For the more complex functions, then, a choice has to be made between the two methods of attack; the fact being borne in mind that only in cases where *definite integrals* are concerned does the graphic method of integration compare favourably with the algebraic.

It is therefore advisable to introduce new processes and artifices to be employed for the algebraic integration of difficult functions; and whilst it is not absolutely essential that all these forms should be remembered, it is well that the various types should be considered, so that they may be recognised when they occur.

It is impossible to deal here with every kind of integral likely to be encountered; all that can be done is to develop the standard forms which cover a wide range, and to leave them to suggest forms for particular cases.

Integration by the Aid of Partial Fractions.—Many complex fractions can be split up into simpler or partial fractions, to which the simple rules of integration may be applied. Thus if we are asked to integrate, with respect to x , the fraction $\frac{8x-30}{2x^2-15x+28}$, we soon discover that we are unable to perform this operation with only the knowledge of integration acquired from the previous chapter.

If, however, we break the fraction up, in the manner explained in Part I, Chap. XII, we find that the integration resolves itself into that of two simple fractions.

Thus— $\frac{8x-30}{2x^2-15x+28} = \frac{2}{x-4} + \frac{4}{2x-7}$ (see Part I, p. 453).

Hence— $\int \frac{8x-30}{2x^2-15x+28} dx = \int \frac{2}{x-4} dx + \int \frac{4}{2x-7} dx$
 $= 2 \log(x-4) + \frac{4}{2} \log(2x-7) + \log C$
 $= \log(x-4)^2 + \log(2x-7)^2 + \log C$
 $= \log\{C(x-4)^2(2x-7)^2\}.$

[Note that $\log C$ may be written to represent the constant in place of C alone; and it can then be combined with the other logs.]

Example 1.—Find the value of $\int \frac{dx}{x^2}$

Let

$$\begin{aligned} x^2 - a^2 &= (x-a)(x+a) \\ &= \frac{A(x+a) + B(x-a)}{x^2 - a^2}. \end{aligned}$$

Equating numerators—

$$I = A(x+a) + B(x-a).$$

Let $x = a$, then

$$I = A(2a) + 0$$

$$\text{and } A = \frac{I}{2a}.$$

Let $x = -a$, then

$$I = 0 + B(-2a)$$

$$\text{and } B = -\frac{I}{2a}$$

$$x^2 - a^2 = 2a(x-a-x+a).$$

Hence—

$$\begin{aligned} \int \frac{dx}{x^2 - a^2} &= \frac{I}{2a} \left\{ \int \frac{dx}{x-a} - \int \frac{dx}{x+a} \right\} \\ &= \frac{I}{2a} \{ \log(x-a) - \log(x+a) + \log C \} \\ &= \frac{I}{2a} \log \frac{C(x-a)}{(x+a)}. \end{aligned}$$

This is a standard form.

A rather more general result may be deduced from it.

Example 2.—To find $\int \frac{dx}{(x+a)^2 - b^2}$.

Explanation.

Let $(x+a) = X$

$$x+a = X$$

Then— $\int \frac{dx}{(x+a)^2 - b^2} = \int \frac{dX}{X^2 - b^2}$

$$\begin{aligned} &= \frac{I}{2b} \log \frac{C(X-b)}{(X+b)} \\ &= \frac{I}{2b} \log \frac{C(x+a-b)}{(x+a+b)}. \end{aligned}$$

$\frac{d}{dx}(x+a) = \frac{dX}{dx}$

$I = \frac{dX}{dx}$

and thus for dx we may write dX .

Integration by the Resolution of a Product into a Sum.—A product cannot be integrated directly; but when the functions are trigonometric the product can be broken up into a sum or difference and the terms of this integrated.

Before proceeding with the work of this paragraph the reader would do well to study again pp. 273 to 286, Part I.

Example 3.—Find the value of $\int_4 \sin 5t \cdot 3 \cos 2t dt$.

$$\begin{aligned} 4 \sin 5t \cdot 3 \cos 2t &= 12 \sin 5t \cos 2t \\ &= 6 \times 2 \sin 5t \cos 2t \\ &= 6\{\sin 7t + \sin 3t\} \quad (\text{cf. p. 286, Part I}). \end{aligned}$$

Hence—

$$\begin{aligned} \int_4 \sin 5t \cdot 3 \cos 2t dt &= 6[\int \sin 7t dt + \int \sin 3t dt] \\ &= 6\left[-\frac{1}{7} \cos 7t - \frac{1}{3} \cos 3t + C\right] \\ &= 6C - \frac{6}{7} \cos 7t - 2 \cos 3t. \end{aligned}$$

Example 4.—Find $\int \sin^2 x dx$.

$$\begin{aligned} \cos 2x &= 1 - 2 \sin^2 x, \text{ so that—} \\ \sin^2 x &= \frac{1 - \cos 2x}{2} \quad (\text{cf. p. 280, Part I}) \end{aligned}$$

$$\begin{aligned} \int \sin^2 x dx &= \frac{1}{2} [\int 1 dx - \int \cos 2x dx] \\ &= \frac{1}{2} \left[x - \frac{1}{2} \sin 2x + C \right] \\ &= .5x - .25 \sin 2x + .5C. \end{aligned}$$

Example 5.—Find $\int \tan^2 x dx$.

We know that $\sec^2 x = 1 + \tan^2 x$.

$$\begin{aligned} \therefore \int \tan^2 x dx &= \int (\sec^2 x - 1) dx = \int \sec^2 x dx - \int 1 dx \\ &= \underline{\tan x} - x + C. \end{aligned}$$

Integration by Substitution.—At times a substitution aids the integration, but the cases in which this happens can only be distinguished after one has become perfectly familiar with the different types.

$\int \frac{(2ax+b)dx}{ax^2+bx+c}$ is a type to which this method applies.

In this fraction it will be observed that the numerator is exactly the differential of the denominator. Hence if u be written for the

denominator, the numerator may be replaced by du , so that the integral reduces to the simple form $\int \frac{du}{u}$, i. e., $\log u + \log C$.

For if

$$u = ax^2 + bx + c$$

$$\frac{du}{dx} = 2ax + b$$

or

$$du = (2ax + b)dx.$$

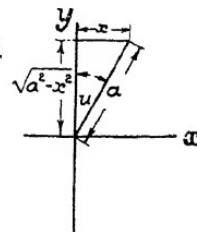
Hence

$$\begin{aligned}\int \frac{(2ax+b)dx}{ax^2+bx+c} &= \int \frac{du}{u} \\ &= \log u + \log C \\ &= \log Cu \\ &= \underline{\underline{\log C(ax^2+bx+c)}}.\end{aligned}$$

In many cases integration may be effected by substitution of trigonometric for the algebraic functions; and Examples 6 to 10 illustrate this method of procedure.

Example 6.—To find $\int \sqrt{a^2 - x^2} dx$.

FIG. 36.



Let $x = a \sin u$, as illustrated by Fig. 36

then $a^2 - x^2 = a^2 - a^2 \sin^2 u = a^2(1 - \sin^2 u) = a^2 \cos^2 u$

and $\sqrt{a^2 - x^2} = a \cos u$, as will be seen from the figure.

Also $\frac{dx}{du} = \frac{d(a \sin u)}{du} = a \cos u$

i. e., $dx = a \cos u \cdot du$.

$$\begin{aligned}\therefore \int \sqrt{a^2 - x^2} dx &= \int a \cos u \cdot a \cos u \, du \\ &= a^2 \int \cos^2 u \, du \\ &= \frac{a^2}{2} \int (1 + \cos 2u) \, du, \text{ since } \cos 2A = 2 \cos^2 A - 1 \\ &= \frac{a^2}{2} \left(u + \frac{1}{2} \sin 2u + C \right).\end{aligned}$$

Although this result is not expressed in terms of x , it is left in a form convenient for many purposes.

To express the result in terms of x —

$$\sin u = \frac{x}{a}, \text{ so that } u = \sin^{-1} \frac{x}{a}$$

$$\text{and also } \cos u = \sqrt{\frac{a^2 - x^2}{a^2}}.$$

Hence $\frac{1}{2} \sin 2u = \sin u \cos u = \frac{x}{a} \times \frac{1}{a} \sqrt{a^2 - x^2}$

$$\therefore \int \sqrt{a^2 - x^2} dx = \left(\frac{a^2}{2} \times \sin^{-1} \frac{x}{a} \right) + \left(\frac{a^2}{2} \times \frac{x}{a^2} \sqrt{a^2 - x^2} \right) + K$$

$$= \frac{a^2}{2} \sin^{-1} \frac{x}{a} + \frac{x}{2} \sqrt{a^2 - x^2} + K.$$

Example 7.—To find $\int \frac{dx}{\sqrt{a^2 - x^2}}$

Let $x = a \sin u$ i. e., $u = \sin^{-1} \frac{x}{a}$
then $\frac{dx}{du} = \frac{d(a \sin u)}{du} = a \cos u$
also $\sqrt{a^2 - x^2} = a \cos u$, as before.

$$\int \frac{dx}{\sqrt{a^2 - x^2}} = \int \frac{a \cos u \cdot du}{a \cos u} = \int du$$

$$= u + C$$

$$\therefore \sin^{-1} \frac{x}{a} + C.$$

Example 8.—To find $\int \frac{dx}{\sqrt{a^2 + x^2}}$

In this case let $x = a \sinh u$, i. e., $u = \sinh^{-1} \frac{x}{a}$
then $\frac{dx}{du} = \frac{d}{du}(a \sinh u) = a \cosh u$.
Now $\cosh^2 u - \sinh^2 u = 1$ (cf. p. 291, Part I)
and thus $\cosh^2 u = 1 + \sinh^2 u$

$$= 1 + \frac{x^2}{a^2}$$

$$= \frac{a^2 + x^2}{a^2}$$

or $a^2 + x^2 = a^2 \cosh^2 u$
and $\sqrt{a^2 + x^2} = a \cosh u$.

$$\therefore \int \frac{dx}{\sqrt{a^2 + x^2}} = \int \frac{a \cosh u \cdot du}{a \cosh u} = \int 1 du = u + C$$

$$\therefore \sinh^{-1} \frac{x}{a} + C.$$

Referring to p. 298, Part I, we see that—

$$\cosh^{-1} \frac{x}{a} = \log \left\{ \frac{x + \sqrt{x^2 - a^2}}{a} \right\}$$

and also $\sinh^{-1} \frac{x}{a} = \log \left\{ \frac{x + \sqrt{x^2 + a^2}}{a} \right\}$.

$$\therefore \int \frac{dx}{\sqrt{a^2 + x^2}} = \sinh^{-1} \frac{x}{a} + C \text{ or } \log \left\{ \frac{x + \sqrt{x^2 + a^2}}{a} \right\} + C$$

Example 9.—Find the value of $\int \frac{dx}{\sqrt{x^2-a^2}}$ and thence the value of $\int \frac{dx}{\sqrt{(x+a)^2-b^2}}$.

Dealing with the first of these—

$$\text{let } x = a \cosh u, \quad i.e., \quad u = \cosh^{-1} \frac{x}{a}$$

$$\frac{dx}{du} = a \sinh u$$

$$\text{or } dx = a \sinh u du$$

$$\text{and } x^2 - a^2 = a^2 \cosh^2 u - a^2 = a^2 (\cosh^2 u - 1) = a^2 \sinh^2 u$$

$$\therefore \int \frac{dx}{\sqrt{x^2-a^2}} = \int \frac{dx}{a \sinh u} = \int \frac{a \sinh u du}{a \sinh u}$$

$$= \int du$$

$$= u + C$$

$$= \cosh^{-1} \frac{x}{a} + C$$

$$= \underline{\log \left\{ \frac{x+\sqrt{x^2-a^2}}{a} \right\} + C.}$$

To evaluate the second integral, let $x+a = X$

$$\begin{aligned} \text{then } dx &= dX \text{ and } \int \frac{dx}{\sqrt{(x+a)^2-b^2}} = \int \frac{dX}{\sqrt{X^2-b^2}} \\ &= \log \left\{ \frac{X+\sqrt{X^2-b^2}}{b} \right\} + C \end{aligned}$$

$$= \underline{\log \left\{ \frac{x+a+\sqrt{(x+a)^2-b^2}}{b} \right\} + C.}$$

Example 10.—Find the value of $\int \frac{dx}{a^2+x^2}$

The substitution in this case is—

$$a \tan u \text{ for } x$$

$$i.e., \quad x = a \tan u \quad \text{or} \quad u = \tan^{-1} \frac{x}{a}$$

$$\text{then } \frac{dx}{du} = \frac{d}{dx} (a \tan u) = a \sec^2 u$$

$$\text{and } x^2 + a^2 = a^2 \tan^2 u + a^2 = a^2 (1 + \tan^2 u) = a^2 \sec^2 u$$

$$\int \frac{dx}{a^2+x^2} = \int \frac{a \sec^2 u du}{a^2 \sec^2 u} = \frac{1}{a} \int du$$

$$= \frac{1}{a} u + C$$

$$= \frac{1}{a} \tan^{-1} \frac{x}{a} + C.$$

By an extension of this result such an integral as $\int \frac{dx}{(x+a)^2+b^2}$ may be evaluated; for let $x+a = X$

$$\text{then } \frac{dX}{dx} = \frac{d(x+a)}{dx} = 1$$

$$\text{i.e., } dX = dx$$

$$\text{hence } \int \frac{dx}{(x+a)^2+b^2} = \int \frac{dX}{X^2+b^2} = \frac{1}{b} \tan^{-1} \frac{X}{b} + C$$

$$\text{i.e., } \frac{1}{b} \tan^{-1} \frac{x+a}{b} + C.$$

The following examples are illustrative of algebraic substitution or transformation.

Example 11.—To find the value of $\int \frac{dx}{\sqrt{2ax-x^2}}$.

Our plan in this case is so to arrange the integral that the method of a previous example may be applied.

$$\begin{aligned} 2ax-x^2 &= a^2-x^2-a^2+2ax \\ &= a^2-(x-a)^2. \end{aligned}$$

$$\text{Hence } \int \frac{dx}{\sqrt{2ax-x^2}} = \int \frac{dx}{\sqrt{a^2-(x-a)^2}} = \int \frac{dX}{\sqrt{a^2-X^2}}$$

the change from dx to dX being legitimate, since $\frac{dX}{dx} = \frac{d(x-a)}{dx} = 1$ and by *Example 7*, p. 150, the value of this integral is seen to be—

$$\sin^{-1} \frac{X}{a} + C.$$

$$\therefore \int \frac{dx}{\sqrt{2ax-x^2}} = \sin^{-1} \frac{X}{a} + C.$$

Example 12.—To find $\int \frac{dx}{(a^2+x^2)^{\frac{3}{2}}}.$

In this case the substitution is entirely algebraic.

$$\text{Let } u = \frac{1}{x} \text{ then } \frac{du}{dx} = -\frac{1}{x^2}$$

$$\text{or } dx = -x^2 du.$$

$$\begin{aligned} \text{Then } (a^2+x^2)^{\frac{3}{2}} &= \left(a^2+\frac{1}{u^2}\right)^{\frac{3}{2}} = (a^2u^2+1)^{\frac{3}{2}} \times \frac{1}{u^3} \\ &= (a^2u^2+1)^{\frac{3}{2}} \times x^3. \end{aligned}$$

$$\begin{aligned} \therefore \int \frac{dx}{(a^2+x^2)^{\frac{3}{2}}} &= \int \frac{-x^2 du}{(a^2u^2+1)^{\frac{3}{2}} \times x^3} = -\int \frac{du}{x(a^2u^2+1)^{\frac{3}{2}}} \\ &= -\int \frac{udu}{(a^2u^2+1)^{\frac{3}{2}}}. \end{aligned}$$

To evaluate this integral we must introduce another substitution.

Let

then

$$y = a^2 u^2 + 1$$

$$\frac{dy}{du} = 2a^2 u$$

or

$$udu = \frac{1}{2a^2} dy.$$

$$\text{Hence the integral} = -\frac{1}{2a^2} \int \frac{dy}{y^{\frac{1}{2}}} = -\frac{1}{2a^2} \times -2 \times \frac{1}{y^{\frac{1}{2}}} + C$$

$$\frac{1}{a^2 y^{\frac{1}{2}}} + C = \frac{1}{a^2 (a^2 u^2 + 1)^{\frac{1}{2}}} + C$$

$$\frac{1}{a^2} \times \frac{1}{(a^2 \times \frac{1}{x^2} + 1)} + C$$

$$a^2(a^2 + x^2)^{-\frac{1}{2}} + C.$$

Example 13.—The equation $\frac{dz}{dt} = \frac{At}{\sqrt{t^2 - 1}}$ occurs in the statement of the mathematical theory of fluid motion, which is of value in connection with aeroplane design. Solve the equation for z .

To obtain z from $\frac{dz}{dt}$ we must integrate with regard to t ; and to effect the integration let $u = t^2 - 1$, so that $\frac{du}{dt} = \frac{d(t^2 - 1)}{dt} = 2t$

or

$$dt = \frac{du}{2t}.$$

$$\begin{aligned} \text{Then } z &= \int \frac{At dt}{\sqrt{t^2 - 1}} = \int \frac{A t du}{u^{\frac{1}{2}} 2t} = \int \frac{A du}{2u^{\frac{1}{2}}} \\ &= A \left(\frac{1}{2} \times 2u^{\frac{1}{2}} \right) + C \\ &= Au^{\frac{1}{2}} + C \\ \text{or } &A\sqrt{t^2 - 1} + C. \end{aligned}$$

Many difficult integrals of the form $\int \frac{dx}{x(a+bx^n)}$ can be evaluated by the substitution $z = x^{-n}$.

For if $z = x^{-n}$

$$\log z = -n \log x$$

$$\frac{d \log z}{dz} = -n \frac{d \log x}{dx}$$

$$\frac{1}{z} = -n \frac{d \log x}{dx} \times \frac{dx}{dz}$$

$$\frac{1}{z} = -n \times \frac{1}{x} \times \frac{dx}{dz}$$

$$dx = -\frac{x dz}{z}$$

The integral $\int \frac{dx}{x(a+bx^n)}$ thus reduces to $-\frac{1}{n} \int \frac{dz}{(az+b)}$, the value of which is $-\frac{1}{na} \log(az+b)$ or $\frac{1}{na} \log\left(\frac{x^n}{a+bx^n}\right)$.

Example 14.—Evaluate $\int \frac{dx}{x(4+5x^7)}$.

For x^7 write z^{-1} , so that in comparison with the standard form $n = 7$.

$$\begin{aligned} \text{Then } \int \frac{dx}{x(4+5x^7)} &= -\frac{1}{7} \int \frac{dz}{4z+5} = -\frac{1}{28} \left\{ \log(4z+5) + \log C \right\} \\ &= -\frac{1}{28} \left\{ \log\left(\frac{4}{z^7} + 5\right) + \log C \right\} \\ &= -\frac{1}{28} \left\{ \log\left(\frac{4+5z^7}{z^7}\right) + \log C \right\} \\ &= -\frac{1}{28} \left\{ \log \frac{C(4+5z^7)}{z^7} \right\} \\ &= \frac{1}{28} \log\left(\frac{z^7}{C(4+5z^7)}\right). \end{aligned}$$

Example 15.—Find the value of $\int \frac{x^4 dx}{(1-2x)^{\frac{1}{2}}}$.

It will be observed that the denominator is a surd quantity; and in many such cases it is advisable to choose a substitution that rationalises the denominator. Thus in this case let $u^2 = 1-2x$.

$$\begin{aligned} \text{Then } -\frac{du^2}{dx} &\times \frac{du^2}{du} \times \frac{du}{dx} = 2u \frac{du}{dx} \\ \text{and } \frac{du}{dx}(1-2x) &= -2 \\ \text{so that } u \frac{du}{dx} &= -2 \quad \text{or} \quad dx = -udu. \end{aligned}$$

$$\text{Also } 1-2x = u^2, \quad \text{whence } \frac{1-u^2}{2} = x \text{ and } x^4 = \left(\frac{1-u^2}{2}\right)^4.$$

Expanding by the Binomial Theorem—

$$x^4 = \frac{1}{16}(1-4u^2+6u^4-4u^6+u^8).$$

$$\begin{aligned} \text{Hence } \int \frac{x^4 dx}{(1-2x)^{\frac{1}{2}}} &= \frac{1}{16} \int \frac{(1-4u^2+6u^4-4u^6+u^8) \times -udu}{u} \\ &= -\frac{1}{16} \left(u - \frac{4u^3}{3} + \frac{6u^5}{5} - \frac{4u^7}{7} + \frac{u^9}{9} \right) + C \\ &= -\frac{u}{16} \left(\frac{1-4u^2}{3} + \frac{6u^4}{5} - \frac{4u^6}{7} + \frac{u^8}{9} \right) + C \\ &= -\frac{(1-2x)^{\frac{1}{2}}}{16} \left[\frac{1}{3} - \frac{4}{3}(1-2x) + \frac{6}{5}(1-2x)^2 - \frac{4}{7}(1-2x)^3 + \frac{1}{9}(1-2x)^4 \right] + C \end{aligned}$$

which result could be further simplified if desired.

The next example introduces the substitution of an algebraic for a trigonometric function.

Example 16.—To find the value of $\int \frac{dx}{\sin x}$

Since $\sin 2A = 2 \sin A \cos A$, then $\sin x = 2 \sin \frac{x}{2} \cos \frac{x}{2}$.

$$\text{Hence } \int \frac{dx}{\sin x} = \frac{1}{2} \int \frac{dx}{\sin \frac{x}{2} \cos \frac{x}{2}} = \frac{1}{2} \int \frac{\frac{dx}{\sin \frac{x}{2} \times \cos^2 \frac{x}{2}}}{\cos \frac{x}{2}} \\ = \frac{1}{2} \int \frac{\sec^2 \frac{x}{2} dx}{\tan \frac{x}{2}}$$

Now let

$$u = \tan \frac{x}{2}$$

then

$$\frac{du}{dx} = \frac{1}{2} \sec^2 \frac{x}{2}$$

or

$$dx = \frac{2du}{\sec^2 \frac{x}{2}}$$

$$\int \frac{dx}{\sin x} = \frac{1}{2} \int \frac{\sec^2 \frac{x}{2} \cdot 2du}{\sec^2 \frac{x}{2} \cdot u} \\ = \int \frac{du}{u} = \log u + C$$

$$= \log \tan \frac{x}{2} + C.$$

Integration by Parts.—When differentiating a product, use is made of the rule—

$$\frac{d}{dx}(uv) = v \frac{du}{dx} + u \frac{dv}{dx} \quad \{ \text{Refer p. 70.} \}$$

If this equation be integrated throughout, with respect to x —

$$uv = \int v du + \int u dv$$

or, transposing—

$$\int u dv = uv - \int v du.$$

Many products may be integrated by the use of this rule.

Example 17.—To find $\int 4x \cdot e^{4x} dx$.

Let

$$u = 4x, \text{ i.e., } du = 4dx$$

and let

$$dv = e^{4x} dx, \text{ i.e., } v = \frac{1}{4} e^{4x}$$

Then

$$\int 4x \cdot e^{4x} dx = \int u dv$$

$$= uv - \int v du$$

$$= 4x \cdot e^{4x} - \int e^{4x} \cdot 4dx$$

$$= 4x \cdot e^{4x} - 4e^{4x} + C.$$

Example 18.—Find $\int 5x^2 \cdot e^{4x} dx$.

Let

$$u = 5x^2, \text{ i.e., } du = 10x dx$$

and

$$dv = e^{4x} dx, \text{ i.e., } v = \frac{1}{4} e^{4x}$$

Then

$$\int 5x^2 \cdot e^{4x} dx = \int u dv$$

$$= uv - \int v du$$

$$= 5x^2 \cdot \frac{1}{4} e^{4x} - \int \frac{1}{4} e^{4x} \cdot 10x dx$$

$$= \frac{5}{4} x^2 \cdot e^{4x} - \frac{5}{2} \int x e^{4x} dx$$

| Now

$$\int x e^{4x} dx = x \cdot \frac{1}{4} e^{4x} - \int \frac{1}{4} e^{4x} dx$$

$$= \frac{1}{4} x \cdot e^{4x} - \frac{1}{16} e^{4x}$$

$$\int 5x^2 \cdot e^{4x} dx = \frac{5}{4} x^2 \cdot e^{4x} - \frac{5}{2} \left(\frac{1}{4} x \cdot e^{4x} - \frac{1}{16} e^{4x} \right) + C$$

$$= \frac{5}{4} e^{4x} \left\{ x^2 - \frac{x}{2} + \frac{1}{8} \right\} + C.$$

[where $u = x$ and $v = \frac{1}{4} e^{4x}$]

Example 19.—To find $\int e^{ax} \sin (bx+c) dx$ and also—

$$\int e^{ax} \cos (bx+c) dx.$$

[The two integrals must be worked together.]

Dealing with the first, which we shall denote by M—

Let $u = \sin (bx+c)$, then $du = b \cos (bx+c) dx$

and $dv = e^{ax} dx$, so that $v = \int e^{ax} dx = \frac{1}{a} e^{ax}$.

$$\text{Then } M = \frac{1}{a} e^{ax} \sin (bx+c) - \int \frac{1}{a} e^{ax} b \cos (bx+c) dx$$

$$= \frac{1}{a} e^{ax} \sin (bx+c) - \frac{b}{a} \int e^{ax} \cos (bx+c) dx$$

$$= \frac{1}{a} e^{ax} \sin (bx+c) - \frac{b}{a} N. \quad$$

where N stands for the second integral whose value we are finding.

By developing this second integral along similar lines we arrive at the value—

$$N = \frac{I}{a} e^{ax} \cos (bx+c) + \frac{b}{a} M \quad \dots \dots \dots \quad (2)$$

We have thus a pair of simultaneous equations to solve.

Multiplying (1) by b and (2) by a and transposing—

$$bM = \frac{b}{a} e^{ax} \sin (bx+c) - \frac{b^2}{a} N$$

$$bM = -e^{ax} \cos (bx+c) + aN.$$

Subtracting $0 = e^{ax} \left[\frac{b}{a} \sin (bx+c) + \cos (bx+c) \right] - N \left(\frac{b^2}{a} + a \right)$

whence $N = e^{ax} \left[\frac{b \sin (bx+c) + a \cos (bx+c)}{a^2 + b^2} \right]$

and, by substitution, $M = e^{ax} \left[\frac{a \sin (bx+c) - b \cos (bx+c)}{a^2 + b^2} \right]$

$\therefore \int e^{ax} \sin (bx+c) dx = \frac{e^{ax}}{a^2 + b^2} [a \sin (bx+c) - b \cos (bx+c)] + C$

and $\int e^{ax} \cos (bx+c) dx = \frac{e^{ax}}{a^2 + b^2} [b \sin (bx+c) + a \cos (bx+c)] + C.$

Example 20.—An electric current i whose value at any time t is given by the relation $i = I \sin pt$ is passed through the two coils of a wattmeter; the resistances of the two coils being R_1 and R_2 respectively, and their respective inductances L_1 and L_2 . Then to find the separate currents in the two branches it is necessary to evaluate the integral—

$$\int Q e^{Pt} dt \quad \text{where } P = \frac{R_1 + R_2}{L_1 + L_2}$$

and $Q = \frac{R_1 I}{L_1 + L_2} \sin pt + \frac{L_1 p I}{L_1 + L_2} \cos pt.$

Evaluate this integral.

$$Q = \frac{1}{L_1 + L_2} (R_1 \sin pt + p L_1 \cos pt) = \frac{1}{L_1 + L_2} \sqrt{R_1^2 + p^2 L_1^2} \sin (pt + c)$$

where $= \tan^{-1} \frac{p L_1}{R_1}$ (see Part I, p. 276)

or $Q = M \sin (pt + c), \text{ where } M = \frac{1}{L_1 + L_2} \sqrt{R_1^2 + p^2 L_1^2}.$

Then $\int Q e^{Pt} dt = \int e^{Pt} M \sin (pt + c) dt = M \int e^{Pt} \sin (pt + c) dt$
and this integral is of the type just discussed; its value being—

$$\frac{M e^{Pt}}{P^2 + p^2} [P \sin (pt + c) - p \cos (pt + c)] + C$$

and in this form it is convenient to leave it, since in any numerical application it would be an easy matter to evaluate P , M and c before substituting into this result.

Some miscellaneous examples now follow, involving the use of the methods of this chapter.

Example 21.—Find the value of $\int_1^2 \frac{5 dx}{x^2+8x+15}$.

$$\text{Let } \frac{5}{x^2+8x+15} = \frac{A}{x+3} + \frac{B}{x+5} = \frac{A(x+5)+B(x+3)}{x^2+8x+15}$$

i.e., $5 = A(x+5) + B(x+3)$.

$$\begin{aligned}\text{Let } x &= -5, \text{ then } 5 = 0 - 2B \\ B &= -2.5.\end{aligned}$$

$$\text{Let } x = -3, \text{ then } 5 = 2A + 0$$

$$A = 2.5, \text{ i.e., } \frac{5}{x^2+8x+15} = \frac{2.5}{x+3} - \frac{2.5}{x+5}.$$

$$\begin{aligned}\therefore \int_1^2 \frac{5 dx}{x^2+8x+15} &= \int_1^2 \frac{2.5 dx}{x+3} - \int_1^2 \frac{2.5 dx}{x+5} \\ &= 2.5 \left[\log(x+3) - \log(x+5) \right]_1^2 \\ &= 2.5 [\log 5 - \log 7 - \log 4 + \log 6] \\ &= 2.5 [1.6094 - 1.9459 - 1.3863 + 1.7918] \\ &= 2.5 \times 0.69 = 1.724.\end{aligned}$$

As an alternative method of solution, the graphic process of integration possesses certain advantages in a case such as this.

It might even be advisable, in all cases of definite integrals where the algebraic integration involves rather difficult rules, to treat the question both algebraically and graphically, the latter method serving as a very good check on the accuracy of the former.

In this example $\int_1^2 \frac{5 dx}{x^2+8x+15} = 5 \int_1^2 \frac{dx}{(x+3)(x+5)}$; $\int_1^2 y dx$

where

$$y = \frac{1}{(x+3)(x+5)}$$

hence it is necessary to plot the curve $y = \frac{1}{(x+3)(x+5)}$ and find the area between it, the axis of x and the ordinates through $x = 1$ and $x = 2$.

The table for the plotting reads—

x	1	1.2	1.4	1.6	1.8	2
y	0.4167	0.3841	0.355	0.3294	0.3064	0.2857

and from these values the curve AB is plotted in Fig. 37.

The sum curve for AB is the curve CD, the last ordinate of which, measured according to the scale of area, is .0095. This figure is the area between the curve AB, the ordinates through $x = 1$ and $x = 2$, and the base line through $y = .025$; and hence the full area under the curve AB = .0095 + area of a rectangle .025 by 1, i.e., .0095 + .025 or .0345.

Thus $\int_1^2 y dx$, i.e., $\int_1^2 \frac{dx}{(x^2+8x+15)} = .0345$
 $\int_1^2 \frac{5 dx}{(x^2+8x+15)} = 5 \times .0345 = .1725.$

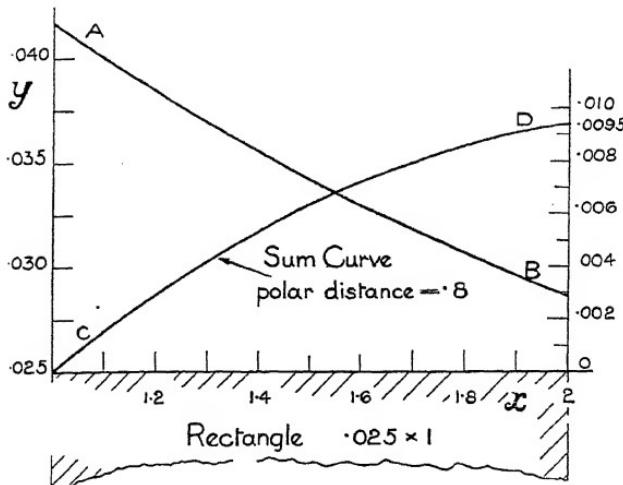


FIG. 37.—Graphic Integration of Ex. 21.

Example 22.—Find the value of $\int \frac{dx}{4x^2-9}$.

$$4x^2-9 = 4\left(x^2-\frac{9}{4}\right) = 4\left[x^2-\left(\frac{3}{2}\right)^2\right].$$

Now $\int \frac{dx}{x^2-a^2} = \frac{1}{2a} \log C \frac{(x-a)}{(x+a)}$ (see *Example 1*, p. 147)

$$\begin{aligned} \therefore \int \frac{dx}{4x^2-9} &= \frac{1}{4} \int \frac{dx}{x^2-\left(\frac{3}{2}\right)^2} = \frac{1}{2 \times \frac{3}{2}} \times \frac{1}{4} \log \frac{C \left(x - \frac{3}{2}\right)}{\left(x + \frac{3}{2}\right)} \\ &= \frac{1}{12} \log \frac{C(2x-3)}{2x+3} \\ \text{or } \log \left\{ \frac{C(2x-3)}{(2x+3)} \right\}^{\frac{1}{12}} \end{aligned}$$

Example 23.—Find the value of $\int_{\frac{1}{4}}^{\frac{7}{4}} \frac{72x-20}{9x^2-5x+12} dx$.

In this case the numerator is of the first degree in x , whilst the denominator is of the second degree. Also we notice that the derivative of the denominator is $18x-5$, and the numerator is $4(18x-5)$. Thus the derivative of the denominator and the numerator are alike except as regards the constant factor 4. Hence the substitution will be u for $9x^2-5x+12$.

$$\text{If } u = 9x^2 - 5x + 12, \frac{du}{dx} = 18x - 5 \text{ or } du = (18x - 5)dx$$

$$\text{that } (72x-20)dx = 4(18x-5)dx = 4du$$

$$\begin{aligned} \int_{\frac{1}{4}}^{\frac{7}{4}} \frac{72x-20}{9x^2-5x+12} dx &= \int_{x=\frac{1}{4}}^{x=\frac{7}{4}} 4 \frac{du}{u} = 4 \int_{x=\frac{1}{4}}^{x=\frac{7}{4}} \frac{du}{u} \\ &= 4(\log_e u)_{x=\frac{1}{4}}^{x=\frac{7}{4}} \\ &= 4 \left[\log_e (9x^2 - 5x + 12) \right]_{x=\frac{1}{4}}^{x=\frac{7}{4}} \\ &= 4 (\log_e 418 - \log_e 136) \\ &= 4 (\log_e 4 \cdot 18 - \log_e 1 \cdot 36) \\ &= 4 (1.4303 - 0.3075) \\ &= 4.49. \end{aligned}$$

Example 24.—To find the value of $\int \frac{dx}{x^2+6x+15}$.

This is evidently of the type $\int \frac{dx}{(x+a)^2+b^2}$

$$\text{for } x^2+6x+15 = x^2+6x+9+6 \\ = (x+3)^2+(\sqrt{6})^2$$

so that $a = 3$ and $b = \sqrt{6}$.

$$\begin{aligned} \int \frac{dx}{x^2+6x+15} &= \frac{1}{b} \tan^{-1} \frac{x+a}{b} + C \quad (\text{cf. Example 10, p. 151}) \\ &= \frac{1}{\sqrt{6}} \tan^{-1} \frac{x+3}{\sqrt{6}} + C. \end{aligned}$$

Example 25.—For a single straight wire at a potential different from that of the earth, if r = radius of wire in cms., l = length of wire in cms., σ = surface density of charge in electrostatic units per sq. cm., then the potential P at any point on the axis of the wire due to the charge on a length δx is given by—

$$P = \frac{2\pi r \sigma \delta x}{\sqrt{r^2+x^2}}$$

that the potential at the middle point = $2\pi r \sigma \int_{-\frac{l}{2}}^{\frac{l}{2}} \frac{dx}{\sqrt{r^2+x^2}}$

Evaluate this integral.

This integral is of the type $\int \frac{dx}{\sqrt{a^2+x^2}}$.

$$\therefore \int \frac{dx}{\sqrt{r^2+x^2}} = \log \left(\frac{x + \sqrt{x^2+r^2}}{r} \right) \quad (\text{cf. Example 8, p. 150})$$

$$\begin{aligned} P_m &= 2\pi r \sigma \left[\log \left(\frac{x + \sqrt{x^2+r^2}}{r} \right) \right]_{-\frac{l}{2}}^{\frac{l}{2}} \\ &= 2\pi r \sigma \left[\log \left(\frac{\frac{l}{2} + \sqrt{\frac{l^2}{4} + r^2}}{r} \right) - \log \left(\frac{-\frac{l}{2} + \sqrt{\frac{l^2}{4} + r^2}}{r} \right) \right] \\ &= 2\pi r \sigma \cdot \left[\frac{\sqrt{\frac{l^2}{4} + r^2 + \frac{l}{2}}}{\sqrt{\frac{l^2}{4} + r^2 - \frac{l}{2}}} \right] \\ &= 2\pi r \sigma \log \left(\frac{\sqrt{\frac{l^2}{4r^2} + 1 + \frac{l}{2r}}}{\sqrt{\frac{l^2}{4r^2} + 1 - \frac{l}{2r}}} \right) \\ &\quad \pi d \sigma \log \frac{\sqrt{\left(\frac{l}{d}\right)^2 + 1 + \frac{l}{d}}}{\sqrt{\left(\frac{l}{d}\right)^2 + 1 - \frac{l}{d}}}. \quad \text{where } d \text{ is the diam. of wire.} \end{aligned}$$

The following example involves the use of three of the methods of this chapter.

Example 26.—Find the value of $\int \frac{(5x+4)dx}{(x^2+2x+7)(x+3)}$.

The fraction under the integral sign should first be resolved into partial fractions.

$$\begin{aligned} \text{Let } \frac{5x+4}{(x^2+2x+7)(x+3)} &= \frac{Ax+B}{(x^2+2x+7)} + \frac{C}{(x+3)} \quad (\text{cf. Part I, p. 454}) \\ &= \frac{(Ax+B)(x+3) + C(x^2+2x+7)}{(x^2+2x+7)(x+3)} \end{aligned}$$

$$\text{i. e.,} \quad 5x+4 = (Ax+B)(x+3) + C(x^2+2x+7).$$

Let $x = -3$, then—

$$-11 = C(9-6+7) = 10C$$

$$\text{i. e.,} \quad C = -\frac{11}{10}.$$

Values of A and B can be found by equating coefficients of x and also those of x^2 .

By equating coefficients of x^2 $0 = A+C$ and hence $A = \frac{11}{10}$

By equating coefficients of x $5 = 3A + B + 2C = \frac{33}{10} + B - \frac{22}{10}$.

$$B = \frac{39}{10}$$

Hence the fraction—

$$\begin{aligned} &= \frac{\frac{11}{10}x + \frac{39}{10}}{x^2 + 2x + 7} + \frac{\left(-\frac{11}{10}\right)}{x+3} \\ &= \frac{1}{10} \left\{ \frac{\frac{11}{10}x + \frac{39}{10}}{x^2 + 2x + 7} - \frac{\frac{11}{10}}{x+3} \right\}. \end{aligned}$$

We can make the numerator of the first of these fractions into some multiple of the derivative of the denominator; thus—

The derivative of the denominator—

$$= 2x + 2 = 2(x + 1)$$

$$\text{and the numerator } = \frac{11}{10}x + \frac{11}{10} + 28 = \frac{11}{10}(x + 1) + 28$$

$$\text{and if } u = x^2 + 2x + 7$$

$$\text{then } du = 2(x + 1)dx$$

$$\text{and } \frac{11}{10}(x + 1) + 28 dx = \frac{11}{10}(x + 1)dx + 28dx$$

$$= \frac{11}{2}du + 28dx$$

$$\therefore \int \frac{(5x + 4)dx}{(x^2 + 2x + 7)(x + 3)}$$

$$= \frac{1}{10} \int \left\{ \frac{\frac{11}{10}x + \frac{39}{10}}{x^2 + 2x + 7} - \frac{\frac{11}{10}}{x+3} \right\} dx$$

$$= \frac{1}{10} \left\{ \int \frac{\frac{11}{10}x + \frac{39}{10}}{x^2 + 2x + 7} dx - \int \frac{\frac{11}{10}}{x+3} dx \right\}$$

$$= \frac{1}{10} \left\{ \int \frac{\frac{11}{2}du + 28dx}{x^2 + 2x + 7} - \int \frac{\frac{11}{10}}{x+3} dx \right\}$$

$$= \frac{1}{10} \left\{ \frac{11}{2} \log u + \frac{28}{\sqrt{6}} \tan^{-1} \frac{(x+1)}{\sqrt{6}} - \frac{11}{10} \log (x+3) + C \right\} \begin{matrix} x^2 + 2x + 7 \\ = x^2 + 2x + 1 + 6 \\ = (x+1)^2 + (\sqrt{6})^2 \end{matrix}$$

$$+ \frac{11}{20} \log (x^2 + 2x + 7) + \frac{14}{5\sqrt{6}} \tan^{-1} \frac{(x+1)}{\sqrt{6}} - \frac{11}{10} \log (x+3) + C$$

$$\text{or log } \frac{(x^2 + 2x + 7)^{\frac{11}{20}}}{(x+3)^{\frac{11}{10}}} + \frac{14}{5\sqrt{6}} \tan^{-1} \frac{(x+1)}{\sqrt{6}} + C.$$

Example 27.—An integral required in the discussion of probability is $\int_0^\infty e^{-x^2} dx$. Find a value for this.

Let this integral be denoted by I , i.e., $I = \int_0^\infty e^{-x^2} dx$.

Replace x by ax and thus dx by adx .

Then $I = \int_0^\infty e^{-a^2x^2} adx$.

Multiply all through by e^{-a^2} .

Then $Ie^{-a^2} = \int_0^\infty e^{-a^2(1+x^2)} \cdot adx$ and integrate throughout with regard to a ; thus—

$$\int_0^\infty Ie^{-a^2} da = \int_{x=0}^{x=\infty} \int_{a=0}^{a=\infty} e^{-a^2(1+x^2)} adadx.$$

But $\int_0^\infty Ie^{-a^2} da = I \int_0^\infty e^{-a^2} da = I \times I$ since $\int_0^\infty e^{-x^2} dx$ and $\int_0^\infty e^{-a^2} da$ have the same value,

$$\text{hence } I^2 = \int_{x=0}^{x=\infty} \int_{a=0}^{a=\infty} e^{-a^2(1+x^2)} adadx \quad (1)$$

The value of the double integral on the right-hand side will be found by integrating first with regard to a and then with regard to x . Dealing with the "inner" integral—

$$\int_{a=0}^{a=\infty} e^{-a^2(1+x^2)} da$$

let $A = a^2$, then $dA = 2ada$, and let M represent $(1+x^2)$.

$$\begin{aligned} & \int_a^{a=\infty} e^{-a^2(1+x^2)} da \\ & \quad = \int_{a=0}^{a=\infty} e^{-AM} \cdot \frac{da}{2a} \\ & \quad = -\frac{1}{2M} \left(e^{-AM} \right)_0^\infty \quad \text{since the limits for } A \text{ are} \\ & \quad \quad \quad 0 \text{ and } \infty \text{ also} \\ & \quad = -\frac{1}{2M} (e^{-\infty} - e^0) \\ & \quad = -\frac{1}{2M} (0 - 1) = \frac{1}{2M}. \end{aligned}$$

Referring to equation (1) and substituting this value therein—

$$\begin{aligned} I^2 &= \int_0^\infty \frac{1}{2M} dx = \int_0^\infty \frac{dx}{2(1+x^2)} \\ &= \frac{1}{2} \left(\tan^{-1} x \right)_0^\infty \quad (\text{cf. Example 10, p. 151}) \\ &= \frac{1}{2} (\tan^{-1} \infty - \tan^{-1} 0) \\ &= \frac{1}{2} \left(\frac{\pi}{2} - 0 \right) = \frac{\pi}{4}. \\ I &= \frac{1}{2} \sqrt{\pi}. \end{aligned}$$

As an extension of this result it could be proved that—

$$\int_0^\infty e^{-\frac{x^2}{h^2}} dx = \frac{h}{2} \sqrt{\pi}.$$

Reduction Formulae.—Many of the exceedingly difficult integrals which arise in advanced problems of thermodynamics,

theory of stresses, and electricity may be made by suitable substitutions to depend upon standard results obtained by a process of reduction. To grasp thoroughly the underlying principles on which the process is based, it is well to commence with a study of the simpler types.

We desire to evaluate the integrals $\int_0^{\frac{\pi}{2}} \sin^n \theta \, d\theta$, $\cos^n \theta$

and $\int_0^{\frac{\pi}{2}} \sin^m \theta \cos^n \theta \, d\theta$, where m and n have any positive integral values. In which $n = m = 0$, we have the results

Taking the case in which $n = m = 0$, we have the results

If $m = n = 1$

$$\int_{0}^{\frac{\pi}{2}} \sin \theta \, d\theta = -\left(\cos \theta\right)_{0}^{\frac{\pi}{2}} = -(\cos 90^\circ - \cos 0^\circ) = 1. \quad . \quad (2)$$

$$\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos \theta d\theta = \left(\sin \theta \right)_{0}^{\frac{\pi}{2}} = (\sin 90^\circ - \sin 0^\circ) = 1 \quad (3)$$

from which pair of results we may say—

$$\int_0^{\frac{\pi}{2}} \sin \theta \, d\theta = \int_0^{\frac{\pi}{2}} \cos \theta \, d\theta = \int_0^{\frac{\pi}{2}} \sin \left(\frac{\pi}{2} - \theta \right) d\theta$$

or more generally—

$$\int_0^a f(x) dx = \int_0^a f(a-x) dx \quad . \quad . \quad (4)$$

a result of great usefulness.

$$\text{Also } \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \sin \theta \cos \theta d\theta = \frac{1}{2} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \sin 2\theta d\theta = -\frac{1}{2} \left(\cos 2\theta \right)_0^{\frac{\pi}{2}} \\ = -\frac{1}{4} (\cos \pi - \cos 0) \\ = \frac{1}{2} \quad (5)$$

By the process of reduction of powers we may express the integral to be evaluated in such a way that it depends on results (1), (2), (3) or (5).

Thus—

$$\int_0^{\frac{\pi}{2}} \sin^2 \theta \, d\theta = \frac{1}{2} \int_0^{\frac{\pi}{2}} (1 - \cos 2\theta) \, d\theta = \frac{1}{2} \left[\int_0^{\frac{\pi}{2}} 1 \, d\theta - \int_0^{\frac{\pi}{2}} \cos 2\theta \, d\theta \right]$$

2 \ 2

and from equation (4)—

$$\int_0^{\frac{\pi}{2}} \cos^2 \theta \, d\theta = \int_0^{\frac{\pi}{2}} \sin^2 \theta \, d\theta = \frac{\pi}{4}.$$

Now let $n = 3$, i.e., we wish to evaluate $\int_0^{\frac{\pi}{2}} \sin^3 \theta \, d\theta$.

$$\begin{aligned} \text{Then } \int_n^{\frac{\pi}{2}} \sin^3 \theta \, d\theta &= \int_n^{\frac{\pi}{2}} \sin^2 \theta \cdot \sin \theta \, d\theta = \int_n^{\frac{\pi}{2}} (1 - \cos^2 \theta) \sin \theta \, d\theta \\ &= - \int_0^{\frac{\pi}{2}} (1 - u^2) \, du \end{aligned}$$

0 and $\frac{\pi}{2}$ being the limits for θ

u being written for $\cos \theta$ and $-du$ for $\sin \theta \, d\theta$, since $\frac{d \cos \theta}{d\theta} = -\sin \theta$

$$\text{and thus } \frac{du}{d\theta} = -\sin \theta.$$

$$\text{Now } \int_{\theta=0}^{\theta=\frac{\pi}{2}} (1 - u^2) \, du = \left(u - \frac{u^3}{3} \right)_{\theta=0}^{\theta=\frac{\pi}{2}} = \left(\cos \theta - \frac{\cos^3 \theta}{3} \right)$$

$$\text{Thus } \int_0^{\frac{\pi}{2}} \sin^3 \theta \, d\theta = - \int_{\theta=0}^{\theta=\frac{\pi}{2}} (1 - u^2) \, du = + \frac{2}{3}$$

and if n be written for 3 we note that the result may be expressed

in the form $\int_0^{\frac{\pi}{2}} \sin^n \theta \, d\theta = \frac{n-1}{n}$ and also $\int_0^{\frac{\pi}{2}} \cos^n \theta \, d\theta = \frac{n-1}{n}$,
 n being an odd integer.

Let $n = 4$, then $\int_0^{\frac{\pi}{2}} \sin^4 \theta \, d\theta$ is required.

Now $\sin^4 \theta \, d\theta = \sin^3 \theta \cdot \sin \theta \, d\theta = uv$, where $u = \sin^3 \theta$,
 and $dv = \sin \theta \, d\theta$ or $v = -\cos \theta$.

$$\begin{aligned}\text{Hence } \int_0^{\frac{\pi}{2}} \sin^4 \theta \, d\theta &= -\left(\cos \theta \sin^3 \theta\right)_0^{\frac{\pi}{2}} + \int_0^{\frac{\pi}{2}} \cos \theta \cdot 3 \sin^2 \theta \cos \theta \, d\theta \\ &= -\left(\cos \theta \sin^3 \theta\right)_0^{\frac{\pi}{2}} + \int_0^{\frac{\pi}{2}} \cos \theta \cdot 3 \sin^2 \theta \cos \theta \, d\theta \\ &= 0 + 3 \int_0^{\frac{\pi}{2}} \sin^2 \theta \cos^2 \theta \, d\theta\end{aligned}$$

$$\text{since } \left(\cos \theta \sin^3 \theta\right)_0^{\frac{\pi}{2}} = (0 \times 1) - (1 \times 0) = 0.$$

$$\begin{aligned}\text{Now } \int_0^{\frac{\pi}{2}} \sin^2 \theta \cos^2 \theta \, d\theta &= \int_0^{\frac{\pi}{2}} \sin^2 \theta (1 - \sin^2 \theta) \, d\theta \\ &= \int_0^{\frac{\pi}{2}} (\sin^2 \theta - \sin^4 \theta) \, d\theta \\ &= \int_0^{\frac{\pi}{2}} \sin^2 \theta \, d\theta - \int_0^{\frac{\pi}{2}} \sin^4 \theta \, d\theta\end{aligned}$$

$$\text{Hence— } \int_0^{\frac{\pi}{2}} \sin^4 \theta \, d\theta = 3 \int_0^{\frac{\pi}{2}} \sin^2 \theta \, d\theta - 3 \int_0^{\frac{\pi}{2}} \sin^4 \theta \, d\theta$$

$$\text{or } 4 \int_0^{\frac{\pi}{2}} \sin^4 \theta \, d\theta = 3 \int_0^{\frac{\pi}{2}} \sin^2 \theta \, d\theta$$

$$\text{and } \int_0^{\frac{\pi}{2}} \sin^4 \theta \, d\theta = \frac{3}{4} \int_0^{\frac{\pi}{2}} \sin^2 \theta \, d\theta.$$

We have thus reduced the power by 2, and knowing the result for $\int_0^{\frac{\pi}{2}} \sin^2 \theta \, d\theta$, we can finally state the value for $\int_0^{\frac{\pi}{2}} \sin^4 \theta \, d\theta$.

$$\text{Thus } \int_0^{\frac{\pi}{2}} \sin^4 \theta \, d\theta = \frac{3}{4} \times \frac{\pi}{4} = \frac{3\pi}{16} \quad \text{or} \quad \frac{3}{4} \times \frac{1}{2} \times \frac{\pi}{2}$$

$$\text{or } \int_0^{\frac{\pi}{2}} \sin^n \theta \, d\theta = \frac{(n-1)}{n} \times \frac{(n-3)}{(n-2)} \times \frac{\pi}{2}, \quad n \text{ being an even integer.}$$

In like manner it could be shown that—

$$\int_0^{\frac{\pi}{2}} \sin^5 \theta \, d\theta = \frac{5-1}{5} \int_0^{\frac{\pi}{2}} \sin^3 \theta \, d\theta.$$

$$\text{Thus } \int_0^{\frac{\pi}{2}} \sin^5 \theta \, d\theta = \frac{5-1}{5} \times \frac{5-3}{5-2} \quad \text{or} \quad \frac{4 \cdot 2}{5 \cdot 3}$$

which is of the form $\int_0^{\frac{\pi}{2}} \sin^n \theta d\theta = \frac{n-1}{n} \cdot \frac{n-3}{n-2}$
 n being an odd integer.

Similarly—

$$\int_0^{\frac{\pi}{2}} \sin^n \theta d\theta = \frac{6-1}{6} \int_0^{\frac{\pi}{2}} \sin^4 \theta d\theta = \frac{6-1}{6} \times \frac{6-3}{6-2} \times \frac{6-5}{6-4} \times \frac{\pi}{2}$$

or $\frac{5 \cdot 3 \cdot 1}{6 \cdot 4 \cdot 2} \times \frac{\pi}{2}$

which is of the form—

$$\int_0^{\frac{\pi}{2}} \sin^n \theta d\theta : \quad \frac{(n-1)(n-3)(n-5)}{n(n-2)(n-4)} \frac{\pi}{2}$$

n being an even integer.

Summarising our results—

$$\int_0^{\frac{\pi}{2}} \sin^n \theta d\theta = \int_0^{\frac{\pi}{2}} \cos^n \theta d\theta = \frac{(n-1)(n-3)(n-5)}{n(n-2)(n-4)} \dots \frac{1}{2} \frac{\pi}{2}$$

if n is an even integer.

$$\int_0^{\frac{\pi}{2}} \sin^n \theta d\theta = \int_0^{\frac{\pi}{2}} \cos^n \theta d\theta = \frac{(n-1)(n-3)(n-5)}{n(n-2)(n-4)}$$

if n is an odd integer.

Example 28.—Find the value of $\int_0^{\frac{\pi}{2}} \sin^9 \theta d\theta$.

In this case $n = 9$ and is odd.

Hence— $\int_0^{\frac{\pi}{2}} \sin^9 \theta d\theta = \frac{8 \cdot 6 \cdot 4 \cdot 2}{9 \cdot 7 \cdot 5 \cdot 3} = \underline{\underline{128}}$

Example 29.—Evaluate $\int_0^{\frac{\pi}{2}} \cos^{10} \theta d\theta$.

Here $n = 10$ and is even.

Hence $\int_0^{\frac{\pi}{2}} \cos^{10} \theta d\theta = \frac{9 \cdot 7 \cdot 5 \cdot 3 \cdot 1}{10 \cdot 8 \cdot 6 \cdot 4 \cdot 2} \cdot \frac{\pi}{2} = \underline{\underline{63\pi}} \cdot \frac{1}{512}$

Example 30.—The expression $-\frac{4pl}{\pi+4} \int_{\infty}^1 \frac{\sqrt{t^2-1}}{t^3} dt$ gives the theoretical thrust on a plane moving through air. Evaluate this.

$$\sqrt{t^2-1} = \sqrt{t^2 \left(1 - \frac{1}{t^2}\right)} = t \sqrt{1 - \sin^2 u} = t \cos u = \frac{\cos u}{\sin u}$$

if $\sin u$ is written in place of $\frac{1}{t}$.

Then since $\sin u = \frac{t}{t^2 - 1} = t^{-1}$ $\frac{d \sin u}{du} = \frac{dt^{-1}}{du} = \frac{dt^{-1}}{dt} \times \frac{dt}{du}$

or

$$\cos u = -\frac{t}{t^2} \frac{dt}{du}$$

whence

$$dt = -\frac{\cos u}{\sin^2 u} du.$$

Again, when $t = \infty$ $\frac{1}{t} = 0$ i.e., $\sin u = 0$ or $u = 0$

and when $t = 1$ $\frac{1}{t} = 1$ i.e., $\sin u = 1$ or $u = \frac{\pi}{2}$.

Hence—

$$\int^1 \frac{\sqrt{t^2 - 1}}{t^3} dt = - \int^{\frac{\pi}{2}} \frac{\cos u \sin^3 u \cos u du}{\sin u \sin^2 u} = - \int^{\frac{\pi}{2}} \cos^2 u du = -\frac{\pi}{2}.$$

$$\text{Thus } -\frac{4pl}{\pi+4} \int_{-\infty}^1 \frac{\sqrt{t^2 - 1}}{t^3} dt = -\frac{4pl}{\pi+4} \times -\frac{\pi}{4} = \frac{\pi pl}{\pi+4}.$$

We can now direct our attention to the determination of the value of $\int_0^{\frac{\pi}{2}} \sin^m \theta \cos^n \theta d\theta$, where m and n are positive integers.

It is convenient to discuss a simple case first, viz.—

$$\int_0^{\frac{\pi}{2}} \sin^2 \theta \cos \theta d\theta.$$

$$\text{Let } u = \sin^2 \theta \quad \text{so that} \quad \frac{du}{d\theta} = \frac{d \sin^2 \theta}{d \sin \theta} \times \frac{d \sin \theta}{d\theta} \\ = 2 \sin \theta \cos \theta$$

and

$$du = 2 \sin \theta \cos \theta d\theta$$

$$\text{also let } dv = \cos \theta d\theta \quad \text{so that} \quad v = \sin \theta.$$

Then, by integrating by parts—

$$\sin^2 \theta \cos \theta d\theta = \left(\sin^3 \theta \right)_0^{\frac{\pi}{2}} - \int_0^{\frac{\pi}{2}} 2 \sin^2 \theta \cos \theta d\theta$$

$$\text{whence } 3 \int_0^{\frac{\pi}{2}} \sin^2 \theta \cos \theta d\theta = \left(\sin^3 \theta \right)_0^{\frac{\pi}{2}} = 1$$

$$\text{or } \int_0^{\frac{\pi}{2}} \sin^2 \theta \cos \theta d\theta = \frac{1}{3}$$

$$\text{and } \frac{1}{3} \text{ might be written as } \frac{m-1}{m+n}.$$

Example 31.—H, the horizontal thrust on a circular arched rib carrying a uniformly distributed load w per foot run of the arch, is obtained from—

$$H = \frac{wR^4 \int_0^\pi \left(\frac{1}{4} - \sin^2 \theta\right) (\cos \theta - .866) d\theta}{2R^3 \int_0^\pi (\cos \theta - .866) d\theta}$$

if the span is equal to the radius of curvature (see Fig. 38).

If $w = .5$ ton per foot, and the span = 60 ft., find the value of H.

Here $w = .5$, $R = \text{span} = 60$.

Hence $H = .5 \times 60 \int_0^\pi \left(\frac{1}{4} - \sin^2 \theta\right) (\cos \theta - .866) d\theta$

$$\int_0^\pi (\cos \theta - .866) d\theta.$$

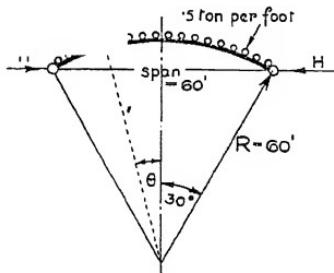


FIG. 38.—Circular Arched Rib.

Dealing with the numerator separately, as this alone presents any difficulty—

$$\left(\frac{1}{4} - \sin^2 \theta\right) (\cos \theta - .866) = \frac{1}{4} \cos \theta - .2165 - \sin^2 \theta \cos \theta + .866 \sin^2 \theta.$$

Then $\int \left(\frac{1}{4} - \sin^2 \theta\right) (\cos \theta - .866) d\theta$

$$= \int \frac{1}{4} \cos \theta d\theta - \int .2165 d\theta - \int \sin^2 \theta \cos \theta d\theta + \int .866 \sin^2 \theta d\theta$$

but, as proved on p. 148, $\int \sin^2 \theta d\theta = \frac{1}{2} \int 1 d\theta - \frac{1}{2} \int \cos 2\theta d\theta$

$$= \frac{\theta}{2} - \frac{1}{4} \sin 2\theta$$

and as proved on p. 168 $\int \sin^2 \theta \cos \theta d\theta = \frac{1}{3} \sin^3 \theta$

$$\begin{aligned}
 \text{thus } & \int_0^{\frac{\pi}{6}} \left(\frac{1}{4} - \sin^2 \theta \right) (\cos \theta - .866) d\theta \\
 &= \left(\frac{1}{4} \sin \theta \right)_0^{\frac{\pi}{6}} - \left(.2165 \theta \right)_0^{\frac{\pi}{6}} - \frac{1}{3} \left(\sin^3 \theta \right)_0^{\frac{\pi}{6}} + .433 \left(\theta - \frac{1}{2} \sin 2\theta \right)_0^{\frac{\pi}{6}} \\
 &= \left(\frac{1}{4} \times .5 - 0 \right) - \left(\frac{.2165 \times \pi}{6} - 0 \right) - \frac{1}{3} \left((.5)^3 - 0 \right) + .433 \left(\frac{\pi}{6} - \frac{1}{2} \times .866 - 0 + 0 \right) \\
 &= .125 - .1134 - .0417 + .2267 - .1875 = .0091.
 \end{aligned}$$

Dealing now with the denominator—

$$\int_0^{\frac{\pi}{6}} (\cos \theta - .866) d\theta = \left(\sin \theta - .866\theta \right)_0^{\frac{\pi}{6}} = .5 - .866 \times \frac{\pi}{6} = .5 - .4534 = .0466.$$

$$\text{Hence } H = \frac{.15 \times .0091}{.0466} = \underline{2.93 \text{ tons.}}$$

Carrying the investigation a step further, let us discuss the case of $\int_0^2 \sin^2 \theta \cos^2 \theta d\theta$.

$$\int_0^{\frac{\pi}{2}} \sin^2 \theta \cos^2 \theta d\theta = \int_0^{\frac{\pi}{2}} (1 - \cos^2 \theta) \cos^2 \theta d\theta = \int_0^{\frac{\pi}{2}} \cos^2 \theta d\theta - \int_0^{\frac{\pi}{2}} \cos^4 \theta d\theta$$

$$\text{and from the previous result this value} = \frac{\pi}{4} - \frac{3 \cdot 1 \cdot \pi}{4 \cdot 2 \cdot 2}$$

$$= \frac{1 \cdot \pi}{8 \cdot 2} \text{ or } \frac{1}{4} \cdot \frac{1}{2} \cdot \frac{\pi}{2}$$

This result might be regarded as obtained by first reducing the power m by 2, and next that of $\cos^2 \theta$ by 2.

Thus for the first step—

$$\int_0^{\frac{\pi}{2}} \sin^2 \theta \cos^2 \theta d\theta = \frac{2-1}{4} \int_0^{\frac{\pi}{2}} \cos^2 \theta d\theta$$

$$\text{or } \frac{m-1}{m+n} \int_0^{\frac{\pi}{2}} \cos^2 \theta d\theta$$

and for the second step—

$$\begin{aligned}
 \int_0^{\frac{\pi}{2}} \cos^2 \theta d\theta &= \frac{2-1}{2} \int_0^{\frac{\pi}{2}} 1 d\theta \\
 &= \frac{2-1}{2}, \frac{\pi}{2} \text{ or } \frac{n-1}{n+m} \frac{\pi}{2}
 \end{aligned}$$

m for the second integral being zero.

In a similar fashion we might reduce $\int_0^{\frac{\pi}{2}} \sin^4 \theta \cos^3 \theta d\theta$ as follows:—

First reduce m by 2, then—

$$\int_0^{\frac{\pi}{2}} \sin^4 \theta \cos^3 \theta d\theta = \frac{4-1}{4+3} \int_0^{\frac{\pi}{2}} \sin^2 \theta \cos^3 \theta d\theta.$$

Next reduce the power of $\sin^2 \theta$ again by 2.

$$\text{Thus } \int_0^{\frac{\pi}{2}} \sin^4 \theta \cos^3 \theta d\theta = \frac{4-1}{4+3} \cdot \frac{2-1}{2+3} \int_0^{\frac{\pi}{2}} \cos^3 \theta d\theta.$$

Now reduce the power of $\cos^3 \theta$ by 2, and remember that m is now = 0. Then—

$$\int_0^{\frac{\pi}{2}} \sin^4 \theta \cos^3 \theta d\theta = \frac{4-1}{4+3} \cdot \frac{2-1}{2+3} \cdot \frac{3-1}{3+0} \int_0^{\frac{\pi}{2}} \cos \theta d\theta = \frac{3 \cdot 1 \cdot 2}{7 \cdot 5 \cdot 3}.$$

In the evaluation of the integral $\int_0^{\frac{\pi}{2}} \sin^m \theta \cos^n \theta d\theta$ we thus proceed by reducing by 2 the powers of m and n in turn until they become 1 or 0. The various cases that arise are—

(a) m and n both even: in which case the final integral is

$$\int_0^{\frac{\pi}{2}} d\theta = \frac{\pi}{2}.$$

(b) m and n both odd: in which case the final integral is

$$\int_0^{\frac{\pi}{2}} \sin \theta \cos \theta d\theta = \frac{1}{2}.$$

(c) m even and n odd or *vice-versa*: in which case the final integral is either $\int_0^{\frac{\pi}{2}} \cos \theta d\theta$ or $\int_0^{\frac{\pi}{2}} \sin \theta d\theta$, the value of either being 1.

The results for the three cases can be thus stated—

(a) m and n both even—

$$\begin{aligned} \int_0^{\frac{\pi}{2}} \sin^m \theta \cos^n \theta d\theta &= \frac{(m-1) \times (m-3) \times \dots \times 1}{(m+n) \times (m-2+n) \times \dots \times (n+2)} \\ &\quad \times \frac{(n-1)(n-3) \times \dots \times 1}{n(n-2) \times \dots \times 2} \times \frac{\pi}{2} \end{aligned}$$

(b) m and n both odd—

$$\int_0^{\frac{\pi}{2}} \sin^m \theta \cos^n \theta d\theta = \frac{(m-1) \times (m-3) \times \dots \times 1}{(m+n) \times (m-2+n) \times \dots \times (n+3)} \\ \times \frac{(n-1) \times (n-3) \times \dots \times 1}{(n+1) \times (n-1) \times \dots \times 1}$$

since, after reducing the power of $\sin^m \theta$ by 2 at a time, we must be left with $\sin \theta \cos^n \theta$, so that the value of m to be used in the reduction of $\cos^n \theta$ must be taken as 1.

(c) m even and n odd—

$$\int_0^{\frac{\pi}{2}} \sin^m \theta \cos^n \theta d\theta = \frac{(m-1) \times (m-3) \times \dots \times 1}{(m+n) \times (m-2+n) \times \dots \times (n+2)} \\ \times \frac{(n-1) \times (n-3) \times \dots \times 1}{n(n-2) \times \dots \times 1}$$

Example 32.—Evaluate $\int_0^{\frac{\pi}{2}} \sin^8 \theta \cos^{10} \theta d\theta$.

This is case (a), i.e., with both m and n even.

$$\text{Hence } \int_0^{\frac{\pi}{2}} \sin^8 \theta \cos^{10} \theta d\theta = \frac{7 \cdot 5 \cdot 3 \cdot 1}{18 \cdot 16 \cdot 14 \cdot 12} \times \frac{9 \cdot 7 \cdot 5 \cdot 3 \cdot 1}{10 \cdot 8 \cdot 6 \cdot 4 \cdot 2} \times \frac{\pi}{2} \\ = \frac{315\pi}{1179648}.$$

Example 33.—Find the value of $\int_0^{\frac{\pi}{2}} \sin^3 \theta \cos^5 \theta d\theta$.

This is case (b), i.e., with both m and n odd.

$$\text{Hence } \int_0^{\frac{\pi}{2}} \sin^3 \theta \cos^5 \theta d\theta = \frac{2 \times 4 \times 2}{8 \times 6 \times 4} \times \frac{1}{2} = \underline{\underline{\frac{1}{24}}}.$$

Example 34.—Find the value of $\int_0^{\frac{\pi}{2}} \sin^7 \theta \cos^4 \theta d\theta$.

This is case (c), but with m odd and n even.

$$\text{Hence } \int_0^{\frac{\pi}{2}} \sin^7 \theta \cos^4 \theta d\theta = \frac{6 \cdot 4 \cdot 2}{11 \cdot 9 \cdot 7} \times \frac{3 \cdot 1}{5 \cdot 3} \times 1 = \underline{\underline{\frac{16}{1155}}}.$$

The value of the foregoing formulæ is found in their employ-

ment in the evaluation of difficult algebraic functions, which may often be transformed by suitable trigonometric substitution.

Thus to evaluate $\int_0^1 x^{m-1}(1-x)^{n-1}dx$, known as the First Eulerian Integral and usually denoted by the form $B(m, n)$, we may substitute $\sin^2\theta$ for x . Then, since when $x = 0$ $\sin^2\theta$ must = 0 and thus $\theta = 0$, and when $x = 1$ $\sin^2\theta$ must = 1 and thus

$$\theta =$$

$$\begin{aligned} \int_0^1 x^{m-1}(1-x)^{n-1}dx &= \int_0^{\frac{\pi}{2}} \sin^{2m-2}\theta(1-\sin^2\theta)^{n-1}d\theta \\ \frac{dx}{d\theta} &= \frac{d \sin^2 \theta}{d\theta} &= \int_0^{\frac{\pi}{2}} \sin^{2m-2}\theta \cos^{2n-2}\theta \times 2 \sin \theta \cos \theta d\theta \\ &= \frac{d \sin^2 \theta}{d \sin \theta} \cdot \frac{d \sin \theta}{d\theta} &= 2 \int_0^{\frac{\pi}{2}} \sin^{2m-1}\theta \cos^{2n-1}\theta d\theta \\ &= 2 \sin \theta \cos & \end{aligned}$$

and this can readily be evaluated.

Example 35.—Evaluate $\int_0^1 x^4(1-x^2)^{\frac{5}{2}}dx$.

Let $x = \sin \theta$ then $1-x^2 = 1-\sin^2\theta = \cos^2\theta$

$$\text{and } \frac{dx}{d\theta} = \frac{d \sin \theta}{d\theta} = \cos \theta.$$

Also when $x = 0$ $\sin \theta = 0$ and thus $\theta = 0$

and when $x = 1$ $\sin \theta = 1$ $\theta = \frac{\pi}{2}$.

Then—

$$\begin{aligned} \int_0^1 x^4(1-x^2)^{\frac{5}{2}}dx &= \int_0^{\frac{\pi}{2}} \sin^4\theta \cos^5\theta d\theta \cos \theta = \int_0^{\frac{\pi}{2}} \sin^4\theta \cos^6\theta d\theta \\ &= \frac{3 \cdot 1}{10 \cdot 8} \times \frac{5 \cdot 3 \cdot 1}{6 \cdot 4 \cdot 2} \times \frac{\pi}{2} = \frac{9\pi}{512}. \end{aligned}$$

Another important result obtained by the process of reduction is the value of $\int_0^\infty e^{-x} x^n dx$. This is termed a Gamma Function; this particular integral being the $(n+1)$ Gamma Function denoted by $\Gamma(n+1)$.

$$\text{Thus } \int_0^\infty e^{-x} x^n dx = \Gamma(n+1)$$

$$\text{and } \int_0^\infty e^{-x} x^{n-1} dx = \Gamma(n)$$

the latter integral being also called the Second Eulerian Integral.

To evaluate $\Gamma(n+1)$ let $u = x^n$ and $dv = e^{-x}dx$
so that $v = -e^{-x}$ and $du = nx^{n-1}dx$.

$$\text{Then } \int_0^\infty e^{-x}x^n dx = \left(-e^{-x}x^n \right)_0^\infty - \int_0^\infty -e^{-x} \cdot nx^{n-1} dx \\ = \left(-e^{-x}x^n \right)_0^\infty + n \int_0^\infty e^{-x}x^{n-1} dx.$$

Now when $x = \infty$ $e^{-x}x^n = \frac{1 \times \infty}{\infty}$, which can be proved = 0

and when $x = 0$ $e^{-x}x^n = \frac{1 \times 0}{e^0} = 0$.

$$\text{Hence } \int_0^\infty e^{-x}x^n dx = n \int_0^\infty e^{-x}x^{n-1} dx$$

$$\text{or } \Gamma(n+1) = n\Gamma(n).$$

In like manner it could be shown that—

$$\Gamma(n) = (n-1)\Gamma(n-1), \text{ and so on.}$$

If n is an integer it will be seen that we finally reduce to $\Gamma(1)$,
i.e., $\int_0^\infty e^{-x}dx$, the value of which is $-(e^{-\infty} - e^0) = -(0 - 1) = 1$.

$$\text{Hence } \Gamma(n+1) = n(n-1)(n-2) \dots 1 = \lfloor n \rfloor.$$

This last relation will not hold, however, if n is not an integer, but the general method of attack holds good; and tables have been compiled giving the values of $\Gamma(n)$ for many values of n , whether n be an integer or fractional. Thus if an integral can be reduced to a Gamma function or a combination of Gamma functions, its complete evaluation may be effected by reference to the tables.

Example 36.—Evaluate the probability integral $\int_0^\infty e^{-\frac{x^2}{h^2}} dx$ by the aid of the Gamma function.

$$\text{Let } X = \frac{x^2}{h^2} \quad \text{then} \quad \frac{dX}{dx} = \frac{d\frac{x^2}{h^2}}{dx} = \frac{2x}{h^2}$$

$$\text{so that} \quad dX = \frac{2xdx}{h^2}$$

$$\text{or} \quad dx = \frac{h^2}{2} \frac{dX}{x} = \frac{h^2}{2} \frac{dX}{h\sqrt{X}} = \frac{hdX}{2\sqrt{X}}.$$

$$\text{Then} \quad \int_0^\infty e^{-\frac{x^2}{h^2}} dx = \int_0^\infty -X \times \frac{hdX}{2\sqrt{X}} = \frac{h}{2} \int_0^\infty -X X^{-\frac{1}{2}} dX = \frac{h}{2} \times \Gamma\left(\frac{1}{2}\right)$$

and the value of $\Gamma\left(\frac{1}{2}\right)$ is $\sqrt{\pi}$.

Hence $\int_0^\infty e^{-\frac{x^2}{b^2}} dx = \frac{b}{2} \sqrt{\pi}.$

On comparing with *Example 27*, p. 162, where a rather simpler form of the integral is evaluated, we see the great saving effected by the use of the Gamma function.

LIST OF INTEGRALS LIKELY TO BE OF SERVICE

$\int (ax^n + b) dx$	$= \frac{ax^{n+1}}{n+1} + bx + C.$
$\int ae^{bx} dx$	$= \frac{a}{b} e^{bx} + C.$
$\int ba^{nx} dx$	$= n \log a \cdot a^x + C.$
$\int a \cos (bx+d) dx$	$= \frac{a}{b} \sin (bx+d) + C.$
$\int a \sin (bx+d) dx$	$= -\frac{a}{b} \cos (bx+d) + C.$
$\int a \tan (bx+d) dx$	$= -\frac{a}{b} \log \cos (bx+d) + C.$
$\int a \cot (bx+d) dx$	$= \frac{a}{b} \log \sin (bx+d) + C.$
$\int a \sec^2 (bx+d) dx$	$= \frac{a}{b} \tan (bx+d) + C.$
$\int a \operatorname{cosec}^2 (bx+d) dx$	$= -\frac{a}{b} \cot (bx+d) + C.$
$\int a \cosh (bx+d) dx$	$= \frac{a}{b} \sinh (bx+d) + C.$
$\int a \sinh (bx+d) dx$	$= \frac{a}{b} \cosh (bx+d) + C.$
$\int a \operatorname{sech}^2 (bx+d) dx$	$= \frac{a}{b} \tanh (bx+d) + C.$
$\int a \operatorname{cosech}^2 (bx+d) dx$	$= -\frac{a}{b} \coth (bx+d) + C.$
$\int e^{ax} \sin (bx+d) dx$	$= \frac{e^{ax}}{a^2+b^2} [a \sin (bx+d) - b \cos (bx+d)] + C.$
$\int e^{ax} \cos (bx+d) dx$	$= \frac{e^{ax}}{a^2+b^2} [b \sin (bx+d) + a \cos (bx+d)] + C.$

$$\begin{aligned}
 \int \sin(bx+d) dx &= \frac{1}{b} \log \left(\tan \frac{bx+d}{2} \right) + C. \\
 \int \frac{dx}{ax+b} &= \frac{1}{a} \log (ax+b) + C. \\
 \int \tan(bx+d) dx &= -\frac{1}{b} \log \cos(bx+d) + C. \\
 \int \cot(bx+d) dx &= \frac{1}{b} \log \sin(bx+d) + C. \\
 \int \frac{dx}{a^2+x^2} &= \frac{1}{a} \tan^{-1} \frac{x}{a} + C. \\
 \int \frac{dx}{(x+a)^2+b^2} &= \frac{1}{b} \tan^{-1} \frac{x+a}{b} + C. \\
 \int \frac{dx}{a^2-x^2} &= \frac{1}{2a} \log \frac{a+x}{a-x} + C. \\
 \int \frac{dx}{(x+a)^2-b^2} &= \frac{1}{2b} \log \frac{x+a-b}{x+a+b} + C. \\
 \int \frac{dx}{\sqrt{a^2-x^2}} &= \sin^{-1} \frac{x}{a} + C. \\
 \int \frac{dx}{\sqrt{x^2+a^2}} &= \log \left(\frac{x+\sqrt{x^2+a^2}}{a} \right) + C. \\
 \int \frac{dx}{\sqrt{(x+a)^2+b^2}} &= \log \left(\frac{x+a+\sqrt{(x+a)^2+b^2}}{b} \right) + C. \\
 \int \frac{dx}{\sqrt{x^2-a^2}} &= \log \left(\frac{x+\sqrt{x^2-a^2}}{a} \right) + C. \\
 \int \frac{dx}{\sqrt{(x+a)^2-b^2}} &= \log \left(\frac{x+a+\sqrt{(x+a)^2-b^2}}{b} \right) + C. \\
 \int \frac{(ax+b)dx}{(ax^2+2bx+d)} &= \frac{1}{a} \log (ax^2+2bx+d) + C. \\
 \int \cosec(ax+b) dx &= \frac{1}{a} \log \left(\tan \frac{ax+b}{2} \right) + C. \\
 \int \sec(ax+b) dx &= \frac{1}{a} \log \tan \left(\frac{\pi}{4} + \frac{ax+b}{2} \right) + C. \\
 \int \frac{dx}{x\sqrt{x^2-a^2}} &= \frac{1}{a} \sec^{-1} \frac{x}{a} + C. \\
 \frac{dx}{\sqrt{2ax-x^2}} &= \text{vers}^{-1} \frac{x}{a} + C \quad \text{or} \quad \frac{1}{2} - \cos^{-1} \frac{x}{a} + C. \\
 \int \sqrt{a^2-x^2} dx &= \frac{x}{2} \sqrt{a^2-x^2} + \frac{a^2}{2} \sin^{-1} \frac{x}{a} + C. \\
 \int \sqrt{x^2-a^2} dx &= \frac{x}{2} \sqrt{x^2-a^2} - \frac{a^2}{2} \cosh^{-1} \frac{x}{a} + C.
 \end{aligned}$$

$$\int \sqrt{(x+a)^2 - b^2} dx = \frac{1}{2}(x+a)\sqrt{(x+a)^2 - b^2} - \frac{b^2}{2} \cosh^{-1} \frac{x+a}{b} + C.$$

$$\int \sqrt{x^2 + a^2} dx = \frac{x}{2}\sqrt{x^2 + a^2} + \frac{a^2}{2} \sinh^{-1} \frac{x}{a} + C.$$

$$\int \sqrt{(x+a)^2 + b^2} dx = \frac{1}{2}(x+a)\sqrt{(x+a)^2 + b^2} + \frac{b^2}{2} \sinh^{-1} \frac{x+a}{b} + C.$$

$$\int \sin^2 x dx = \frac{x}{2} - \frac{1}{4} \sin 2x + C.$$

$$\int \cos^2 x dx = \frac{x}{2} + \frac{1}{4} \sin 2x + C.$$

$$\begin{aligned} \int \sin^m x \cos^n x dx &= \frac{m-1}{m+n} \int \sin^{m-2} x \cdot \cos^n x dx \\ &\quad - \frac{\sin^{m-1} x \cdot \cos^{n+1} x}{m+n} + C. \end{aligned}$$

$$\int \frac{dx}{(a^2 - x^2)^{\frac{3}{2}}} = \frac{x}{a^2 \sqrt{a^2 - x^2}} + C.$$

$$\int_0^\infty e^{-x^2} dx = \frac{\sqrt{\pi}}{2}.$$

$$\int_0^\infty e^{-\frac{x^2}{h^2}} dx = h\sqrt{\pi}$$

$$\int_0^{\frac{\pi}{2}} \sin^2 \theta d\theta = \int_0^{\frac{\pi}{2}} \cos^2 \theta d\theta = \frac{\pi}{4}.$$

$$\int_0^{\frac{\pi}{2}} \sin^n \theta d\theta = \int_0^{\frac{\pi}{2}} \cos^n \theta d\theta = \frac{(n-1)(n-3)(n-5) \dots 1}{n(n-2)(n-4) \dots 2} \frac{\pi}{2} \quad \text{if } n \text{ is an even integer.}$$

$$\int_0^{\frac{\pi}{2}} \sin^n \theta d\theta = \int_0^{\frac{\pi}{2}} \cos^n \theta d\theta = \frac{(n-1)(n-3)(n-5) \dots 2}{n(n-2)(n-4) \dots 1} \frac{\pi}{2} \quad \text{if } n \text{ is an odd integer.}$$

$$\int_{-\infty}^1 \frac{\sqrt{x^2 - 1}}{x^3} dx = -\frac{\pi}{4}.$$

$$\int_0^{\frac{\pi}{2}} \sin^m \theta \cos^n \theta d\theta = \frac{(m-1)(m-3) \dots 1}{(m+n)(m+n-2) \dots (n+2)} \times \frac{(n-1)(n-3) \dots 1}{n(n-2) \dots 2} \times \frac{\pi}{2} \quad \text{if } m \text{ and } n \text{ are both even.}$$

$$\int_0^{\frac{\pi}{2}} \sin^m \theta \cos^n \theta d\theta = \frac{(m-1)(m-3) \dots 2}{(m+n)(m+n-2) \dots (n+3)} \times \frac{(n-1)(n-3) \dots 2}{(n+1)(n-1) \dots 4} \times \frac{\pi}{2} \quad \text{if } m \text{ and } n \text{ are both odd.}$$

$$\int_0^{\frac{\pi}{2}} \sin^m \theta \cos^n \theta \, d\theta = \frac{(m-1)(m-3)\dots 1}{(m+n)(m+n-2)\dots(n+2)} \times \frac{(n-1)(n-3)\dots 1}{n(n-2)\dots 1} \\ \text{if } m \text{ is even and } n \text{ is odd.}$$

$$\int_{v_1}^{v_2} p dv \text{ (where } pv^n = C) = \frac{C}{1-n} (v_2^{1-n} - v_1^{1-n}) = \frac{p_2 v_2 - p_1 v_1}{1-n}.$$

$$\int_{v_1}^{v_2} p dv \text{ (where } pv = C) = C \log_e \frac{v_2}{v_1}.$$

$$\int_{\tau_1}^{\tau_2} \frac{a+b\tau}{\tau} \, d\tau = a \log \frac{\tau_2}{\tau_1} + b(\tau_2 - \tau_1).$$

$$\sin^{-1} ax \, dx = x \sin^{-1} ax + \frac{1}{a} \sqrt{1-a^2x^2} + C.$$

$$\int \tan^{-1} ax \, dx = x \tan^{-1} ax - \frac{1}{2a} \log(1+a^2x^2) + C.$$

$$\int (a^2-x^2)^{\frac{3}{2}} \, dx = \frac{x}{4}(a^2-x^2)^{\frac{1}{2}} + \frac{3a^2}{8} \left(x\sqrt{a^2-x^2} + a^2 \sin^{-1} \frac{x}{a} \right) + C.$$

$$\int_a^b (a^2-x^2)^{\frac{3}{2}} \, dx = \frac{3\pi a^4}{16}.$$

Exercises 15.—On Further Integration.

Evaluate the integrals in Nos. 1 to 18.

$$1. \int \frac{dx}{2x^2-5}. \quad 2. \int \frac{dx}{3x^8+6x+21}. \quad 3. \int \frac{(x-1)dx}{9x^2-18x+17}.$$

$$4. \frac{4}{3} \int_1^{11} \frac{(3.5-y)dy}{y+3}, \text{ which occurred when finding stresses in a crane hook.}$$

$$5. t = 95.5 \int_0^3 (6-h)^{\frac{1}{2}} dh, \text{ referring to the time for emptying a tank.}$$

$$6. \int \sqrt{3-4y^2} dy. \quad 7. \frac{2}{\pi} \int_0^{\frac{\pi}{2}} \sin 5t \cos t \, dt. \quad 8. \int 8 \cos^4 t \, dt.$$

$$9. \int \frac{dx}{\sin^2 5x}. \quad 10. \int_0^{\frac{\pi}{2}} \frac{WR}{EI} \left(\frac{1}{\pi} - \frac{1}{2} \sin \theta \right) R^2 \cos \theta \, d\theta.$$

$$11. \int_4 \tan 5t \, dt. \quad 12. \int \sin^{-1} x \, dx. \quad 13. \int x \sqrt{a^2-x^2} dx.$$

$$14. \int_5 e^{3x} \sin 2x \, dx \quad 15. \int \frac{2dx}{(1+x^2)^2}. \quad 16. \int_0^{\frac{\pi}{2}} x \sin x \, dx.$$

$$17. \int \cos \theta \sin^2 \theta \, d\theta. \quad 18. h = \int_0^l \frac{64fQ^2}{2g\pi^2} \frac{dx}{(d+kx)^5}, \text{ relating to the}$$

flow of water through a pipe of uniformly varying diameter; the diameter at distance x from the small end being = small end diam. + kx .

19. The time taken (t secs.) to lower the level of the liquid in a certain vessel having two orifices in one side can be found from

$$dt = \frac{100dh}{\sqrt{h+12} + \sqrt{h}}$$

Find this time if the limits of h are 0 and 10.

20. Express e^{-t^2} as a series, and thence find the value of—

$$\frac{\pi}{\sqrt{\pi}} \int e^{-t^2} dt.$$

21. The maximum intensity of shearing stress over a circular section of radius $r = S = \frac{F}{2rl} \int_0^r 2(r^2 - y^2)^{\frac{1}{2}} y dy$.

If $I = \frac{\pi r^4}{4}$, find a simple expression for S .

22. Evaluate the integral $\int \frac{dt}{t - \sqrt{t^2 - 4}}$. [Hint.—Rationalise the denominator.]

23. Write down the value of $\int_0^{\frac{\pi}{2}} \cos^8 \theta d\theta$.

24. If the value of $\log(1.85)$ is given in the tables as 0.9757, find the value of $\int_0^{\infty} e^{-x} x^{1.85} dx$.

25. Write down the value of $\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \sin^2 \theta \cos^7 \theta d\theta$.

26. When finding the forces in a circular arched rib it was found necessary to find the value of—

$$2 \int_0^{\frac{\pi}{6}} R^3 \left(\cos^2 \theta - \sqrt{3} \cos \theta + \frac{3}{4} \right) d\theta. \text{ Evaluate this integral.}$$

27. Evaluate the indefinite integral $\int \sqrt{21 - 5x - x^2} dx$.

28. The attraction F of a thin circular disc of radius r on a body on the axis of the disc, and distant z from the centre, is given by—

$$F = -2\pi\sigma kz \int_0^a \frac{r dr}{(r^2 + z^2)^{\frac{3}{2}}}$$

where σ is the density of the disc, and k is a constant.

Find the value of F for this case.

CHAPTER VII

**MEAN VALUES : ROOT MEAN SQUARE VALUES :
VOLUMES : LENGTH OF ARC : AREA OF SURFACE
OF SOLID OF REVOLUTION : CENTROID : MOMENT
OF INERTIA**

Determination of Mean Values.—It is frequently necessary to calculate the mean value of a varying quantity: thus if a variable force acts against a resistance, the work done will be dependent on the mean value of the force; or to take an illustration from electrical theory, if we can find the values of the current and electro-motive force at various instants during the passage of the current, then the mean rate of working is the mean value of their product.

The mean value of a series of values is found by adding the values together and then dividing by the number of values taken. If, however, a curve is drawn to give by its ordinate the magnitude of the quantity at any instant, the mean value of the quantity is determined by the mean height of the diagram, which is the area divided by the length of the base. This really amounts to the taking of an exceedingly large number of ordinates and then calculating their average.

The area may be measured by the planimeter, in which case the instrument may be set to record the mean height directly, or by any of the methods enumerated in Part I, Chap. VII.

A clear conception of the idea of mean values can be gained by consideration of the examples that follow; the first example being merely of an arithmetical nature.

Example 1.—The corresponding values of an electric current and the E.M.F. producing it are as in the table :—

C	0	1·8	3·5	5	6·1	6·8	6·1	5	3·5	1·8
E	0	9	17·5	25	30·5	34	30·5	25	17·5	9

Find the mean value of the power over the period during which these values were measured.

The power is measured by the product current \times E.M.F., and thus the values of the power are—

$$\begin{array}{ccccccccc} 0 & 16.2 & 61.25 & 125 & 186.05 & 231.2 & 186.05 & 125 & 61.25 & 16.2 \\ \text{the sum} = 1008.2 & & & & & & & & & \end{array}$$

the number of values = 10

$$\text{hence the average or mean value} = \frac{1008.2}{10} = 100.8.$$

A better result would probably be obtained if the values of the power were plotted and the area of the diagram found.

Thus in Fig. 39 the base is taken as 10 units (merely for convenience), and the area is found to be 1013 sq. units. Then the mean height of the diagram, which is $\frac{1013}{10} = 101.3$, is also the mean value of the power; and a line drawn at a height of 101.3 units divides the figure in such a way that the area B is equal to the areas A+A.

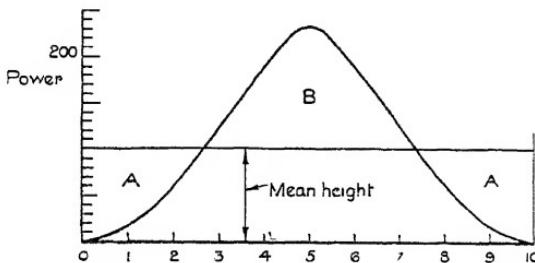


FIG. 39.

Let it next be required to find the mean value of a function—say, the mean value of y when $y = 4x^2 + 7x - 5$, the range of x being 1 to 6. We have seen that it is really necessary first to find the area under the curve $y = 4x^2 + 7x - 5$ within the proper boundaries and then to divide by the length of the base; and since the relation between y and x is stated, it is possible to dispense with the graph and work entirely by algebraic integration; thus also ensuring the true result, for in reality the mean is automatically taken of an infinite number of ordinates.

In the case taken as an illustration, the base is the axis of x , or, more strictly, the portion of it between $x = 1$ and $x = 6$, so that the length of the base = $6 - 1 = 5$ units, and the area between the curve, the axis of x and the ordinates through $x = 1$

and $x = 6$ is given by the value of $\int_1^6 y \, dx$, i.e., $\int_1^6 (4x^2 + 7x - 5) \, dx$,

so that the mean value (for which we shall write m.v.) is—

$$\begin{aligned} \text{m.v.} &= \frac{\int_1^6 (4x^2 + 7x - 5) dx}{5} \\ &= \frac{\left[\frac{4x^3}{3} + \frac{7x^2}{2} - 5x \right]_1^6}{5} \\ &= \frac{\left(\frac{4 \times 216}{3} \right) + \left(\frac{7 \times 36}{2} \right) - 30 - \frac{4}{3} - \frac{7}{2} + 5}{5} \\ &= \frac{384.17}{5} = 76.83. \end{aligned}$$

It is instructive to compare this result with the results obtained by the use of the mid-ordinate rule :—

(a) Taking 5 ordinates only, we have the values—

	$4x^2 + 7x - 5$	y
$1\frac{1}{2}$	$9 + 10.5 - 5$	14.5
$2\frac{1}{4}$	$25 + 17.5 - 5$	37.5
$3\frac{1}{2}$	$49 + 24.5 - 5$	68.5
$4\frac{1}{2}$	$81 + 31.5 - 5$	107.5
$5\frac{1}{2}$	$121 + 38.5 - 5$	154.5

$$\text{Their sum} = \frac{382.5}{5}$$

and the average = 76.5.

(b) Taking 10 ordinates, viz., those at $x = 1\frac{1}{4}, 1\frac{3}{4}, 2\frac{1}{4}$, etc.. the values of y are 10, 19.5, 31, 44.5, 60, 77.5, 97, 118.5, 142 and 167.5

$$\begin{array}{ll} \text{their sum} & = 767.5 \\ \text{and the average} & = 76.75. \end{array}$$

Therefore, by increasing the number of ordinates measured, a better approximation is found.

The curve is a parabola with axis vertical, and hence Simpson's rule should give the result accurately if 3 ordinates only are taken, viz., at $x = 1, 3.5$ and 6.

Thus, A = 6, M = 68.5, B = 181.

$$\begin{aligned} \text{Hence the mean height} &= \frac{6 + (4 \times 68.5) + 181}{6} \\ &= \frac{461}{6} = 76.83. \end{aligned}$$

If, then, the law connecting the two variables is known, the mean value of the one over any range of the other can be found by integrating the former with regard to the latter between the proper limits and then dividing by the range; or to express in symbols, if $y = f(x)$, the mean value of y , as x ranges from a to b , is given by—

$$\frac{\int_a^b y \, dx}{b-a}$$

Example 2.—Find the mean value of e^{5x} between $x = -2$ and $x = -7$

$$\begin{aligned} \text{m.v.} &= \frac{\int_{-2}^{-7} e^{5x} \, dx}{-7 - (-2)} = \frac{1}{5} \left\{ \frac{1}{5} e^{5x} \right\}_{-2}^{-7} \\ &= \frac{2}{5} \{e^{3.5} - e^{1.0}\} \\ &= \frac{2}{5} \{33.12 - 2.72\} \\ &= \underline{\underline{12.16}} \end{aligned}$$

i.e., if the curve $y = e^{5x}$ were plotted between $x = -2$ and $x = -7$ its mean ordinate would be 12.16 units.

Example 3.—If $C = 5 \sin 3t$, find the m.v. of C , when—

$$(a) t \text{ varies from } 0 \text{ to } \frac{2\pi}{3}$$

$$(b) t \text{ varies from } 0 \text{ to } \frac{\pi}{3}.$$

Whenever dealing with the integration of trigonometric functions it is advisable first to determine the period of the function, since much numerical work may often be saved in this way. The sine and cosine curves are curves symmetrical about the axis of the I.V. (i.e., x or t , as the case may be); hence there is as much area above this axis as below it, if a full period or a multiple of periods be considered. Therefore, regarding the area above the x axis as positive and the area below this axis as negative, the net area over the full period is zero, so that the mean height of the curve, and therefore the m.v. of the function, must be zero.

$$\text{For the case of } C = 5 \sin 3t, \text{ the period} = \frac{2\pi}{\text{coefft. of } t} = \frac{2\pi}{3}$$

and hence if the m.v. is required for t ranging from 0 to $\frac{2\pi}{3}$

$$0 \text{ to } \frac{4\pi}{3}, \text{ etc.}$$

the result is zero.

Hence, whenever the analysis shows that the full period is involved, there is no need to go through the process of integration. In this case, however, the integration is performed for purposes of verification.

$$(a) \quad \text{m.v. of } C = \int_0^{\frac{\pi}{3}} \frac{5 \sin 3t \, dt}{2\pi} = \frac{3 \times 5}{2\pi} \left(-\frac{1}{3} \cos 3t \right)_0^{\frac{\pi}{3}}$$

$$= -\frac{5}{2\pi} (\cos 2\pi - \cos 0)$$

$$= -\frac{5}{2\pi} (1 - 1) = 0.$$

$$(b) \quad \text{m.v. of } C = \int_0^{\frac{\pi}{3}} \frac{5 \sin 3t \, dt}{\pi} = \frac{3}{\pi} \times 5 \left(-\frac{1}{3} \cos 3t \right)_0^{\frac{\pi}{3}}$$

$$= -\frac{5}{\pi} (\cos \pi - \cos 0)$$

$$= -\frac{5}{\pi} (-1 - 1) = \frac{10}{\pi}.$$

Comparing this with the amplitude, which is the maximum ordinate of the curve and has the value $5 \sin \frac{\pi}{2} = 5$, we note that—

$$\frac{\text{Mean ordinate for } \frac{1}{2} \text{ period}}{\text{Maximum ordinate for } \frac{1}{2} \text{ period}} : \frac{\frac{10}{\pi}}{\pi \times 5} = \frac{2}{\pi} = .637.$$

The average height of a sine curve is always $.637 \times$ the maximum height.

Example 4.—If an alternating electric current is given by the relation—

$$C = .5 \sin 120\pi t + .06 \sin 600\pi t$$

find the mean value of C .

The graph is of great assistance in this evaluation; and consequently the curves $c_1 = .5 \sin 120\pi t$, $c_2 = .06 \sin 600\pi t$, and $C = c_1 + c_2 = .5 \sin 120\pi t + .06 \sin 600\pi t$ are plotted in Fig. 40. The period of $c_1 = .5 \sin 120\pi t$ is $\frac{2\pi}{120\pi}$ or $\frac{1}{60}$, and of $c_2 = .06 \sin 600\pi t$ is

$\frac{2\pi}{600\pi}$ or $\frac{1}{300}$, so that the period of the compound curve must be $\frac{1}{60}$.

From the previous reasoning it is seen that the mean height of the curve $c_1 = .5 \sin 120\pi t$ must be $.637 \times$ amplitude $= .637 \times .5 = .3185$; and the mean height of the curve $c_2 = .06 \sin 600\pi t$ considered over the same period, viz., 0 to $\frac{1}{120}$, must be the mean height of the wave A, since the positive and negative areas are otherwise balanced, but this

must be spread over five times its usual base; now the mean height of the wave A is $\cdot 637 \times \cdot 06$, so that the mean height of the curve $c_2 = \cdot 06 \sin 600\pi t$ over the period 0 to $\frac{I}{120}$ is $\frac{\cdot 637 \times \cdot 06}{5}$ or $\cdot 0076$.

Then the mean value of $C = \cdot 3185 + \cdot 0076 = \underline{\underline{\cdot 3261}}$.

The nature of the average should be clearly understood; for it is possible that the same quantity may have two different averages according to the way those averages are considered. Suppose a piston is pushed by a variable force; then the average value of that force might be found by taking readings of it at every foot of the stroke and dividing by the number of readings taken, in

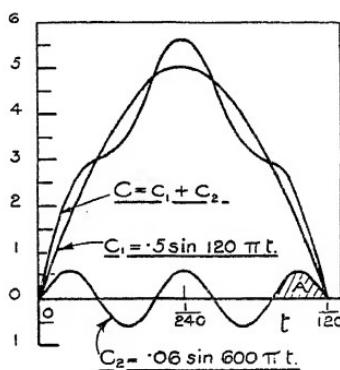


FIG. 40.—Problem on Alternating Current.

which case the average would be termed a space average; or the force might be measured at equal intervals of time, whence the time average of the force would result.

To take another instance:—Suppose a bullet penetrates a target to a depth of s ft.; the average value of the force calculated from the formula $P_s = \frac{mv}{2g}$ where P is the force, would be a space average, but P calculated from the formula $P_t = \frac{mv}{g}$, i.e., the force causing change of momentum in a definite time, would be a time average.

To illustrate further: A body starts from rest and its speed increases at the uniform rate of 4 ft. per sec.². Find the time and space averages of the velocity if the motion is considered to take

place for 6 secs. {Use the relations $s = \frac{1}{2}at^2$, $v = at$ and $v^2 = 2as$.

$$s = \frac{1}{2}at^2 = \frac{1}{2} \times 4 \times 6^2 = 72$$

and if the limits of t are 0 and 6

then the limits of s are 0 and 72.

To find the time average of the velocity—

$$\begin{aligned} \text{t.a.} &= \frac{\int_0^6 v dt}{6-0} = \frac{\int_0^6 at dt}{6} \\ &= \frac{1}{6} \left(\frac{1}{2} at^2 \right)_0^6 = \frac{1}{12} \times 4 (36-0) \\ &= 12 \text{ f.p.s.} \end{aligned}$$

To find the space average of the velocity—

$$\begin{aligned} v^2 &= 2as = 8s \\ \text{or} \quad v &= \sqrt{8s} \end{aligned}$$

and the mean value of $v = \text{mean value of } \sqrt{8s^{\frac{1}{2}}}$.

$$\begin{aligned} \text{Hence the space average} &= \frac{\int_0^{72} \sqrt{8s^{\frac{1}{2}}} ds}{72-0} = \frac{1}{72} \times \sqrt{8} \left(\frac{2}{3} s^{\frac{3}{2}} \right)_0^{72} \\ &= \frac{\sqrt{8}}{72} \times \frac{2}{3} (72^{\frac{3}{2}} - 0) \\ &= \frac{\sqrt{8}}{108} (432\sqrt{2}) \\ &= \frac{432 \times 4}{108} = 16 \text{ f.p.s.} \end{aligned}$$

Example 5.—The electrical resistance R_t of a rheostat at temperature $t^\circ \text{ C.}$ is given by—

$$R_t = 38(1 + 0.004t).$$

Find its average resistance as t varies from 10° to 40° C. (This will be a temperature average.)

$$\begin{aligned} \frac{\int_{10}^{40} R_t dt}{40-10} &= \frac{1}{30} \int_{10}^{40} 38(1 + 0.004t) dt \\ &= \frac{38}{30} \left(t + 0.002t^2 \right)_{10}^{40} \\ &= \frac{38}{30} (40 + 3.2 - 10 - 2) \\ &= \frac{38 \times 33}{30} \\ &= 41. \end{aligned}$$

Example 6.—If $V = V_0 \sin qt$ and $C = C_0 \sin (qt - c)$, find the average value of the power, *i.e.*, the average value of VC .

$$\begin{aligned} VC &= V_0 \sin qt \cdot C_0 (\sin qt - c) \\ &= \frac{V_0 C_0}{2} \{2 \sin qt \cdot \sin (qt - c)\} \\ &= \frac{V_0 C_0}{2} \{\cos c - \cos (2qt - c)\} \end{aligned}$$

also the period $= \frac{2\pi}{q}$.

Hence the m.v. of VC

$$\begin{aligned} &\frac{V_0 C_0}{2} \int_{\frac{2\pi}{q}}^{\frac{2\pi}{q}} [\cos c - \cos (2qt - c)] dt \\ &= \frac{V_0 C_0 q}{2 \times 2\pi} \left[\cos c \times t - \frac{1}{2q} \sin (2qt - c) \right]_0^{\frac{2\pi}{q}} \\ &= \frac{q}{2\pi} \times \frac{V_0 C_0}{2} \left\{ \frac{2\pi}{q} \cos c - \frac{1}{2q} \sin (4\pi - c) - 0 + \frac{1}{2q} \sin (-c) \right\} \\ &= \frac{V_0 C_0 q}{4\pi} \times \frac{2\pi}{q} \cos c \quad \left[\text{for } \sin (4\pi - c) = \sin (-c) \right] \\ &\quad \left[\text{and } -\sin (-c) + \sin (-c) = 0 \right] \\ &= \frac{1}{2} V_0 C_0 \cos c \end{aligned}$$

i.e., the mean value of the power = one-half the products of the maximum values or amplitudes with the cosine of the lag.

This is a most important result.

If $c = 90^\circ$, *i.e.*, if the lag is $\frac{\pi}{2}$, then $\cos c = 0$ and the mean value of the watts $= \frac{1}{2} V_0 C_0 \times 0 = 0$; this being spoken of as the case of *wattless current*.

Exercises 16.—On Mean Values.

1. If a gas expands so as to follow the law $\rho v = 120$, find the average pressure between the volumes 2 and 4.
2. Find the mean value of e^{2-5y} as y varies from 0 to 4.
3. The mean height of the curve $y = 3x^3 + 5x - 7$ is required between the limits $x = -2$ and $x = +3$; find this height.
4. Find the mean value of $2 \cdot 18 \sin (3t - 1 \cdot 6)$ as t ranges from 1.4 to 1.6.
5. What is the mean value of $4 \cdot 5 + 2 \sin 60t$, t ranging from 0 to $\frac{\pi}{30}$? Discuss this question from its graphic aspect.

6. Find the mean value of p , when $pv^{1.37} = 550$, for the range of v from 4 to 22.

7. The illumination I (foot candles) of a single arc placed 22 ft. above the ground, at d ft. from the foot of the lamp is given by $I = 14 \cdot 0 \cdot d$. Find the mean illumination as d varies from $\frac{1}{2}$ ft. to 10 ft.

8. An alternating current is given by $C = 2 \sin 100\pi t + 0.1 \sin 300\pi t$. Find the mean value of C for the range of t , 0 to 0.02 sec.

9. Taking the figures in Question 8, find the mean value of C when t ranges from 0 to 0.1 sec.

10. Find the mean value of $5 \sin 6t \times 220 \sin 4t$, t ranging from 0 to $\frac{\pi}{3}$.

11. The table gives the values of the side thrust on the piston of a 160 H.P. Mercedes aero engine for different positions of the crank; the positive values being the thrust on the right-hand wall, and the negative values being the thrust on the left-hand wall of the piston.

Angle of crank from top dead centre }	0	40	80	120	160	180	200	220	240	280	300	320	330
Total side thrust (lbs.) }	0	+210	0	-170	-175	-185	-100	0	+95	+240	+100	0	-30 0
	345	360	10	40	80	120	160	180	200	220	240	280	290
	+20	0	-600	-780	-720	-580	-170	0	+90	+170	+160	+150	+50
											0	-210	0

Plot these values (treating them all as positive) and thence determine the mean side thrust throughout the cycle.

Root Mean Square Values.—A direct electric current may be measured by its three effects—chemical decomposition, magnetic effect or heating effect. An alternating current (A.C.), however, flowing first in one direction and then in the reverse, cannot be measured by either the first or the second of these effects, because the effect due to the flow in one direction would be neutralised by that due to the opposite flow ; hence an A.C. must be measured by its heating effect.

The heating effect of a current expressed by the heat units H may be measured by—

$$H = \frac{C^2 R t}{J} \text{ where } C \text{ is the current,}$$

so that it will be seen that $H \propto C^2$.

The measuring instruments are graduated to give the root of the mean value of this heating effect, *i.e.*, the square root of the

mean value of the squares (called the root mean square value and written R.M.S.); in other words, the instrument records what are termed virtual amperes, a virtual ampere being the current that produces the same heat in a resistance as a steady or direct current of 1 ampere in the same time.

In place of the measurement of the current by its heating effect, the ammeter might be of the electro-dynamometer type, and in such the instrument records the mean value of C^2 , and the square root of this value is called the effective current.

Similar remarks apply also to the measurement of alternating E.M.F.

It is therefore necessary to determine R.M.S. values of functions likely to be encountered, and to compare the virtual with the steady.

While the determination of R.M.S. values is of greatest importance from the application to electrical problems, it is also occasionally of use in problems of mechanics; thus the calculation of what is known as a swing radius (see p. 240) is in reality a determination of a R.M.S. value.

In order to convey the full interpretation of the term R.M.S. value, we shall discuss first a simple arithmetical example, then some algebraic examples, leading up finally to the trigonometric functions.

Example 7.—The values of an alternating electric current at various times are given in the table—

<i>t</i>	0	·01	·02	·03	·04	·05	·06	·07	·08	·09	·1
<i>C</i>	0	1·8	3·5	5	6·1	6·8	6·1	5	3·5	1·8	0

Find the mean value and also the R.M.S. value of the current, and compare the two values.

The mean value, as before explained, is the average of the given values and is 3·96.

We must now tabulate the values of the squares; thus—

0 3·24 12·25 25 37·21 46·24 37·21 25 12·25 3·24 and 0.

The sum of the squares = 201·64

the mean of the squares or M.S. = $\frac{201\cdot64}{10}$

for we must only reckon the end values as half-values when adding

up the ordinates, since the end values belong equally to the sequences on either side.

Thus—

$$\text{M.S.} = 20 \cdot 16$$

and the square root of the result = R.M.S. = $\sqrt{20 \cdot 16} = 4 \cdot 5$.

This question might have been worked entirely by graphic methods, according to the following plan—

Plot the values of C to a base of t , giving the curve ABD in Fig. 41; find the area under the curve and divide by the base, thus obtaining the mean height; plot also the values of C^2 against those of t , giving the curve EFG. By graphic summation determine the area under the curve EFG and draw the line MM at the mean height of the diagram. Make MN = 1 unit on the scale of C^2 and on PN describe a semicircle; produce MM to cut the semicircle in R. Then MR = 4.5 is the R.M.S. value.

Thus the mean value = 3.96 and the R.M.S. value = 4.5, and the ratio $\frac{\text{R.M.S. value}}{\text{mean value}} = \frac{4.5}{3.96} = 1.14$; this ratio being termed the *form factor*.

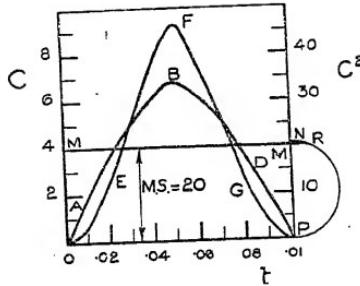


FIG. 41.—R.M.S. Value of an Alternating Current.

Example 8.—Find the R.M.S. value of the function $2x^{1.5} - 3x$ as x ranges from 2 to 5.

$$\text{The square } = (2x^{1.5} - 3x)^2 = 4x^3 + 9x^2 - 12x^{2.5}$$

Explanation.

$$\begin{aligned} \text{and the M.S.} &= \frac{1}{5-2} \int_{2}^{5} (4x^3 + 9x^2 - 12x^{2.5}) dx \\ &= \frac{1}{3} \left(x^4 + 3x^3 - 3 \cdot 43x^{3.5} \right) \Big|_2^5 \\ &= \frac{1}{3} [(625 + 375 - 959) - (16 + 24 - 38.8)] \\ &= 13.27. \end{aligned}$$

Hence the R.M.S. value—

$$= \sqrt{13.27} = 3.64.$$

No.	Log.
6990	.6990
35	35
34950	34950
20970	20970
244650	244650
5353	5353
959	959
29918	29918
2	3010
35	35
15050	15050
9030	9030
105550	105550
3843	3843
5353	5353
38.8	38.8
15883	15883

Example 9.—Suppose that an alternating electric current at any time follows the sine law, *i.e.*—

$$C = C_0 \sin qt$$

where C is the instantaneous value of the current at any time t , and C_0 is the maximum value of the current.

Find the R.M.S. value of the current.

As we have already seen, the determination of the R.M.S. value implies that first the square of the function at various times must be calculated, then the mean value of these squares found, and finally the square root of this average extracted.

To assist in the study of this important problem, the curve $y = \sin x$, the simple sine curve, is shown in Fig. 42, and also the

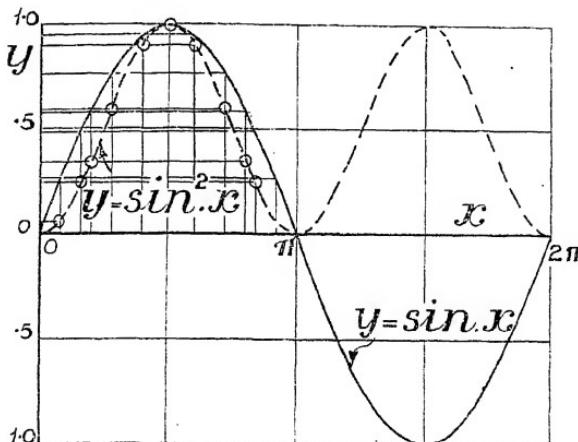


FIG. 42.—R.M.S. Value of an Alternating Current.

curve $y = \sin^2 x$, which is obtained from the former curve by squaring its ordinates. It will be observed that whilst for the curve $y = \sin x$ there are both positive and negative ordinates, in the case of the curve of squares all the ordinates are positive. Also the period of the curve of squares is noted to be one-half that of the simple curve; and therefore when calculating the mean height of this curve, it is immaterial whether the full or the half period of the simple sine curve is taken as the range.

In the case with which we are here particularly concerned the square $= C^2 = C_0^2 \sin^2 qt = \frac{C_0^2}{2} (1 - \cos 2qt)$, and the period $= \frac{2\pi}{q}$, so that the integration may be performed either over the range 0 to $\frac{2\pi}{q}$ or 0 to $\frac{\pi}{q}$.

Taking the latter range—

$$\text{Mean of the squares} = \text{M.S.} = \frac{\int_0^{\pi} C_0^2 \sin^2 qt dt}{\frac{\pi}{q}}$$

$$= \frac{qC_0^2}{\pi} \int_0^{\frac{\pi}{q}} (1 - \cos 2qt) dt$$

$$= \frac{qC_0^2}{2\pi} \left[\left(t - \frac{1}{2q} \sin 2qt \right) \right]_0^{\frac{\pi}{q}}$$

$$= \frac{qC_0^2}{2\pi} \left[\frac{\pi}{q} - \frac{1}{2q} \sin 2\pi - 0 + \frac{1}{2q} \sin 0 \right]$$

$$= \frac{qC_0^2}{2\pi} \times \frac{\pi}{q} = \frac{C_0^2}{2}$$

$$\therefore \text{R.M.S.} = \frac{C_0}{\sqrt{2}} = .707 C_0$$

or R.M.S. value = $.707 \times$ maximum value
i.e., virtual value of current or E.M.F. = $.707 \times$ maximum value of current or E.M.F.

Hence if a meter registers 10 amps., the maximum current is $\frac{10}{.707}$
i.e., 14.14 amps., or there is a variation between +14.14 and -14.14.

* In the evaluation of the integral $\int_0^{\frac{\pi}{q}} (1 - \cos 2qt) dt$, it should be noted that it can be written $\int_0^{\frac{\pi}{q}} dt - \int_0^{\frac{\pi}{q}} \cos 2qt dt$, and the value of the second term is zero, because it is the area under a cosine curve taken over its full period. Hence the integral reduces to $\int_0^{\frac{\pi}{q}} dt$, and there is no need to say anything further about the second term.

Example 10.—Find the R.M.S. value of $a+b \sin 4t$.

For this function the period = $\frac{2\pi}{4} = \frac{\pi}{2}$.

Then $S = (a+b \sin 4t)^2 = a^2 + b^2 \sin^2 4t + 2ab \sin 4t$
 $= a^2 + \frac{b^2}{2} (1 - \cos 8t) + 2ab \sin 4t$.

Hence M.S. = $\frac{2}{\pi} \int_0^{\frac{\pi}{2}} (a^2 + \frac{b^2}{2} - \frac{b^2}{2} \cos 8t + 2ab \sin 4t) dt$
 $= \frac{2}{\pi} \left[a^2 t + \frac{b^2}{2} t - \frac{b^2}{16} \sin 16t + 2ab \int_0^{\frac{\pi}{2}} \sin 4t dt \right]$

$$\begin{aligned}
 &= \frac{2}{\pi} \left[a^2 t + \frac{b^2 t}{2} - o + o \right]_0^{\frac{\pi}{2}} \\
 &= \frac{2}{\pi} \left(a^2 \frac{\pi}{2} + \frac{b^2 \pi}{2} - o - o \right) = a^2 + \frac{b^2}{2} \\
 \text{R.M.S.} &= \sqrt{a^2 + \frac{b^2}{2}}
 \end{aligned}$$

Exercises 17.—On Root Mean Square Values.

Find the R.M.S. values of the functions in Nos. 1 to 7.

1. $x^3 + 2$ (x ranging from 1 to 3).
2. e^{-tx} (x ranging from -1 to $+65$).
3. $3 \cdot 4 \sin 5 \cdot 1t$.
4. $165 \cos (0 \cdot 07 - 2t)$.
5. $1 \cdot 4 \tan 2t$ (t ranging from 0 to $0 \cdot 43$).
6. $1 \cdot 14 + 0 \cdot 5 \cos 8t$.
7. $0 \cdot 72 \sin (3 - 4t)$; compare with the mean value.
8. Find the form factor $\left(\frac{\text{R.M.S. value}}{\text{mean value}} \right)$ of the wave—

$$e = E_1 \sin pt + E_3 \sin 3pt.$$
9. Compare the "effective" values of two currents, one whose wave form is sinusoidal, having a maximum of 100 amperes, and another of triangular shape with a maximum of 150 amperes.
10. An A.C. has the following values at equal intervals of time :
 3, 4, 4.5, 5.5, 8, 10, 6, 0, -3, -4, -4.5, -5.5, -8, -10, -6, 0.
 Find the R.M.S. value of this current.
11. A number of equal masses are attached to the ends of rods rotating about one axis. If the lengths of these rods are 10, 9, 5, 8, 4, 13 and 15 ins. respectively, find the effective radius (called the swing radius) of the system. (This is the R.M.S. value of the respective radii.)
12. Find the R.M.S. value of the function $\sin^2 \theta \cos^3 \theta$ over the period 0 to $\frac{\pi}{2}$. (Refer to p. 178.)
13. The value of the primary current through a transformer at equal time intervals was—
 .20 .05 .07 .11 .14 .19 .21 .04 .08 .12 .15 .18 .21 .08 .04
 Find the R.M.S. value of this current.

Volumes.—If a curve be drawn, the ordinates being the values of the cross sections of a solid at the various points along its length, then the area under the curve will represent, to some scale, the volume of the solid. For, considering a small element

volume δV of the small portion of the solid is $A\delta l$, and the total volume of the solid is the sum of all such small volumes, i.e., $\Sigma A\delta l$. If the length δl is diminished until infinitely small, $\Sigma A\delta l$ becomes $\int Adl$, and hence—

$$\text{Volume of solid} = \int_0^l Adl.$$

Comparing this with the formula giving the area of a closed figure, viz., $\int ydx$, it is seen to be of the same form, and it is made identical if A is written in place of y (i.e., areas must be plotted vertically) and l in place of x (i.e., lengths must be plotted horizontally).

When values of A and l are given the curve should be drawn and integrated by any of the given methods; and if it is preferred to find the actual area of the figure in sq. ins. first, the number of units of volume represented will be deduced from a consideration of the scales used in the plotting. Thus if $1''$ (horizontally) represents x ft. of length, and $1''$ (vertically) represents y sq. ft. of area, then 1 sq. in. of area represents xy cu. ft. of volume. To take a numerical example: If $1'' = 15''$ of length, and $1'' = 5$ sq. ft. of area, then 1 sq. in. of area $= \frac{15}{12} \times 5 = 6\frac{1}{4}$ cu. ft. of volume.

If the area is found by the sum curve this conversion is unnecessary, as the scales are settled in the course of the drawing. The Example on p. 122 is an illustration of the determination of volumes by graphic integration; in that case the actual areas of sections are not plotted directly, but values of d^2 , the multiplication by the constant factor being left until the end. Had the solid not been of circular section the actual areas would have been plotted as ordinates and the work carried on as there detailed.

We thus see that the determination of the volume of any irregular solid can be effected, if the cross sections at various distances from the ends can be found, by a process of graphic integration.

If, however, the law governing the variation in section is known, it may be more direct to perform the integration by algebraic methods.

To take a very simple illustration:—

Example 11.—The cross section of a certain body is always equal to $(5x^3 + 8)$ sq. ft., where x ft. is the distance of the section from one end. If the length of the body is 5 ft., find its volume.

The body might have an elevation like Fig. 43, and its cross section might be of any shape; the only condition to be satisfied being that the area of a cross section such as that at BB must = $5x^3 + 8$. Thus the area at AA must = $(5 \times 0) + 8 = 8$ and area at CC = $(5 \times 5^3) + 8 = 633$.

$$\begin{aligned} \text{Then the volume} &= \int_0^5 (5x^3 + 8) dx \\ &= \left(\frac{5x^4}{4} + 8x \right)_0^5 = \frac{3125}{4} + 40 = \underline{\underline{821.25 \text{ cu. ft.}}} \end{aligned}$$

Volumes of Solids of Revolution.—A solid of revolution is generated by the revolution of some closed figure round an axis which does not cut the figure. Thus, dealing with familiar solids, the right circular cone, the cylinder and the sphere are solids of revolution, being generated respectively by the revolution of a right-angled triangle about one of the sides including the right angle, a rectangle about one of its sides, and a semicircle about its diameter; and of the less well-known solids of revolution the most important to the engineer is the hyperboloid of revolution which is generated by the revolution of a hyperbola about one of its axes and occurs in the design of skew wheels. The axis about which the revolution is made in all these examples lies along a boundary of the revolving figure; whereas an anchor ring is generated by the revolution of a circle about an axis parallel to a diameter but some distance from it.

The revolving figure may have any shape whatever, the only conditions being, for the following rule to hold, that the axis about which the revolution is made does not cut the figure and that the cross section perpendicular to this axis is always circular.

Imagine the revolving cross section to be of the character shown in the sketch (ABCD in Fig. 44); and let the revolution be about the axis of x . It is required to find the volume of the solid of revolution generated.

Working entirely from first principles, *i.e.*, reverting to our idea of dealing with a small element and then summing: if the strip MN of height y and thickness δx revolves about OX it will generate a cylinder.

The radius of this cylinder will be y and its height or length δx ; and hence its volume = $\pi y^2 \delta x$.

Accordingly the volume swept out by the revolution of ABCD

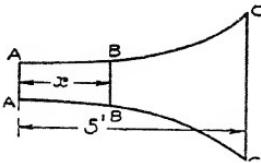


FIG. 43.

will be $\Sigma \pi y^2 \delta x$ (the proper limits being assigned to x) approximately, or $\int \pi y^2 dx$ accurately.

Again, it will be seen that such a volume can be measured by the area of a figure, for, writing Y in place of πy^2 , the volume $= \int Y dx$, which is the standard form for an area. Hence, if values of y are given, corresponding values of πy^2 must be calculated and plotted as ordinates, and the area of the resulting figure found.

It should be noted that $\int \pi y^2 dx$ might be written as $\pi \int y^2 dx$, thus saving labour by reserving the multiplication by π until the

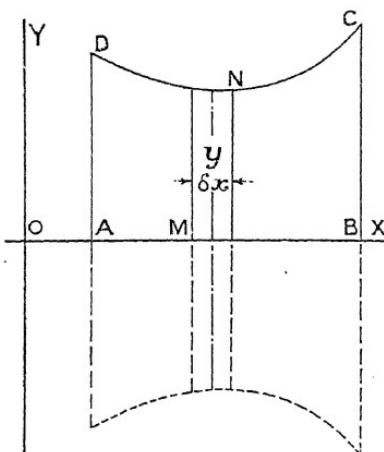


FIG. 44.—Volume of Solid of Revolution.

area has been found, i. e., the values of y^2 and not those of πy^2 are plotted as ordinates.

The following example will illustrate :—

Example 12.—The curve given by the figures in the table revolves about the axis of x ; find the volume of the solid generated, the bounding planes being those through $x = 2$ and $x = 7$, perpendicular to the axis of revolution.

x	2	3	4	5	6	7
y	44	42	44	46	45	38

$$\text{Values of } y^2 \text{ must first be calculated, since the volume} = \int_2^7 \pi y^2 dx \\ = \pi \int_2^7 y^2 dx$$

Hence the table for plotting reads—

x	2	3	4	5	6	7
y^2	1936	1764	1936	2116	2025	1444

and the values of y^2 are plotted vertically, the curve ABC (Fig. 45) resulting.

This curve is next integrated from the axis of x as base, the curve DEF resulting; the polar distance being taken as 3, so that the new

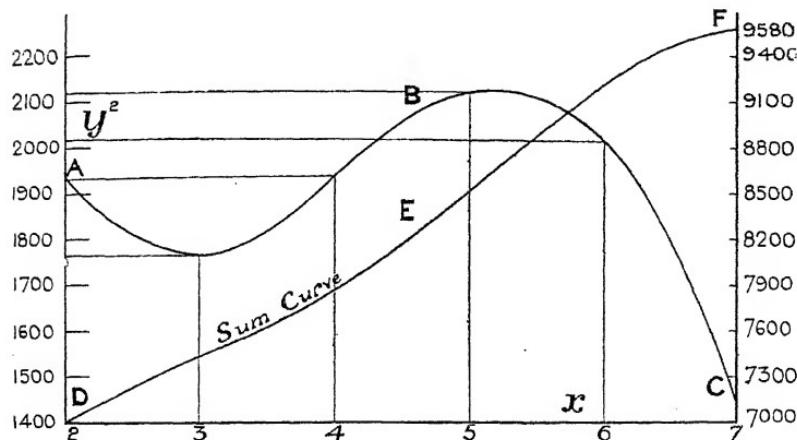


FIG. 45.—Volume of Solid of Revolution.

vertical scale = 3 × old vertical scale. It must be remembered, however, that the base from which the summation has been made in the figure is not the true base, since the first value of the ordinate is 1400 and not 0; thus a rectangle 1400 × 5 has been omitted. Hence we must start to number our scale at 7000; and according to this numbering the last ordinate reads 9580, hence $\int_2^7 y^2 dx = 9580$, or—

$$\begin{aligned}\text{Volume} &= \pi \int_2^7 y^2 dx \\ &= \pi \times 9580 \\ &= \underline{\underline{30,100 \text{ cu. ins.}}}\end{aligned}$$

In cases in which y and x are connected by a law the integra-

tion may be performed in accordance with the rules for the integration of functions.

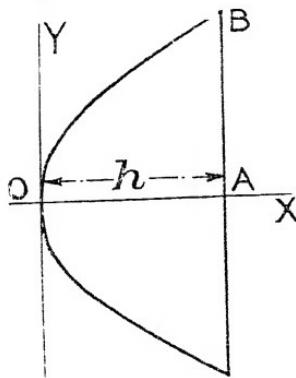


FIG. 46.

Example 13.—Find the volume of a paraboloid of revolution and compare it with the volume of the circumscribing cylinder.

A paraboloid of revolution is generated by the revolution of a parabola about its axis. Suppose the parabola is placed as shown in Fig. 46; the revolution is therefore about OX.

The equation to the curve OB is $y^2 = 4ax$ (see Part I, p. 106), i.e., if OA = h , $(AB)^2 = 4ah$.

Hence the volume of the solid swept out by the revolution of OBA—

$$\begin{aligned} &= \int_0^h \pi y^2 dx = \pi \int_0^h 4ax dx \\ &= 4a\pi \left(\frac{x^2}{2}\right)_0^h \\ &= \frac{4a\pi \times h^2}{2} = 2a\pi h^2. \end{aligned}$$

Now the volume of the circumscribing cylinder—

$$\begin{aligned} &= \pi(AB)^2 \times h \\ &= \pi \times 4ah \times h \\ &= 4a\pi h^2 \end{aligned}$$

and hence the volume of the paraboloid—

$$= \underline{\frac{1}{2} \times \text{vol. of circumscribing cylinder.}}$$

Example 14.—The curve $y^2 = 64 - 2x^2$ revolves about the axis of y . Find the volume of the solid generated, the limits to be applied to x being 0 and 5.

This differs from the cases previously treated in that the revolution is to be about the y axis and not about the x axis.

Hence the volume = $\int \pi x^2 dy$ and not $\int \pi y^2 dx$, the y replacing x and *vice versa*. Also another point must be noted: the limits given are those for x , whereas the limits in the integral $\int \pi x^2 dy$ must apply to the I.V., which is now y . Therefore a preliminary calculation must be made to determine the corresponding limits of y —

$$y^2 = 64 - 2x^2$$

When

$$x = 0, y^2 = 64, y = \pm 8$$

and when

$$x = 5, y^2 = 14, y = \pm 3.74.$$

The double signs occurring here may possibly confuse, but actually the equation given is that of an ellipse, symmetrical about the axes of x and y , and the volume required is the volume generated by the revolution of the two shaded portions (Fig. 47), which will be twice that generated by one of these; hence, taking the upper shaded portion, we use the positive limits, viz., 3.74 and 8.

$$\begin{aligned} \text{Then the volume} &= \int_{3.74}^8 \pi x^2 dy = \pi \int_{3.74}^8 \left(3^2 - \frac{y^2}{2}\right) dy \\ &= \pi(3^2 y - \frac{y^3}{6}) \\ &= \pi(256 - 85.3 - 119.5 + 8.7) \\ &= 59.9\pi. \end{aligned}$$

The solid due to the revolution of the lower portion will be also 59.9π , and hence the total volume generated = $119.8\pi = 376$ cu. units.

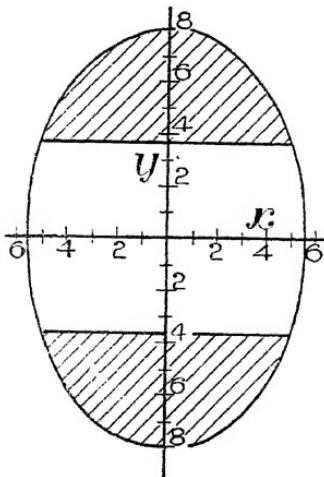


FIG. 47.

If the limits for y were -8 and $+8$, the volume of the whole solid would be required; then—

$$\begin{aligned} \text{Volume} &= \int_{-8}^8 \pi x^2 dy = 2\pi \int_0^8 \left(3^2 - \frac{y^2}{2}\right) dy = 2\pi \left[3^2 y - \frac{y^3}{6}\right]_0^8 \\ &= 2\pi(256 - 85.3) \\ &= 341.4\pi = \underline{\underline{1070}} \text{ cu. units.} \end{aligned}$$

The solid generated by the revolution of an ellipse about its major axis is known as a *prolate spheroid*; while if the revolution is about the minor axis the solid is an *oblate spheroid*.

The volumes of these may be necessary, so that they are given in a general form.

The general equation of an ellipse is $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ (cf. Part I, p. 344).

Let $a > b$, i.e., the major axis is horizontal.

For a prolate spheroid the revolution is about the major axis, and the volume = $2\int_0^a \pi y^2 dx = 2\pi \int_0^a \frac{b^2}{a^2}(a^2 - x^2)dx$

$$= \frac{2\pi b^2}{a^2} \left(a^2x - \frac{x^3}{3} \right)_0^a$$

$$= \frac{2\pi b^2}{a^2} \times \frac{2}{3} a^3$$

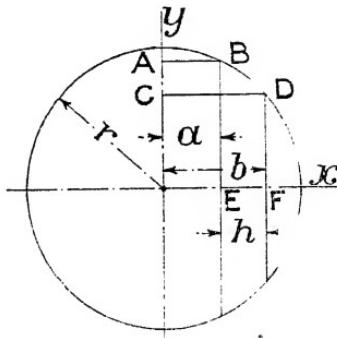
$$= \frac{4}{3}\pi ab^2.$$


FIG. 48.

In like manner, the volume of an oblate spheroid = $\frac{4}{3}\pi a^2 b$; and it should be noted that if $b = a$, the spheroid becomes a sphere and its volume = $\frac{4}{3}\pi a^3$.

Example 15.—Find the volume of a zone of a sphere of radius r , the bounding planes being those through $x = a$ and $x = b$.

The equation of the circle is $x^2 + y^2 = r^2$ (Fig. 48)
whence

$$\therefore \text{Volume of a zone} = \int_a^b \pi y^2 dx = \pi \int_a^b (r^2 - x^2) dx$$

$$= \pi \left(r^2x - \frac{x^3}{3} \right)_a^b$$

$$= \pi \left[r^2(b-a) - \frac{1}{3}(b^3 - a^3) \right]$$

$$= \frac{\pi(b-a)}{3} [3r^2 - (b^2 + ab + a^2)].$$

This can be put in the form given on p. 120, Part I, if for $(b-a)$ we write h , and for BE and DF their respective values r_1 and r_2 .

Thus

$$a^2 = r^2 - r_1^2, \quad b^2 = r^2 - r_2^2$$

$$h^2 = (b-a)^2 = b^2 + a^2 - 2ab = r^2 - r_1^2 + r^2 - r_2^2 - 2ab$$

and hence

$$ab = \frac{-h^2 + 2r^2 - r_1^2 - r_2^2}{2}$$

So that the volume of the zone—

$$\begin{aligned} &= \frac{\pi h}{3} \left\{ 3r^2 - r_1^2 + r_2^2 - r^2 + r_1^2 + \frac{h^2 - 2r^2 + r_1^2 + r_2^2}{2} \right\} \\ &= \frac{\pi h}{3} \left\{ \frac{3r_2^2}{2} + \frac{3r_1^2}{2} + \frac{h^2}{2} \right\} \\ &= \frac{\pi h}{6} \{ 3(r_1^2 + r_2^2) + h^2 \}. \end{aligned}$$

Length of Arc.—Consider a small portion of a curve, PQ in Fig. 49, P and Q being points near to one another.

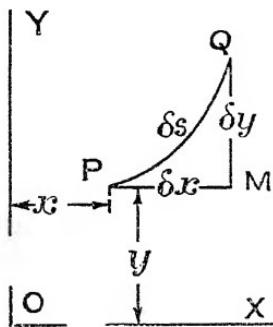


FIG. 49.

The small length of arc PQ is denoted by δs , so that a complete arc would be denoted by s .

Let $PM = \delta x$, and $QM = \delta y$.

Then the arc $PQ =$ the chord PQ very nearly, so that we may say—

$$(\delta s)^2 = (\text{chord } PQ)^2 = (\delta x)^2 + (\delta y)^2.$$

$$\frac{(\delta s)^2}{\delta x} = 1 + \left(\frac{\delta y}{\delta x} \right)^2 \quad \text{or} \quad \left(\frac{\delta s}{\delta x} \right)^2 = \frac{\delta x^2}{\delta y^2} + 1$$

$$\text{i. e.,} \quad \frac{\delta s}{\delta x} = \sqrt{1 + \left(\frac{\delta y}{\delta x} \right)^2} \quad \text{or} \quad \frac{\delta s}{\delta y} = \sqrt{1 + \left(\frac{\delta x}{\delta y} \right)^2}.$$

Hence when δx becomes infinitely small, $\frac{\delta s}{\delta x}$ becomes $\frac{ds}{dx}$, etc.

$$\text{and} \quad \frac{ds}{dx} = \sqrt{1 + \left(\frac{dy}{dx} \right)^2} \quad \text{or} \quad \frac{ds}{dy} = \sqrt{1 + \left(\frac{dx}{dy} \right)^2}.$$

Integrating—

$$s = \int \sqrt{1 + \left(\frac{dy}{dx}\right)^2} \cdot dx \quad \text{or} \quad 1 + \left(\frac{dx}{dy}\right)^2 \cdot dy.$$

The length of arc can thus be found if the value of the integral on the R.H.S. can be evaluated.

In only a few cases is the evaluation of the integral simple; and for most curves an approximation is taken, *e.g.*, to find the perimeter of an ellipse by this method one would become involved in a most difficult integral known as an elliptic integral, this being treated later in the chapter; and hence the approximate rules are nearly always used in practice.

To deal with a case of a very simple character :—

Example 16.—If $y = ax + b$, find the length of arc between $x = m$ and $x = n$.

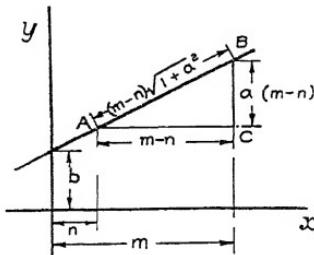


FIG. 50.

In this case it is really a matter of determining the length of the line AB (Fig. 50); the slope of the line being a .

Then if $y = ax + b$, $\frac{dy}{dx} = a$ and $1 + \left(\frac{dy}{dx}\right)^2 = 1 + a^2$.

$$\begin{aligned} \text{Hence } &= \int_n^m \sqrt{1 + a^2} dx = \sqrt{1 + a^2} (x)_n^m \\ &= \sqrt{1 + a^2} (m - n). \end{aligned}$$

On reference to the figure it will be seen that this is a true result, since $AB = \sqrt{(AC)^2 + (CB)^2} = \sqrt{(m - n)^2 + a^2(m - n)^2} = \sqrt{1 + a^2} (m - n)$.

Example 17.—Use this method to determine the approximate length of a cable hanging in a parabola, when the droop is D and the span is $2L$.

For convenience, put the figure in the form of Fig. 51.

$$\text{Then } L^2 = 4aD$$

$$\text{whence } a = \frac{L^2}{4D}, \text{ so that } a \text{ must be very large.}$$

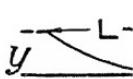
The equation of the curve is in reality—

$$y^2 = 4ax$$

y being written in place of L , and x in place of D

Then $\frac{dy^2}{dx} = 4a$, and also $\frac{dy^2}{dx} = \frac{dy^2}{dy} \times \frac{dy}{dx}$

so that $\frac{dy}{dx} \cdot 2y = 4a$

or $\frac{dy}{dx} = \frac{4a}{2y} = \frac{2a}{y}$ 

whence $\frac{dx}{dy} = \frac{y}{2a}$.

FIG. 51.

Thus

$$\begin{aligned}\sqrt{1 + \left(\frac{dx}{dy}\right)^2} &= \sqrt{1 + \frac{y^2}{4a^2}} = \left(1 + \frac{y^2}{4a^2}\right) \\ &= 1 + \frac{1}{2} \cdot \frac{y^2}{4a^2} + \frac{\frac{1}{2}(1-\frac{1}{2})}{1 \cdot 2} \left(\frac{y^2}{4a^2}\right)^2 + \dots \\ &= 1 + \frac{y^2}{8a^2} \text{ approximately,}\end{aligned}$$

since all the subsequent terms contain a^4 and higher powers of a in the denominator, so that all these terms must be very small.

Hence

$$\begin{aligned}&= 2 \int_0^L \sqrt{1 + \left(\frac{dx}{dy}\right)^2} \cdot dy \\ &= 2 \int_0^L \left(1 + \frac{y^2}{8a^2}\right) dy \\ &= 2 \left(y + \frac{y^3}{24a^2}\right)_0^L \\ &= 2 \left(L + \frac{L^3}{24a^2}\right) \\ &= 2 \left(L + \frac{L^3 \times 16D^2}{24 \times L^4}\right) \quad \text{for } a = \frac{L^2}{4D} \\ &= 2 L + \frac{4D^2}{3L} \quad \text{or Span} + \frac{8 (\text{Drop})^2}{3 \text{Span}}.\end{aligned}$$

Example 18.—Find the length of the circumference of a circle of radius r .

The equation of the circle is $y^2 + x^2 = r^2$.

Thus $y^2 = r^2 - x^2$

and $2y \cdot \frac{dy}{dx} = -2x$ {differentiating with regard to x }

or $\frac{dy}{dx} = -\frac{x}{y} = \frac{-x}{\sqrt{r^2 - x^2}}$

$$\text{Hence } 1 + \left(\frac{dy}{dx}\right)^2 = 1 + \frac{x^2}{r^2 - x^2} = \frac{r^2 - x^2 + x^2}{r^2 - x^2} = \frac{r^2}{r^2 - x^2}$$

$$\begin{aligned}\text{Length of circumference} &= 4 \times \text{length of } \frac{1}{4} \text{ circumference} \\ &= 4 \int_0^a \sqrt{1 + \left(\frac{dy}{dx}\right)^2} \cdot dx \\ &= 4 \int_0^a \frac{r}{\sqrt{r^2 - x^2}} dx.\end{aligned}$$

To evaluate this integral, let $x = r \sin u$ (cf. *Example 7*, p. 150).

$$\begin{aligned}\text{Then } r^2 - x^2 &= r^2 - r^2 \sin^2 u = r^2(1 - \sin^2 u) \\ &= r^2 \cos^2 u\end{aligned}$$

and also

$$\frac{dx}{du} = r \cos u$$

i.e.,

$$dx = r \cos u \cdot du.$$

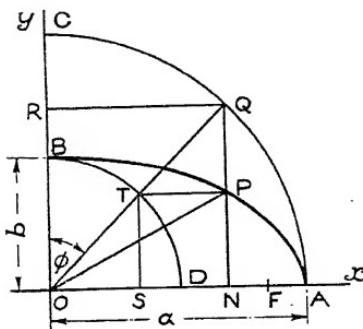


FIG. 52.

To find the limits to be assigned to u —

$$\sin u = \frac{x}{r}; \text{ and when } x = 0, u = 0$$

$$\text{and when } x = r, u = 90^\circ \text{ or } \frac{\pi}{2}$$

Thus the circumference

$$= 4r \int_0^a \frac{dx}{\sqrt{r^2 - x^2}}$$

$$= 4r \int_0^{\frac{\pi}{2}} \frac{r \cos u \, du}{r \cos u}$$

$$= 4r \int u$$

$$= 2\pi r$$

Example 19.—Find an expression for the length of the perimeter of the ellipse whose major and minor axes are $2a$ and $2b$ respectively

Let BPA (Fig. 52) be the ellipse, CQA the quadrant of a circle on the major axis as diameter, and BTD the quadrant of a circle on the minor axis as diameter. Selecting P as any point on the ellipse, draw the lines QPN, PT, TS, QR and OTQ as shown.

The point P has the co-ordinates x and y , viz., ON and PN, which are respectively equal to QR and TS.

$$\text{Now } QR = OQ \sin \phi \text{ or } x = a \sin \phi$$

$$\text{and } TS = OT \cos \phi \text{ or } y = b \cos \phi.$$

$$\text{Thus } \frac{dx}{d\phi} = a \cos \phi \text{ and } \frac{dy}{d\phi} = -b \sin \phi$$

$$\text{and } ds = \sqrt{\left(\frac{dx}{d\phi}\right)^2 + \left(\frac{dy}{d\phi}\right)^2} = \sqrt{a^2 \cos^2 \phi + b^2 \sin^2 \phi}$$

$$\text{or } s = \int \sqrt{a^2 \cos^2 \phi + b^2 \sin^2 \phi} d\phi$$

Now the equation to the ellipse is $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$, and the eccentricity, which we shall denote by K, is given by—

$$K = \frac{\text{distance between foci}}{\text{major axis}} = \frac{\sqrt{a^2 - b^2}}{a} = \frac{OF}{OA}, \text{ F being a focus.}$$

$$\text{Hence } K^2 = \frac{a^2 - b^2}{a^2} \text{ and } K^2 a^2 - a^2 = -b^2$$

$$\text{or } b^2 = a^2(1 - K^2)$$

$$\text{so that } a^2 \cos^2 \phi + b^2 \sin^2 \phi = a^2 \cos^2 \phi + a^2 \sin^2 \phi - a^2 K^2 \sin^2 \phi \\ = a^2(1 - K^2 \sin^2 \phi).$$

Thus our integral reduces to the form—

$$s = \int a \sqrt{1 - K^2 \sin^2 \phi} d\phi$$

and for the quarter of the ellipse the perimeter = $\int_0^{\frac{\pi}{2}} a \sqrt{1 - K^2 \sin^2 \phi} d\phi$,

since the limits for ϕ are obviously 0 and $\frac{\pi}{2}$.

$$\text{Also the full perimeter of the ellipse} = 4 \int_0^{\frac{\pi}{2}} a \sqrt{1 - K^2 \sin^2 \phi} d\phi.$$

This integral, called an "elliptic integral of the second kind," is extremely difficult to evaluate; but in view of the importance of the perimeter of the ellipse it is well that we should carry the work a little further.

Knowing the values of a and K for any particular ellipse, recourse may be made to tables of values of elliptic integrals, but if these are not available, a graphic method presents itself which is not at all difficult to use. According to this plan, various values of ϕ are

chosen between 0 and $\frac{\pi}{2}$, and the calculated values of $\sqrt{1 - K^2 \sin^2 \phi}$ are plotted as ordinates to a base of ϕ . Then the area under the resulting curve when multiplied by $4a$ gives the perimeter of the ellipse.

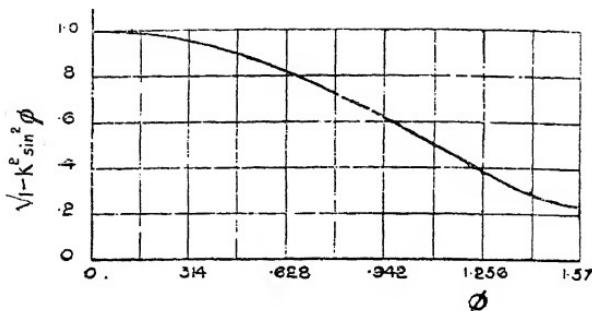


FIG. 53.—Perimeter of Ellipse.

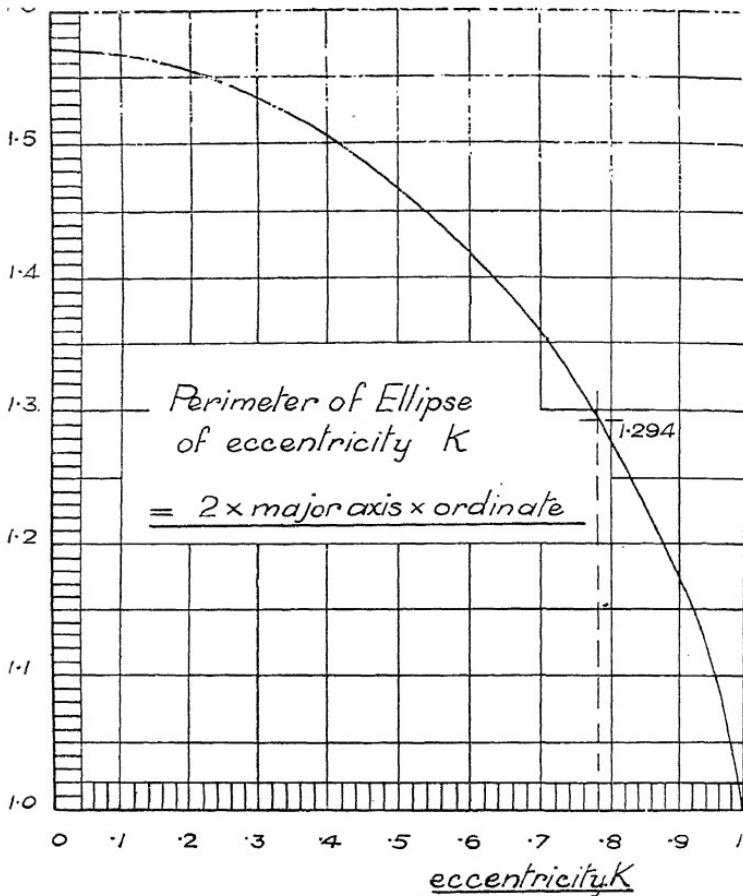


FIG. 54.

Example 20.—A barrier before a ticket office in a works was constructed out of sheet metal, which was bent to the form of an ellipse of major axis 21 ins. and minor axis 5 ins. Find the area of sheet metal required if the height of the barrier is 5 ft.

$$\text{In this case } a = 10.5 \text{ and } K = \frac{\sqrt{10.5^2 - 2.5^2}}{10.5} = .9714$$

so that

$$K^2 = .944.$$

The table for the plotting reads—

ϕ	$\sin \phi$	$\sin^2 \phi$	$1 - K^2 \sin^2 \phi$	$\sqrt{1 - K^2 \sin^2 \phi}$
0	0	0	I	I
.157	.1564	.0245	I - .0232 = .977	.99
.314	.309	.0951	I - .0898 = .91	.955
.471	.454	.206	I - .195 = .805	.897
.628	.5878	.345	I - .326 = .674	.821
.785	.7071	.5	I - .472 = .528	.726
.942	.809	.652	I - .616 = .384	.62
1.099	.891	.793	I - .749 = .251	.501
1.256	.9511	.9	I - .85 = .15	.388
1.413	.9877	.976	I - .922 = .078	.279
1.570	I	I	I - .944 = .056	.235

and the values in the extreme columns are plotted in Fig. 53.

The area under this curve = 1.0663 sq. unit

$$\text{and thus the perimeter} = 4a \times 1.0663 = 4 \times 10.5 \times 1.0663 \\ = 44.78 \text{ ins.}$$

$$\text{Hence the area required} = \frac{5 \times 44.78}{4} = 18.66 \text{ sq. ft.}$$

It is well to compare this value of the perimeter with those obtained by the approximate rules given in Part I, p. 105—

$$(a) \text{ Perimeter} = \pi(a+b) = \pi(10.5+2.5) = 40.84 \text{ ins.}$$

$$(b) \text{ Perimeter} = 4.443\sqrt{a^2+b^2} = 4.443 \times 10.8 = 47.96 \text{ ins.}$$

$$(c) \text{ Perimeter} = \pi[1.5(a+b) - \sqrt{ab}] = \pi \times 14.38 = 45.16 \text{ ins.}$$

and the perimeter, correct to two places of decimals, is given in the tables * as 44.79 ins.

* The tables of complete elliptic integrals give the values of

$\int_0^{\frac{\pi}{2}} \sqrt{1 - K^2 \sin^2 \phi} d\phi$ for various values of θ , θ being the angle whose sine is K , the eccentricity of the ellipse. Thus to use the tables for this particular case we put $\sin \theta = K = .9714$, whence $\theta = 76^\circ 16'$; we then read the values of the integral for 75° , 76° and 77° , and by plotting these values and interpolation we find that for the required

Thus the errors in the results found by the different rules are—

(a) 8·82 % too small (b) 7·08 % too large (c) ·83 % too large showing that the rule of Boussinesq gives an extremely good result in this case of a very flat ellipse, whilst the other approximate methods are practically worthless.

Area of Surface of a Solid of Revolution.—When a solid of revolution is generated, the boundary of the revolving figure sweeps out the surface of that solid. The volume of the solid depends upon the area of the revolving figure, whilst the surface depends upon the perimeter of the revolving figure.

To find the surface generated by the revolution of the curve CD about OX (Fig. 55) we must find the sum of the surfaces swept out by small portions of the curve, such as PQ. Let $PQ = a$ small element of arc $= \delta s$. Then the outside surface of the solid generated by the revolution of the strip PQMN about OX will be equal to the circumference of the base \times slant height, i.e., $2\pi y \delta s$. Hence the total surface will be the sum of all similar elements, i.e.,

$\sum_{x=a}^{x=b} 2\pi y \delta s$, approximately, or if δx becomes smaller and smaller—

$$\text{Surface} = \int_{x=a}^{x=b} 2\pi y ds.$$

For ds we may substitute its value, viz.—

$$ds = \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

$$\text{so that } \text{Surface} = \int_a^b 2\pi y \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx.$$

angle, viz., 1·0664. Multiplication by $4a$, i.e., 42, gives the result 44·79. For the convenience of readers interested in this question, and who desire a result more exact than that given by the approximate

rules, a curve is here given (Fig. 54) with values of $\int_0^{\pi} \sqrt{1 - K^2 \sin^2 \phi} d\phi$ plotted against values of K ; and for the full perimeter of the ellipse the ordinates of this curve must be multiplied by twice the length of the major axis.

E.g., if the major axis = 16 and the minor axis = 10

$$K = \frac{\sqrt{8^2 - 5^2}}{8} = .7807.$$

Erecting an ordinate at $K = .7807$ to meet the curve, we read the value 1·294; multiplying this by 32, we arrive at the figure 41·41, which is thus the required perimeter.

Example 21.—Find the area of the surface of a lune of a sphere of radius a , the thickness or height of the lune being b .

The surface will be that generated by the revolution of the arc CD of the circle about its diameter OX (Fig. 56).

From the figure

$$y^2 = a^2 - x^2$$

whence

$$2y \cdot \frac{dy}{dx} = -2x$$

$$\frac{dy}{dx} = -\frac{x}{y}$$

$$\text{Thus } \left(\frac{ds}{dx}\right)^2 = 1 + \left(\frac{dy}{dx}\right)^2 = 1 + \frac{x^2}{y^2} \therefore \frac{y^2 + x^2}{y^2} = \frac{a^2}{a^2 - x^2}.$$

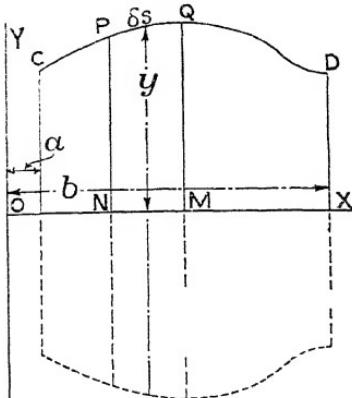


FIG. 55.

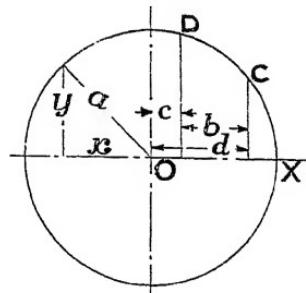


FIG. 56.

$$\begin{aligned} \text{Hence the surface} &= \int_c^d 2\pi \sqrt{a^2 - x^2} \frac{a}{\sqrt{a^2 - x^2}} dx \quad \{d = b+c\} \\ &= 2\pi a \int_c^d dx \\ &= 2\pi a(d - c) = 2\pi ab. \end{aligned}$$

but $2\pi ab$ is the area of a portion of the lateral surface of the cylinder circumscribing the sphere.

Thus the surface of a lune of a sphere = the lateral surface of the portion of the cylinder circumscribing the sphere (the heights being the same).

Exercises 18.—On Volumes, Areas of Surfaces and Length of Arc.

1. The cross sections at various points along a cutting are as follows—

Distance from one end (ft.)	0	40	82	103	134	166	192	200
Area of cross section (sq. ft.)	0	210	296	295	244	154	50	0

Find the volume of earth removed in making the cutting.

2. Find the weight of the stone pillar shown in Fig. 57. The flanges are cylindrical, whilst the radius of the body at any section is determined by the rule, radius = $\frac{2}{\sqrt{x}}$, where x is the distance of the section from the fixed point O. (Weight of stone = 140 lbs. per cu. ft.)

3. The curve $y = 2x^2 - 3x$ revolves about the axis of x . Find the volume of the solid thus generated, the bounding planes being those for which $x = -2$ and $x = +4$.

4. Find, by integration, the surface of a hemisphere of radius r .

5. The curve $y = ae^{bx}$ passes through the points $x = 1$, $y = 3.5$, and $x = 10$, $y = 12.6$; find a and b . This curve rotates about the axis of x , describing a surface of revolution. Find the volume between the cross sections at $x = 1$ and $x = 10$.

6. Find the weight of a cylinder of length l and diameter D, the density of the material varying as the distance from the base. (Let the density of a layer distant x from base = Kx .)

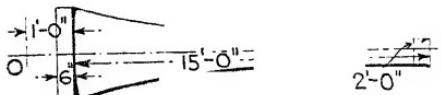


FIG. 57.—Weight of Stone Pillar.

7. The rectangular hyperbola having the equation $x^2 - y^2 = 25$ revolves about the axis of x . Find the volume of a segment of height 5 measured from the vertex.

8. The line $4y - 5x = 12$ revolves about the axis of x . Find the surface of the frustum of the cone thus generated, the limits of x being 1 and 5.

9. The radius of a spindle weight at various points along its length is given in the table—

Distance from one end (ins.)		.375	.5	1.3	1.6	1.85
Radius (ins.)		1.61	1.61	.78	.42	.4

Find its weight at .283 lb. per cu. in., the end portions cylindrical.

10. Determine by the method indicated in *Example 19*, p. 204, the perimeter of an ellipse whose major axis is 30 ins. and whose minor axis is 18 ins. Compare your result with those obtained by the use of the approximate rules (a), (b) and (c) on p. 207.

11. The curve taken by a freely hanging cable weighing 3 lbs. per foot and strained by a horizontal pull of 300 lbs. weight conforms to the equation—

$$y = c \cosh \frac{x}{c}$$

where $c = \frac{300}{3}$. Find the total length of the cable if the span is 60 ft., i.e., x ranges from -30 to $+30$.

12. Find the weight (in cast iron) of the centrifugal casting shown in Fig. 91A, p. 256.

Centre of Gravity and Centroid.—The Centre of Gravity (C. of G.) of a body is that point at which the resultant of all the forces acting on the body may be supposed to act, *i.e.*, it is the balancing point. The term *Centroid* has been applied in place of C. of G. when dealing with areas; and as our work here is more concerned with areas it will be convenient to adopt the term centroid.

From the definition it will be seen that the whole weight of a body may be supposed to act at its C. of G.; and in problems in Mechanics this property is most useful. Thus, movements of a complex system of weights may be reduced to the movement of the C. of G. of these. Or to take another instance: in structural work, in connection with fixed beams unsymmetrically loaded, it is necessary to find the position of the centroid of the bending-moment diagram. It is thus extremely important that rules should be found for fixation of the position of the centroid in all cases; and the methods adopted may be divided into two classes: (a) algebraic (including purely algebraic, and partly algebraic and partly graphic), (b) graphic.

The rules will best be approached by way of a simple example on moments. In place of areas or solids, afterwards to be dealt with, let us consider the case of a uniform bar loaded as shown in Fig. 58.

For equilibrium the two conditions to be satisfied are—

- (1) The upward forces balance the downward forces.
- (2) The right-hand moments about any point balance the left-hand moments about the same point; or, in other words, the algebraic sum of the moments about any point is zero.

If C is the balancing point or fulcrum, the upward reaction of the fulcrum = $M = m_1 + m_2 + m_3 + m_4 + m_5$ from condition (1).

Taking moments about A, let \bar{x} (x bar) be the distance AC.

Then, by condition (2)—

$$M\bar{x} = m_1x_1 + m_2x_2 + m_3x_3 + \dots$$

$$\begin{aligned} \text{or } \bar{x} &= \frac{m_1x_1 + m_2x_2 + m_3x_3 + \dots}{m_1 + m_2 + m_3 + \dots} \\ &= \frac{\Sigma mx}{\Sigma m}. \end{aligned}$$

The product of a force into its distance from a fixed point or axis is called its *first moment* about that point or axis; whilst the

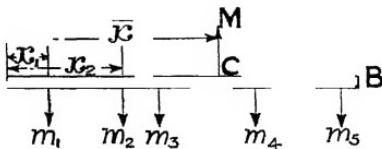


FIG. 58.—Centre of Gravity or Centroid.

product of a force into the square of its distance from a fixed point is called its *second moment* about that point.

Hence our statement concerning the distance AC can be written—

$$x = \frac{\Sigma \text{1st moments}}{\Sigma \text{masses}}$$

To extend this rule to meet the case of a number of scattered masses arranged as in Fig. 59, the co-ordinates of the centroid must be found, viz., \bar{x} and y .

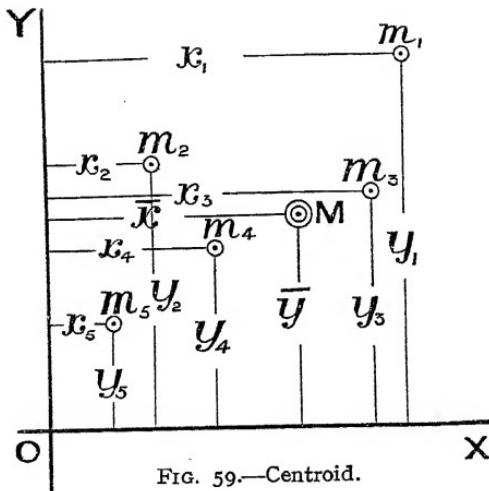


FIG. 59.—Centroid.

Thus $\bar{x} = \frac{\Sigma mx}{\Sigma m} : \frac{\Sigma \text{1st moments about } OY}{\Sigma \text{masses}}$

and $\bar{y} = \frac{\Sigma my}{\Sigma m} : \frac{\Sigma \text{1st moments about } OX}{\Sigma \text{masses}}$

If the masses are not all in one plane, their C. of G. must be found by marking their positions in a plan and elevation drawing and determining the C. of G. of the elevations and also that of their plan. Thus the C. of G. is located by its plan and elevation.

It will be observed that some form of summation is necessary for the determination of the positions of centroids or centres of gravity; and this summation may be called by a different name, viz., integration, all the rules of which may be utilised; the integration in some cases being graphic, in some cases algebraic, and in others a combination of the two.

Rules for the Determination of the Centroid of an Area.—Let it be required to find the centroid of the area ABCD in Fig. 60.

The area may be considered to be composed of an infinite number of small elements or masses, each being the mass of some thin strip like PQMN; the co-ordinates of the centre of gravity of which may be determined in the manner already explained.

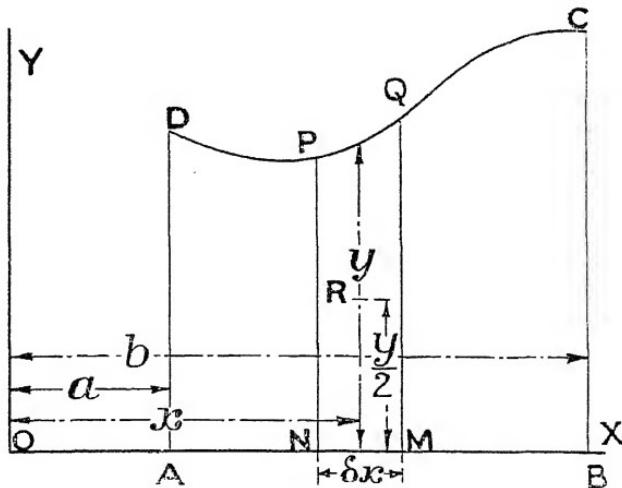


FIG. 60.—Centroid of an Area.

To find \bar{x} , i. e., the distance of the centroid from OY—

Mass of strip PQMN = area \times density (considering the strip as of unit thickness)

$$= y\delta x \times \rho$$

1st moment of strip about OY = mass \times distance = $\rho y\delta x \times x$
 $= \rho xy\delta x$.

Hence $x = \frac{\Sigma \text{1st moments about OY}}{\Sigma \text{masses}}$

$$= \frac{\Sigma \rho xy\delta x}{\Sigma \rho y\delta x} \quad \text{the limits being } a \text{ and } b$$

and if the strips are made extremely narrow—

$$x = \frac{\int_a^b \rho xy dx}{\int_a^b \rho y dx} - \frac{\int_a^b xy dx}{\int_a^b y dx}$$

ρ cancelling from both numerator and denominator.

Thus a vertical is found on which the centroid of the area must lie; and this line is known as the *centroid vertical*.

To fix the actual position of the centroid some other line must be drawn, say a horizontal line, the intersection of which with the centroid vertical is the centroid.

Thus the height of the centroid above OX must be found; this being denoted by \bar{y} .

To find \bar{y} .—The whole mass of the strip PQMN may be supposed to act at R, its mid-point, because the strip is of uniform density; and hence the moment of the strip PQMN about OX

$$\begin{aligned} &= \text{mass} \times \text{distance} = \rho y \delta x \times \frac{\gamma}{2} \\ &= \frac{\rho}{2} y^2 \delta x. \end{aligned}$$

Hence $y = \frac{\sum^b \text{rst moments about OX}}{\sum^b \text{masses}}$

$$= \frac{\int_a^b \frac{\rho}{2} y^2 dx}{\int_a^b \rho y dx} = \frac{\frac{1}{2} \int_a^b y^2 dx}{\int_a^b y dx}$$

As in previous cases, the integration may be algebraic, this being so when y is stated in terms of x , or graphic, when a curve or values of y and x are given.

Suppose the latter is the case, and we desire to find x —

Then $x = \frac{\int xy dx}{\int y dx}$

and the values of the numerator and denominator must be found separately. Each of these gives the area of a figure, for if Y is written in place of xy , the numerator becomes $\int Y dx$, which is the standard expression for the area under the curve in which Y is plotted against x ; and the denominator is already in the required form.

Thus a new set of values must be calculated, viz., those of Y , these being obtained by multiplication together of corresponding values of x and y ; and these values of Y are plotted to a base of x . Then the area under the curve so obtained is the value of the numerator, and the denominator is the area under the curve with y plotted against x ; and, finally, division of the one by the other fixes the value of x .

Example 22.—Find the centroid of the area bounded by the curve given by the table, the axis of x and the ordinates through $x = 10$ and $x = 60$.

x	10	25	40	45	50	60
y	4	5.3	6.2	6.4	6.6	6.8

We thus wish to find the centroid of the area ABCD (Fig. 61). To find \bar{x} :

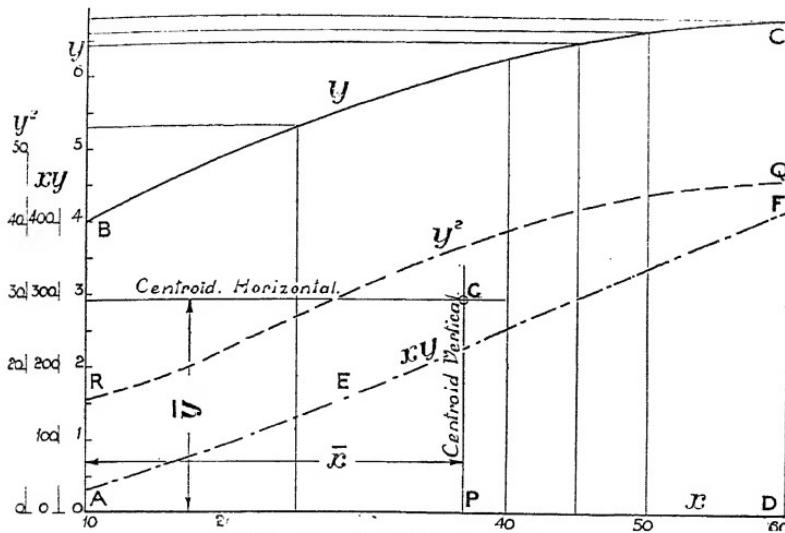


FIG. 61.—Centroid of an Area.

The table for the plotting of Y against x reads—

x	10	25	40	45	50	60
Y or xy	40	132.4	248	288	330	408

From this we get the curve AEF.

The area of the figure ABCD—

$$\text{i.e., } \int_{10}^{60} y dx = 289$$

and the area of the figure AEFD—

$$\int_{10}^{60} xy dx = 10650$$

$$\frac{\int_{10}^{60} xy dx}{\int_{10}^{60} y dx} = \frac{10650}{289} = 36.9.$$

The method of integration is not shown, to avoid confusion of curves.

Thus the centroid vertical, or the line PG is fixed.

We need now to find the centroid horizontal, i.e., y must be determined.

$$\text{Now } y = \frac{\frac{I}{2} \int_{10}^{60} y^2 dx}{\int_{10}^{60} y dx} = \frac{\frac{I}{2} \int_{10}^{60} Y dx}{\text{area of ABCD}} \quad \left\{ \begin{array}{l} \text{where } Y \text{ in this case} \\ \text{stands for } y^2 \end{array} \right.$$

so that the following table must be compiled—

x	10	25	40	45	50	60
Y or y^2	16	28	38.4	41	43.5	46.1

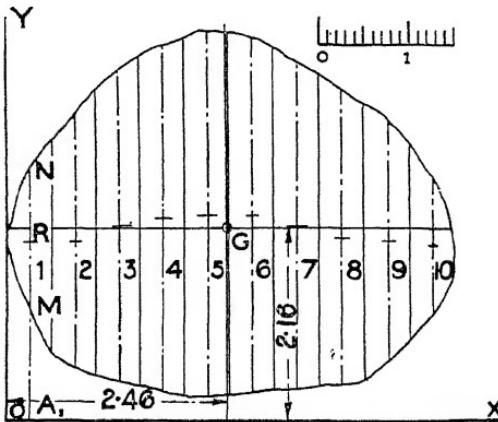


FIG. 62.—C. of G. of Thin Plate.

Plotting from this table, the curve RQ results, and the area of the figure ARQD is 1689.

$$\therefore \bar{y} = \frac{\frac{1}{2} \text{area of ARQD}}{\text{area of ABCD}} = \frac{\frac{1}{2} \times 1689}{289} = 2.92.$$

The intersection of the centroid vertical and the centroid horizontal at G fixes the centroid of ABCD.

A modification of this method is necessary when the actual area is given in place of the tabulated list of values, the procedure being outlined in the following example.

Example 23.—It is required to find the C. of G. of a thin plate having the shape shown in Fig. 62. Show how this may be done.

Draw two convenient axes at right angles and divide up the area into thin strips by lines drawn parallel to OY. Draw in, also, the mid-ordinates of these strips. The area of any strip can be assumed

to be "mean height \times thickness"; and therefore measure ordinates such as MN and multiply by the thickness or width of the strip. Repeat for each strip, and the sum of all these will be the area of the figure.

To find \bar{x} .— OA_1 = the distance of the centre of 1st strip from OY so that the area of strip $\times OA_1$ = 1st moment of strip about OY.

Hence, multiply the area of each strip by the distance of its mid-ordinate from OY and add the results; then the sum will be the 1st moment of the area about OY.

$$\text{Then } \bar{x} = \frac{\text{Sum of 1st moments}}{\text{Area}} = \frac{\text{2nd total}}{\text{1st total}}.$$

To find \bar{y} .—Fix R, the mid-point of MN, and do the same for all the strips. The area of the strip has already been found; multiply this by A_1R and repeat for all strips. The sum of all such will be the 1st moment about OX; dividing this by the area of the figure, the distance, \bar{y} , of the centroid from OX is found.

[Note that R is the mid-point of MN and not of NA_1 , because OX is a purely arbitrary axis.]

For this example the calculation would be set out thus—

Strip	Length of mid-ordinate (like MN)	Width of Strip	Area of Strip	Distance of centre from OY (like OA_1)	Distance of centre from OX (like RA_1)	1st moment about OX	1st moment about OY
1	1.55	.5	.775	.25	2.0	1.55	.19
2	2.79	.5	1.395	.75	2.0	2.79	1.05
3	3.44	.5	1.720	1.25	2.18	3.75	2.05
4	3.85	.5	1.925	1.75	2.27	4.37	3.36
5	4.01	.5	2.005	2.25	2.32	4.64	4.50
6	3.92	.5	1.960	2.75	2.3	4.51	5.40
7	3.60	.5	1.800	3.25	2.18	3.92	5.85
8	3.26	.5	1.630	3.75	2.04	3.32	6.11
9	2.66	.5	1.330	4.25	2.02	2.68	5.65
10	1.47	.5	.735	4.75	1.95	1.43	3.49
Totals	.		15.275			32.96	37.65

$$\bar{x} = \frac{37.65}{15.28} = 2.46$$

$$\text{and } \bar{y} = \frac{32.96}{15.28} = 2.16.$$

Thus the position of G is fixed by the intersection of a horizontal at a height of 2.16 with a vertical 2.46 units distance from OY.

If the centroid of an arc was required, the lengths of small elements of arc would be dealt with in place of the small areas, but otherwise the procedure would be the same.

"Double Sum Curve" Method of Finding the Centroid
Vertical.—This method is convenient when only the centroid vertical is required; for although entirely graphic, it is rather too long to be used for fixing the centroid definitely.

Method of Procedure.—To find the centroid vertical for the area APQH (Fig. 63).

Sum curve the curve PQ in the ordinary way, thus obtaining the curve AegE; for this construction the pole is at O, and the polar distance is ρ .

Produce PA to O_1 , making the polar distance $\rho_1 = HE =$ last ordinate of the sum curve of the original curve (viz., PQ).

Sum curve the curve AegE from AP as base and with O_1 as

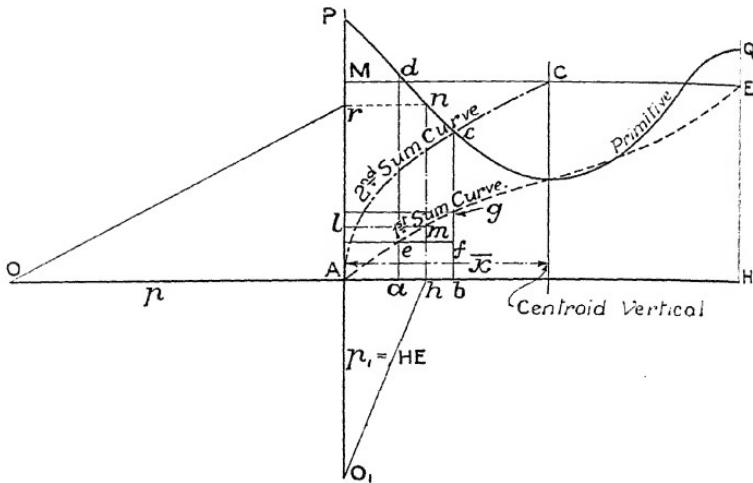


FIG. 63.—Centroid Vertical of an Area.

pole; then the last ordinate of this curve, viz., CM, is of length x , so that the vertical through C is the centroid vertical.

Proof.—Consider the strip $abcd$, a portion of the original area. Then Or and eg are parallel (by construction)—

$$\text{and thus } \frac{\rho}{Ar} = \frac{ef}{fg} = \frac{ab}{fg}$$

$$\text{or } Ar \times ab = \rho \times fg \\ \text{i. e., } hn \times ab = \rho \times fg$$

$$\therefore \Sigma hn \times ab = \Sigma \rho \times fg = \rho \Sigma fg = \rho . HE.$$

$$\begin{aligned} \text{Again, the 1st moment of the strip about AP} &= \text{area} \times \text{distance} \\ &= hn \times ab \times Ah \\ &= hn \times ab \times ml \\ &= \rho \times fg \times ml \end{aligned}$$

and hence 1st moment of area APQH about AP—

$$\begin{aligned} &= \sum p \times fg \times ml = p \sum fg \times ml \\ &= p \times p_1 \times CM \end{aligned}$$

but 1st moment of area APQH about AP—

$$= \text{area} \times \text{distance of centroid from A}$$

$$= p \times HE \times x$$

$$\therefore p \times p_1 \times CM = p \times HE \times x \quad (\text{also } p_1 = HE)$$

and $x = MC.$

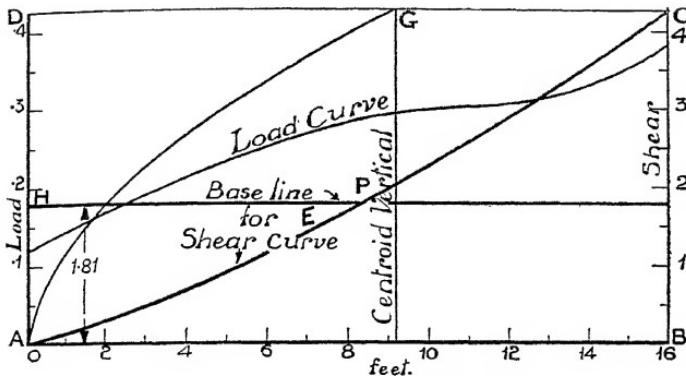


FIG. 64.—Problem on Loaded Beam.

Example 24.—A beam, 16 ft. long, simply supported at its ends is loaded with a continuously varying load, the loading being as expressed in the table.

Distance from left-hand support (feet)	Load in tons per foot run	14	16
		.17 .21	.29 .31 .34 .38

Find the centroid vertical of the load curve, and hence determine the reactions of the supports and the point at which the maximum bending moment occurs.

We first plot the load curve from the figures given in the table (Fig. 64); and next we sum curve this curve, taking a polar distance of 10 horizontal units; the last ordinate of this sum curve reads 4.27, so that the total load is 4.27 tons. We now set off AD equal in length to BC, and with this as polar distance we sum curve the curve AEC from the vertical axis as base. This sum curve finishes at the point G on the horizontal through C, and a vertical through G is the centroid vertical, distant 9.2 ft. from the end A.

For purposes of calculation, the whole load may be supposed to

act in this line; the total load is 4.27 tons, and taking moment round A—

$$4.27 \times 9.2 = R_B \times 16$$

whence

$$R_B = 2.46 \text{ tons}$$

and

$$R_A = 4.27 - 2.46 = 1.81 \text{ tons.}$$

We now set up AH, a distance to represent R_A , to the new vertical scale, and then a horizontal through H is the true base line of shear.

At the point P the shear is zero; but the shear is measured by the rate of change of bending moment, so that zero shear corresponds to maximum bending moment; and hence, grouping our results—

Reaction at left-hand support = 1.81 tons

Reaction at right-hand support = 2.46 tons

and the maximum bending moment occurs at a distance of 8.4 ft. from the left-hand end.

Centroids of Sections by Calculation (for a graphic method especially applicable to these, see p. 251).—Special cases arise in

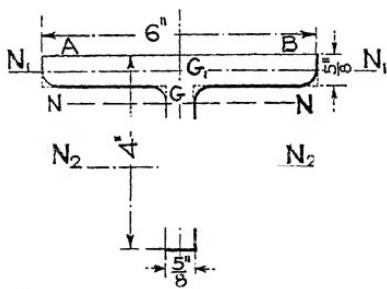


FIG. 65.

the form of sections of beams, joists, rails, etc., for which a modification of the previous methods is sufficient.

If the section is composed of a combination of simple figures, such as rectangles or circles, as in the great majority of cases it is, its centroid can be found by loading each of its portions, into which for purposes of calculation it may be divided, with a weight proportional to its area, and treating the question as one for the determination of the C. of G. of a number of isolated weights.

Example 25.—Find the position of the centroid of the Tee section shown in Fig. 65.

We may consider the section to be made up of two rectangles; then—

$$\text{Area of flange} = 6 \times \frac{5}{8} = \frac{30}{8} \text{ sq. ins.} = \frac{240}{64} \text{ sq. ins.}$$

and the centroid of the flange is at $\frac{5}{8}$ in.

$$\text{Area of web} = 3\frac{3}{8} \times \frac{5}{8} = \frac{135}{64} \text{ sq. ins.}$$

and the centroid of the web is at G_2 .

From considerations of symmetry we see that the centroid of the section must lie on the line G_1G_2 , at the point G , say.

Treat G_1G_2 (of length $\frac{5}{16} + \frac{27}{16} \text{ i.e., } 2"$) as a bar loaded with $\frac{240}{64}$ units at G_1 and $\frac{135}{64}$ units at G_2 .

$$\begin{aligned}\text{Let } G_1G &= \bar{x}; \text{ then the upward force at } G = \frac{240}{64} + \frac{135}{64} \\ &= \frac{375}{64} \text{ units.}\end{aligned}$$

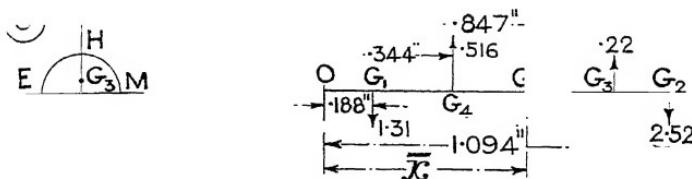
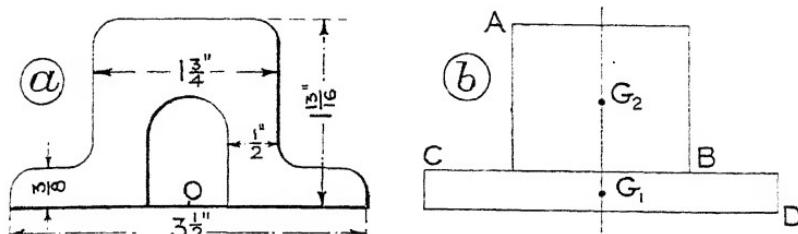


FIG. 66.—Centroid of Bridge Rail.

(In the further calculation we may disregard the denominators, since they are alike.)

Taking moments about G_1

$$375 \times \bar{x} = 135 \times 2$$

$$\text{whence } \bar{x} = \frac{270}{375} = .72.$$

Hence the distance of the centroid from the outside of the flange—

$$= \frac{5}{16} + .72" = \underline{1.03"}.$$

Example 26.—Determine the position of the centroid of the bridge rail section shown at (a), Fig. 66.

This example presents rather more difficulty than the one immediately preceding it. The plan of procedure is, for cases such as this,

that adopted in the work on the calculation of weights, viz., we first treat the section as "solid" and then subtract the part cut away.

Neglecting the small radii at the corners, and treating the section as "solid," the section has the form shown at (b), Fig. 66.

The area of AB = $\frac{23}{16} \times \frac{7}{4} = 2.52$ sq. ins., and its centroid is at G_4 , the intersection of its diagonals.

Similarly the area of CD = $\frac{3}{8} \times \frac{7}{2} = 1.313$ sq. ins., and its centroid is at G_1 .

For the part cut away (see (c), Fig. 66)

The area of EHM = $\frac{\pi}{2} \times \left(\frac{3}{8}\right)^2 = .221$ sq. in.; and we know from Part I, p. 130, that its centroid G_3 is distant $.424 \times \text{radius}$, $.424 \times .375$ or $.159"$ from EM.

Again, the area of EF = $\frac{11}{16} \times \frac{3}{4} = .516$ sq. in., and its centroid is at G_4 .

Our problem is thus reduced to that of determining the C. of G. of four isolated weights, two of which act in the direction opposed to that of the others, placed as shown at (d), Fig. 66.

Let the centroid of the whole section be at G, distant \bar{x} from O.

Now the upward forces = the downward forces

$$\text{and thus } R_G + .516 + .221 = 2.52 + 1.313$$

$$\text{whence } R_G = 3.096.$$

Also, by taking moments about O—

$$(3.096 \times \bar{x}) + (.516 \times .344) + (.221 \times .847) = (1.313 \times .188) + (2.52 \times 1.094)$$

$$\text{whence } \bar{x} = .855 \text{ in.}$$

or the centroid of the section is .855" distant from the outside of the flange.

Centroids found by Algebraic Integration.—Suppose that the equation of the bounding curve is given, then the centroid of the area between the curve, the axis and the bounding ordinates may be determined by algebraic integration.

We have already seen that—

$$\bar{x} = \frac{\int xy \, dx}{\int y \, dx} \text{ and } \bar{y} = \frac{\frac{1}{2} \int y^2 \, dx}{\int y \, dx}$$

so that if y is stated as a function of x , xy and y^2 may be expressed in terms of x , and the integration performed according to the rules given.

- The examples here given should be carefully studied, for there

are many possibilities of error arising due to the incorrect substitution of limits.

Example 27.—Find the centroid of the area between the curve $y = 2x^{1.5}$, the axis of x and the ordinates through $x = 2$ and $x = 5$.

The curve is plotted in Fig. 67, and it is seen that the position of the centroid of the area ABCD is required.

$$\text{Now } y = 2x^{1.5}, \text{ and thus } xy = 2x^{\frac{3}{2}} \times x = 2x^{\frac{5}{2}}$$

$$\text{and } y^2 = 4x^3.$$

To find x —

$$\begin{aligned} &= \int_2^5 xy \, dx = \int_2^5 2x^{\frac{5}{2}} \, dx \\ &= \int_2^5 2x^{\frac{3}{2}} \, dx \\ &= \left(\frac{2}{7} x^{\frac{7}{2}} \right)_2 \\ &= \left(\frac{2}{7} x^{\frac{7}{2}} \right)_2 \\ &= \frac{2}{7} \times 5 \left\{ 5^{\frac{7}{2}} - 2^{\frac{7}{2}} \right\} \\ &= \frac{2}{7} \times 5 \left\{ 5^{\frac{5}{2}} - 2^{\frac{5}{2}} \right\} \\ &= \frac{5}{7} \times \frac{268}{50.25} \\ &= 3.81 \end{aligned}$$

or the centroid vertical is distant 3.81 units from the left-hand boundary.

To find y —

$$\begin{aligned} y &= \frac{\frac{1}{2} \int_2^5 y^2 \, dx}{\int_2^5 y \, dx} \\ &= \frac{\frac{1}{2} \times 4 \int_2^5 x^3 \, dx}{\int_2^5 x^{\frac{3}{2}} \, dx} \\ &= \frac{\frac{1}{2} \times 4 \left(\frac{x^4}{4} \right)_2}{\left(\frac{2}{5} x^{\frac{5}{2}} \right)_2} \\ &= \frac{1}{4} \times \frac{4}{2} \left(\frac{5^{\frac{5}{2}} - 2^{\frac{5}{2}}}{5^{\frac{5}{2}} - 2^{\frac{5}{2}}} \right) \\ &= \frac{5}{8} \times \frac{609}{50.25} = 7.57 \text{ units.} \end{aligned}$$

Hence the co-ordinates of the centroid are 3.81, 7.57.

Example 28.—The bending moment curve for a beam fixed at one end and loaded uniformly over its whole length is a parabola, as

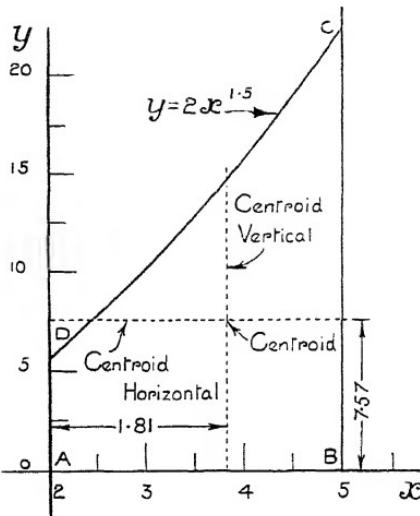


FIG. 67.

shown in Fig. 68. The vertex is at A and the ordinate at B, viz., BC is $\frac{wl^2}{2}$; the loading being w units per foot and l being the span.

We wish to determine the position of the centroid of the figure ABC so that we may find the moment of the area ABC about AD, and finally the deflection at A.

From the equation to a parabola, $y^2 = 4ax$, we see that—

$$l^2 = 4a \cdot \frac{wl^2}{2}, \text{ whence } 4a = \frac{2}{w} \text{ or } y^2 = \frac{2}{w}x$$

$$\text{i.e., } (\text{ND})^2 = \frac{2}{w} \text{AD.}$$

The distance of the centroid from AD = y

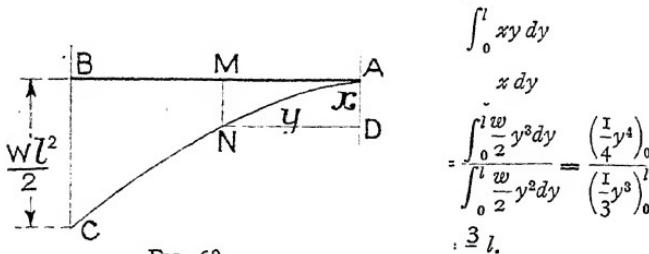


FIG. 68.

$$\begin{aligned} & \int_0^l xy dy \\ & \quad x dy \\ & = \int_0^l \frac{w}{2} y^3 dy = \frac{\left(\frac{1}{4}y^4\right)_0^l}{\left(\frac{1}{3}y^3\right)_0^l} \\ & = \frac{w}{2} \cdot \frac{l^4}{3} = \frac{wl^4}{6}. \end{aligned}$$

$$\begin{aligned} \text{Area of } ABCD &= \frac{1}{3} \text{ of surrounding rectangle} = \frac{1}{3} \times l \times \frac{wl^2}{2} \\ &= \frac{wl^3}{6}. \end{aligned}$$

All this area may be supposed to be concentrated at its centroid, and hence the moment of ABC about AD = $\frac{wl^3}{6} \times \frac{3}{4}l = \frac{wl^4}{8}$.

Now the deflection at A = $\frac{I}{EI} \times \text{moment of the bending moment diagram about the vertical through A}$

$$= \frac{I}{EI} \times \frac{wl^4}{8}.$$

$$\text{Hence the deflection at A} = \frac{wl^4}{8EI} = \frac{Wl^3}{8EI}, \text{ where W} = \text{total load.}$$

Example 29.—Find the position of the centroid of a quadrant of a circle of radius r .

The equation of the circle is $x^2 + y^2 = r^2$

hence

$$y = \sqrt{r^2 - x^2}$$

so that

$$xy : x \sqrt{r^2 - x^2}.$$

Thus x (and consequently \bar{y})—

$$\int_0^r x \sqrt{r^2 - x^2} dx$$

The value of the denominator is $\frac{\pi r^2}{4}$, for it is the area of the quadrant. (This integral would be evaluated as shown on p. 149.)

To evaluate the numerator, let $u = r^2 - x^2$

$$\text{then } du = -2x dx$$

$$\text{or } x dx = -\frac{du}{2}.$$

Then-

$$\begin{aligned} \int_0^r x \sqrt{r^2 - x^2} dx &= \int_{x=0}^{x=r} -\frac{du}{2} u^{\frac{1}{2}} \\ &= -\frac{1}{2} \left(\frac{2}{3} u^{\frac{3}{2}} \right) \Big|_{x=0}^{x=r} \\ &= -\frac{1}{3} \left[(r^2 - x^2)^{\frac{3}{2}} \right]_0^r \\ &= -\frac{1}{3} [0 - (+r^2)^{\frac{3}{2}}] \\ &= \frac{1}{3} r^3. \\ \bar{x} = \bar{y} &= \frac{3}{\pi r^2} = \frac{4r}{3\pi} \quad \text{or } .424r. \end{aligned}$$

Centre of Gravity of Irregular Solids.—The methods given for the determination of the centroids of irregular areas apply equally well when solids are concerned. For if A is the area of the cross section of a solid at any point along its length, distant x , say, from one end, and the length is increased by a small amount δx (and if this is small there will be no appreciable change in the value of A), then the increase in the volume = $A\delta x$ or the increase in the weight = $\rho A\delta x$, ρ being the density.

The moment of this element about the end = $\rho A\delta x \times x$

$$\begin{aligned} \text{so that } \frac{\Sigma \text{ 1st moments}}{\Sigma \text{ weights}} &= \frac{\int_0^l \rho A x dx}{\int_0^l \rho A dx} \\ &= \frac{\int_0^l A x dx}{\int_0^l A dx} \end{aligned}$$

As before, two cases arise, viz., (a) when values of A and x are given, and (b) when A is defined in terms of x . To deal with these—

In case (a) plot one curve in which A is the ordinate and x is the abscissa and find the area under it; this is the value of $\int_0^x A dx$.

Plot a second curve whose ordinates are the products of corresponding values of A and x and find the area; this is the value of the numerator, and division of the latter area by the former gives the value of \bar{x} . Thus the centroid vertical is found, and if the solid is symmetrical about the axis of x , this is all that is required; otherwise the centroid horizontal must be found, the procedure being exactly that previously described when dealing with areas in place of volumes.

An example on the application of this method is here worked.

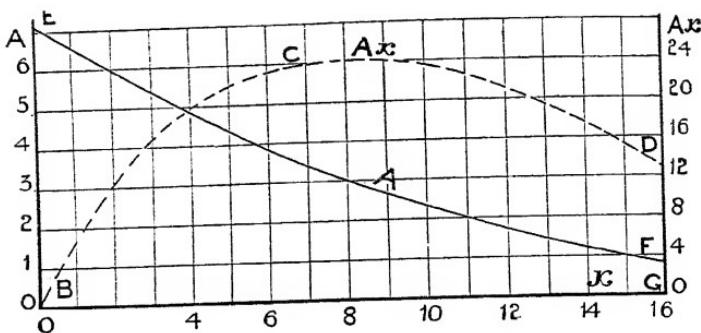


FIG. 69.—Problem on C.I. Column.

Example 30.—The circumference of a tapering cast iron column, 16 ft. long, at 5 equidistant places is 9.43, 7.92, 6.15, 4.74 and 3.16 ft. respectively. Find its volume and the distance of its C. of G. from the larger end.

The areas must first be found from the circumferences.

$$\text{Now the area of a circle} = \frac{(\text{Circ})^2}{4\pi}$$

So that the table for plotting reads—

$$r = \text{distance from larger end (ft.)}$$

16

$$A = \text{area of cross section (sq. ft.)} \quad | \quad 7.09 \quad | \quad 4.98 \quad | \quad 3.0 \quad | \quad 1.78 \quad | \quad .79$$

By plotting these values the curve EF (Fig. 69) is obtained.

The figure here given is a reproduction of the original drawing to rather less than half-size, and since the measurements were made on the original, the results now stated refer to that.

In the original drawing the scales were: 1" vertically = 2 sq. ft., and 1" horizontally = 2 ft., so that 1 sq. in. of area represented 4 cu. ft. of volume. The area under the curve EF was found, by means of the planimeter, to be 13.66 sq. ins., and accordingly the volume = $13.66 \times 4 = 54.64$ cu. ft.

The curve BCD results from the plotting of values of Ax as ordinates, the table for which plotting reads—

x	0	4	8	12	16
Ax	0	19.9	24	21.4	12.6

The area under this curve was found to be 19.06 sq. ins., which

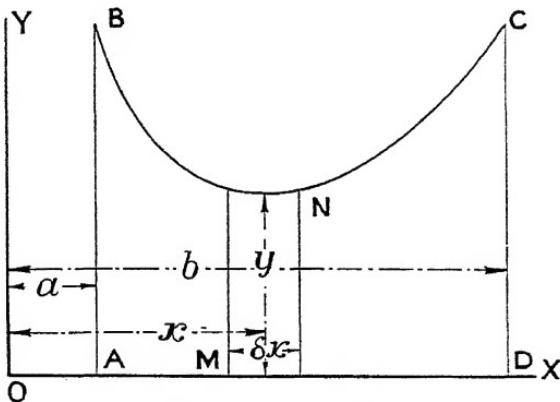


FIG. 70.—C. of G. of Solid of Revolution.

represented 19.06×16 units of moment, since for the plotting of BCD 1" vertically = 8 units of Ax , and 1" horizontally = 2 units of x .

$$\text{Hence } x = \frac{\text{area } BCDG}{\text{area } BEFG} - \frac{16 \times 19.06}{54.64} = 5.58 \text{ ft.}$$

For case (b), when A is stated in terms of x , the integration is entirely algebraic. Thus if A is a function of x , integrate Ax and also A with regard to x , and divide the former integral by the latter to determine the value of x .

Example 31.—The area of cross section of a rod of uniform density varies as the cube root of the distance of the section from one end; find the distance of the C. of G. from that end, being given that the area at a distance x from the end = $4.5\sqrt[3]{x}$.

Consider a strip distant x from the stated end and of thickness δx .

Then, from hypothesis, the area of section $= 4 \cdot 5 \sqrt[3]{x}$, and thus the volume $= \text{area} \times \text{thickness} = 4 \cdot 5 \sqrt[3]{x} \times \delta x$.

Also the mass of the strip $= \text{volume} \times \text{density}$

$$= 4 \cdot 5 \sqrt[3]{x} \times \delta x \times \rho$$

and the moment of the strip about the end $= \text{mass} \times \text{distance}$

$$\begin{aligned} &= 4 \cdot 5 \rho x^{\frac{1}{3}} \delta x \times x \\ &= 4 \cdot 5 \rho x^{\frac{4}{3}} \delta x. \end{aligned}$$

Hence $x = \sum \frac{\text{1st moments of small elements}}{\text{their masses}}$

$$\begin{aligned} &= \frac{\int_0^l 4 \cdot 5 \rho x^{\frac{4}{3}} dx}{\int_0^l 4 \cdot 5 \rho x^{\frac{1}{3}} dx} = \frac{\int_0^l x^{\frac{4}{3}} dx}{\int_0^l x^{\frac{1}{3}} dx} \\ &= \frac{\frac{3}{7} \times 4/l^{\frac{7}{3}}}{\frac{3}{7} \times l^{\frac{1}{3}}} \\ &= \frac{4l}{7} \end{aligned}$$

or the C. of G. is distant $\frac{4}{7}$ of the length from the given end.

C. of G. of a Solid of Revolution.—Suppose that the curve BC in Fig. 70 rotates round OX as axis; and we require to find the position of the C. of G. of the solid so generated.

Consider a small strip of area MN; its mean height is y and its width is δx , so that the volume generated by the revolution of this is $\pi y^2 \delta x$, or the mass $= \rho \pi y^2 \delta x$. The 1st moment of this strip about OY $= \text{mass} \times \text{distance} = \rho \pi y^2 \delta x \times x = \rho \pi x y^2 \delta x$.

Thus the total 1st moment about OY $= \sum_a^b \rho \pi x y^2 \delta x$

and the total mass $= \sum_a^b \rho \pi y^2 \delta x$

$$\therefore x = \frac{\int_a^b \rho \pi x y^2 dx}{\int_a^b \rho \pi y^2 dx} = \frac{\int_a^b x y^2 dx}{\int_a^b y^2 dx}.$$

As before, the two cases arise, viz.—

(a) When values of x and y are given. For this case make a table of values of $x \times y^2$ and also one of values of y^2 .

Plot the values of xy^2 against those of x and find the area under the resulting curve

$$\text{This area} = \int x y^2 dx \quad \dots \quad \dots \quad \dots \quad \dots \quad (1)$$

Plot the values of y^2 against those of x —

$$\text{Area of figure so obtained} = \int y^2 dx \quad (2)$$

and

$$\frac{(1)}{(2)}.$$

Also we know that y must be zero, for the axis of x is the axis of rotation; and thus the C. of G. is definitely fixed.

(b) When y is expressed as a function of x . In this case find both xy^2 and also y^2 in terms of x , integrate these functions algebraically and thence evaluate the quotient.

Example 32.—The curve given by the tabulated values of y and x revolves about the x -axis; find the position of the C. of G. of the solid thus generated.

	2	3	4	
10	21	26.4	25	

For the first curve, values of xy^2 are required, and for the second curve, values of y^2 ; these values being—

	1	2	3	4
y^2	64	100	441	696
xy^2	100	882	2088	2500

The curve AB (Fig. 71) is obtained by plotting the values of xy^2 as ordinates; and the area under this curve is 4323; this being thus the value of $\int_0^4 xy^2 dx$.

By plotting the values of y^2 as ordinates the curve CD is obtained; and the area under this curve is 1699, i. e., $\int_0^4 y^2 dx = 1699$.

Then—

$$x = \frac{\int_0^4 xy^2 dx}{\int_0^4 y^2 dx} = \frac{4323}{1699} = 2.55 \text{ units}$$

i. e., the C. of G. is at G, the point (2.55, 0).

Example 33.—The curve $x = 5y - 2\sqrt{y}$ revolves about the axis of y . Find the position of the centre of gravity of the solid generated, the solid being bounded at its ends by the horizontal planes distant 1 and 5 units respectively from the axis of x .

Since the revolution is about the axis of y and not that of x , y must take the place of x in our formulæ and x the place of y ; therefore the limits employed must be those for y .

In Fig. 72 AB is the curve $x = 5y - 2\sqrt{y}$, and we see that it is

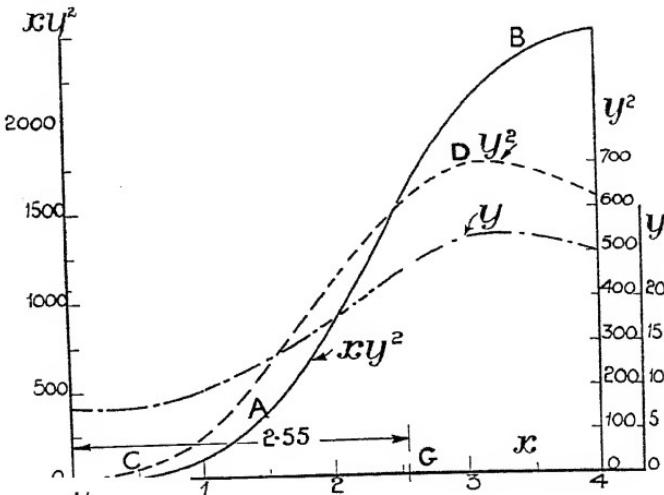


FIG. 71.

required to find the height of the centroid above the axis of x of the solid generated by the curve AB about the axis of y .

Then to find \bar{y} —

$$\bar{y} = \frac{\int_1^5 yx^2 dy}{\int_1^5 x^2 dy}$$

Now $x = 5y - 2\sqrt{y}$, and thus $x^2 = 25y^2 + 4y - 20y^{\frac{3}{2}}$

$$\text{and } yx^2 = 25y^3 - 20y^{\frac{5}{2}} + 4y^2.$$

$$\begin{aligned} \text{Then } \int_1^5 yx^2 dy &= \int_1^5 (25y^3 - 20y^{\frac{5}{2}} + 4y^2) dy = \left[\frac{25y^4}{4} - \frac{20 \times 2}{7} y^{\frac{7}{2}} + \frac{4y^3}{3} \right]_1^5 \\ &= \left(\frac{25 \times 625}{4} \right) - \left(\frac{40}{7} \times 280 \right) + \left(\frac{4 \times 125}{3} \right) - \frac{25}{4} + \frac{40}{7} - \frac{4}{3} \\ &= 2454 \end{aligned}$$

$$\begin{aligned} \text{and } \int_1^5 x^2 dy &= \int_1^5 (25y^2 + 4y - 20y^{\frac{3}{2}}) dy = \left[\frac{25y^3}{3} + \frac{4y^2}{2} - \frac{20 \times 2}{5} y^{\frac{5}{2}} \right]_1^5 \\ &= \left(\frac{25 \times 125}{3} \right) + (2 \times 25) - (8 \times 562) - \frac{25}{3} - 2 + 8 \\ &= 639 \end{aligned}$$

$$= \frac{\int_1^5 yx^2 dy}{\int_1^5 x^2 dy} = \frac{2454}{639} = 3.84.$$

Then since the centroid must lie along the axis of y , its position is definitely fixed at the point G, viz., (0, 3.84).

Example 34.—Find the mass and also the position of the C. of G. of a bar of uniform cross section a and length l , whose density is proportional to the cube of the distance from one end.

Let us consider a small length δx of the bar, distant x from the end mentioned above; the density of the material here = Kx^3 , where K is some constant; hence—

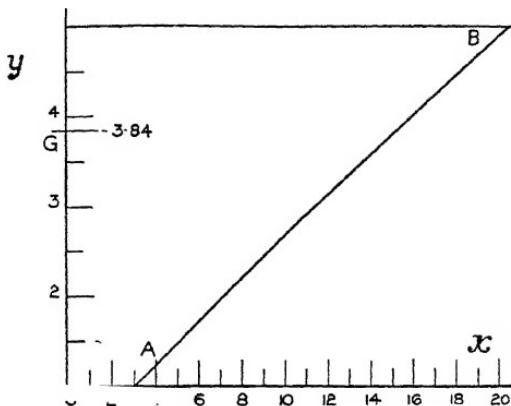


FIG. 72.

Mass of small element = volume \times density = $a\delta x \times Kx^3 = Kax^3\delta x$.

$$\begin{aligned} \text{Thus the total mass } &= \int_0^l Kax^3dx = Ka \left(\frac{x^4}{4} \right)_0^l \\ &= \frac{Kal^4}{4}. \end{aligned}$$

Also the 1st moment of the element about the end—

$$\begin{aligned} &= \text{mass} \times \text{distance} \\ &= Kax^3\delta x \times x. \end{aligned}$$

$$\text{Total 1st moment } = \int_0^l Kax^4dx = \frac{Kal^5}{5}$$

and if \bar{x} = distance of C. of G. from the lighter end—

$$Kal^5$$

$$\frac{\underline{Kal^4}}{4} : \therefore \frac{4}{5} l.$$

Example 35.—Find the position of the C. of G. of a triangular lamina whose density varies as the distance from the apex. (Let the thickness of the lamina = t .)

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Consider a small strip of width δx , distant x from the apex (Fig. 73).

The area of the strip = $y\delta x$, and thus its volume = $y\delta x$.

Now the density $\propto x$ or density = Kx

$$\text{and also, by similar triangles, } \frac{y}{x} = \frac{B}{H}$$

$$\text{or } y = \frac{Bx}{H}$$

$$\begin{aligned} \text{that the mass of the strip} \\ &= y\delta x \times Kx \\ &= \frac{BKt}{H} x^2 \delta x \end{aligned}$$

and the 1st moment of the strip about OY—

$$= \frac{BKt}{H} x^3 \delta x.$$

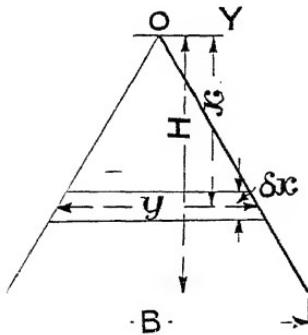


FIG. 73.

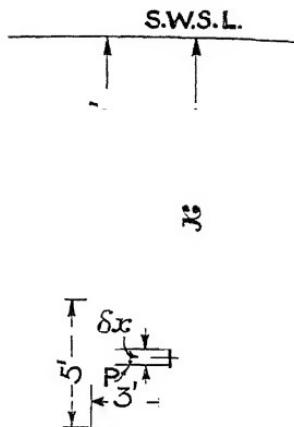


FIG. 74.

Hence—

$$= \int_0^H \frac{BKt}{H} x^3 dx$$

$$= \int_0^H \frac{BKt}{H} x^3 dx$$

$$= \frac{1}{4} \left. \frac{BKt}{H} x^4 \right|_0^H = \frac{H^4}{4} \times \frac{3}{H^3}$$

$$= \frac{3}{4} H.$$

Centre of Pressure.—If a body is immersed in a liquid, then the pressure per sq. in. of surface is not uniform over the solid, for the pressure is proportional to the depth. The point at

which the total pressure may be supposed to act is known as the *centre of pressure* (C. of P.).

To find positions of centres of pressure we are, in effect, finding centres of gravity of solids whose density is proportional to the distance from some fixed axis.

The C. of G. found in the example last worked is in reality the C. of P. of a triangular lamina immersed vertically in a liquid, with OY as the level of the top of the liquid.

Just as, when discussing the stability of solids in air, we have supposed the whole mass to be concentrated at the C. of G., so now, when the solid is immersed in a liquid, the total pressure may be assumed to act at the one point, viz., the C. of P.

To find the positions of the C. of P. for various sections and solids we must start from first principles, dealing with the pressure on small elements, and then summing.

Example 36.—Find the whole pressure on one side of a rectangular sluice gate of depth 5 ft. and breadth 3 ft., if the upper edge is 10 ft. below the level of the water (which we shall speak of as the still water surface level or S.W.S.L). Find also the depth of the centre of pressure.

Consider a strip of the gate δx deep and x ft. below S.W.S.L (Fig. 74).

$$\text{Then the area of the strip} = 3 \times \delta x$$

$$\text{and the pressure per sq. ft} = K \times \text{depth}.$$

Now at a depth of x ft. the pressure per sq. ft. = weight of a column of water x ft. high and 1 sq. ft. in section, i.e., wt. of x cu. ft. of water or $62.4x$ lbs.

Also the pressure is the same in all directions;

and thus the pressure on the strip = $3\delta x \times 62.4x$
and the moment of the pressure on the strip about S.W.S.L.—

$$\begin{aligned} &= 187.2x\delta x \times x \\ &= 187.2x^2\delta x. \end{aligned}$$

$$\text{Hence the total pressure} = \int_{10}^{15} 187.2x^2 dx \text{ lbs.}$$

$$\begin{aligned} &= 187.2 \left(\frac{x^3}{3} \right)_{10}^{15} \\ &= \frac{187.2 \times 125}{2} \text{ lbs.} \\ &= 11700 \text{ lbs. or} \end{aligned}$$

Again, the total 1st moment about S.W.S.L.—

$$\begin{aligned} &= \int_{10}^{15} 187.2x^2 dx = 187.2 \left(\frac{x^3}{3} \right)_{10}^{15} \\ &= 62.4 \times 2375. \end{aligned}$$



Thus the depth of the C. of P. below S.W.S.L.—

$$= \frac{62.4 \times 2375}{11700} \text{ ft.}$$

$$= 12.65 \text{ ft.}$$

Hence C. of P. is at the point P, at a depth of 12.65 ft. below the surface of the liquid.

The more general investigation for the position of the C. of P. is given in Chap. X.

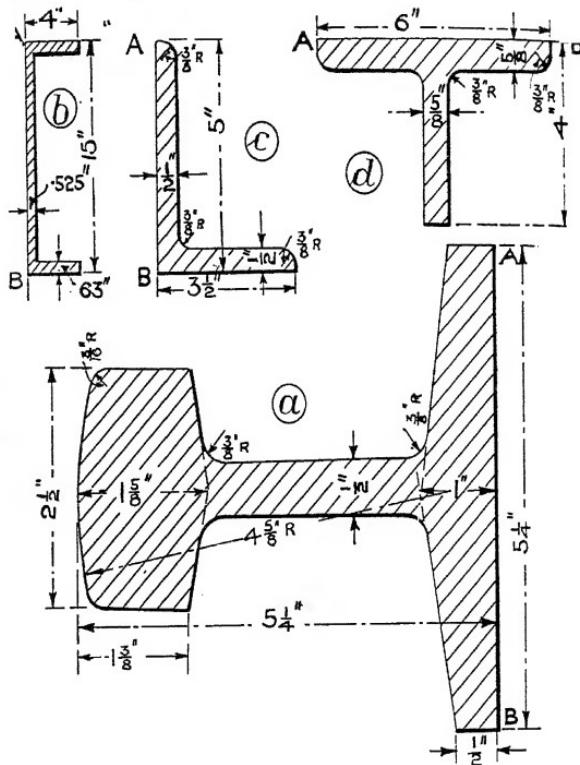


FIG. 75.—Centroids.

Exercises 19.—On the Determination of the Positions of Centroids and Centres of Gravity.

1. The density of the material of which a right circular cone is composed varies as the square of the distance from the vertex. Find the position of the centre of gravity of the cone.

2. The equidistant half-ordinates of the load water plane of a ship are as follows, commencing from forward : -6, 2.85, 9.1, 15.54, 18, 18.7, 18.45, 17.6, 15.13 and 6.7 ft. respectively. Find the area of the load water plane and the longitudinal position of its centroid. The length of the ship on the load water line is 270 ft.

3. A triangular plate of base 5" and height 8" is immersed in water, its base being along the S.W.S.L. Find the total pressure on the plate and the depth of the centre of pressure if the plate is vertical.

4. A vertical retaining wall is 8 ft. wide and 15 ft. deep. Find the depth of the centre of pressure of the earth on the wall.

5. Draw the quadrant of a circle of 4" radius, and by the double sum curve method determine the position of its centroid.

6. The portion of the parabola $y = 2x^2 - 9x$ below the x axis revolves about that axis. Find the volume of the paraboloid so generated, and the distance of its C. of G. from the axis of y .

7. Find the position of the centroid of the area bounded by the curve $y = 1.7 - 2x^2$, the axis of x and the ordinates through $x = -1$ and $x = +4$.

8. Reproduce (a), Fig. 75, to scale (full size), and find the position of the centroid of the section represented, employing the method outlined in Example 23, p. 216.

9. Draw a segment of a circle of diameter = 6" on a base of 5.92", and find by the method of Example 23, p. 216, the height of the centroid above the base. (Take the segment that is less than a semicircle.)

Find the distance of the centroid from the line AB for the sections in Nos. 10, 11 and 12.

10. Channel Section, (b), Fig. 75.

11. Unequal Angle, (c), Fig. 75.

12. Tee Section, (d), Fig. 75.

13. Make a careful drawing of (a) Fig. 76, which represents the half-section of the standard form of a stream line strut for an aeroplane, taking i as 2", and by the method of Example 23, p. 216, determine the distance of the centroid from the leading edge.

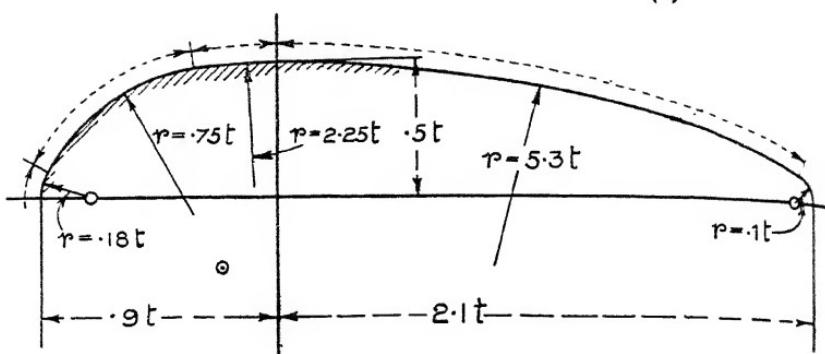
14. Find the position of the centroid of the pillar shown in Fig. 57, p. 210, of which further explanation is given in Question 2 on p. 210. [Deal with the flanges and the body as three separate portions.]

15. One end of a horizontal water main 3 ft. in diameter is closed by a vertical bulkhead, the centre of the main being 35 ft. below the level of the water. Find the total pressure on the bulkhead.

16. A semicircular plate is immersed vertically in sea water, its diameter being along the water surface. Find the total pressure on the plate if its diameter is 12 ft. and the weight of 1 cu. ft. of sea water is 64 lbs.; find also the depth of the centre of pressure. [Note.—The reduction formulæ given on p. 178 assist in the evaluation of the integrals.]

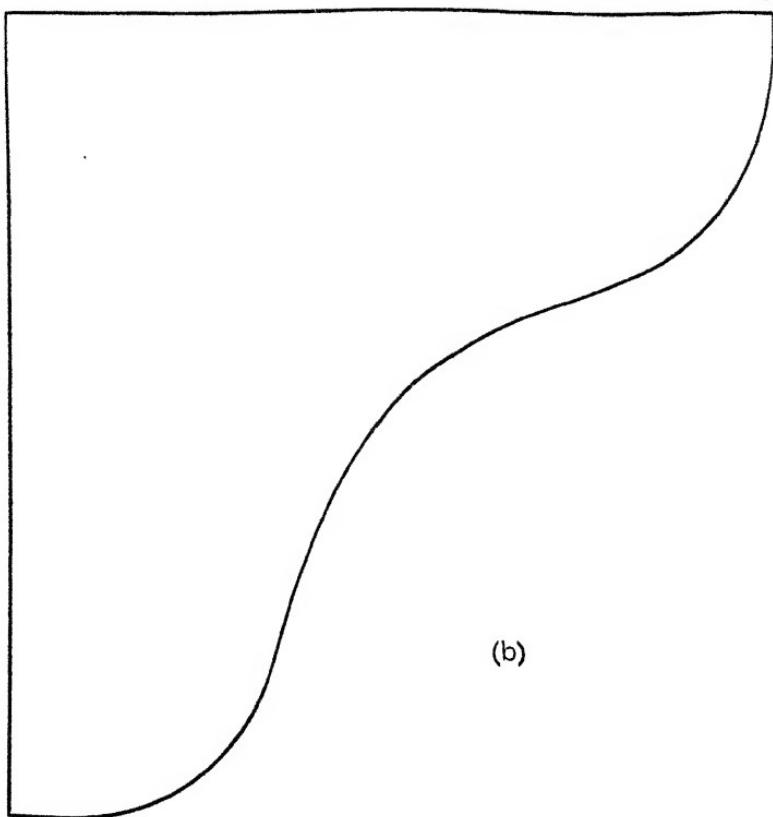
17. The parabola $y^2 = 6x$ revolves about the axis of x . Find the distance from the vertex of the C. of G. of the paraboloid thus generated, if the diameter of the end of the paraboloid is 18.

(a)



A

B



(b)

FIG. 76.

18. The diameter of a spindle at various distances along its length is measured with the following results—

Distance from end (ins.)

Diameter (ins.)	1.5	1.12	.83	.85	1.18	1.5	1.78	1.96	2
-----------------	-----	------	-----	-----	------	-----	------	------	---

Find the distance of the C. of G. from the smaller end.

19. Find, by means of the double sum curve method, the distance from AB of the centroid of the rail section shown at (a), Fig. 75.

20. An aluminium right circular cone is of height 7 ins. and the diameter of its base is 10 ins. Find (a) its mass, the density of aluminium being .093 lb. per cu. in.; (b) the height of its centroid above the base.

21. Use the double sum curve method to find the distance from AB of the centroid of the area shown at (b), Fig. 76.

22. A segment of a parabola is of height h and stands on a base b . Find the height of the centroid above the base.

23. A triangular plate of height h is immersed in water, its vertex being at the water surface, and its base being horizontal. Find the depth of the centre of pressure of the plate.

Moment of Inertia.—The product of a mass into the square of its distance from some fixed point or axis is called its second moment about that point or axis; and for a number of masses the sum of their respective second moments becomes the second moment, or *moment of inertia* of the system. When the number of masses is infinite, *i. e.*, when they merge into one mass, the limiting value of the sum of the second moments is spoken of as the moment of inertia of the body.

The moment of inertia of a section or body determines to a large extent the strength of the section or body to resist certain strains; the symbol I , which always stands for moment of inertia, occurs in numerous engineering formulæ; also when dealing with the formulæ of angular movement the mass is replaced by I , and so on, so that it is extremely important that one should be able to calculate values of I for various sections or solids.

A few examples will emphasise the frequent recurrence of the letter I . Consider first the case of a loaded beam:—

Let the figure (Fig. 77) represent the section of a beam loaded in any way. Then it is customary to make the following assumptions—

(a) There is to be no resultant stress over the section, *i. e.*, the sum of the tensions = the sum of the compressions.

(b) That the stress varies as the strain, and that the Young modulus for the material is the same for tension as for compression.

(c) That the original radius of curvature of the beam is exceedingly great compared with the dimensions of the cross section of the beam.

The surface of the beam which is neither compressed nor stretched is spoken of as the *neutral surface*, and the line in which this cuts any cross section of the beam is known as the *neutral axis*.

Referring to Fig. 77, let NN be the neutral axis, and let σ be

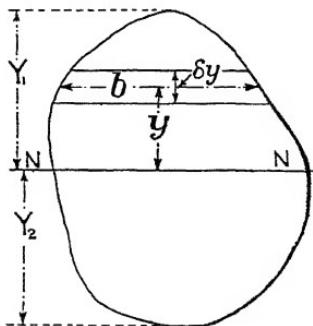


FIG. 77.

the stress at unit distance from NN, i.e., σ_y = the stress at a distance y from NN.

Thus the stress at y on a section of breadth b and depth δy = σ_y , and the force = stress \times area = $b\delta y \times \sigma_y$.

Now the forces on one side of NN must balance those on the other (by hypothesis).

$$\int_{-Y_2}^{Y_1} bdy\sigma_y = 0.$$

but $\int_{-Y_2}^{Y_1} \sigma bdy \times y = \text{total 1st moment of the forces}$

and the line about which this is zero must pass through the centroid of the section; hence the line NN passes through the centroid.

The tensile and compressive forces form a couple, the moment of which—

$$\begin{aligned} &= \Sigma \text{ force} \times \text{distance} = \sum_{-Y_2}^{Y_1} b\delta y \sigma_y \times y \\ &= \sigma \sum_{-Y_2}^{Y_1} b\delta y \times y^2 \end{aligned}$$

i.e., in the limit the moment of resistance of the internal forces

$$\begin{aligned} &= \sigma \int_{-Y_2}^{Y_1} bdy \times y^2, \quad i.e., \sigma \int \text{area} \times (\text{distance})^2 \\ &\quad i.e., \sigma (\text{2nd moment of section about NN}) \\ &= \sigma I. \end{aligned}$$

If M is the bending moment at the section, i.e., the moment of the external forces, it must be exactly balanced by the moment of the internal forces, so that $M = \sigma I$.

Also if f_1 = maximum tensile stress and $= \sigma Y_1$

f_2 = maximum compressive stress and $= \sigma Y_2$

$$\text{then } \tau = \frac{f_1}{Y_1} = \frac{f_2}{Y_2} = \frac{M}{I}$$

$$\text{or, in general, } \frac{M}{I} = \frac{f}{y}$$

Hence, in considering the strength of a beam to resist bending, it is necessary to know the moment of inertia of its section; knowing this and the bending moment, we can calculate the maximum skin stress.

As a further illustration of the importance of I in engineering formulæ let us deal with the following case : If a magnet is allowed to swing in a uniform field, the time T of a complete oscillation is given by—

$$T = 2\pi \sqrt{\frac{I}{MH}}$$

where I = moment of inertia of the magnet

M = magnetic moment of the magnet

H = strength of the uniform field in which the magnet swings.

In this case the I of a cuboid is required; and it will be seen that no mention of the mass is made in this formula. Actually the I takes account not only of the mass, but also of its disposition, the latter being a most important factor in all questions of angular movement. Thus for a mass of 1 lb. swinging at the end of an arm of 10 ft. the energy would be 10^2 , i.e., 100 times that of the same mass placed at a radius of 1 ft. only, although the angular velocities in the two cases were the same.

The reason for the presence of I in formulæ concerning the energy of rotation will be better understood if the next Example is carefully studied.

Example 37.—A disc revolves at n revs. per sec.; find an expression for its energy of rotation, or its kinetic energy.

If the total mass = m , let a small element δm of mass be considered, distant r from the axis of rotation (Fig. 78).

Now the linear velocity at the rim = $V = 2\pi nR$

$$\text{and the angular velocity} \quad \omega = \frac{\text{number of radians per sec}}{2\pi n}$$

then

$$\text{or} \quad R\omega = 2\pi nR = V \quad \omega = \frac{V}{R}$$

thus ω is constant throughout, whilst V depends on the radius.

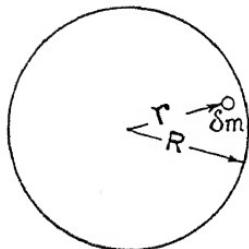


FIG. 78.

Kinetic Energy of mass δm

$$\begin{aligned} \text{mass} \times (\text{veloc.})^2 &= \frac{\delta m \times v^2}{2g} \\ &= \frac{I}{2g} \omega^2 r^2 \delta m \\ &= \frac{\omega^2}{2g} r^2 \delta m. \end{aligned}$$

$$\text{Hence the total K.E. of the disc} = \int_0^{R\omega^2} \frac{I}{2g} r^2 dm$$

$$\begin{aligned} &= \frac{\omega^2}{2g} \int_0^R \text{mass} \times (\text{distance})^2 \\ &= \frac{\omega^2}{2g} \times I \text{ for disc.} \end{aligned}$$

Thus the K.E. = $\frac{I}{2g} I \omega^2$. Comparing this formula with the corresponding one for linear motion, viz., K.E. = $\frac{I}{2g} mv^2$, we see that when changing from linear to angular movement, I takes the place of m and ω the place of v .

Suppose that the average velocity = $v_1 = r_1 \omega$

$$\text{then} \quad \frac{I}{2g} mv_1^2 = \frac{I}{2g} I \omega^2$$

$$\text{i.e.,} \quad mr_1^2 \omega^2 = I \omega^2$$

$$\text{or} \quad I = mr_1^2.$$

Hence I is of the nature of $\text{mass} \times (\text{distance})^2$, so that if the whole mass were concentrated at the distance r_1 from the axis, the K.E. of the system would be unaltered.

Hence the distance r_1 (which is usually denoted by k) is referred to as the *swing or spin radius*, or *radius of gyration*, i.e., it is the effective radius as regards all questions of rotation.

Note that k is not the arithmetic mean of the various radii, but the R.M.S. value for—

$$k = \sqrt{\frac{\sum (\text{radius})^2}{\text{number considered}}}$$

In general, I can be written as mk^2 (if dealing with a mass) or Ak^2 (if concerned with an area).

Method of Determination of the Value of I for any Section.—Whilst it is found desirable to commit to memory the values of I for the simpler sections, it is not wise to trust entirely to this plan. It is a far better policy to understand thoroughly the meaning of the term "moment of inertia," and to derive its value for any section or solid by working directly from first principles.

Thus, knowing that the moment of inertia is obtained by summing up a series of second moments, we divide the area or mass into a number of very small elements, find the area or mass of each of these and multiply each area or mass by the square of its distance from the axis or point about which moments are required; the sum of all such products being the value of I .

If the length of the swing radius is required, it can be determined from the relation $I = Ak^2$ (for an area) or $I = Mk^2$ (for a solid); the area or mass being obtained by the summation of the areas or the masses of the separate elements.

$$\text{Thus } k = \sqrt{\frac{\sum \text{second moments of elements}}{\sum \text{areas or masses of elements}}}.$$

Confusion often arises over the units in which I is measured; and to avoid this it is well to think of I in the form Ak^2 or Mk^2 , when it is observed that I is of the nature area \times (length) 2 , i.e., (inches) 2 \times (inches) 2 or (inches) 4 for a section, and mass \times (length) 2 or lbs. \times (inches) 3 for a solid.

The moment of inertia must always be expressed with regard to some particular axis; and it is frequently necessary to change from one axis to another. To assist in this change of axis the following rules are necessary:—

The Parallel Axis Theorem.—By means of this theorem, if I is known about an axis through the C. of G., the I about an axis parallel to the first can be deduced.

In Fig. 79 NN is the neutral axis of the section; and the moment of inertia is required about AB, i.e. I_{AB} is required.

Dealing with the strip indicated—

$$I_{AB} \text{ of the strip} = \rho b \delta y \times y^2.$$

$$\begin{aligned}\text{Hence the total } I_{AB} &= \rho \int b dy \times y^2 \\ &= \rho \int b dy \times (Y-d)^2 \\ &= \rho \int b dy (Y^2 + d^2 - 2Yd) \\ &= \rho b dy \times Y^2 + \rho \int b dy \times d^2 - 2\rho \int b dy Yd.\end{aligned}$$

$$\text{Now } \int \rho b dy \times Y^2 = \text{the total } I_{NN}$$

$$\text{and } \int \rho b dy \times d^2 = d^2 \int \rho b dy = d^2 \times \text{total mass} = md^2$$

$$\begin{aligned}\text{also } 2d \int \rho b dy \times Y &= 2d \times \text{total 1st moment about NN} \\ &= 2d \times 0 \text{ (for the moments on the strips on} \\ &\quad \text{one side of NN balance those on the} \\ &\quad \text{other)} \\ &= 0.\end{aligned}$$

$$\text{Hence } I_{AB} = I_{NN} + md^2$$

i.e., to find the moment of inertia about any axis, find the moment of

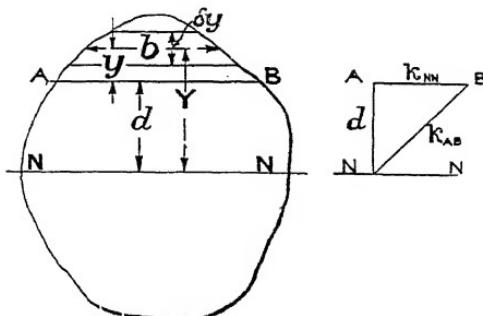


FIG. 79.

inertia about an axis through the C. of G. parallel to the axis given, and to this add the product of the mass into the square of the distance between the axes.

$$\begin{aligned}\text{e.g., if } I_{NN} &= 47, \text{ mass} = 12.4 \text{ and } d \text{ (between AB and NN)} = 2.3 \\ \text{then } I_{AB} &= I_{NN} + md^2 = 47 + (12.4 \times 2.3^2) \\ &= 47 + 65.7 = 112.7.\end{aligned}$$

$$\text{Since } I_{AB} = I_{NN} + md^2$$

$$\text{then } mk_{AB}^2 = mk_{NN}^2 + md^2$$

$$\text{or } k_{AB}^2 = k_{NN}^2 + d^2$$

and this relation is represented by Fig. 79, which suggests a graphic method of finding k_{AB} when k_{NN} is known.

Theorem of Perpendicular Axes.—We require to find I about an axis perpendicular to the plane of the paper and passing through O ; such being spoken of as a *polar second moment*.

To distinguish between the moment about an axis perpendicular to the plane of the paper and that about an axis in the paper, we shall adopt the notation I_O for the former and I_{OX} or I_{OY} , as the case may be, for the latter.

To find I_O :—

Consider a small element of mass δm at P (Fig. 80).

$$\text{Then } I_{OX} \text{ of this element} = \delta m \times y^2, I_{OY} = \delta m \times x^2, \\ \text{and } I_O = \delta m \times r^2.$$

$$\begin{aligned} \text{Now } r^2 &= x^2 + y^2 \\ \text{hence } \delta m \cdot r^2 &= \delta m \cdot x^2 + \delta m \cdot y^2 \\ \text{and } \int dm \cdot r^2 &= \int dm \cdot x^2 + \int dm \cdot y^2 \\ \text{total } I_O &= \text{total } I_{OY} + \text{total } I_{OX} \\ \text{or } I_O &= I_{OY} + I_{OX} \end{aligned}$$

so that if the moments of inertia about two perpendicular axes in the area are known, the sum of these is the moment of inertia about an axis perpendicular to the area and through the point of intersection of these axes.

$$\begin{aligned} \text{In special cases for which } I_{OY} &= I_{OX} \\ \text{then } I_O &= 2I_{OX}. \end{aligned}$$

To find the Relation between the Moment of Inertia about a Point in a Solid Body and the Moments of Inertia about three mutually Perpendicular Axes meeting in that Point.

Thus, referring to Fig. 81, it is desired to connect I_O with I_{OX} , I_{OY} and I_{OZ} .

$$\begin{aligned} \text{Consider a small element of the mass } \delta m \text{ placed at the point } P, \\ \text{Then if } PS = x, PT = y, PM = z, OP = r \\ (ON)^2 + (NM)^2 + (PM)^2 = (OP)^2, \text{ and } ON = PS, NM = PT \\ \text{i.e., } x^2 + y^2 + z^2 = r^2. \end{aligned}$$

$$\text{Now } I_{OX} \text{ of the element} = \delta m(PN)^2 = \delta m(z^2 + y^2)$$

$$\text{and in like manner } I_{OY} = \delta m(x^2 + z^2) \text{ and } I_{OZ} = \delta m(y^2 + x^2)$$

$$\text{also } I_O = \delta m(OP)^2 = \delta m r^2.$$

$$\begin{aligned} \text{Thus } I_O &= \delta m r^2 = \delta m(x^2 + y^2 + z^2) \\ &= \delta m \frac{x^2 + y^2 + y^2 + z^2 + z^2 + x^2}{2} \\ &= \delta m \times \frac{I}{2}(I_{OZ} + I_{OX} + I_{OY}) \end{aligned}$$

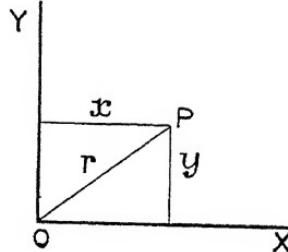


FIG. 80.

And for the total mass—

$$\int \delta m r^2 = \frac{I}{2} \int \delta m (I_{ox} + I_{oy} + I_{oz})$$

$$\text{or} \quad \text{total } I_O = \frac{I}{2} (I_{ox} + I_{oy} + I_{oz}).$$

We may now apply the principles already enunciated to the determination of the moments of inertia of various sections and

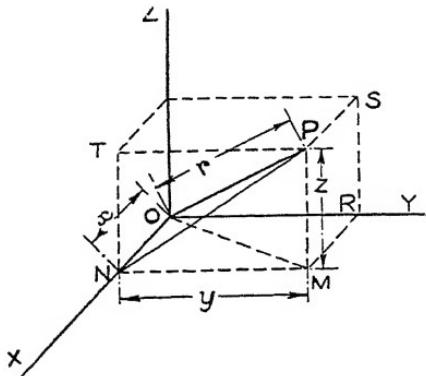


FIG. 81.

solids; and we take as our first example the case of a rectangular section.

Example 38.—To find the moments of inertia of a rectangle about various axes.

(a) To find I_{NN} (Fig. 82), NN being the neutral axis.

Dealing with the small strip, of thickness δx —

$$I_{NN} \text{ of strip} = b\delta x \times x^2 \quad i.e., \text{area} \times (\text{distance})^2$$

$$\text{Hence the total } I_{NN} = \int_{-\frac{h}{2}}^{\frac{h}{2}} b x^2 dx = b \left(\frac{x^3}{3} \right) \Big|_{-\frac{h}{2}}^{\frac{h}{2}} = \frac{bh^3}{12}$$

$$= bh \times \frac{h^2}{12}$$

$$= \text{area} \times \frac{h^2}{12}$$

$$\text{but } I_{NN} = A \times (k_{NN})^2, \quad \text{where } A \text{ is the area of the section}$$

$$\text{thus } A \frac{h^2}{12} = A (k_{NN})^2$$

$$\text{or } (k_{NN})^2 = \frac{h^2}{12}.$$

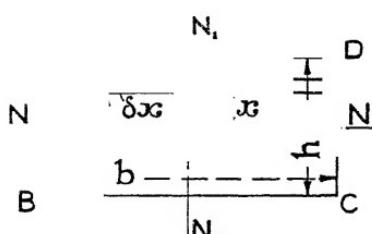


FIG. 82.

By symmetry it will be seen that $I_{N_1 N_1} = A \times \frac{b^2}{12}$.

b) To find I_{AB} .

$$I_{N_1 N_1} = \frac{Ab^2}{12}$$

and the distance between AB and $N_1 N_1 = \frac{b}{2}$

$$\text{hence } I_{AB} = I_{N_1 N_1} + \left\{ A \times \left(\frac{b}{2} \right)^2 \right\} = A \frac{b^2}{12} + A \frac{b^2}{4} \\ = \frac{Ab^2}{3}.$$

I_{AB} is larger than $I_{N_1 N_1}$, as would be expected, for the effective radius must be greater if the plate swings about AB than if it swings about $N_1 N_1$.

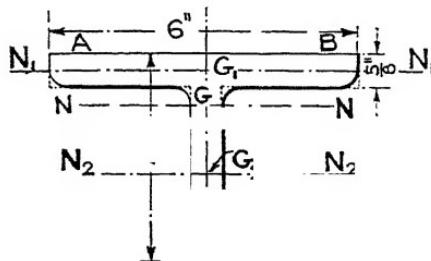


FIG. 83.

In like manner—

$$I_{AD} = \frac{Ah^2}{3}$$

$$I_A = I_{AB} + I_{AD} = A \frac{b^2}{3} + A \frac{h^2}{3} \\ = \frac{A}{3}(h^2 + b^2) = \frac{I}{3} A \times (BD)^2.$$

The rule for the moment of inertia of a rectangle is required very frequently, since many sections can be broken up into rectangles.

Example 39.—To find I_{NN} of the Tee section shown in Fig. 83.

The neutral axis NN is distant 1.03" from AB (cf. *Example 25*, p. 220). Dealing with the flange—

$$I_{N_1 N_1} = \frac{I}{12} bh^3 = \frac{I}{12} \times 6 \times \left(\frac{5}{8} \right)^3 = .122 \text{ in.}^4$$

also the distance $G_1 G = .72"$.

Hence by the parallel axis theorem—

I_{NN} of the flange $= I_{N_1 N_1} + [A \times (G_1 G)^2]$ (A being the area of the flange)

$$= 1.22 + (6 \times \frac{5}{8} \times 7^2) = 1.22 + 1.94 \\ = 2.06 \text{ ins.}^4$$

For the web $I_{N_2 N_2} = \frac{I}{12} b h^3 = \frac{I}{12} \times \left(\frac{27}{8}\right)^3 \times \frac{5}{8} = 2 \text{ ins.}^4$

and also $G_2 G = 1.28''.$

Hence I_{NN} of the web $= I_{N_2 N_2} + A_1 \times (G_2 G)^2$ (A_1 is area of the web)

$$= 2 + \left(\frac{27}{8} \times \frac{5}{8} \times 1.28^2\right) \\ = 5.45 \text{ ins.}^4$$

Hence the total I_{NN} of the section $= 2.06 + 5.45 = 7.51 \text{ ins.}^4$

Example 40.—Find the polar 2nd moment of a circular disc of radius R; and also the moment of inertia about a diameter.

Consider a ring of width δr , distant r from the centre (Fig. 84).

Then I_O of the annulus $= \text{mass (or area)} \times (\text{distance})^2$

$$= 2\pi r \delta r \times r^2 \\ = 2\pi r^3 \delta r.$$

Hence

$$\text{the total } I_O = \int_0^R 2\pi r^3 dr = 2\pi \int_0^R r^3 dr \\ = \frac{2\pi R^4}{4} = \frac{\pi R^4}{2}.$$

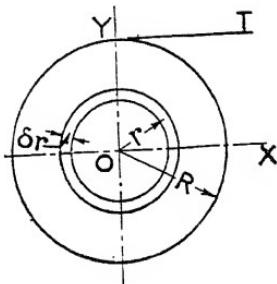


FIG.

$$\text{Now } I_{OX} = I_{OY} \\ \text{and } I_O = I_{OX} + I_{OY} = 2I_{OX} \\ I_{OX} = \frac{1}{2} I_O = \frac{\pi R^4}{4}$$

To find the respective swing radii—

$$Ak_O^2 = I_O = \frac{\pi R^4}{2}$$

$$\pi R^2 k_O^2 = \frac{\pi R^4}{2}$$

$$\text{i.e., } k_O^2 = \frac{R^2}{2}$$

$$\text{or } k_O = \frac{R}{\sqrt{2}}, \text{ i.e., } \frac{\sqrt{2}}{2} R. \quad \left\{ \begin{array}{l} \text{Cf. with the R.M.S.} \\ \text{value of a sine function} \\ \text{of amplitude R.} \end{array} \right.$$

$$\text{Also } Ak_{OX}^2 = I_{OX} = \frac{\pi R^4}{4}$$

$$(k_{OX})^2 = \frac{\pi R^4}{4 \times \pi R^2} \cdot \frac{R^2}{4}$$

$$k_{OX} = \frac{R}{2} = \underline{.5R}$$

To find the swing radius about a tangent—

$$(\text{distance})^2 (\text{OX to YT}) = R^2$$

$$\therefore I_{YT} = I_{OX} + AR^2$$

$$= A \frac{R^2}{4} + AR^2 \quad A \frac{5R^2}{4}$$

hence

$$k_{YT}^2 = \frac{5}{4} R^2$$

or

$$k_{YT} = \underline{1.12R}$$

Example 41.—To find the moment of inertia of a right circular cylinder of length h and radius R , about various axes.

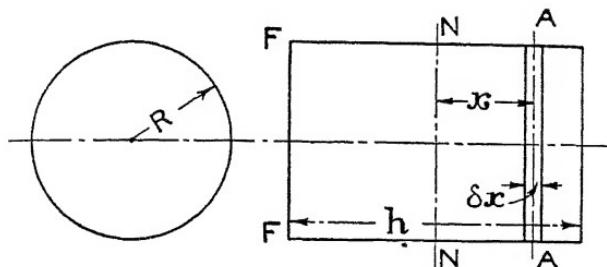


FIG. 85.

(a) About the axis of the cylinder.

(b) About an axis through the C. of G. perpendicular to the axis of the cylinder.

(c) About an axis parallel to that in (b), but through one end.

(a) The 2nd moment about the axis of the thin cylinder of length δx (Fig. 85)—

$$= \text{mass} \times \frac{R^2}{2} \quad \text{from Example 40}$$

$$= \rho \pi R^2 \delta x \times \frac{R^2}{2} \quad \rho \text{ being the density of the material.}$$

Hence the total 2nd moment about the axis—

$$= \int_0^h \rho \pi R^2 \frac{R^2}{2} dx = \frac{\rho \pi R^4}{2} h$$

$$= \rho \pi R^2 h \times \frac{R^2}{2}$$

$$= m \frac{R^2}{2}$$

where m = the mass of the cylinder.

(b) The 2nd moment of the strip about AA, which is parallel to NN—

$$\begin{aligned} &= \text{mass} \times \frac{R^2}{4} \quad (\text{see Example 40}) \\ &= \rho\pi R^2 \delta x \times \frac{R^2}{4} \end{aligned}$$

Hence I_{NN} of the strip = I_{AA} of the strip + (its mass $\times x^2$) since AA is an axis through the C. of G. of the strip.

Thus I_{NN} of the strip = $\frac{\rho\pi R^4}{4} \delta x + \rho\pi R^2 x^2 \delta x$

$$\begin{aligned} \text{and thus the total } I_{NN} &= \int_{-\frac{h}{2}}^{\frac{h}{2}} \frac{\rho\pi R^4}{4} dx + \int_{-\frac{h}{2}}^{\frac{h}{2}} \rho\pi R^2 x^2 dx \\ &= \frac{\rho\pi R^4}{4} \left(\frac{h}{2} + \frac{h}{2} \right) + \rho\pi R^2 \left(\frac{h^3}{24} + \frac{h^3}{24} \right) \\ &= \rho\pi R^2 h \left(\frac{R^2}{4} + \frac{h^2}{12} \right) \\ &= m \left(\frac{R^2}{4} + \frac{h^2}{12} \right) \end{aligned}$$

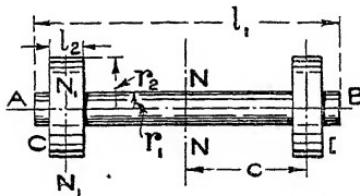


FIG. 86.

(c) To find I_{FF} , FF being parallel to AA and NN.

The distance between FF and NN = $\frac{h}{2}$.

Also it has just been proved that $I_{NN} = m \left(\frac{R^2}{4} + \frac{h^2}{12} \right)$

Hence

$$\begin{aligned} I_{FF} &= m \left(\frac{R^2}{4} + \frac{h^2}{12} \right) + m \left(\frac{h}{2} \right)^2 \\ &= m \left(\frac{R^2}{4} + \frac{h^2}{3} \right). \end{aligned}$$

Example 42.—Find an expression for the moment of inertia of a large pulley wheel of outside radius R and thickness of rim t . Neglect the arms or spokes of the wheel.

Let r = inside radius of wheel, i. e., $r = R - t$.

Then, using the result of *Example 40*, p. 246, we know that the moment of inertia of the wheel as solid = $\frac{\pi R^4}{2} \times \rho b$; from this must

be subtracted the moment of inertia of a disc of radius r , viz., $\frac{\pi r^4}{2} \times \rho b$ (ρ being the density of the material and b the breadth of the rim along the face).

$$\begin{aligned}\text{Hence } I_O &= \frac{\pi R^4}{2} \rho b - \frac{\pi r^4}{2} \rho b = \frac{\pi \rho b}{2} (R^4 - r^4) \\ &= \frac{\pi \rho b}{2} (R^2 + r^2) (R^2 - r^2) \\ &= \pi \rho b (R^2 - r^2) \times \frac{R^2 + r^2}{2} \\ &= M \left(\frac{R^2 + r^2}{2} \right) \quad . . . \quad (1)\end{aligned}$$

where M is the mass of the wheel.

$$\text{Writing } R-t \text{ for } r, I_O = \frac{M}{2} (R^2 + R^2 + t^2 - 2Rt) = \frac{M}{2} (2R^2 - 2Rt + t^2).$$

From (1) it will be seen that in order to get I_O as large as possible, R and r must be very nearly equal, i.e., t must be very small compared with R . Thus for an approximation t^2 may be neglected in the expression for I_O , so that $I_O = \frac{M}{2} \times 2R(R-t) = MR(R-t)$.

Referring once again to (1), $I_O = M \left(\frac{R^2 + r^2}{2} \right)$, i.e., $Mk_O^2 = M \left(\frac{R^2 + r^2}{2} \right)$ or $k_O^2 = \frac{R^2 + r^2}{2}$ and $k_O = 1.07 \sqrt{R^2 + r^2}$. As an approximation for this the rule $k_O = \frac{1}{2}(R+r)$ is often used; k_O being thus taken as the average radius.

Moment of Inertia of Compound Vibrators.—To find the modulus of rigidity of a sample of wire by the method of torsional oscillations, various forms of vibrators may be used. In the calculations which follow the experiments, the moment of inertia of the vibrator occurs, so that it is necessary to understand how to obtain this. To illustrate by an example of one form of compound vibrator, suppose that the I about an axis through the C. of G. of the one shown in Fig. 86 is required.

Let m_1 = mass of AB, r_1 be its radius and l_1 its length

m_2 = mass of C and also of D, r_2 be its radius and l_2 its length.

Then I_{NN} of AB = $m_1 \left(\frac{r_1^2}{4} + \frac{l_1^2}{12} \right)$ (from Example 41, p. 248)

and $I_{N_1 N_1}$ of C = $m_2 \left(\frac{r_2^2}{4} + \frac{r_1^2}{4} + \frac{l_2^2}{12} \right)$ { for the inner radius } $= r_1$

$$I_{NN} \text{ of } C = m_2 \left(\frac{r_2^2}{4} + \frac{r_1^2}{12} + \frac{l_2^2}{12} \right) + m_2 c^2 \quad \text{by the parallel axis theorem.}$$

This is also the I_{NN} of D.

$$\text{total } I_{NN} = m_1 \left(\frac{r_1^2}{4} + \frac{l_1^2}{12} \right) + 2m_2 \left(\frac{r_2^2}{4} + \frac{r_1^2}{4} + \frac{l_2^2}{12} + c^2 \right).$$

Maxwell's needle is a very convenient form of compound vibrator, and is utilised to determine the modulus of rigidity of the sample of wire by which it is supported. It consists essentially of a tube along which weights may be moved from one position to another, the movement being a definite amount.

Referring to Fig. 87—

m_1 = the mass of each of the movable weights

m_2 = the mass of each of the fixed weights.

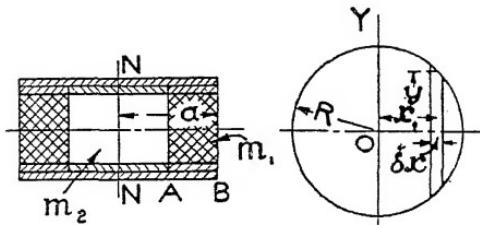


FIG. 87.

FIG. 88.

Then the time of torsional oscillations is measured when the movable weights are placed as shown, and again when they are moved to the centre; and it can be proved that the modulus of rigidity depends upon the difference between the moments of inertia under the two sets of conditions.

Thus, since a mass m_1 is shifted from the position AB to the position NA, the only difference in the moments of inertia is that due to the changing of the C. of G. of a mass $(m_1 - m_2)$ from a distance $\frac{3}{4}a$ from the axis of oscillation to $\frac{1}{4}a$; for I_{NN} of m_2 is unaltered.

Hence the change of I } = $I_1 - I_2 = (m_1 - m_2) \left(\frac{9}{16}a^2 - \frac{1}{16}a^2 \right)$,
considering one mass only }

$$\begin{aligned} \text{and thus for the two masses } I_1 - I_2 &= 2(m_1 - m_2) \left(\frac{1}{2}a^2 \right) \\ &= (m_1 - m_2)a^2. \end{aligned}$$

Example 43.—Find the moment of inertia of a sphere of radius R about its diameter.

Consider the thin disc (Fig. 88) of radius y , and thickness δx .
I of the strip about a diameter parallel to OY—

$$= \frac{\pi\rho}{4}y^4\delta x \quad (\text{cf. Example 40, p. 246}).$$

Hence I of the strip about OY (distant x from the diameter considered)

$$= \frac{\pi\rho}{4}y^4\delta x + (\pi\rho y^2\delta x \times x^2)$$

Now $y^2 = R^2 - x^2$.

Thus I_{OY} of disc $= \pi\rho \int (R^4 + x^4 - 2R^2x^2 + 4R^2x^2 - 4x^4) \delta x$

$$\text{and hence } I_{OY} \text{ of sphere} = \frac{\pi\rho}{4} \int_{-R}^R (R^4 - 3x^4 + 2R^2x^2) dx$$

$$= \frac{2\pi\rho}{4} \int_0^R (R^4 - 3x^4 + 2R^2x^2) dx$$

$$= \frac{2\pi\rho}{4} \left[R^4x - \frac{3x^5}{5} + \frac{2R^2x^3}{3} \right]_0^R$$

$$= \frac{2\pi\rho}{4} \times \frac{16R^5}{15} = \frac{8}{15}\rho\pi R^5$$

$$= \frac{4}{3}\rho\pi R^3 \times \frac{2}{3}R^2$$

$$= m \times \frac{2}{3}R^2 \quad (\begin{matrix} m \text{ being the mass} \\ \text{of the sphere.} \end{matrix})$$

and

$$k_{OY}^2 = \frac{2}{5}R^2.$$

Determination of 1st and 2nd Moments of Sections by means of a Graphic Construction and the Use of a Planimeter.

The graphic construction now to be described is extremely simple to understand, and has the additional merit of being utilised to give 3rd, 4th and higher moments if desired.

It being required to find the 1st and 2nd moments about MM of the rail section shown in Fig. 89, and also the position of the neutral axis, the procedure is as follows :—

Construction.—Divide the half-area into a number of strips by means of horizontal lines; the half-area only being treated, since the section is symmetrical.

At a convenient distance h from MM draw M_1M_1 parallel to MM. From P, the end of one of the horizontals, draw PR perpendicular to MM, and from P^1 , the other end of the same horizontal, drop P^1R^1 perpendicular to M_1M_1 ; join R^1R and note Q, its point of intersection with P^1P . Repeat the process for all the other horizontals (of which only three are shown in the diagram) and

join up all the points like Q_1 , thus obtaining the curve CQLS, which is termed the 1st moment curve.

To obtain the 2nd moment curve treat the area CPKXSLQ in the same way as the original area was treated, i.e., drop QR'' perpendicular to M_1M_1 and join RR'' ; join up all points like Q_1 and the 2nd moment curve is obtained.

Calculation.—Find by the planimeter the areas of the original

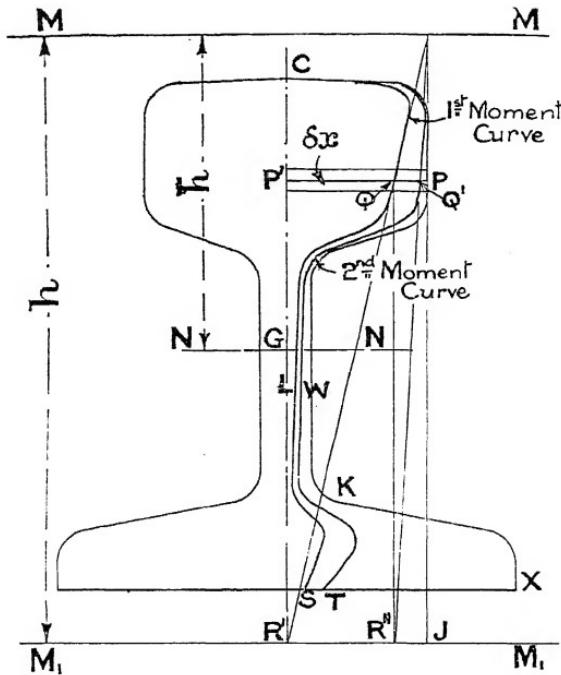


FIG. 89.—Moments of Sections by Graphic Construction.

half-section, $CPKXSLQ$ and $CPKXTWQ^1$; call these A_0 , A_1 and A_2 respectively.

Then 1st moment of the section about $MM = 2 \times hA_1$
(for A_1 is for the half-section only).

Distance of the centroid of the section from $MM = \frac{hA_1}{A_0}$

2nd moment of section about $MM = 2h^2A_2$

$$\text{i.e., } (\text{swing radius}_{MM})^2 = \frac{h^2A_2}{A_0}$$

and by the theorem of parallel axes, I can be found about NN .

In this case the actual results are as follows:—

$$h = 3 \text{ ins. } A_0 = 1.11 \text{ sq. ins. } A_1 = .573 \text{ sq. in. } A_s = .39 \text{ sq. in.}$$

Hence $\bar{h} = \frac{3 \times .573}{1.11} = 1.55 \text{ ins.}$

$$\text{1st moment of section about MM} = 2 \times 3 \times .573 = 3.44 \text{ ins.}^3$$

$$\text{2nd moment of section about MM} = 2 \times 3^2 \times .39 = 7.02 \text{ ins.}^4$$

$$\text{Swing radius about MM} = \sqrt{\frac{7.02}{2.22}} = 1.78 \text{ ins.}$$

N.B.—To distinguish which area is to be read off by the planimeter the following rule should be observed: Read the area between the 1st or 2nd moment curve, as the case may be, and the side of the original contour from which we dropped perpendiculars on the line about which we required moments.

Proof.—Consider P^1P as the centre line of a thin strip (such as the one indicated). Then the area of the strip $= P^1P \times \delta x$, and 1st moment about MM $= P^1P \times \delta x \times RP$.

From the similar triangles RPQ and RJR^1

$$\frac{RP}{QP} = \frac{RJ}{JR^1} = \frac{h}{PP^1}$$

whence $RP \times PP^1 = h \times QP$

and $RP \times PP^1 \times \delta x = h \times QP \times \delta x$

i. e., 1st moment of the strip about MM—

$= h \times$ the area of which QP is the centre line.

Then, by summing—

Total 1st moment of the half-area about MM—

$= h \times$ the area between 1st moment curve and right-hand boundary of section

$$= hA_1.$$

Again, the 2nd moment of the strip about MM $=$ area \times (distance)²
 $= PP^1 \times \delta x \times (RP)^2$

and $\frac{RP}{RJ} = \frac{PQ^1}{JR''} = \frac{PQ^1}{PQ}$

$$\therefore \frac{RP}{h} = \frac{PQ^1}{PQ} \quad \text{i. e., } RP = \frac{hPQ^1}{PQ}.$$

Hence the 2nd moment of the strip about MM—

$$= P^1P \times RP \times RP \times \delta x$$

$$= h \times QP \times h \times \frac{PQ^1}{PQ} \delta x = h^2 \times PQ^1 \times \delta x$$

$= h^2 \times$ area of which PQ^1 is the centre line.

And the total 2nd moment of the half-area about MM—
 $= h^2 \times \text{area between the 2nd moment curve and the right-hand boundary of the section.}$
 $= h^2 \times A_2.$

Exercise 20.—On Moment of Inertia.

1. Find the swing radius about the lighter end of a rectangular rod of uniform section and breadth and length l , for which the density is proportional to the square root of the distance from that end.

2. The swing radius of a connecting rod about its centre of suspension was found to be 35.8 ins., and the distance of the C. of G. from the point of suspension was 31.43 ins. Find the swing radius about the neutral axis.

If the connecting rod weighed 86.5 lbs., find its moment of inertia about the neutral axis.

FIG. 90.

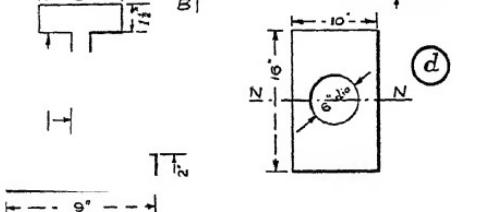
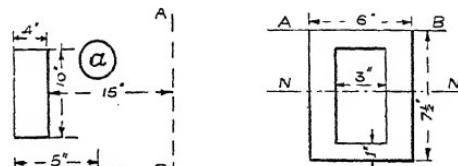


FIG. 91.

3. A circular disc, 7" diameter, has a circular hole through it, of diameter 3", the centre of the hole being $\frac{1}{2}$ " distant from the centre of the disc. Find the swing radius of the disc about an axis through its centre of gravity, perpendicular to the face of the disc.

4. Find the moment of inertia of a rectangle (5" by 3") about a diagonal as axis.

5. Find the swing radius of a triangular plate (of height h)—

(a) When swinging about its base.

(b) When swinging about an axis through the vertex, parallel to the base.

6. By dividing into strips, by lines parallel to AB, find the moment of inertia, about AB, and also the swing radius, of the section shown at (a), Fig. 75, p. 234.

7. Find the radius of gyration about the axis of rotation, of the

rim of a flywheel, of outside diameter 5' 2", the radial thickness of the rim being 4".

Find the moment of inertia about the neutral axis of the sections in Nos. 8, 9 and 10.

8. Channel Section, (b), Fig. 75.

9. Unequal Angle, (c), Fig. 75.

10. Tee Section, (d), Fig. 75.

11. Find the swing radius, about the axis, of a paraboloid, the diameter of the bounding plane, which is perpendicular to the axis, being d .

12. The *flexural rigidity* of a beam is measured by the product of the Young's Modulus E for the material into the moment of inertia of the section. Compare the flexural rigidity of a beam of square section with that of one of the same material but of circular section, the span and weight of the two beams being alike.

13. A cylinder 6" long and of $1\frac{1}{2}$ " diameter is suspended horizontally by means of a long wire attached to a hook, and the wire is then twisted to give an oscillatory movement to the cylinder. Find the moment of inertia of the cylinder about the hook.

14. Determine the moment of inertia and also the swing radius about AB of the rectangular section shown at (a), Fig. 90.

15. Calculate the moment of inertia and also the swing radius of the box section shown at (b), Fig. 90, both about NN and about AB.

16. Find the position of the neutral axis of the section shown at (c), Fig. 91, and then calculate the moment of inertia and also the swing radius about this axis.

17. Determine the swing radius of the section shown at (d), Fig. 91, about the axis NN.

18. The moment of inertia of the pair of driving wheels of a locomotive connected by a crank axle was found by calculation to be 34133 lbs. ft.². If the total weight of the two wheels and the axle was 8473 lbs., and the diameter of the driving wheels was 6 ft. 1 in., find the swing radius of the wheel and also the ratio $\frac{k^2}{r^2}$, where r is the radius of the wheel.

19. Find the swing radius about the axis of a right circular cone of uniform density, the radius of the base being 5 ins.

20. Employing the method explained on p. 251, determine (a) the 1st moment about AB, (b) the 2nd moment about AB, (c) the distance of the centroid from AB, and (d) the swing radius about AB, of the area shown at (b) Fig. 76, p. 236.

21. A steel wire, .15 in. in diameter, hangs vertically; its upper end is clamped, and its lower end is secured to the centre of a horizontal disc of steel, which is 6 in. in diameter and $\frac{3}{8}$ in. thick. If the length of the wire is 3 ft., and if C, the modulus of transverse elasticity of the steel, has the value 12,540,000 lbs. per sq. in., find the time of a torsional oscillation of the wire, from the formula—

$$t^2 = 402.5 \frac{Il}{Cd^4}$$

where I = moment of inertia of the disc about the axis of suspension in lbs. ins.², l = length of wire in feet, d = diameter of wire in inches.

22. An anchor ring is generated by the revolution of a circle of radius r about an axis distant R from the centre of the circle. Find the moment of inertia of the ring about this axis. (*Hint*.—Commerce with the polar moment, *i. e.*, the moment about the given axis, of an annulus made by a section at right angles to this axis, finding an expression for the inner and outer radii of the annulus in terms of the distance from the central annulus, and then sum up.)

23. Find the swing radius about the major axis of the ellipse whose equation is—

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1.$$

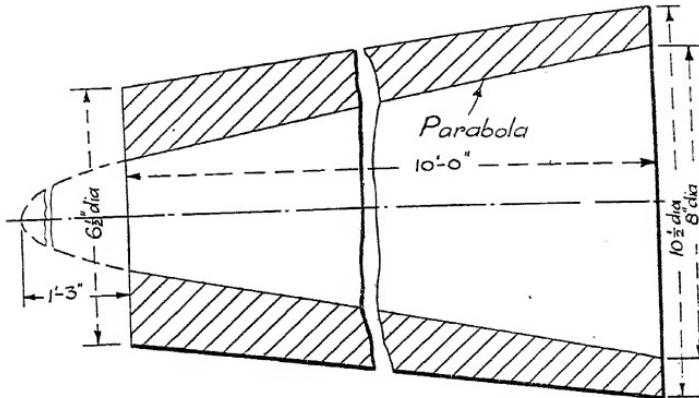


FIG. 91A.—Weight of a Centrifugal Casting (see p. 210).

CHAPTER VIII

POLAR CO-ORDINATES

Polar Co-ordinates.—A point on a plane may be fixed by its distances from two fixed axes, or by its distance along a line which makes a definite angle with some fixed axis. In the former case we are concerned with rectangular co-ordinates and the point is written as the point (x, y) ; whilst in the latter case the co-ordinates are *polar* and the point is denoted by (r, θ) , r being the length along the ray inclined at an angle θ to the fixed axis.

It is really immaterial as to what line is taken as the fixed axis: in many cases the horizontal axis is taken, but in order to agree with the convention adopted for the measurement of angles (see Part I, Chapter VI) we shall here consider the N. and S. line, *i. e.*, a vertical line, as the starting axis and regard all angles as positive when measured in a right-handed direction from that axis. A point is next fixed on that line from which all the rays or radii vectors originate, and this point is spoken of as the *pole* for the system: thus the reason for the term *polar* is seen.

To illustrate this method of plotting, let us refer to Fig. 92. Taking OY as the starting axis and O as the pole, the point $(2, 35^\circ)$ is obtained by drawing a line making 35° with OY and then stepping off a distance OP along it to represent 2 units, *i. e.*, $r=2$ and $\theta=35^\circ$. In like manner Q is the point $(1.7, 289^\circ)$; whilst R is the point $(2.4, -20^\circ)$.

One advantage of this method of plotting is that it is not necessary to classify into quadrants and to remember the arrange-

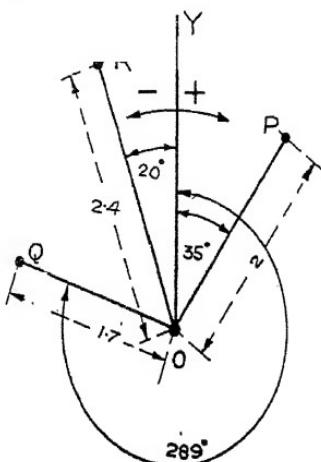


FIG. 92.

ment of the algebraic signs; all lengths measured outwards from the pole being reckoned as positive.

Example 1.—The following table gives the candle power of an arc lamp for various positions below the lamp: plot the polar diagram.

Angle below horizontal	20°	30°	40°	50°	60°	70°	80°
Candle power	1800	1470	1800	1720	1200	960	800

In reality we have to plot a number of polar co-ordinates, the lengths representing the values of the candle power; but since the horizontal axis is specified, we shall take that as the main axis. Draw rays making 10°, 20°, 30°, etc. (Fig. 93), with the horizontal axis, and along these lines set off distances to represent the respective candle powers, always measuring outwards from the centre. Join the ends of the rays and the polar diagram is completed.

The Archimedean spiral and the logarithmic or equiangular spiral, important in connection with the forms of cams and gear wheels respectively, may be easily plotted from their polar equations.

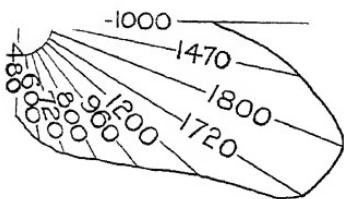


FIG. 93.—Candle Power of Arc Lamp.

secutive terms in an arithmetic progression, whilst in the latter case the rays are in geometric progression.

To illustrate the forms of these curves by taking numerical examples:—

Example 2.—Plot the Archimedean spiral $r = .573\theta$, showing one convolution.

In the equation θ must be in radians, but to simplify the plotting we can transform the equation so that values of a (in degrees) may replace θ (radians).

$$\text{Thus} \quad r = .573\theta = \frac{.573a}{57.3} \text{ (degrees)} = .01a.$$

Then the table for the plotting reads :—

α	0	30	60	90	120	150	180	210	240	270	300	330	360
r	0	.3	.6	.9	1.2	1.5	1.8	2.1	2.4	2.7	3.0	3.3	3.6

and the plotting is shown in Fig. 94.

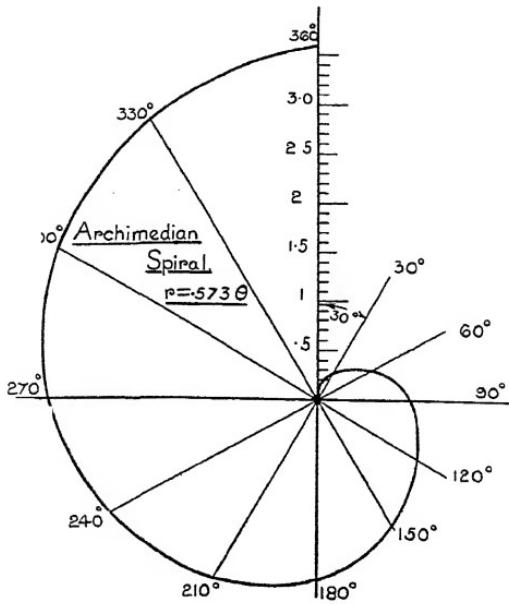


FIG. 94.

Example 3.—Plot one convolution of the equiangular spiral

$$r = .5e^{.25\theta}.$$

$$r = .5e^{.25\theta} = .5e^{.257.3} = .5e^{.00436a}.$$

$$\begin{aligned} \text{In the log form } \log r &= \log .5 + .00436a \log e \\ &= 1.6990 + (.00436 \times .4343 \times a) \\ &= 1.6990 + .001894a \end{aligned}$$

and thus the table of values reads :—

a	0	30	60	90	120	150	180	210	240	270	300	330	360
a	0	.0568	.1136	.1705	.2273	.2841	.3409	.3977	.4546	.5114	.5682	.625	.6818
$\log r$	1.6990	1.7558	1.8126	1.8695	1.9263	1.9831	2.0399	2.0967	2.1536	2.2104	2.2672	2.324	2.3808
r	.5	.5699	.6495	.7407	.8439	.9618	1.096	1.249	1.424	1.624	1.85	2.109	2.403

The curve is drawn in Fig. 95.
It will be seen that the ratio of

$$\frac{\text{second ray}}{\text{first ray}} = \frac{.5699}{.5} = 1.14$$

$$\frac{\text{third ray}}{\text{second ray}} = \frac{.6495}{.5699} = 1.14$$

so that this spiral might alternatively have been defined as one for which the rays at equiangular intervals of 30° form a geometric progression in which the common ratio is 1.14, the first ray being .5".

Comparing the given equation $r = .5e^{25\theta}$ with that connecting the tensions at the ends of a belt passing round a pulley, viz.,

$T = te^{u\theta}$, we observe that the forms are identical, or in other words the equiangular spiral might be used to demonstrate the growth of the tension as the belt continuously embraces more of the pulley.

Selecting any point P on the spiral, and drawing the tangent PT there and also the ray OP which makes an angle ϕ with the tangent, it is found that $\cot \phi = .25$ = coefficient of θ in the original equation. This relation would hold wherever the point P was taken on the spiral,

so that the angle between the ray and the curve is constant: and thus the spiral is called "equiangular."

If $\cot \phi = 1$, $\phi = 45^\circ$ and $r = ae^\theta$, or taking $a = 1$, $r = e^\theta$ and $\log_e r = \theta$. Thus a spiral could be constructed in which the angles (in radians) would be the values of the logs of the rays: this spiral, however, is extremely tedious to draw, and its value consists merely in its geometric demonstration of the relationship between the natural logarithms and their numbers.

Connection between Rectangular and Polar Co-ordinates.—Let P be a given point, with rectangular co-ordinates x and y and with polar co-ordinates r and θ .

Then referring to Fig. 96—

$$\frac{ON}{OP} = \frac{y}{r} = \cos \theta$$

so that

$$y = r \cos \theta$$

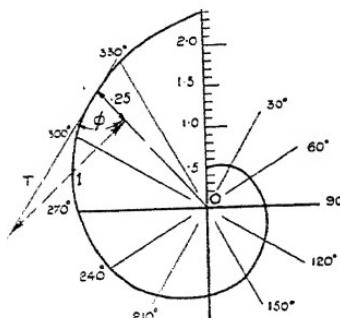


FIG. 95.

and

$$\frac{OM}{OP} = \frac{x}{r} = \sin \theta$$

so that

$$x = r \sin \theta$$

and also

$$\frac{x}{y} = \frac{r \sin \theta}{r \cos \theta} = \tan \theta.$$

Use of Polar Co-ordinates for the Determination of Areas.—Polar co-ordinates may be usefully employed to find areas of certain figures.

It is stated in the previous work on mensuration that—

$$\text{Area of sector of circle} = \frac{1}{2}r^2\theta$$

where θ = angle of the sector in radians.

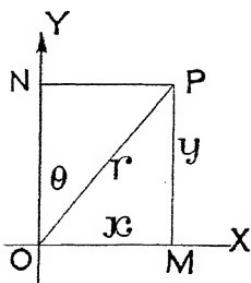


FIG. 96.

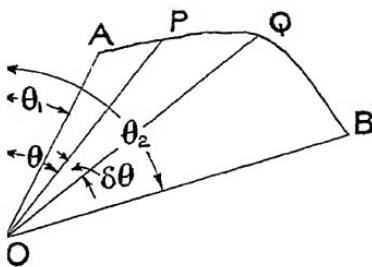


FIG. 97.

Let P and Q (Fig. 97) be the two points (r, θ) and $(r+\delta r, \theta+\delta\theta)$ and close to one another.

Then, since r and $r+\delta r$ differ very slightly

$$\text{Area } POQ = \frac{1}{2}r^2\delta\theta$$

and the total area AOB = $\sum_{\theta_1}^{\theta_2} \frac{1}{2}r^2\delta\theta$, approximately

$$\int_{\theta_1}^{\theta_2} \frac{1}{2}r^2 d\theta \quad \text{exactly.}$$

For the evaluation of this integral the working may be either graphic or algebraic, according to the manner in which the relation between r and θ is stated.

As a simple illustration we may take the case of a circle of radius a . The area of the circle was found at an earlier stage (see p. 225) by evaluating $\int y dx$, i.e., by expressing the integral in terms of the rectangular co-ordinates. To evaluate the integral, however, it was found necessary to make the substitution $x = a \sin \theta$, the change thus being from rectangular to polar co-ordinates.

Evidently the rotating ray is constant in length and equal to a , the radius of the circle, and the limits to θ are 0 and 2π , if the sum area is required; hence—

$$\text{Area of circle} = \int_0^{2\pi} \frac{1}{2}a^2 d\theta = \frac{1}{2}a^2 \int_0^{2\pi} d\theta = \frac{1}{2}a^2 \cdot 2\pi \\ = \pi a^2.$$

Example 4.—Find the area of the cardioid given by the equation $r = a(1 + \cos \theta)$, θ ranging from 0 to 2π .

In this case r is of variable length, but there is a definite connection between r and θ , so that the integration is algebraic.

$$\begin{aligned} r &= a(1 + \cos \theta) \text{ and } r^2 = a^2(1 + \cos \theta)^2 \\ &= a^2(1 + \cos^2 \theta + 2 \cos \theta) \\ &= a^2(1 + \frac{1}{2} \cos 2\theta + \frac{1}{2} + 2 \cos \theta) \\ &= a^2(1.5 + \frac{1}{2} \cos 2\theta + 2 \cos \theta). \end{aligned}$$

$$\begin{aligned} \text{Hence} \quad \text{area} &= \int_0^{2\pi} \frac{1}{2}r^2 d\theta \\ &= \frac{a^2}{2} \int_0^{2\pi} (1.5 + \frac{1}{2} \cos 2\theta + 2 \cos \theta) d\theta \\ &= \frac{a^2}{2} \left(1.5\theta + \frac{1}{4} \sin 2\theta + 2 \sin \theta \right)_0^{2\pi} \\ &= \frac{a^2}{2} (1.5 \times 2\pi) = \underline{\underline{\frac{3\pi a^2}{2}}} \end{aligned}$$

The Rousseau Diagram.—The use of the Rousseau diagram simplifies the determination of the *mean spherical candle power* of a lamp.

The candle power of the lamp varies according to the direction in which the illumination is directed (cf. Fig. 93); in the case there discussed, however, we considered the illumination in one plane only. If we imagine the polar curve to revolve round the vertical axis we see that a surface is obtained by means of which the illumination in any direction can be measured. The mean of all these candle powers is spoken of as the mean spherical candle power of the lamp. If the arc is placed at the centre of a spherical enclosure, of radius R , then, if I_M is the mean spherical candle power (M.S.C.P.) of the lamp, the total illumination is expressed by $4\pi R^2 I_M$: this total might be arrived at, however, by summing the products of the candle power in any direction into the area of the zone over which this intensity is spread; and putting this statement into the form of an equation,

$$4\pi R^2 I_M = \Sigma IA$$

where I is the intensity on a zone of surface area A .

To find the M.S.C.P. proceed as follows:—Suppose that the lamp is at O (Fig. 98). With centre O and any convenient radius R describe a semicircle; also let the polar diagram be as shown (the curve OPQMC). The greatest candle power is that given by OC; draw a horizontal through N, the point in which the line OC meets the circumference of the semicircle, and make $ab = OC$. Through a and b draw verticals and through A and B draw horizontals, thus obtaining the rectangle DE; draw a number of rays, OP, OQ, OS, etc., and also horizontals through the points p, q, s , etc., marking along these lines distances equal to OP, OQ, OS, etc., working from DF as base. By joining up the points so obtained the curve $FLbD$ is obtained, known as the Rousseau

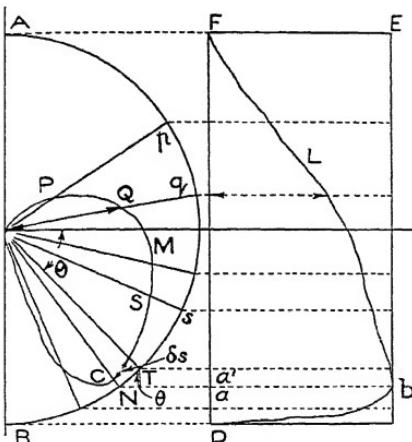


FIG. 98.

curve; then the mean height of this curve (which can readily be obtained by means of a planimeter) gives the M.S.C.P. of the lamp.

Proof of this Construction.—Let I_M = M.S.C.P. of the lamp

$$\text{then } I_M = \frac{\Sigma \text{ area of zone} \times \text{C.P.}}{4\pi R^2}.$$

Consider the zone generated by the revolution of TN ($= \delta s$) about AB; its area is of the form $2\pi y \delta s$ and the intensity of illumination is OC, say. The length y is the projection on the horizontal axis through O of either the line OT, the line ON, or the line midway between these (for these differ in length but slightly if δs is taken as very small), i. e., $y = OT \cos \theta$

or

$$y = R \cos \theta.$$

Hence, for this zone,

$$\begin{aligned} &= \text{candle power} \times \text{area} \\ &= OC \times 2\pi R \cos \theta \delta s \\ &= ab \times 2\pi R \times aa' \left\{ \text{for } \frac{aa'}{\delta s} = \cos \theta \right\}. \end{aligned}$$

Hence the total illumination

$$\begin{aligned} &= 2\pi R \sum ab \times aa' \\ &= 2\pi R \times \text{area under the curve } FLbD \end{aligned}$$

and thus

$$I_M = \frac{\text{Total illumination}}{4\pi R^2} = \frac{2\pi R \times \text{area under the curve } FLbD}{4\pi R^2}$$

$$= \frac{\text{area under the curve } FLbD}{2R}$$

$$= \text{mean height of the curve } FLbD$$

since $2R$ is the base of the curve.

Dr. Fleming's Graphic Method for the Determination of R.M.S. Values.—The determination of R.M.S. values is of some

importance to electrical engineers, and the subject, previously discussed in Chapter VII, is here treated from a different aspect. Instead of squaring the given values of the current and then extracting the square root of the mean of these squares, we may, by a simple graphic construction, obtain the mean of the squares very readily.

Let the values of an alternating current at various times be as in the table:—

time t . . .	0	.001	.002	.003	.004	.005	.006	.007	.008
Current C	5	8	12	7	0	-6	-8.3	-3	5

then, to find the R.M.S. value of C we proceed as follows:—

Treat the given values as polar co-ordinates, taking t for the angles and C for the rays. Select some convenient scale for t , say $20^\circ = .001$ sec., and a scale for C, say $1'' = 4$ units, these being the scales chosen for the original drawing of which Fig. 99 is a copy to

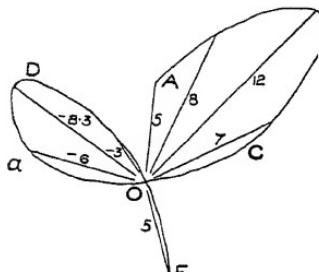


FIG. 99.

about one-half scale; and set out a polar diagram as indicated, making $OA = \frac{1}{2}5$, $O\alpha = -6$, etc. Join the extremities of the rays, so obtaining, with the first and last rays, the closed figure ABCDAE. Measure the area of this figure by means of a planimeter—in this case the area was found to be 4·23 sq. ins.

Now the area of the figure $= \frac{1}{2} \int r^2 d\theta = \frac{1}{2} \int C^2 dt$, or

$$2 \times \text{area} = \int C^2 dt$$

so that if we divide twice the area by the range in t , the mean value of the squares is determined.

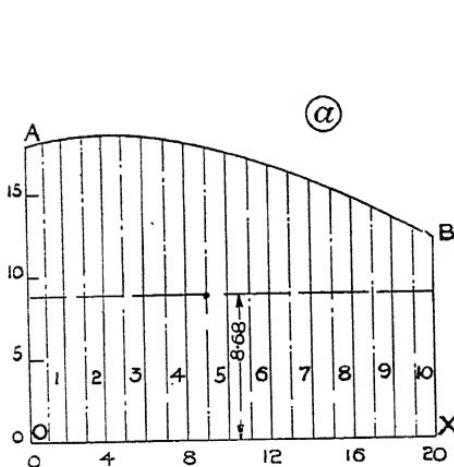
In this case the range of $t = 160^\circ = 2.79$ radians, and also $\int C^2 dt = 2 \times 16 \times 4.23 = 135.5$, for $1'' = 4$ units, and thus 1 sq. in. = 16 sq. units.

$$\text{Then } M.S. = \frac{135.5}{2.79} = 48.65,$$

$$\text{and hence } R.M.S. = \sqrt{48.65} = 6.98.$$

The rule for the area of a figure, viz., $\frac{1}{2} \int r^2 d\theta$, may be usefully employed to find the height of the centroid of an area above a certain base.

Example 5.—Find the height above the base OX of the centroid of the irregular area OABX [(a) Fig. 100].



(a)

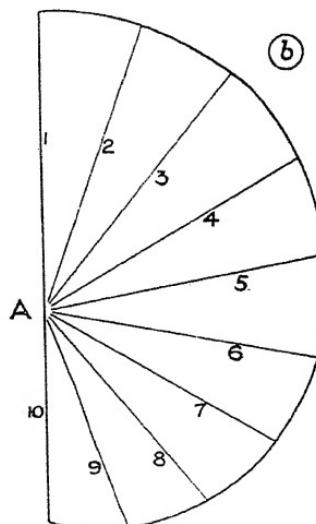


FIG. 100.—Centroid of Irregular Area by Polar Diagram.

To do this, first divide the base into a number of equal divisions, and erect mid-ordinates in the usual way. Measure these mid-ordinates and set off lengths to represent them as radii vectors from A in Fig. 100, the angles at which the rays are drawn representing the values of x , i.e., the lengths of the divisions of the base. Join the ends of these rays and measure the area of the polar diagram thus obtained; divide this area by the area of the original figure and the result is the height \bar{y} required.

For the area of the polar diagram $= \frac{1}{2} \int r^2 d\theta = \frac{1}{2} \int y^2 dx$, since rays represent values of y and the angles represent values of x . Also the area of the original figure $= \int y dx$, so that

$$\frac{\text{area of polar diagram}}{\text{area of original figure}} = \frac{\frac{1}{2} \int y^2 dx}{\int y dx} = \bar{y} \quad (\text{cf. p. 214}).$$

For the particular case illustrated (the scales referring to the original drawing) :—

For (a) Fig. 100 $1'' = 5$ units vertically
 $1'' = 4$ units horizontally

so that 1 sq. in. represents 20 units of area. The area was found by the planimeter to be 16.82 sq. ins., so that the actual area is 336.4 sq. units, i.e., $\int y dx = 336.4$.

For (b) Fig. 100 $1'' = 5$ units radially
and each angular interval $= 20^\circ$, so that the total range $= 180^\circ$ or 3.14 radians. Hence 3.14 radians represent 20 units, the length of the base in (a) Fig. 100,

or $1 \text{ radian} = \frac{20}{3.14} = 6.36 \text{ units.}$

Now the area is of the nature $r^2 \times \theta$, i.e., $(\text{length})^2 \times \text{angle}$, hence 1 sq. in. of area $= 5^2 \times 6.36$ or 159 units. Area of the polar figure (found by the use of the planimeter)

$$= 18.34 \text{ sq. ins.} = 18.34 \times 159 \text{ units} = 2920.$$

Hence $\bar{y} = \frac{2920}{336.4} = 8.68,$

i.e., the centroid horizontal is found.

Theory of the Amsler Planimeter.—The principle upon which the planimeter is based may be explained quite simply, in the following way.

In Fig. 101 let PP'' be a portion of the outline of the figure whose area is to be measured, and let the fixed centre of the instrument be at O. Then in the movement of the tracing point P from P to P'' along the curve, the tracing arm changes from the position AP to $A'P''$. This movement may be regarded as made up of two distinct parts: firstly, a sliding or translational movement from AP to $A'P'$, and next, a rotation round A' as centre,

from $A'P'$ to $A''P''$. In the former of these movements the recording wheel moves from W to W' , but part of this movement only, viz., that perpendicular to the axis of the wheel, is actually recorded, so that the wheel records the distance p .

The area swept out by the tracing arm AP during the small change from P to $P'' = APP'P''A' = APP'A' + P'P''A'$

$$= (AP \times p) + (\frac{1}{2}(AP)^2 \delta\theta).$$

Hence for the whole area,

$$\begin{aligned} \text{area swept out} &= \Sigma AP \times p + \Sigma \frac{1}{2}(AP)^2 \delta\theta \\ &= AP \Sigma p + \frac{1}{2} AP^2 \Sigma \delta\theta. \end{aligned}$$

Now the net angular movement is zero, so that $\Sigma \delta\theta = 0$.

Hence $\text{area swept out} = AP \Sigma p$,

or if $l = \text{length of the tracing arm}$,

$\text{area} = l \times \text{travel of wheel}$

and hence the reading of the wheel

$$= \frac{\text{area of figure}}{l}$$

Thus the length of the tracing arm determines the scale to which the area is measured. Hence by suitable adjustment of this length of arm the area of a figure may be read in sq. ins. or sq. cms. as may be necessary. If the average height of the figure is required, the length of the tracing arm must be made exactly equal to the length of the figure. This is done by using the points LL (Part I, Fig. 301), and not troubling about the adjustment at A. The difference between the first and last readings gives, when multiplied or divided by a constant, the actual mean height of the figure. If the ordinary Amsler is used, then the mean height in inches is obtained by dividing the difference between the readings by 400 ; thus if the first reading was 7243 and the last 7967, the mean height would be the difference, viz., 724, divided by 400, i.e., 1.81 ins.

The area of the figure = average height \times length, but the area of the figure = length of tracing arm \times wheel reading, hence if the length of the tracing arm = the length of the diagram, the wheel reading must be the average height of the diagram.

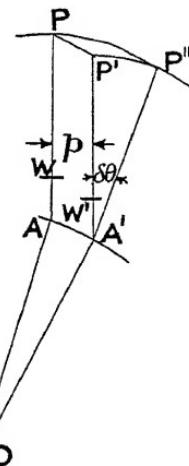


FIG. 101.—Theory of Amsler Planimeter.

[It should be noticed that the area recorded by the instrument is really the difference between the areas swept out by the ends A and P of the arm AP, but as A moves along an arc of circle, coming back finally to its original position, no area is swept out.]

Exercises 21.—On Polar Co-ordinates.

1. Plot a polar curve of crank effort for the following case, the connecting rod being infinitely long.

θ°	0	15	30	45	60	75	90	105	120	135	150	165	180
Crank Effort (lbs.) . . .	0	2.4	3.9	5.1	6.4	7.1	7.3	7	6.1	4.9	3.3	1.5	

2. As for Question 1, but taking the connecting rod = 5 cranks.

60	75	90	105	120	135	150	165	172.5	180			
C.E. (lbs.) . . .	4.4	6.1	7.4	7.4	6.6	5	4.4	3.0	1.5	0.6	0	

3. An A.C. is given by $C = 7.4 \sin 50\pi t$. Draw the polar curve to represent the variation in C and hence find its R.M.S. value.

4. What is the polar equation of a circle, the extremity of a diameter being taken as the centre from which the various rays are to be measured?

Of what curve (to Cartesian ordinates, i.e., rectangular axes) is the circle the polar curve?

5. Plot the polar diagram for the arc lamp, from the table.

Angle (degrees) . . .	0	10	20	30	40	50	60	70	80	90° (vertical)
Candle Power . . .	800	1200	1600	2000	2200	2200	2300	2500	2300	1800

6. Plot the Rousseau diagram for the arc lamp in Question 5 and from it calculate the M.S.C.P. of the lamp.

7. An A.C. has the following values at equal intervals of time: 3, 4, 4.5, 5.5, 8, 10, 6, 0, -3, -4, -4.5, -5.5, -8, -10, -6, 0. Find by Dr. Fleming's method (cf. p. 264) the R.M.S. value of this current.

8. Eiffel's experiments on the position of the centre of pressure for a flat plane moved through air at various inclinations gave the following results:—

Inclination to horizontal	0	15	30	45	60	75	90
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Ratio $\frac{BC}{AB}$ (see Fig. 102).	2.63	2.91	3.33	3.75	4.1	4.15	4.15	4.47	5
---------------------------------------	------	------	------	------	-----	------	------	------	---

Plot a polar diagram to represent the variation of this ratio.

9. Draw the polar curve to represent the illuminating power of a U.S. standard searchlight from the following figures:—

Angle (degrees) (vertical) 10 20 30 40

Candle Power 3000 10000 20500 33000 41500 41500 4200

(above horizontal) 20 30 40

6000 5000 5000 2000 3000 1500 1500 1500

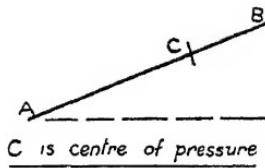


FIG. 102.

CHAPTER IX

SIMPLE DIFFERENTIAL EQUATIONS

Differential Equations.—An equation containing one or more derived functions is called a “differential equation.”

Thus a very simple form of differential equation is

$$\frac{dy}{dx} = 5$$

and $4 \frac{d^2y}{dx^2} + 7 \frac{dy}{dx} - 5 = 0$

and $y' \frac{dy}{dx} + 2x \frac{dy}{dx} - y = 0$

are more complex forms.

Differential equations are classified according to “order” or “degree”; the order being fixed by that of the highest differential coefficient occurring in it. Thus $\frac{dy}{dx}$ is a differential coefficient of the first order, $\frac{d^3y}{dx^3}$ is of the third order, and so on.

Hence $4 \cdot 2 + y \frac{dy}{dx} = 5 \cdot 34$ is an equation of the first order

and $8 \frac{d^4y}{dx^4} + y = 7 \cdot 16$ is an equation of the fourth order.

The “degree” of an equation is fixed by that of the highest derivative occurring when the equation is free from radicals and fractions.

Thus $\frac{d^2y}{dx^2} = c$ is of the second order and of the first degree

whilst $4 \left(\frac{d^2y}{dx^2} \right)^2 + \left(\frac{d^2y}{dx^2} \right) = 7$ is of the second order and of the second degree.

Much has been written concerning the solution of the many types of differential equations, but it is only possible here to treat

the forms that are likely to arise in the derivation of the proofs of engineering formulae; the plan being to discuss the solution according to the types of equation.

Type :— $\frac{dy}{dx}$ given as a function of x .—With the solution of such simple forms we have already become familiar, for the equations connecting the bending moment at various sections of a beam with the distances of those sections from some fixed point are of this character.

Thus taking the case of a simply supported beam carrying a load W at the centre

$$\frac{d^2y}{dx^2} = \frac{W}{EI}$$

$$\text{whence } \frac{dy}{dx} = \frac{Wx}{EI} + C$$

which is of the type under consideration.

Evidently this equation can be solved by integration throughout, attention being paid to the constants which are necessarily introduced. Expressing in algebraical symbols,

$$\text{If } \frac{dy}{dx} = f(x)$$

then by integrating throughout with regard to x

$$\int \frac{dy}{dx} dx = \int f(x) dx + C$$

$$\text{or } y = \int f(x) dx + C.$$

Example 1.—If $\frac{dy}{dx} = 4x^2 + 7x - 2$ and $y = 5$ when $x = 1$, find an expression for y in terms of x .

This equation is of the type with which we are now dealing, since

$$4x^2 + 7x - 2 = f(x)$$

$$\frac{dy}{dx} = 4x^2 + 7x - 2.$$

$$\text{Integrating } y = \frac{4x^3}{3} + \frac{7x^2}{2} - 2x + C.$$

The value of C must now be found: thus $y = 5$ when $x = 1$

$$\text{so that } 5 = \frac{4}{3} + \frac{7}{2} - 2 + C$$

$$\text{or } C = 2.17.$$

$$\text{Hence } y = 1.33x^3 + 3.5x^2 - 2x + 2.17.$$

Type :— $\frac{dy}{dx}$ given as a function of y . i.e., $\frac{dy}{dx} = f(y)$.

This type of equation differs somewhat from the preceding in that a certain amount of transposition of terms has to be effected before the integration can be performed.

The equation may be written $\frac{dy}{f(y)} = dx$

the transposition being spoken of as "separating the variables," and thence by integration $\int \frac{dy}{f(y)} = \int dx + C = x + C$.

Example 2.—If $\frac{dy}{dx} = y^3$, find an expression for y .

Separating the variables $\frac{dy}{y^3} = dx$.

Integrating $\int \frac{dy}{y^3} = \int dx + C$

or $-\frac{1}{2}y^{-2} = x + C$

whence $x + \frac{5}{y^2} + C = 0$.

The two following examples are really particular cases of the type discussed generally on p. 275, but they may also be included here as illustrations of this method of solution.

Example 3.—Solve the equation $\frac{dy}{dx} + ay = b$.

Here $\frac{dy}{dx} = b - ay$

$$\frac{dy}{b - ay} = dx$$

so that $\frac{dy}{b - ay} = \int dx + C$

i.e., $-\frac{1}{a} \log_e(b - ay) = x + C$

or $\log_e(b - ay) = -(ax + aC)$

whence $e^{-ax-aC} = (b - ay)$.

Now let $A = e^{-aC}$; then $e^{-ax-aC} = e^{-ax} \times e^{-aC} = Ae^{-ax}$

and $Ae^{-ax} - b = -ay$

or $y = \frac{b}{a} - \frac{A}{a} e^{-ax}$.

Example 4.—Solve the equation $4\frac{dy}{dx} = 11 + 7y$.

Separating the variables

$$\int \frac{4dy}{11+7y} \quad \int dx + C$$

i.e.,

$$\frac{1}{7} \log_e(11+7y) = x + C$$

or

$$\log_e(11+7y) = 7x + 7C$$

whence

$$e^{7x+7C} = (11+7y)$$

and if A be written in place of e^{7C}

$$11+7y = Ae^{7x}$$

or

$$y = \frac{A}{7} e^{7x} - \frac{11}{7}$$

Example 5.—The difference in the tensions at the ends of a belt subtending an angle of $d\theta$ at the centre of a pulley $= dT = T\mu d\theta$, where μ is the coefficient of friction between the belt and pulley. If the greatest and least tensions on the belt are T and t respectively, whilst the lap is θ , find an expression for the ratio $\frac{T}{t}$.

The equation $dT = T\mu d\theta$ is of the type dealt with in this section; to solve it we must separate the variables, thus:—

$$\frac{dT}{T} = \mu d\theta.$$

Integrate both sides of the equation, applying the limits t and T to T and 0 and θ for the angle.

Then

$$\int_t^T \frac{dT}{T} = \mu \int_0^\theta d\theta.$$

$$\left(\log_e T\right)_t^T = \mu \left(\theta\right)_0^\theta,$$

$$\log_e T - \log_e t = \mu\theta.$$

But

$$\log_e \frac{T}{t} = \log_e T - \log_e t.$$

Hence

$$\log_e \frac{T}{t} = \mu\theta$$

or

$$\frac{T}{t} = e^{\mu\theta}.$$

A word further might be added about *Example 3*, or a modification of it.

Let

$$\frac{dy}{dx} = ay,$$

If $a = 1$, then $\frac{dy}{dx} = y$, i. e., the rate of change of y with regard to x , for any value of x , is equal to the value of y for that particular value of x . Now we have seen (Part I, p. 353) that this is the case only when $y = ex$.

If a has some value other than 1, y must still be some power of e , for the rate of change of y is proportional to y ; actually, if $y = e^{ax}$, $\frac{dy}{dx} = ae^{ax} = ay$, so that $y = e^{ax}$ would be one solution of the equation $\frac{dy}{dx} = ay$; but to make more general we should write the solution in the form $y = e^{ax} + C$ or $y = Ae^{ax}$, whichever form is the more convenient. Whenever, therefore, one meets with a differential equation expressing the Compound Interest law (*i.e.*, when the rate of change is proportional to the variable quantity) one can write down the solution according to the method here indicated.

Example 6.—Find the equation to the curve whose sub-normal is constant and equal to $2a$.

The sub-normal = $y \frac{dy}{dx}$. (See p. 43.)

Thus $y \frac{dy}{dx} = 2a$.

or, separating the variables, $\int y dy = \int 2adx$.

Hence $\frac{y^2}{2} = 2ax + C$ (Integrating)

$$\text{or } y^2 = 4ax + K.$$

This is the equation of a parabola; if $y = 0$ when $x = 0$, then $K = 0$ and $y^2 = 4ax$, i. e., the vertex is at the origin.

Example 7.—Find an expression giving the relation between the height above the ground and the atmospheric pressure; assuming that the average temperature decrease is about $3\cdot5^{\circ}\text{F}.$ per 1000 feet rise, and the ground temperature is $50^{\circ}\text{F}.$

Let τ be the absolute temperature at a height h ,
then, from hypothesis

$$= 510 - 0035h \quad . \quad (1)$$

pressure, viz., δp , is due to a layer of air δh feet high and 1 sq. ft. in section, and thus

$$\delta p = -\frac{\delta h}{v} \quad (3)$$

From equations (1) and (2)

$$pv = C(510 - .0035h)$$

and substituting for v its value from equation (3)

$$-\frac{p\delta h}{\delta p} = C(510 - .0035h)$$

or, in the limit

$$-\frac{dp}{pdh} = \frac{1}{C(510 - .0035h)}$$

Separating the variables

$$-\frac{dp}{p} = \frac{dh}{C(510 - .0035h)}$$

Integrating, the limits to p being p_0 and p , and those to h being 0 and h ,

$$(-\log p)_{p_0}^p = \frac{1}{C} \times \frac{1}{-.0035} [\log (510 - .0035h) - \log 510]$$

whence $\log p - \log p_0 = \frac{286}{C} [\log (510 - .0035h) - 6.234]$

or $\underline{\log p = \log p_0 + \frac{286}{C} [\log (510 - .0035h) - 6.234]}$

which may be further simplified by substituting the values for p_0 and C .

General Linear Equations of the First Order, i.e.,
equations of the type

$$\frac{dy}{dx} + ay = b$$

where a and b may be either constants or functions of x .

The solution of this equation may be written as

$$y = e^{-\int adx} \{ \int b e^{\int adx} dx + C \}.$$

The proof of this rule depends upon the rule used for differentiating a product, viz., $\frac{d(uv)}{dx} = v \frac{du}{dx} + u \frac{dv}{dx}$; the reasoning being as follows:—

Let us first consider the simplest case in which this type of equation occurs, viz., the case of the solution of the equation

$$\frac{dy}{dx} + ay = 0$$

where a is a constant.

Multiplying through by e^{ax} the equation becomes

$$e^{ax} \frac{dy}{dx} + ay e^{ax} = 0,$$

which can be written as $v \frac{dy}{dx} + y \frac{dv}{dx} = 0$ (where $v = e^{ax}$ and thus $\frac{dv}{dx} = ae^{ax}$).

But $v \frac{dy}{dx} + y \frac{dv}{dx} = \frac{d}{dx}(yv)$, so that $\frac{d}{dx}(yv) = 0$; hence yv must be a constant, since the result of its differentiation is to be zero.

Accordingly $yv = C$,

$$\text{or } y = Cv^{-1} = Ce^{-ax}.$$

Extending to the case in which b is not zero, whilst a remains a constant, i. e., the equation is

$$\frac{dy}{dx} + ay = b,$$

we find that after multiplying through by e^{ax} the result arrived at is

$$\frac{d}{dx}ye^{ax} = be^{ax}.$$

Integrating both sides with regard to x ,

$$ye^{ax} = \int be^{ax} dx + C$$

$$\text{or } y = e^{-ax} \left\{ \int be^{ax} dx + C \right\}.$$

This may be evaluated if the product of b and e^{ax} can be integrated.

For the general case, that in which a and b are functions of x , the multiplier or *integrating factor* is $e^{\int adx}$, for after multiplication by this the equation reads

$$e^{\int adx} \frac{dy}{dx} + ae^{\int adx} y = be^{\int adx}$$

and this may be written

$$\frac{d}{dx}(ye^{\int adx}) = be^{\int adx},$$

whence by integration we find that

$$ye^{\int adx} = \int be^{\int adx} dx + C,$$

$$\text{or } y = e^{-\int adx} \left\{ \int be^{\int adx} dx + C \right\}.$$

Example 8.—Solve the equation $7\frac{dy}{dx} + 12y = e^{5x}$.

The equation may be written

$$\frac{dy}{dx} + \frac{12}{7}y = \frac{1}{7}e^{5x}$$

so that in comparison with the standard form

$$a = \frac{12}{7} \text{ and } b = \frac{1}{7}e^{5x}.$$

$$\begin{aligned}\text{Hence } y &= e^{-\int \frac{12}{7} dx} \left\{ \int \frac{1}{7} e^{5x} \cdot e^{\int \frac{12}{7} dx} dx + C \right\} \\ &= e^{-\frac{12}{7}x} \left\{ \int \frac{1}{7} e^{5x} \cdot e^{\frac{12}{7}x} dx + C \right\} \\ &= e^{-\frac{12}{7}x} \left\{ \frac{1}{7} \times \frac{7}{47} e^{\frac{37}{7}x} + C \right\} \\ &= \frac{1}{47} e^{5x} + Ce^{-\frac{12}{7}x}.\end{aligned}$$

Example 9.—If $\frac{dy}{dx} - y = 2x + 1$, find an expression for y .

$$\frac{dy}{dx} - y = (2x + 1) \text{ so that } a = -1, b = 2x + 1.$$

$$\begin{aligned}\text{Hence } y &= e^{\int dx} \left\{ \int (2x + 1) e^{-\int dx} dx + C \right\} \\ &= e^x \left\{ \int (2x + 1) e^{-x} dx + C \right\}^* \\ &= e^x \left\{ -2xe^{-x} - 3e^{-x} + C \right\} \\ &= -2x - 3 + Ce^x.\end{aligned}$$

* The value of the integral $\int (2x + 1) e^{-x} dx$ is found by integrating by parts.

Thus, let $(2x + 1)e^{-x} = uv$ where $dv = e^{-x}$, i.e., $v = -e^{-x}$ and $u = 2x + 1$, i.e., $\frac{du}{dx} = 2$,

$$\begin{aligned}\text{then } \int uv du &= uv - \int v du \\ &= [(2x + 1) \times (-e^{-x})] - \int -e^{-x} 2 dx \\ &= -e^{-x}(2x + 1) - 2e^{-x} \\ &= -2xe^{-x} - 3e^{-x}.\end{aligned}$$

Example 10.—Solve for T the equation $\frac{dT}{dx} + PT = P(t - cx)$ (referring to the transmission of heat through cylindrical tubes), P , t and c being constants.

The equation $\frac{dT}{dx} + PT = P(t-cx)$ is of the type $\frac{dy}{dx} + ay = b$, where $a = P$ and $b = P(t-cx)$.

Hence the solution may be written

$$T = e^{-\int P dx} \left\{ \int P(t-cx) e^{\int P dx} dx + K \right\},$$

the integrating factor being $e^{\int P dx}$, i.e., e^{Px} .

$$\text{Hence } T = e^{-Px} \left\{ \int P(t-cx) e^{Px} dx + K \right\};$$

and to express this in a simple form the integral $\int P(t-cx) e^{Px} dx$ must first be evaluated.

Let $\int P(t-cx) e^{Px} dx = fudv$ where $u = P(t-cx)$ and $dv = e^{Px} dx$ so that $v = \frac{1}{P} e^{Px}$; and also $du = -Pc dx$,

$$\text{then } \int P(t-cx) e^{Px} dx = fudv = uv - \int v du$$

$$= \left(P(t-cx) \times \frac{1}{P} e^{Px} \right) + \int \frac{1}{P} \times e^{Px} \cdot P c dx$$

$$= (t-cx) e^{Px} + \left(\frac{1}{P} \times ce^{Px} \right) + M.$$

$$\therefore T = e^{-Px} \left\{ (t-cx) e^{Px} + \frac{ce^{Px}}{P} + M + K \right\}$$

$$= (t-cx) + \frac{c}{P} + L e^{-Px}$$

since $e^{-Px} \times e^{Px} = e^0 = 1$ and $L = M + K$.

Example 11.—When finding the currents x and y in the two coils of a wattmeter we arrive at the following differential equation :

$$\frac{dy}{dt} + \frac{R_1 + R_2}{L_1 + L_2} y = \frac{L_1 \phi I}{L_1 + L_2} \cos pt + \frac{R_1 I}{L_1 + L_2} \sin pt$$

where R_1 and L_1 are respectively the resistance and inductance of the one coil and R_2 and L_2 are the resistance and inductance of the other coil; I being the amplitude of the main current.

Solve this equation for y .

Comparing with the standard form of equation, viz., $\frac{dy}{dx} + ay = b$, we see that $a = \frac{R_1 + R_2}{L_1 + L_2}$ and $b = \frac{L_1 \phi I}{L_1 + L_2} \cos pt + \frac{R_1 I}{L_1 + L_2} \sin pt$.

Hence

$$y = e^{-\int \frac{R_1 + R_2}{L_1 + L_2} dt} \left\{ \int \left(\frac{L_1 \phi I}{L_1 + L_2} \cos pt + \frac{R_1 I}{L_1 + L_2} \sin pt \right) e^{\int \frac{R_1 + R_2}{L_1 + L_2} dt} dt + C \right\}$$

$$= e^{-\frac{(R_1 + R_2)t}{L_1 + L_2}} \left\{ \int \frac{L_1 \phi I}{L_1 + L_2} \cos pt \cdot e^{\frac{(R_1 + R_2)t}{L_1 + L_2}} dt + \int \frac{R_1 I}{L_1 + L_2} \sin pt \cdot e^{\frac{(R_1 + R_2)t}{L_1 + L_2}} dt + C \right\}$$

$$= e^{-At} \left\{ \int B \cos pt \cdot e^{At} dt + \int D \sin pt \cdot e^{At} dt + C \right\}.$$

Now, as proved on p. 157,

$$\int Be^{At} \cos pt dt = \frac{Be^{At}}{A^2 + p^2} (p \sin pt + A \cos pt) + C_1$$

and $\int De^{At} \sin pt dt = \frac{De^{At}}{A^2 + p^2} (A \sin pt - p \cos pt) + C_2$

Hence

$$y = \frac{e^{-At} \times e^{At}}{A^2 + p^2} \left\{ pB \sin pt + AB \cos pt + DA \sin pt - Dp \cos pt + K_1 \right\}$$

$$+ \frac{e^{-At} \times e^{At}}{A^2 + p^2} \left\{ Bp \sin pt + AB \cos pt + DA \sin pt - Dp \cos pt + K_2 \right\}$$

$$\text{where } A = \frac{R_1 + R_2}{L_1 + L_2}, \quad B = \frac{L_1 p I}{L_1 + L_2}, \quad \text{and} \quad D = \frac{R_1 I}{L_1 + L_2}.$$

Exact Differential Equations.—An exact differential equation is one that is formed by equating an *exact differential* to zero; thus $Pdx + Qdy = 0$ is the type, $Pdx + Qdy$ being an *exact differential*.

The term *exact differential* must first be explained.

$Pdx + Qdy$ is said to be an exact differential if $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$, the derivatives being partial, or, to use the more familiar notation

$$\text{if } \left(\frac{dP}{dy} \right) = \left(\frac{dQ}{dx} \right).$$

To solve such an equation proceed as follows: If the equation is exact, integrate Pdx as though y were constant, integrate the terms in Qdy that do not contain x , and put the sum of the results equal to a constant.

[For, let $Pdx + Qdy = du$.

Now, du is the total differential, $(\frac{du}{dx})dx$ and $(\frac{du}{dy})dy$ being the partial differentials (see p. 82);

$$\text{i. e., } du = \left(\frac{du}{dx} \right) dx + \left(\frac{du}{dy} \right) dy.$$

$$\text{Then if } du = 0, \left(\frac{du}{dx} \right) dx + \left(\frac{du}{dy} \right) dy = 0,$$

and this is exactly the same as the original equation

$$\text{if } \left(\frac{du}{dx} \right) = P \text{ and } \left(\frac{du}{dy} \right) = Q,$$

$$\therefore \left(\frac{dP}{dy} \right) = \left(\frac{d}{dy} \right) \left(\frac{du}{dx} \right) = \left(\frac{d^2 u}{dy \cdot dx} \right),$$

$$\left(\frac{d^2 u}{dx \cdot dy} \right) = \left(\frac{d}{dx} \right) \left(\frac{du}{dy} \right) = \left(\frac{dQ}{dx} \right).$$

Our equation thus reduces to $du = 0$, or, by integrating, to $u = C$, but $u = \int P dx$ (y being constant) + $\int Q dy$ (x being constant), and hence we have the rule as given.]

Example 12.—Solve the equation

$$(x^2 - 4xy - 2y^2) dx + (y^2 - 4xy - 2x^2) dy = 0.$$

Here $P = x^2 - 4xy - 2y^2$ $\left(\frac{dP}{dy}\right) = -4x - 4y$

$$Q = y^2 - 4xy - 2x^2$$
 $\left(\frac{dQ}{dx}\right) = -4x - 4y$

and thus the equation is exact.

$$\begin{aligned} & \int P dx \text{ (as though } y \text{ were a constant)} \\ &= \int (x^2 - 4xy - 2y^2) dx = \frac{x^3}{3} - \frac{4x^2y}{2} - 2y^2x. \end{aligned}$$

$$\begin{aligned} & \int Q dy \text{ (as though } x \text{ were a constant)} \\ &= \int (y^2 - 4xy - 2x^2) dy = \frac{y^3}{3} - \frac{4xy^2}{2} - 2x^2y; \end{aligned}$$

but of this only $\frac{1}{3}y^3$ must be taken, since the other terms have been obtained by the integration of terms containing x .

Hence $\frac{1}{3}x^3 - 2x^2y - 2xy^2 + \frac{1}{3}y^3 = C$

or $\underline{x^3 - 6x^2y - 6xy^2 + y^3 = K.}$

Example 13.—Solve the equation $v du - u dv = 0$.

If this equation is multiplied through by $\frac{1}{v^2}$ we have a form on the left-hand side with which we are familiar, viz.,

$$v du - u dv = 0,$$

for the left-hand side is $d\left(\frac{u}{v}\right)$.

Then by integrating, $\frac{u}{v} = C$

or $u = Cv.$

[This equation might have been regarded as one made exact through multiplication by the *integrating factor* $\frac{1}{v^2}$.]

Equations Homogeneous (i.e., of the same power throughout) in x and y .

Rule.—Make the substitution $y = vx$ and separate the variables.

Example 14.—Solve the equation $(x^2+y^2) dx = 2xy dy$.

Let

$$y = vx,$$

then

$$\frac{dy}{dx} = v \frac{dx}{dx} + x \frac{dv}{dx} = v + x \frac{dv}{dx}. \quad (1)$$

Now

$$(x^2+y^2) dx = 2xy dy$$

so that

$$\frac{dy}{dx} = \frac{x^2+y^2}{2xy} = \frac{x^2+x^2v^2}{2x^2v} = \frac{1+v^2}{2v}.$$

Substituting for $\frac{dy}{dx}$ from (1)

$$v + x \frac{dv}{dx} = \frac{1+v^2}{2v}$$

$$\text{or } x \frac{dv}{dx} = \frac{1+v^2-2v^2}{2v} = \frac{1-v^2}{2v}.$$

Separating the variables, and integrating,

$$\int \frac{2v}{1-v^2} dv = \int \frac{dx}{x}$$

$$\text{i.e., } -\log(1-v^2) = \log x + \log C \quad \left\{ \begin{array}{l} \text{the substitution being} \\ u = 1-v^2 \\ du = -2v \, dv \end{array} \right.$$

$$\text{or } \log x(1-v^2) = -\log C = \log K \quad \text{and } du = -2v \, dv$$

$$\text{i.e., } x(1-v^2) = K$$

$$\text{or } x\left(1-\frac{y^2}{x^2}\right) = K$$

$$\text{and } \underline{x^2-y^2=Kx}.$$

Linear Equations of the Second Order.

Type :—

$$\frac{d^2y}{dx^2} + a \frac{dy}{dx} + by = 0.$$

Let $y = e^{\lambda x}$, then $\frac{dy}{dx} = \lambda e^{\lambda x}$ and $\frac{d^2y}{dx^2} = \lambda^2 e^{\lambda x}$

$$\text{so that } \lambda^2 e^{\lambda x} + a\lambda e^{\lambda x} + b e^{\lambda x} = 0$$

$$\text{or } \lambda^2 + a\lambda + b = 0 \quad \text{for } y = 0 \text{ would be a special case.}$$

There are three possible solutions to this quadratic.

The general solution is:

$$\lambda = \frac{-a \pm \sqrt{a^2 - 4b}}{2}$$

and let

$$\lambda_1 = \frac{-a + \sqrt{a^2 - 4b}}{2}$$

$$\lambda_2 = \frac{-a - \sqrt{a^2 - 4b}}{2}$$

We shall now discuss the three cases.

Case (1).—If $a^2 > b$, then λ_1 and λ_2 are real quantities and unequal.

Now if $y = A_1 e^{\lambda_1 x}$, $\frac{d^2y}{dx^2} + a \frac{dy}{dx} + by$ will equal 0, as would be the case also if $y = A_2 e^{\lambda_2 x}$, so that to complete the solution the two must be included (for the equation is true if either or both are included).

Thus

$$y = A_1 e^{\lambda_1 x} + A_2 e^{\lambda_2 x}$$

the constants A_1 and A_2 being fixed by the conditions.

Case (2).—If $a^2 = 4b$, then $\lambda_1 = \lambda_2$.

According to the preceding case we might suppose that the solution was

$$y = Ae^{\lambda x}.$$

This, however, is not the complete solution,

which is

$$y = (A + Bx)e^{\lambda x}.$$

Case (3).—If $a^2 < 4b$. This means that $\sqrt{a^2 - 4b}$ is the square root of a negative quantity, i. e., it is an *imaginary*.

Now, $a^2 - 4b = -1(4b - a^2)$, $(4b - a^2)$ being positive;

$$\begin{aligned} \text{hence } \sqrt{a^2 - 4b} &= \sqrt{-1} \sqrt{4b - a^2} \\ &= j\sqrt{4b - a^2} \end{aligned}$$

$$\text{and } \lambda_1 = \frac{-a + j\sqrt{4b - a^2}}{2}$$

$$\lambda_2 = \frac{-a - j\sqrt{4b - a^2}}{2}$$

Use might be made of the solution to *Case (1)*, adopting these values of λ_1 and λ_2 , but this does not give the most convenient form in which to write the solution.

$$\left. \begin{aligned} \text{Let } c &= \sqrt{4b - a^2} & \text{then } \lambda_1 &= \frac{-a + jc}{2} \\ \text{and } & & \lambda_2 &= \frac{-a - jc}{2} \end{aligned} \right\}$$

Then $y = A_1 e^{\lambda_1 x} + A_2 e^{\lambda_2 x}$ from Case (i)
 $= A_1 e^{\frac{(-a+jc)x}{2}} + A_2 e^{\frac{(-a-jc)x}{2}}$

Developing one of these only, viz., the first, and neglecting A_1 for the time being,

$$e^{\frac{-ax+jcx}{2}} = e^{-\frac{ax}{2}} \times e^{\frac{jcx}{2}}.$$

Now $e^{jcx} = \cos x + j \sin x$ (see p. 110),

and by writing $\frac{cx}{2}$ for x

$$e^{\frac{jcx}{2}} = \cos \frac{cx}{2} + j \sin \frac{cx}{2}$$

Hence

$$\begin{aligned} y &= A_1 e^{-\frac{ax}{2}} \left(\cos \frac{cx}{2} + j \sin \frac{cx}{2} \right) + A_2 e^{-\frac{ax}{2}} \left(\cos \frac{cx}{2} - j \sin \frac{cx}{2} \right) \\ &= e^{-\frac{ax}{2}} \left[(A_1 + A_2) \cos \frac{cx}{2} + j(A_1 - A_2) \sin \frac{cx}{2} \right] \\ &= e^{-\frac{ax}{2}} A \sin \left(\frac{cx}{2} + \phi \right) \\ &= Ae^{-\frac{ax}{2}} \sin \left(\frac{cx}{2} + \phi \right) \end{aligned}$$

where

$$A = \sqrt{(A_1 + A_2)^2 + j^2(A_1 - A_2)^2} = 2\sqrt{A_1 A_2} \quad (\text{see Part I, p. 277})$$

and

$$\tan \phi = \frac{A_1 + A_2}{j(A_1 - A_2)}.$$

Taking as the standard equation

$$\frac{d^2y}{dx^2} + a \frac{dy}{dx} + by = 0$$

and grouping our results, we have the following :—

(1) If $a^2 > 4b$: the solution is

$$y = A_1 e^{\frac{-a+\sqrt{a^2-4b}}{2}x} + A_2 e^{\frac{-a-\sqrt{a^2-4b}}{2}x}.$$

(2) If $a^2 = 4b$: the solution is

$$y = (A + Bx)e^{-\frac{ax}{2}}.$$

(3) If $a^2 < 4b$: the solution is

$$y = Ae^{-\frac{ax}{2}} \sin \left(\frac{\sqrt{4b-a^2}}{2}x + \phi \right).$$

The last of these forms occurs so frequently that very careful consideration should be given to it, and to the equation of which it gives the solution.

Example 15.—Solve the equation

$$5\frac{d^2y}{dx^2} + 12\frac{dy}{dx} - 2y = 0.$$

This can be written (after dividing through by 5)

$$\frac{d^2y}{dx^2} + 2 \cdot 4 \frac{dy}{dx} - 4y = 0,$$

so that $a = 2 \cdot 4$ and $b = -4$ (in comparison with the standard form).

$$\begin{aligned} y &= A_1 e^{-2 \cdot 4 x} + A_2 e^{+2 \cdot 4 x}, \\ &= \underline{\underline{A_1 e^{16x} + A_2 e^{-2 \cdot 56x}}}. \end{aligned}$$

It is really easier to work a question of this kind from first principles rather than to try to remember the rule in the form given; thus the values of λ will be the roots of the equation

$$5\lambda^2 + 12\lambda - 2 = 0.$$

Then, calling these roots λ_1 and λ_2 respectively

$$y = A_1 e^{\lambda_1 x} + A_2 e^{\lambda_2 x}.$$

If the values of A_1 and A_2 were required, two values of y with the corresponding values of x would be necessary.

Example 16.—A body is moving away from a fixed point in such a way that its acceleration is directed towards that point, and is given in magnitude by 64 times the distance of the body from that point. Find the equation of the motion and state of what kind the motion is.

The motion is Simple Harmonic. (See p. 60.)

If s = displacement at time t from the start

$$\frac{d^2s}{dt^2} = \text{acceleration and } = -64s$$

(the reason for the minus sign being obvious).

Thus $\frac{d^2s}{dt^2} + 64s = 0$, which is of the type $\frac{d^2y}{dx^2} + a \frac{dy}{dx} + b = 0$, where $a = 0$ and $b = 64$.

If $s = e^{\lambda t}$

$$\lambda^2 + 64 = 0$$

$$\text{so that } * \quad \lambda = \pm \sqrt{-64} = \pm 8j.$$

Hence the solution (according to Case (3)) is

$$y = Ae^{-\frac{x}{2}} \sin\left(\frac{cx}{2} + p\right)$$

where $a = 0$ and $c = \sqrt{b - a^2} = 16$

so that $s = A \sin(8t + p)$.

The general equation of S.H.M. is

$$s = A \sin(\omega t + p)$$

ω being the angular velocity, so that the angular velocity in this case is 8 and the amplitude is A.

Example 17.—Solve the equation

$$\frac{d^2y}{dx^2} + 8 \frac{dy}{dx} + 16y = 0.$$

Let

$$y = e^{\lambda x}$$

then

$$\lambda^2 + 8\lambda + 16 = 0$$

i. e.,

$$(\lambda + 4)^2 = 0$$

i. e., the roots are equal.

Hence

$$y = (A + Bx)e^{\lambda x}, \quad (\text{Cf. Case (2), p. 282})$$

where

$$\lambda = -4.$$

hence

$$\underline{y = (A + Bx)e^{-4x}.}$$

Example 18.—Solve the equation

$$\frac{d^2y}{dx^2} + 7 \frac{dy}{dx} + 10y = 5$$

This differs from the preceding examples in the substitution of a constant in place of 0.

The equation can be written

$$\frac{d^2y}{dx^2} + 7 \frac{dy}{dx} + 10(y - .5) = 0.$$

Let

$$(y - .5) = e^{\lambda x}$$

then

$$\frac{dy}{dx} = \lambda e^{\lambda x} \quad \text{and} \quad \frac{d^2y}{dx^2} = \lambda^2 e^{\lambda x}$$

and

$$\lambda^2 + 7\lambda + 10 = 0$$

whence

$$\lambda = -5 \text{ or } -2$$

then

$$y - .5 = A_1 e^{-5x} + A_2 e^{-2x}$$

or

$$y = A_1 e^{-5x} + A_2 e^{-2x} + .5.$$

In other words, the solution is that of $\frac{d^2y}{dx^2} + 7 \frac{dy}{dx} + 10y = 0$ plus $\frac{5}{10}$, i. e., the constant coefficient of y . This is correct because, if $y = .5$, $\frac{dy}{dx}$ and $\frac{d^2y}{dx^2}$ each equals 0, and thus one solution is $y = .5$. The complete solution is the sum of the two solutions.

The Operator D.—The differential coefficient of y with respect to x may be expressed in a variety of forms: thus either $\frac{dy}{dx}$, $\frac{df(x)}{dx}$, $f'(x)$ or Dy might be used to denote the process of differentiation. The last of these forms, which must only be used when there is no ambiguity about the independent variable, proves to be of great advantage when concerned with the solution of certain types of differential equations. It is found that the symbol D has many important algebraic properties, which lend themselves to the employment of D as an "operator."

The first derivative of y with regard to $x = Dy$, and the second derivative of y with regard to $x = \frac{d^2y}{dx^2}$, which is written as D^2y ; D^2 indicating that the operation represented by D must be performed twice. This is in accordance with the ordinary rules of indices, so the fact suggests itself that the operator D may be dealt with according to algebraic rules. Thus D^3 must equal $D.D.D$ (this implying not multiplication, but the performance of the operation three times); for

$$D^3y = \frac{d^3y}{dx^3} = \frac{d}{dx} \left(\frac{d^2y}{dx^2} \right) = \frac{d}{dx} \cdot \frac{d}{dx} \cdot \frac{dy}{dx} = D.D.Dy.$$

Our rule then holds, at any rate, so long as the index is positive, or the operation is direct; and for complete establishment we must test for the case when the index is negative.

$$\text{If } Dy = \frac{dy}{dx} \quad D = \frac{d}{dx} : \text{let } \frac{dy}{dx} = m, \quad i.e., Dy = m.$$

$$\text{Then by integration } y = \int m dx,$$

but if $Dy = m$ and the rules of algebra can be applied to D

$$y \text{ must } = \frac{m}{D} \text{ or } \frac{1}{D} \cdot m.$$

$$\text{Hence } \frac{1}{D}m = \int m dx$$

• or $\frac{1}{D}$ indicates the operation of integration.

Again, if the rules of indices are to hold,

$$D.D^{-1}y \text{ must } = D^0y \text{ or } y,$$

hence D^{-1} must represent the process of integration; since if we

differentiate a function we must integrate the result to arrive at the original function once again.

Hence

$$D^{-1} = \frac{1}{D}.$$

Having satisfied ourselves that the ordinary rules of indices may be applied to D, we may now prove that the rules of factorisation apply also.

Taking the expression $D^2 - 12D + 32$, we can easily show that it can be written in the factor form $(D-4)(D-8)$:

for let $y = 7x^2 - 5x$, then $Dy = 14x - 5$ and $D^2y = 14$.

$$\begin{aligned} \text{Also } (D^2 - 12D + 32)y &= D^2y - 12Dy + 32y \\ &= 14 - 168x + 60 + 224x^2 - 160x \\ &= 224x^2 - 328x + 74 \end{aligned}$$

and

$$\begin{aligned} (D-4)(D-8)y &= (D-4)(Dy - 8y) \\ &= (D-4)(14x - 5 - 56x^2 + 40x) \\ &= D(14x - 5 - 56x^2 + 40x) - 4(14x - 5 - 56x^2 + 40x) \\ &= 14 - 112x + 40 - 56x + 20 + 224x^2 - 160x \\ &= 224x^2 - 328x + 74 \end{aligned}$$

so that

$$(D^2 - 12D + 32) = (D-4)(D-8).$$

These properties make D of great usefulness in the solution of certain types of differential equations : e.g.,

$$\text{Suppose } 5\frac{d^2y}{dx^2} + 7\frac{dy}{dx} + 10y = M \quad \dots \dots \dots \quad (1)$$

then this equation may be re-written as

$$5D^2y + 7Dy + 10y = M$$

$$\text{or } y(5D^2 + 7D + 10) = M$$

$$\text{so that } y = \frac{M}{5D^2 + 7D + 10}$$

and the solution of equation (1) may be found by this artifice. Many differential equations occurring in electrical theory may be solved in a very simple manner by the treatment of D as a "quasi-algebraic" quantity: before proceeding to these, however, we must enunciate the following theorems.

Useful Theorems, involving the Operator D :—(1) $(p+qD)$ operating on the function $a \sin(bt+c)$ gives the result $a\sqrt{p^2+b^2q^2} \sin\left(bt+c+\tan^{-1}\frac{qb}{p}\right)$

$$(2) \quad \frac{1}{p+qD} a \sin(bt+c) = \frac{a}{\sqrt{p^2+b^2q^2}} \sin\left(bt+c-\tan^{-1}\frac{qb}{p}\right).$$

Proof of (1).

$$(p+qD)a \sin(bt+c)$$

$$= ap \sin(bt+c) + aqb \cos(bt+c)$$

$$= a\sqrt{p^2+q^2b^2} \sin\left(bt+c+\tan^{-1}\frac{qb}{p}\right) \quad (\text{See Part I, p. 277.})$$

Proof of (2).

$$\begin{aligned} \frac{1}{p+qD} a \sin(bt+c) &= \frac{a(p-qD)}{p^2-q^2D^2} \sin(bt+c) \\ &= a \left\{ \frac{p \sin(bt+c) - bq \cos(bt+c)}{p^2+q^2b^2} \right\}^* \\ &= \frac{a\sqrt{p^2+q^2b^2}}{p^2+q^2b^2} \sin\left(bt+c-\tan^{-1}\frac{qb}{p}\right) \\ &= \frac{a \sin\left(bt+c-\tan^{-1}\frac{qb}{p}\right)}{\sqrt{p^2+q^2b^2}} \end{aligned}$$

As a test of the correctness of the above rules the combination of the two operations should give the original function.

$$\text{Thus } \frac{p+qD}{p+qD} a \sin(bt+c)$$

$$= \frac{a\sqrt{p^2+q^2b^2}}{\sqrt{p^2+q^2b^2}} \sin\left(bt+c+\tan^{-1}\frac{qb}{p}-\tan^{-1}\frac{qb}{p}\right)$$

$$= a \sin(bt+c).$$

A third theorem might thus be added.

$$\begin{aligned} &\frac{p_1+q_1D}{p_2+q_2D} a \sin(bt+c) \\ &= \frac{a\sqrt{p_1^2+q_1^2b^2}}{\sqrt{p_2^2+q_2^2b^2}} \sin\left(bt+c+\tan^{-1}\frac{q_1b}{p_1}-\tan^{-1}\frac{q_2b}{p_2}\right). \end{aligned}$$

$$* \quad D \sin(bt+c) = b \cos(bt+c)$$

$$D^2 \sin(bt+c) = -b^2 \sin(bt+c)$$

$$\text{or } D^2 = -b^2$$

$$\text{hence } p^2-q^2D^2 = p^2+q^2b^2.$$

Application of these Rules to the Solution of Differential Equations.

Example 19.—Solve the equation $\frac{d^2y}{dx^2} + 7\frac{dy}{dx} + 12y = e^{5x}$.

This equation might be written

$$(D^2 + 7D + 12)y = e^{5x}$$

so that

$$y = \frac{e^{5x}}{D^2 + 7D + 12}.$$

The solution of this equation gives the particular integral, whilst the *complementary function*, as it is termed, will be obtained by the solution of the equation

$$\frac{d^2y}{dx^2} + 7\frac{dy}{dx} + 12y = 0.$$

[The solution of this equation we know from the previous work to be

$$y = A_1 e^{-3x} + A_2 e^{-4x}$$

Now $D e^{5x} = 5e^{5x}$, $D^2 e^{5x} = 25e^{5x}$, i.e., $D = 5$ and $D^2 = 25$.

Hence the particular integral is

$$y = \frac{e^{5x}}{25 + 35 + 12}$$

and the general solution is

$$y = A_1 e^{-3x} + A_2 e^{-4x} + \frac{e^{5x}}{72}$$

To test this by differentiation of the result:—

$$y = A_1 e^{-3x} + A_2 e^{-4x} + \frac{e^{5x}}{72}$$

$$\frac{dy}{dx} = -3A_1 e^{-3x} - 4A_2 e^{-4x} + \frac{5}{72} e^{5x}$$

$$\frac{d^2y}{dx^2} = 9A_1 e^{-3x} + 16A_2 e^{-4x} + \frac{25}{72} e^{5x}$$

$$\therefore \frac{d^2y}{dx^2} + 7\frac{dy}{dx} + 12y = 9A_1 e^{-3x} + 16A_2 e^{-4x} + \frac{25}{72} e^{5x}$$

$$-21A_1 e^{-3x} - 28A_2 e^{-4x} + \frac{35}{72} e^{5x}$$

$$+ 12A_1 e^{-3x} + 12A_2 e^{-4x} + \frac{12}{72} e^{5x}$$

Example 20.—Solve the equation $\frac{d^2s}{dt^2} + 4\frac{ds}{dt} + 4s = 5 \sin 7t$. (This type of equation occurs frequently in electrical problems and in problems on forced vibrations of a system.)

The solution of $\frac{d^2s}{dt^2} + 4\frac{ds}{dt} + 4s = 0$

is

$$s = (A + Bt)e^{-2t} \quad (\text{See p. 283.})$$

To find the particular integral:—

$$(D^2 + 4D + 4)s = 5 \sin 7t.$$

$$\therefore s = \frac{5 \sin 7t}{D^2 + 4D + 4}.$$

$$D \sin 7t = 7 \cos 7t \quad \text{and} \quad D^2 \sin 7t = -49 \sin 7t.$$

(Note that $D^2 = -49$, but D does not = 7.)

We must thus eliminate D from the denominator: to do this, multiply both numerator and denominator by $D^2 + 4 - 4D$.

$$\begin{aligned} \text{Then } s &= \frac{5(D^2 + 4 - 4D) \sin 7t}{(D^2 + 4)^2 - 16D^2} \\ &= \frac{5(-49 \sin 7t + 4 \sin 7t - 28 \cos 7t)}{(-49 + 4)^2 - (16 \times -49)} \\ &= \frac{-5(45 \sin 7t + 28 \cos 7t)}{2809} \\ &= \frac{-5 \times 53 \sin \left(7t + \tan^{-1} \frac{28}{45}\right)}{2809} \\ &= -\frac{5}{53} \sin \left(7t + \tan^{-1} \frac{28}{45}\right). \end{aligned}$$

Hence the complete solution is

$$s = (A + Bt)e^{-2t} - \underline{\frac{5}{53} \sin \left(7t + \tan^{-1} \frac{28}{45}\right)}.$$

The particular integral might have been found in a more direct fashion by the use of Theorem 2, p. 288.

$$\text{For } \frac{\sin 7t}{(D+2)^2} = \frac{1}{(D+2)} \cdot \frac{1}{(D+2)} \sin 7t$$

$$\therefore \frac{\sin \left(7t - \tan^{-1} \frac{7}{2}\right)}{\sqrt{4+49}} \text{ from Theorem 2, p. 288, } \begin{cases} q=1 \\ c=0 \\ b=7 \end{cases}$$

$$= \frac{1}{\sqrt{53}} \cdot \frac{\sin \left(7t - \tan^{-1} \frac{7}{2}\right)}{(D+2)}$$

$$= \frac{1}{\sqrt{53}} \times \frac{1}{\sqrt{53}} \sin \left(7t - \tan^{-1} \frac{7}{2} - \tan^{-1} \frac{7}{2}\right)$$

$$= \frac{1}{53} \sin \left(7t - 2 \tan^{-1} \frac{7}{2}\right).$$

The two results do not appear at first sight to be the same, but they can be reconciled in the following manner :—

$$\tan^{-1} \frac{28}{45} = \tan^{-1} 1.6223 = 31^\circ 54'$$

$$\tan^{-1} \frac{7}{2} = 74^\circ 3'$$

$$\text{Thus } -\sin\left(7t + \tan^{-1} \frac{28}{45}\right) = -\sin(7t + 31^\circ 54')$$

$$\begin{aligned} \text{also } \sin\left(7t - 2\tan^{-1} \frac{7}{2}\right) &= \sin(7t - 2 \times 74^\circ 3') = \sin(7t - 148^\circ 6') \\ &= -\sin(180 + 7t - 148^\circ 6') \\ &= -\sin(7t + 31^\circ 54') \\ &= -\sin\left(7t + \tan^{-1} \frac{28}{45}\right). \end{aligned}$$

Example 21.—The equation $EI \frac{d^2y}{dx^2} + Fy + \frac{Bl}{8} \cos \frac{\pi x}{l} = 0$ occurs in Mechanics, y being the deflection of a rod of length l , and F being the end load.

Solve this equation.

We may rewrite the equation as $\frac{d^2y}{dx^2} + \frac{F}{EI}y = -\frac{Bl}{8EI} \cos \frac{\pi x}{l}$

The solution of $\frac{d^2y}{dx^2} + \frac{F}{EI}y = 0$ is $y = A \sin\left(\sqrt{\frac{F}{IE}}x + p\right)$ (2)

Reverting to form (1)

$$D^2y + \frac{F}{EI}y = -\frac{Bl}{8EI} \cos \frac{\pi x}{l}$$

$$\text{or } y = \frac{-\frac{Bl}{8EI} \cos \frac{\pi x}{l}}{D^2 + \frac{F}{EI}}$$

$$= -\frac{Bl}{8IE} \cos \frac{\pi x}{l} \times \frac{-\frac{\pi^2}{l^2} - \frac{F}{EI}}{-\frac{\pi^2}{l^2} + \frac{F}{EI}} \quad \text{for } D^2 = -\frac{\pi^2}{l^2}$$

$$\frac{Bl}{8} \cos \frac{\pi x}{l} \\ EI\pi^4 - F$$

Hence the complete solution is $y = A \sin\left(\sqrt{\frac{F}{IE}}x + p\right) + \frac{\frac{Bl}{8} \cos \frac{\pi x}{l}}{EI\pi^4 - F}$

Example 22.—A pin-jointed column, initially bent to a curve of cosines, has a vertical load W applied to it. Find an expression for the deflection at any point.

Given that the equation of the initial bent form is

$$y_1 = A \cos\left(\frac{\pi x}{l}\right)$$

y being the deflection at distance x from the centre of the column, which is of length l .

Also $-EI\frac{d^2y}{dx^2} = W\left\{y + A \cos\left(\frac{\pi x}{l}\right)\right\}$

this equation being obtained from a consideration of the bending moment at distance x from the centre.

$$-EI\frac{d^2y}{dx^2} = W\left\{y + A \cos\left(\frac{\pi x}{l}\right)\right\}$$

and thus $\frac{d^2y}{dx^2} + \frac{W}{EI}\left\{y + A \cos\left(\frac{\pi x}{l}\right)\right\} = 0$

or $\frac{d^2y}{dx^2} + \frac{W}{EI}y = -\frac{AW}{EI}\cos\left(\frac{\pi x}{l}\right)$

Now, as shown on p. 283, the solution of the equation

$$\frac{d^2y}{dx^2} + \frac{W}{EI}y = 0$$

is $y = B \sin\left(\sqrt{\frac{W}{EI}}x + p\right)$

To find the particular integral, viz., the solution of the equation

$$\frac{d^2y}{dx^2} + \frac{W}{EI}y = -\frac{AW}{EI}\cos\left(\frac{\pi x}{l}\right)$$

write the equation as

$$\left(D^2 + \frac{W}{EI}\right)y = -\frac{AW}{EI}\cos\left(\frac{\pi x}{l}\right)$$

so that $y = \frac{-\frac{AW}{EI}\cos\left(\frac{\pi x}{l}\right)}{D^2 + \frac{W}{EI}}$

$$\frac{-\frac{AW}{EI}\cos\left(\frac{\pi x}{l}\right)}{\frac{W - \frac{\pi^2}{l^2}}{EI}}$$

Combining the two results

$$y = B \sin\left(\sqrt{\frac{W}{EI}}x + p\right) + \frac{l^2 AW \cos\left(\frac{\pi x}{l}\right)}{\pi^2 EI - WL^2}$$

The following example combines the methods of solution employed in *Examples 17, 18, 19 and 20.*

Example 23.—Solve the equation

$$\frac{d^2s}{dt^2} - 12 \frac{ds}{dt} + 20s = e^{-5t} + \sin 60\pi t + 5.$$

(a) The solution of

$$\frac{d^2s}{dt^2} - 12 \frac{ds}{dt} + 20s = 0 \text{ is } s = A_1 e^{10t} + A_2 e^{2t}.$$

(b) The particular integral for

$$\frac{d^2s}{dt^2} - 12 \frac{ds}{dt} + 20s = e^{-5t}$$

may be thus found :—

$$\begin{aligned} & D^2 - 12D + 20 \\ & \frac{1}{D^2 - 12D + 20} e^{-5t} \\ & \frac{1}{25 + 60 + 20} \frac{e^{-5t}}{e^{-5t}} \\ & \frac{1}{105} \end{aligned}$$

(c) To find the particular integral for

$$\frac{d^2s}{dt^2} - 12 \frac{ds}{dt} + 20s = \sin 60\pi t$$

$$\begin{aligned} s &= \frac{\sin 60\pi t}{D^2 - 12D + 20} \\ &= \frac{1}{D-10} \cdot \frac{\sin 60\pi t}{D-2} \\ &= \frac{1}{D-10} \cdot \frac{1}{\sqrt{4+3600\pi^2}} \sin [60\pi t - \tan^{-1}(-30\pi)] \quad \left\{ \begin{array}{l} p = -2 \\ q = 1 \\ b = 60\pi \end{array} \right. \\ &= \frac{1}{\sqrt{4+3600\pi^2}} \cdot \frac{1}{\sqrt{100+3600\pi^2}} \sin [60\pi t - \tan^{-1}(-30\pi) - \tan^{-1}(-6\pi)] \\ &= \frac{\sin [60\pi t - \tan^{-1}(-30\pi) - \tan^{-1}(-6\pi)]}{20\sqrt{(1+900\pi^2)(1+36\pi^2)}}. \end{aligned}$$

(d) The particular integral for

$$\frac{d^2s}{dt^2} - 12 \frac{ds}{dt} + 20s = 5$$

$$\text{is } s = \frac{5}{20} = \frac{1}{4}$$

Hence the complete solution is the sum of those in (a), (b), (c) and (d), viz.,

$$s = A_1 e^{10t} + A_2 e^{2t} + \frac{e^{-5t}}{105} + \frac{\sin [60\pi t - \tan^{-1}(-30\pi) - \tan^{-1}(-6\pi)]}{20\sqrt{(1+900\pi^2)(1+36\pi^2)}} + \frac{1}{4}$$

Equations of the Second Degree.—The treatment of these equations is very similar, up to a certain point, to that employed in the solution of ordinary quadratic equations; particularly the solution by factorisation.

Example 24.—Solve the equation

$$\left(\frac{dy}{dx}\right)^2 - 8\frac{dy}{dx} - 33 = 0.$$

Let $Y = \frac{dy}{dx}$ then $Y^2 - 8Y - 33 = 0$

or $(Y - 11)(Y + 3) = 0$.

Thus $Y = 11$ or $Y = -3$

i.e., $\frac{dy}{dx} = 11$ or $\frac{dy}{dx} = -3$,

whence $y = 11x + C_1$ or $y = -3x + C_2$

or $y - 11x - C_1 = 0$ or $y + 3x - C_2 = 0$,

and the complete solution is the *product* of these two solutions, since the equation is of "degree" higher than the first.

Thus the solution is

$$(y - 11x - C_1)(y + 3x - C_2) = 0.$$

Example 25.—Solve the equation $5\left(\frac{dy}{dx}\right)^2 - 8y^3 = 0$.

$$5\left(\frac{dy}{dx}\right)^2 - 8y^3 = 0.$$

Dividing by 5 $\frac{dy}{dx}^2 - 1.6y^3 = 0$.

Factorising $\left(\frac{dy}{dx} + 1.265y^{\frac{2}{3}}\right)\left(\frac{dy}{dx} - 1.265y^{\frac{2}{3}}\right) = 0$

Hence $\frac{dy}{dx} + 1.265y^{\frac{2}{3}} = 0$ or $\frac{dy}{dx} - 1.265y^{\frac{2}{3}} = 0$.

Separating the variables and integrating

$$\int \frac{dy}{y^{\frac{2}{3}}} + 1.265 \int dx = 0 \quad \text{or} \quad \int \frac{dy}{y^{\frac{2}{3}}} - 1.265 \int dx = 0$$

$$-\frac{2}{y^{\frac{1}{3}}} + 1.265x = C_1 \quad \text{or} \quad -\frac{2}{y^{\frac{1}{3}}} - 1.265x = C_2$$

whence the complete solution is,

$$1.265x - C_1 - \frac{2}{y^{\frac{1}{3}}} \left(-1.265x - C_2 - \frac{2}{y^{\frac{1}{3}}} \right) = 0.$$

Two further examples are added to illustrate methods of solution other than those already indicated.

Example 26.—Solve the equation $\frac{d^3y}{dx^3} - \frac{d^2y}{dx^2} - 14\frac{dy}{dx} + 24y = 0$.

The equation may be written $(D^3 - D^2 - 14D + 24)y = 0$

$$\text{or} \quad (D-2)(D-3)(D+4)y = 0,$$

whence $\underline{y = Ae^{2x} + Be^{3x} + Ce^{-4x}}$.

Example 27.—The equation $\frac{d^4y}{dx^4} = m^4y$ occurs in the discussion of the whirling of shafts. Solve this equation.

$$\frac{d^4y}{dx^4} = m^4y,$$

$$\text{i.e.,} \quad D^4 = m^4$$

$$\text{or} \quad (D^2 - m^2)(D^2 + m^2) = 0,$$

$$\text{whence} \quad D = \pm m \text{ or } \pm jm.$$

$$\text{Hence} \quad y = a_1 e^{mx} + a_2 e^{-mx} + a_3 e^{jmx} + a_4 e^{-jmx}.$$

$$\text{But} \quad e^{jx} = \cos x + j \sin x, \quad e^{jmx} = \cos mx + j \sin mx$$

$$\text{and} \quad e^x = \cosh x + \sinh x,$$

$$\text{i.e.,} \quad e^{mx} = \cosh mx + \sinh mx.$$

$$\begin{aligned} \therefore y &= a_1(\cosh mx + \sinh mx) + a_2(\cosh mx - \sinh mx) \\ &\quad + a_3(\cos mx + j \sin mx) + a_4(\cos mx - j \sin mx) \\ &= (a_3 + a_4) \cos mx + (a_3 - a_4)j \sin mx + (a_1 + a_2) \cosh mx \\ &\quad + (a_1 - a_2) \sinh mx \\ &= \underline{\underline{A \cos mx + B \sin mx + C \cosh mx + D \sinh mx}}. \end{aligned}$$

The constants A, B, C and D are found by consideration of the conditions; four equations must be formed, these being found by successive differentiation and by substituting for $\frac{dy}{dx}$, $\frac{d^2y}{dx^2}$ and $\frac{d^3y}{dx^3}$ their values for various values of x .

Exercises 22.—On the Solution of Differential Equations.

1. If $\frac{dy}{dx} = 5x^2 - 2.4$ and $y = 1.68$ when $x = 2.29$, find y in terms of x .

2. Given that $\frac{ds}{dt^2} = 16 \cdot 1$; $\frac{ds}{dt} = 4 \cdot 3$ when $t = 1 \cdot 7$ and $s = 9 \cdot 8$ when $t = 2 \cdot 2$, find s in terms of t .

3. If $\frac{dy}{dx} = 8y + 5$, find an expression for y .

4. Given that $8.76 \frac{dy}{dx} + 9.15y = 76.4$ and also that $y = 2.17$ when $x = 0$, find an expression for y in terms of x .

5. A beam simply supported at its ends is loaded with a concentrated load W at the centre. The bending moment M at a section distant x from the centre is given by

$$M = \frac{W}{2} \left(\frac{l}{2} - x \right).$$

If $\frac{M}{EI} = \frac{d^2y}{dx^2}$, find the equation of the deflected form, y being the deflection.

6. For the case of a fixed beam uniformly loaded, M , the bending moment, $= \left\{ \frac{w(l^2)}{2} - \frac{x^2}{4} - K \right\}$. If $\frac{M}{EI} = \frac{d^2y}{dx^2}$, $\frac{dy}{dx} = 0$ when $x = \frac{l}{2}$ and also when $x = 0$; and $y = 0$ when $x = \frac{l}{2}$, find an expression for y .

7. Solve the equation

$$\frac{\pi r D}{s(r+r)} \frac{dx}{dT} = \frac{1}{T-t},$$

the limits to T being T_1 and T_2 , and to x being 0 and l ; the remaining letters representing constants.

8. If $\frac{dv}{dx} = -\frac{x^2}{4l\mu}$ and $v = 0$ when $x = s$, find v in terms of x .

9. If τ_1 = the absolute temperature of the gases entering a tube of length l and diam. D ,

τ_2 = the absolute temperature of the gases leaving this tube,

θ = temperature of the water,

Q = amount of heat transmitted through the tube per sq. ft. per sec. per degree difference of temperature on the two sides,

w = weight of gases along the tube per sec., and s = specific heat of gases,

$$\text{then } \frac{d\tau}{\tau-\theta} + \frac{Q\pi D dx}{ws} = 0.$$

Find an expression for Q , x being the distance from one end of the tube.

10. Find Q if $Qr^2\pi D dx + ws d\tau = 0$ (the letters having the same meanings as in No. 9, and the limits being the same).

11. If τ_1 and τ_2 are the inside and outside temperatures respectively of a thick tube of internal radius r_1 and external radius r_2 , then

$$\frac{d\tau}{dx} = -\frac{H}{2\pi K(r_2-r_1)l}.$$

l is the length of the tube, H is a quantity of heat, and the limits to x are 0 and r_2-r_1 . Find an expression for H , K being a constant.

12. A compound pendulum swings through small arcs. If I = moment of inertia about the point of suspension, h = the distance of C. of G. from point of suspension, then

$$I \times \text{angular acceleration} \left(i.e., I \frac{d^2\theta}{dt^2} \right) = -mh\theta.$$

Find an expression for θ .

If μ = couple for unit angle = mh , prove that t , the time of a complete oscillation, = $2\pi \sqrt{\frac{I}{\mu g}}$ (in Engineers' units).

13. To find an expression for the stress p in thick cylinders it is necessary to solve the equation

$$\frac{r dp}{dr} + 2p = 2A.$$

Solve this equation for p .

14. For a thick spherical shell, if p = radial pressure,

$$3a + 3p = -x \frac{dp}{dx}.$$

Find an expression for p , a being a constant.

15. If $-K_v vdp = K_p p dv$, prove that $pv = \text{constant}$, γ being the ratio the specific heat at constant pressure of a gas, i. e., $\frac{K_p}{K_v}$.

16. Solve for z in the equation

$$\frac{dz}{dx} + \frac{w \omega^2}{g f} zx = 0.$$

✓ 17. Solve the equation

$$\frac{d^2y}{dx^2} - 17 \frac{dy}{dx} + 70y = 0$$

and thence the equation

$$\frac{d^2y}{dx^2} - 17 \frac{dy}{dx} + 70y = 70.$$

✓ 18. Solve the equation $\frac{ds}{dt^2} = 87s$.

✓ 19. Solve the equation $\frac{ds}{dt^2} + 87s = 0$.

20. Find the time that elapses whilst an electric condenser of capacity K discharges through a constant resistance R , the potential difference at the start being v_1 and at the end v_2 , being given that

$$-K \times \text{rate of change of potential } v = \frac{v}{R}.$$

21. If $V = RC + L \frac{dC}{dt}$ and $V = 0$, find an expression for C ; C_0 being the initial current, i. e., the value of C when $t = 0$.

22. If $V = RC + L \frac{dC}{dt}$, and $V = V_0 \sin qt$, find an expression for C .

23. If $\frac{dy}{dx} = \frac{1}{a}\sqrt{y^2 + 2ay}$, find x in terms of y , a being a constant.

24. An equation occurring when considering the motion of the piston of an indicator is

$$M \frac{d^2x}{dt^2} + \frac{a}{SM} x = \frac{pa}{M}.$$

Solve this equation for x ; M , a , S and p being constants.

25. If $-Py = EI \frac{d^2y}{dx^2}$

(an equation referring to the bending of struts), find y ; given that $x = 0$ when $y = 0$, and $y = Y$ when $x = \frac{L}{2}$.

26. To find the time t of the recoil of a gun, it was necessary to solve the equation $\frac{dx}{dt} = n\sqrt{x^2 - a^2}$.

If $a = 47.5$, $n = 3.275$ and the limits to x are 0 and 57.5 , find t .

27. Solve the equation $\frac{d^2x}{dt^2} + 2f\frac{dx}{dt} + n^2x = 0$.

Take $n^2 = 200$, $f = 7.485$; also let $x = 0$ and $\frac{dx}{dt} = 10$ when $t = 0$.

28. The equation $\frac{d^2x}{dt^2} + 2f\frac{dx}{dt} + n^2x = a \sin qt$

expresses the forced vibration of a system. If $n^2 = 49$, $f = 3$, $q = 5$, find an expression for x .

29. Solve the equation $\frac{d^2V}{dx^2} - V \frac{r_1}{r_2} = 0$.

30. If H is the amount of heat given to a gas, p is its pressure and v its volume (of 1 lb.), then $\frac{dH}{dv} = \frac{1}{(n-1)} \left(v \frac{dp}{dv} + np \right)$. Assuming that there is no change of heat (*i.e.*, the expansion is adiabatic and $\frac{dH}{dv} = 0$), find a simple equation to express the connection between the pressure and volume during this expansion.

31. Newton's law of cooling may be expressed by the equation

$$\frac{d\theta}{dt} = -k(\theta - \theta_a)$$

where k is a constant, and θ_a is the temperature of the air.

If $\theta = \theta_0$ when $t = 0$, find an expression for θ .

32. The equation $1.04 \frac{d^2\theta}{dt^2} + 12.3 \frac{d\theta}{dt} + 13\theta - 634 = 0$

occurred in an investigation to find θ , the angle of incidence of the main planes of an aeroplane.

If $t = 0$ when $\theta = 1$ and $\frac{d\theta}{dt} = 0$ when $t = 0$, find an expression for θ .

33. A circular shaft weighing ρ lbs. per ft. rotates at ω radians per second, and is subjected to an endlong compressive force F . The deflection y can be found from the equation

$$\frac{d^4y}{dx^4} + \frac{F}{EI} \frac{d^2y}{dx^2} - \frac{\rho}{g} \frac{\omega^2 y}{EI} - \frac{\rho}{EI} = 0.$$

Solve this equation for y .

34. An equation relating to the theory of the stability of an aeroplane is

$$\frac{dv}{dt} = g \cos a - kv$$

where v is a velocity; g , a and k being constants. Find an expression for the velocity, if it is known that $v = 0$ when $t = 0$.

CHAPTER X

APPLICATIONS OF THE CALCULUS

THE idea of this chapter is to illustrate the use of the Calculus as applied to many Engineering problems; and the reader is supposed to be acquainted with the technical principle involved.

The various cases will be dealt with as though examples.

Examples in Thermodynamics.

Example 1.—To prove that $(V-w) = \frac{L}{\tau} \frac{d\tau}{dP}$, an equation occurring in Thermodynamics,

where L = latent heat at absolute temperature τ ,

V = vol. of 1 lb. of steam at absolute temperature τ ,

w = vol. of 1 lb. of water = .016 cu. ft.,

P = pressure.

A quantity q of heat taken in at $\tau + \delta\tau$ and discharged at τ will, according to the Carnot cycle, give out work = $q \frac{\tau + \delta\tau - \tau}{\tau + \delta\tau}$ or approximately $q \frac{\delta\tau}{\tau}$.

Hence for 1 lb. of steam at the boiling temperature,

$$\text{work} = q \frac{\delta\tau}{\tau} = L \frac{\delta\tau}{\tau},$$

but the work done = volume of steam in the cylinder \times change in pressure
 $= (V-w) \times \delta P$.

Hence $(V-w)\delta P = L \frac{\delta\tau}{\tau}$,

and thus $V-w = \frac{L}{\tau} \frac{\delta\tau}{\delta P}$,

or, as $\delta\tau$ becomes infinitely small,

$$V-w = \frac{L}{\tau} \frac{d\tau}{dP}.$$

Now $\frac{d\tau}{dP}$ is the slope of the pressure-temperature curve (plotted from

the tables) and can be easily found for any temperature τ . Hence V can also be found.

A numerical example will illustrate further.

It is required to find the volume of 1 lb. of dry steam at 228°F , i.e., at 20 lbs. per sq. in. pressure.

From the steam tables

When $P = 19$, $t = 225.3$, $\tau = \frac{460 + 225.3}{144} = 685.3$.
$"$ $P = 20$, $t = 228$, $\tau = 688$.
$"$ $P = 21$, $t = 230.6$, $\tau = 690.6$.

Plotting these temperatures to a base of pressures, we find that the portion of the curve dealt with in this range is practically straight.

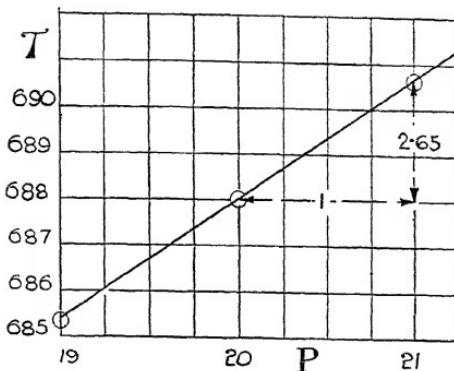


FIG. 103.—Problem in Thermodynamics.

The slope of this line = 2.65 (Fig. 103), and this is the value of $\frac{d\tau}{dP}$, P being given in lbs. per sq. in. and the latent heat in thermal units. To change the formula to agree with these units,

$$V = w + \frac{778L}{144\tau} \frac{d\tau}{dP}.$$

Also L at 228°F . = 953.

$$\therefore V = 0.016 + \frac{778 \times 953 \times 2.65}{144 \times 688} \\ = \underline{\underline{19.82 \text{ cu. ft.}}}$$

Example 2.—To prove that the specific heat of saturated steam (expanding dry) is negative.

Let

Q = the quantity of heat added.

H = total heat from 32°F .

I = internal energy of the steam.

Then $H = \text{internal} + \text{external energy}$
 $= I + PV,$
i.e., $I = H - PV$
or $\delta I = \delta H - \delta(PV) = \delta H - (P\delta V + V\delta P).$

Now $\delta Q = \delta I + P\delta V$
 $= \delta H - P\delta V - V\delta P + P\delta V$
 $= \delta H - V\delta P$
 $= \delta H - \frac{L}{\tau}$ {from Example 1, neglecting
 w , which is very small}.

Then $\frac{\delta Q}{\delta \tau} = \frac{\delta H}{\delta \tau} - \frac{L}{\tau}$

and $\frac{dQ}{d\tau} = \frac{dH}{d\tau} - \frac{L}{\tau}$
 $= .305 - \frac{L}{\tau}$ $\left. \begin{array}{l} H = 1082 + .305\tau \\ \therefore \frac{dH}{d\tau} = .305 \end{array} \right\}$

Now the specific heat = heat to raise the temperature τ°

$$= \frac{dQ}{d\tau}$$

hence $s = .305 - \frac{L}{\tau}$

and since $\frac{L}{\tau}$ is greater than .305, s is a negative quantity.

E.g., if $t = 300^\circ \text{ F.}, i.e., \tau = 761^\circ \text{ F. absol.}$
 $L = 1115 - 7t$
 $= 1115 - 210 = 905.$
 $\therefore s = .305 - \frac{905}{761}$
 $= -.882.$

Work Done in the Expansion of a Gas.

Example 3.—Find the work done in the expansion of a gas from volume v_1 to volume v_2 .

There are two distinct cases, which must be treated separately; but for both cases the work done in the expansion is measured by the area $ABCD = \Sigma$ areas of strips like MN (Fig. 104)

$$= \sum_{v_1}^{v_2} p \delta v \text{ or } \int_{v_1}^{v_2} p dv \text{ more exactly.}$$

Case (a), for which the law of the expansion is $p v = C$.

$$\text{Work done} = \int_{v_1}^{v_2} p dv = \int_{v_1}^{v_2} Cv^{-1} dv = C \left(\log v \right)_{v_1}^{v_2}$$

$$= C \log \left(\frac{v_2}{v_1} \right)$$

or $C \log r$

r being the ratio of expansion, and $= \frac{v_2}{v_1}$.

Thus the work done $= p v \log r$.

Case (b), for which the law of the expansion is $p v^n = C$, n having any value other than 1.

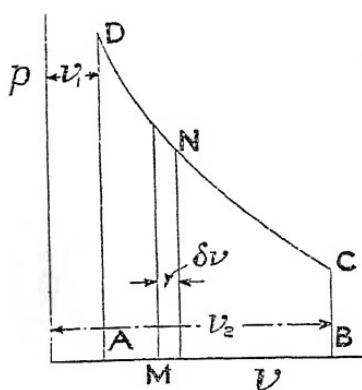


FIG. 104.

Work Done in the Expansion of a Gas.

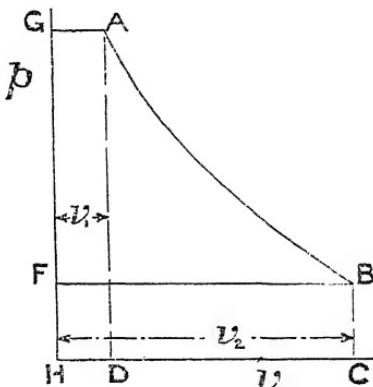


FIG. 105.

$$\begin{aligned} \text{Work done} &= \int_{v_1}^{v_2} p \, dv = \int_{v_1}^{v_2} C v^{-n} \, dv \\ &= \frac{1}{1-n} (v_1^{1-n} - v_2^{1-n}) \\ &= \frac{1}{1-n} (C v_2^{1-n} - C v_1^{1-n}) \\ &= \frac{1}{1-n} (p_2 v_2^n v_2^{1-n} - p_1 v_1^n v_1^{1-n}) \\ &= \frac{p_2 v_2 - p_1 v_1}{1-n}. \end{aligned}$$

Work Done in a Complete Theoretical Cycle.

Example 4.—Find the work done in the complete cycle represented by the diagram FGABF in Fig. 105.

$$\begin{aligned} \text{The work done} &= \text{area GABF} = \text{area } GADH + \text{area } FBCH \\ &= \frac{p_2 v_2 - p_1 v_1}{1-n} + \frac{p_1 v_1 - p_2 v_2}{1-n} \\ &= (p_1 v_1 - p_2 v_2) \left(1 - \frac{1}{1-n} \right) \\ &= (p_1 v_1 - p_2 v_2) \frac{(-n)}{1-n} \\ &= \frac{p_1 v_1 - p_2 v_2}{n-1}. \end{aligned}$$

Note that, if

$$n = \frac{17}{16}$$

work done

$$= \frac{p_1 v_1 - p_2 v_2}{\frac{1}{17}}$$

$$= 17(p_1 v_1 - p_2 v_2).$$

If the expansion is adiabatic, and n is calculated according to Zeuner's rule,
 $n = 1.035 + \cdot1q$
 $(q$ being the initial dryness fraction).

If $q = 1$, then $n = 1.035 + 1 = 1.135$, so that the work done

$$= \frac{1.135}{1.135} (p_1 v_1 - p_2 v_2) = 8.41 (p_1 v_1 - p_2 v_2).$$

To Find the Entropy of Water at Absolute Temperature τ .

Example 5.—When a substance takes in or rejects heat (at temperature τ) the change in entropy $\delta\phi = \frac{\delta q}{\tau}$ (δq = heat taken in).

Let

σ = specific heat,

then

$$\sigma \delta \tau = \delta q.$$

$$\begin{aligned} \text{Change in entropy from } \tau_0 \text{ to } \tau &= \int_{\tau_0}^{\tau} \frac{dq}{\tau} \\ &= \sigma \int_{\tau_0}^{\tau} \frac{d\tau}{\tau} \\ &= \sigma \log_e \frac{\tau}{\tau_0}. \end{aligned}$$

[For steam, the heat taken in at $\tau = L$ (i.e., in the change from the liquid to the gas).]

Hence the change of entropy $= \frac{L}{\tau}$

Efficiency of an Engine working on the Rankine Cycle.

Example 6.—Find the efficiency of an engine working on the Rankine cycle; using the $\tau\phi$ diagram for the calculation.

Work done = area of ABCD (Fig. 106.)

$$= ABCK + ADMN - DCKM$$

$$= \frac{q_1 L_1}{\tau_1} (\tau_1 - \tau_2) + \text{heat taken in from } \tau_2 \text{ to } \tau_1 - (\tau_2 \times DK).$$

Now DK = the change in entropy from water at τ_2 to water at τ_1

$$= \log_e \frac{\tau_1}{\tau_2} \text{ as proved above.}$$

$$\text{Hence the work done} = \frac{q_1 L_1}{\tau_1} (\tau_1 - \tau_2) + (\tau_1 - \tau_2) - \tau_2 \log \frac{\tau_1}{\tau_2}$$

$$= (\tau_1 - \tau_2) \left(1 + \frac{q_1 L_1}{\tau_1} \right) - \tau_2 \log \frac{\tau_1}{\tau_2}.$$

The heat put in $= \tau_1 - \tau_2 + q_1 L_1$ (q_1 being the dryness fraction at τ_1),

$$\text{and thus the efficiency } \eta = \frac{\tau_1 - \tau_2 \left(1 + \frac{q_1 L_1}{\tau_1} \right) - \tau_2 \log \frac{\tau_1}{\tau_2}}{\tau_1 - \tau_2 + q_1 L_1}$$

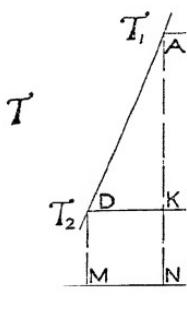


FIG. 106.

Efficiency of an Engine.

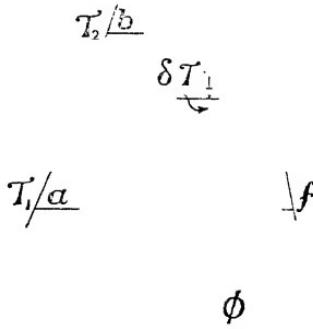


FIG. 107.

Efficiency of an Engine working on the Rankine Cycle, with steam kept saturated by jacket steam.

Example 7.—Find the efficiency of the engine whose cycle is given by $abcf$ in Fig. 107.

Work done = area $abcf$

$$= \int_{\tau_1}^{\tau_2} \frac{L}{\tau} d\tau \quad (\text{the summation being of horizontal strips})$$

$$= \int_{\tau_1}^{\tau_2} \frac{a+b\tau}{\tau} d\tau \quad \left\{ \begin{array}{l} \text{for } L = 1115 - .7\tau \\ \quad \quad \quad = 1437 - .7\tau \\ \quad \quad \quad = a + b\tau \end{array} \right\}$$

$$= \int_{\tau_1}^{\tau_2} \frac{a}{\tau} d\tau + \int_{\tau_1}^{\tau_2} bd\tau$$

$$= a \log_e \frac{\tau_2}{\tau_1} + b(\tau_2 - \tau_1).$$

$$\text{Total heat received} = L_2 + \tau_2 - \tau_1 + H_j \dots (1)$$

$$\text{total heat rejected} = L_1 \dots \dots \dots \dots (2)$$

$$\text{Hence the work done} = (1) - (2).$$

$$\begin{aligned} \text{from which } H_j &= a \log \frac{\tau_2}{\tau_1} + b(\tau_2 - \tau_1) - (L_2 - L_1) - (\tau_2 - \tau_1) \\ &= a \log \frac{\tau_2}{\tau_1} + b(\tau_2 - \tau_1) - (a + b\tau_2 - a - b\tau_1) \\ &\quad - (\tau_2 - \tau_1) \\ &= a \log \frac{\tau_2}{\tau_1} - (\tau_2 - \tau_1). \end{aligned}$$

Now the total heat received = $L_2 + \tau_2 - \tau_1 + H_j$

$$\begin{aligned} &= L_2 + \tau_2 - \tau_1 + a \log \frac{\tau_2}{\tau_1} - (\tau_2 - \tau_1) \\ &= a \log \frac{\tau_2}{\tau_1} + L_2. \end{aligned}$$

$$a \log \frac{\tau_2}{\tau_1} + b(\tau_2 - \tau_1)$$

Hence

$$\eta = \frac{a \log \frac{\tau_2}{\tau_1} + a + b\tau_2}{a \log \frac{\tau_2}{\tau_1} + a + b\tau_2}$$

$$\text{where } a = 1437 \text{ and } b = -7.$$

Example 8.—To prove that the equation for adiabatic expansion of air is $\dot{p}v^\gamma = C$, where

$$\gamma = \frac{\text{specific heat at constant pressure}}{\text{specific heat at constant volume}} = \frac{K_p}{K_v}.$$

Dealing throughout with 1 lb. of air, let the air expand under constant pressure from conditions $p_1 v_1 \tau_1$ to $p_1 v \tau$.

$$\begin{aligned} \text{Then the heat added} &= K_p(\tau - \tau_1) = K_p \left(\frac{p_1 v}{C_1} - \frac{p_1 v_1}{C_1} \right) \\ &= K_p p_1 \frac{v - v_1}{C_1} \end{aligned}$$

Now keep the volume constant at v , and subtract as much heat as was previously added: then the pressure falls to p_2 and the temperature to τ_2 .

$$\begin{aligned} \text{The heat subtracted} &= K_v(\tau - \tau_2) = K_v \left(\frac{p_1 v}{C_1} - \frac{p_2 v}{C_1} \right) \\ &= \frac{K_v v}{C_1} (p_1 - p_2). \end{aligned}$$

Now, if the changes are regarded as being very small, we may write $\frac{dp}{p}$ for $v - v_1$ and δp for $p_1 - p_2$

$$\text{and thus } -K_v v \delta p = K_p \delta v$$

$$\text{whence } \int \frac{dp}{p} = -\frac{K_p}{K_v} \int \frac{dv}{v}$$

$$\log p = -\gamma \log v + \log (\text{constant})$$

$$p = Cv^{-\gamma}$$

$$\dot{p}v^\gamma = C.$$

Examples relating to Loaded Beams.

Example 9.—Prove the most important rule

$$\frac{M}{I} = \frac{E}{R} = E \frac{d^2y}{dx^2}$$

applied to a loaded beam; M , I and E having their usual meanings, and R being the radius of curvature of the bent beam.

Assuming the beam to be originally straight, take a section of length l along the neutral lamina, and let $l + \delta l$ be the strained length at distance y (Fig. 108).

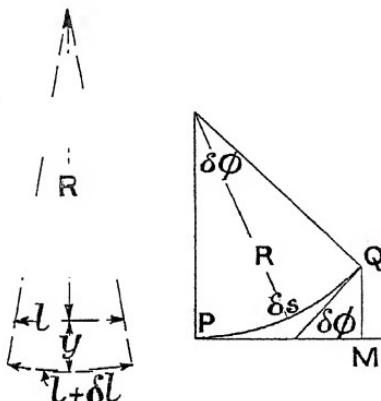


FIG. 108.—Problem on Loaded Beam.

Then, if R = radius of curvature,

$$\frac{l + \delta l}{l} = \frac{R + y}{R}$$

$$\text{whence } \frac{l + \delta l}{l} - 1 = \frac{R + y}{R} - 1$$

$$\text{or } \frac{\delta l}{l} = \frac{y}{R}$$

$$\text{but } E = \frac{\text{stress}}{\text{strain}} = \frac{f}{\frac{\delta l}{l}} = \frac{f}{\frac{y}{R}} = \frac{fR}{y}$$

$$\text{and thus } \frac{E}{R} = \frac{f}{y}$$

but it has already been proved (see p. 239) that $\frac{M}{I} = \frac{f}{y}$

$$\text{Hence } \frac{M}{I} = \frac{E}{R}.$$

The total curvature of an arc of a curve is the angle through which the tangent turns as its point of contact moves from one end of the arc to the other; and the mean curvature is given by the total curvature divided by the length of arc.

In Fig. 108 $\delta\phi =$ total curvature for the arc δs , and the mean curvature $= \frac{\delta\phi}{\delta s}$.

We know that the slope of the tangent is given by $\frac{dy}{dx}$

$$\therefore \tan \phi = \frac{dy}{dx}.$$

Now $\frac{a}{d\phi} \tan \phi = \sec^2 \phi$ and $\frac{d \tan \phi}{ds} = \frac{d \tan \phi}{d\phi} \times \frac{d\phi}{ds}$

$$\sec^2 \phi \cdot \frac{d\phi}{ds} = \frac{d}{ds} \left(\frac{dy}{dx} \right)$$

$$\sec^2 \times \frac{I}{R} = : \frac{d}{ds} \left(\frac{dy}{dx} \right)$$

$$: \frac{d}{dx} \left(\frac{dy}{dx} \right) \times \frac{dx}{ds}$$

$$: \frac{d^2y}{dx^2} \times \frac{dx}{ds}$$

Hence $\frac{I}{R} = \frac{d^2y}{dx^2} \times \frac{dx}{ds} \times \cos^2 \phi$

$$= \frac{d^2y}{dx^2} \times \frac{I}{\sqrt{I + \left(\frac{dy}{dx} \right)^2}}$$

$$\tan \phi = \frac{dy}{dx}$$

$$\tan^2 \phi = \left(\frac{dy}{dx} \right)^2$$

$$\begin{aligned} \sec^2 \phi &= I + \tan^2 \phi \\ &= I + \left(\frac{dy}{dx} \right)^2 \end{aligned}$$

$$\frac{d^2y}{dx^2}$$

$$: \frac{\left(\frac{dy}{dx} \right)^2}{I + \left(\frac{dy}{dx} \right)^2} :$$

When, as for a beam, $\frac{dy}{dx}$ is very small, $\left(\frac{dy}{dx} \right)^2$ may be neglected in comparison with I , and hence

$$\frac{I}{R} = \frac{d^2y}{dx^2}.$$

This result may be arrived at more briefly, but approximately, in the following manner:—

$\delta\phi = \delta \tan \phi$ very nearly (when the angle is very small).

Hence $\frac{\delta\phi}{\delta s} = \frac{\delta \tan \phi}{\delta s} = \frac{\delta}{\delta x} \tan \phi =$ rate of change of the tangent (for PM and PQ are sensibly alike).

Thus

$$\frac{d\phi}{ds} = \frac{d}{dx} \cdot \frac{dy}{dx} = \frac{d^2y}{dx^2}$$

and

$$\frac{I}{R} = \frac{d^2y}{dx^2}.$$

$$\therefore \frac{M}{I} = \frac{f}{y} = \frac{E}{R} = E \frac{d^2y}{dx^2}.$$

In the use of this rule there should be no difficulty in finding expressions for y in terms of x in cases in which the beam is simply supported; for an expression is found for the bending moment at distance x from one end, or the centre, whichever may be more convenient, and then the relation

$$\frac{M}{I} = E \frac{d^2y}{dx^2}$$

is used; whence double integration from the equation so formed gives an expression for the deflected form.

A few harder cases are here treated, the beam not being simply supported.

Example 10.—A beam is fixed at one end and supported at the other; the loading is uniform, w being the intensity. Find the equation of the deflected form.

We must first find the force P (part of the couple keeping the end fixed) and then combine this force with the reaction at B calculated on the assumption that the beam is simply supported. Referring to Fig. 109:—

If the beam is simply supported, the bending moment at distance x from B

$$= \frac{wl}{2} \cdot x - \frac{wx^2}{2}$$

Hence the actual bending moment

$$= M = \frac{wlx}{2} - \frac{wx^2}{2} - Px$$

$$i.e., EI \frac{d^2y}{dx^2} = \frac{wlx}{2} - \frac{wx^2}{2} - Px$$

whence, by integration,

$$EI \frac{dy}{dx} = \frac{wlx^2}{4} - \frac{wx^3}{6} - \frac{Px^2}{2} + C_1$$

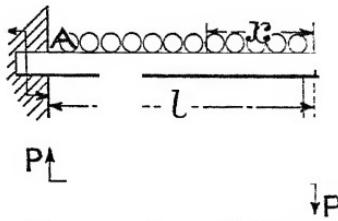


FIG. 109.—Beam Uniformly Loaded.

but $\frac{dy}{dx} = 0$ when $x = l$

for the deflected form is horizontal at this end.

$$\therefore 0 = \frac{wl^3}{4} - \frac{wl^3}{6} - \frac{Pl^2}{2} + C_1$$

$$i.e., C_1 = \frac{Pl^2}{2} - \frac{wl^3}{12}.$$

$$\text{Hence } EI \frac{dy}{dx} = \frac{wlx^2}{4} - \frac{wx^3}{6} - \frac{Px^2}{2} + \frac{Pl^2}{2} - \frac{wl^3}{12}.$$

$$\text{Integrating, } EIy = \frac{wlx^3}{12} - \frac{wx^4}{24} - \frac{Px^3}{6} + \frac{Pl^2x}{2} - \frac{wl^3x}{12} + C_2.$$

In this equation there are the two unknowns P and C_2 , and to evaluate them we must form two equations from the statements

$y = 0$ when $x = 0$ and $y = 0$ when $x = l$.

If $y = 0$ when $x = 0$, then it is readily seen that $C_2 = 0$.

$$\text{Also if } x = l \quad 0 = \frac{wl^4}{12} - \frac{wl^4}{24} - \frac{Pl^3}{6} + \frac{Pl^3}{2} - \frac{wl^4}{12}$$

$$\text{whence } P = \frac{wl}{\alpha}.$$

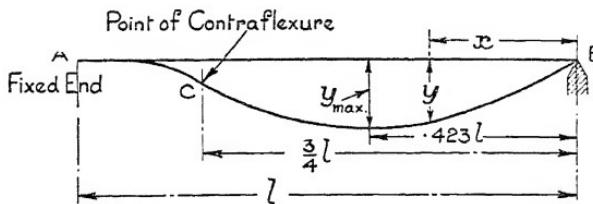


FIG. 110.—Deflected Form of Beam.

If the beam were simply supported, the upward reaction would be $\frac{wl}{2}$, and thus the net reaction $= \frac{wl}{2} - \frac{wl}{8} = \frac{3}{8}wl$.

Substituting $\frac{wl}{8}$ in place of P in the expression for y , we arrive at the equation of the deflected form

$$y = \frac{w}{48EI} (3lx^3 - 2x^4 - l^3x),$$

the curve for which is shown in Fig. 110.

We may now proceed to find where the maximum deflection occurs, and also the position of the point of contraflexure.

$$\frac{dy}{dx} = \frac{w}{48EI} (9lx^2 - 8x^3 - l^3)$$

$$\text{and } \frac{dy}{dx} = 0 \text{ if } 9lx^2 - 8x^3 = l^3,$$

the solution of which, applicable to the present case, is $x = .423l$.

The maximum deflection is thus

$$\begin{aligned}y_{\max} &= \frac{wl^4}{48EI} (228 - 064 - 423) \\&= -\frac{0054wl^4}{EI}.\end{aligned}$$

To find C the point of inflexion or contraflexure

$$\frac{d^2y}{dx^2} = \frac{w}{48EI} (18lx - 24x^2)$$

$$\text{and } \frac{d^2y}{dx^2} = 0 \text{ if } x = 0 \text{ or if } x = \frac{3}{4}l.$$

Example 11.—A beam is fixed at one end and supported at the other, the loading and the section both varying. Find the equation of the deflected form.

Let m = bending moment at a point distant x from B if the beam were simply supported, and let P = the force of the fixing couple. (See Fig. 109.)

Then

$$M = m - Px$$

$$EI \frac{d^2y}{dx^2} = m - Px$$

and

$$EI \frac{d^2y}{dx^2} = \frac{m}{I} - \frac{Px}{I}$$

the equation being written in this form since I is now a variable.

$$\text{By integrating } EI \frac{dy}{dx} = \int_0^x \frac{m}{I} dx - P \int_0^x \frac{x}{I} dx + C_1 \quad \dots \quad (1)$$

Now

$$\frac{dy}{dx} = 0 \text{ when } x = l.$$

$$\therefore C_1 = P \int_0^l \frac{x}{I} dx - \int_0^l \frac{m}{I} dx,$$

i.e., C_1 can be found, for the two integrals may be evaluated.

By integrating (1),

$$Ey = \int_0^x \int_0^x \frac{m}{I} (dx)^2 - P \int_0^x \int_0^x \frac{x}{I} (dx)^2 + C_1 x + C_2.$$

But $y = 0$ when $x = l$ and also when $x = 0$, and thus $C_2 = 0$

$$\text{and } 0 = \int_0^l \int_0^x \frac{m}{I} (dx)^2 - P \int_0^l \int_0^x \frac{x}{I} (dx)^2 + l \left\{ P \int_0^l \frac{x}{I} dx - \int_0^l \frac{m}{I} dx \right\},$$

i.e., P can be found.

The integrations must be performed graphically and with extreme care, or otherwise very serious errors arise.

Example 12.—A beam is fixed at both ends and the loading and the section both vary. Find the equation of the deflected form.

Let m_1 and m_2 be the end fixing couples; then to keep the system in equilibrium it is necessary to introduce equal and opposite forces P (Fig. III), i.e., $Pl + m_2 = m_1$.

Let m = the "simply supported" bending moment at section x from the right-hand end.

Then

$$M = m - m_2 - Px$$

and consequently $EI \frac{d^2y}{dx^2} = m - m_2 - Px$

or $E \frac{d^2y}{dx^2} = \frac{m}{I} - \frac{m_2}{I} - \frac{Px}{I}$.

Integrating,

$$E \frac{dy}{dx} = \int_0^x \frac{m}{I} dx - m_2 \int_0^x \frac{dx}{I} - P \int_0^x \frac{x}{I} dx + C_1.$$

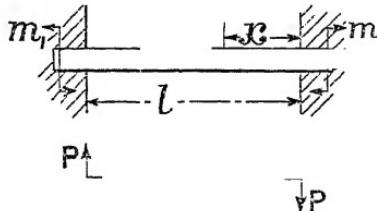


FIG. III.

Now

$$\frac{dy}{dx} = 0 \text{ when } x = 0 \text{ or } l$$

hence

$$C_1 = 0 \quad (\text{taking } x = 0)$$

and also, taking $x = l$,

$$0 = \int_0^l \frac{m}{I} dx - m_2 \int_0^l \frac{1}{I} dx - P \int_0^l \frac{x}{I} dx \dots \dots \dots \quad (1)$$

Integrating again,

$$Ey = \int_0^x \int_0^x \frac{m}{I} (dx)^2 - m_2 \int_0^x \int_0^x \frac{1}{I} (dx)^2 - P \int_0^x \int_0^x \frac{x}{I} (dx)^2 + C_2.$$

Now $y = 0$ when $x = 0$ and also when $x = l$.

Then taking $x = 0$, $C_2 = 0$,

and taking $x = l$,

$$0 = \int_0^l \int_0^x \frac{m}{I} (dx)^2 - m_2 \int_0^l \int_0^x \frac{1}{I} (dx)^2 - P \int_0^l \int_0^x \frac{x}{I} (dx)^2 \dots \dots \quad (2)$$

From equations (1) and (2) the values of m_2 and P (and hence m_1) may be found, the integration being graphical (except in a few special cases); and again it must be emphasised that the integration must be performed most accurately.

Example 13.—A uniform rectangular beam, fixed at its ends, is 20 ft. long, and has a load of 10 tons at its centre and one of 7 tons at 5 ft. from one end. Find the fixing couples and the true B.M. diagram.

This is a special case of *Example 12* since the section, and therefore I , is constant.

The B.M. diagram for the beam if simply supported would be as ABCD (Fig. 112).

The bending moment diagram, due to the fixing couples only, would have the form of a trapezoid, as APQD.

Unless the integration, explained in the previous example, is done extremely carefully, there will be serious errors in the results; and since there are only the two loads to consider, it is rather easier to

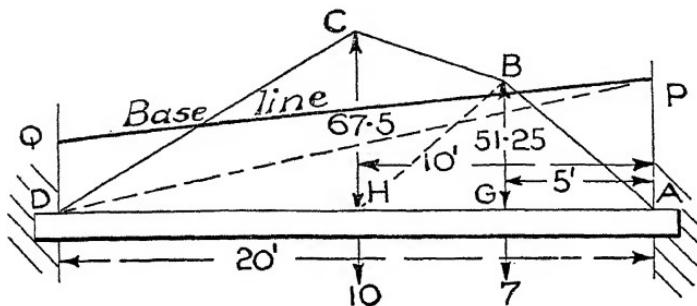


FIG. 112.—Fixing Couples and B.M. Diagram of Loaded Beam.

work according to the Goodman scheme. [See *Mechanics applied to Engineering*, by Goodman.]

According to this plan: (1) the opposing areas (*i. e.*, of the *free* and *fixing* bending moment diagrams) must be equal; and (2) the centroids of the opposing areas must be on the same vertical, *i. e.*, their centroid verticals must coincide.

To satisfy condition (1),

$$\begin{aligned} \text{Area of } ABCD &= \left(\frac{1}{2} \times 5 \times 51.25 \right) + \left(\frac{51.25 + 67.5}{2} \times 5 \right) + \left(\frac{1}{2} \times 10 \times 67.5 \right) \\ &= 762.5. \end{aligned}$$

$$\begin{aligned} \text{Area of } APQD &= \frac{1}{2} \times 20 \times (m_1 + m_2) \quad \text{where } m_1 = AP \\ &\quad \text{and } m_2 = DQ \} \\ &= 10 (m_1 + m_2). \end{aligned}$$

$$\text{Equating these areas, } m_1 + m_2 = 76.25 \quad (1)$$

To satisfy condition (2), taking moments about AP,

$$\text{Moment of } ABG = \frac{5}{2} \times 51.25 \times \frac{2}{3} \times 5 = 427$$

$$\text{Moment of } BGH = \frac{5}{2} \times 51.25 \times \left(5 + \frac{1}{3} \times 5\right) = 854$$

$$\text{Moment of } BHC = \frac{5}{2} \times 67.5 \times \left(5 + \frac{2}{3} \times 5\right) = 1405$$

$$\text{Moment of } DCH = \frac{10}{2} \times 67.5 \times \left(10 + \frac{1}{3} \times 10\right) = 4500$$

i.e., total moment of ABCD about AP = 7186

$$\text{Moment of } APD = \frac{20}{2} \times m_1 \times \frac{20}{3} = \frac{200}{3} n$$

$$\text{Moment of } DPQ : \frac{20}{2} \times m_2 \times \frac{40}{3} = \frac{400}{3} m_2$$

$$\text{Hence } \frac{200}{3} m_1 + \frac{400}{3} m_2 = 7186 . \quad (2)$$

The solution of equations (1) and (2) for m_1 and m_2 gives the results
 $m_1 = 44.71$ and $m_2 = 31.54$.

Thus PQ is the true base of the complete bending moment diagram, AP being made equal to 44.71, and DQ equal to 31.54.

Shearing Stress in Beams.

Example 14.—To find an expression for the maximum intensity of shearing stress over a beam section.

The shearing stress at any point in a vertical section of a beam is always accompanied by shearing stress of equal intensity in a horizontal plane through that point.

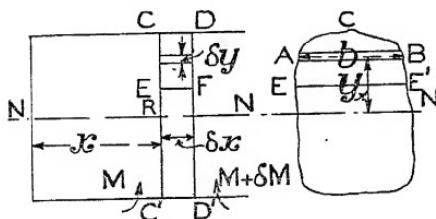


FIG. 113.—Shearing Stress in Beams.

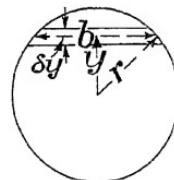


FIG. 114.

We require to know the tangential or shearing stress f at E on the plane CEC' (Fig. 113); this must be equal to the tangential stress in the direction EF on the plane EF at right angles to the paper. Suppose that the bending moment at CC' = M and that at DD' = $M + \delta M$. Then the total pushing forces on DF > total pushing forces on CE, the difference being the tangential forces on EFE'.

Let P = the total pushing force on ECE'

$$\text{then } P = \int_{RE}^{RC} (\text{stress}) \times \text{area} \quad \left| \begin{array}{l} \frac{\text{stress}}{y} = \frac{M}{I} \\ \text{area} : bdy \end{array} \right.$$

$$= \int_{RE}^{RC} \frac{yM}{I} bdy$$

$$= \frac{M}{I} \int_{RE}^{RC} by dy = \frac{M}{I} \times \text{1st moment of area ECE}'.$$

$$\text{Now the tangential force on EFE}' = \text{stress} \times \text{area}$$

$$= f \times EE' \times \delta x$$

and this must equal the difference in the total pushing forces on DF and CE, i.e., δP .

$$\text{Hence } \delta P = f \times EE' \times \delta x$$

$$\text{i.e., } \frac{\delta M}{I} \times \text{1st moment of area ECE}' = f \times EE' \times \delta x,$$

$$\text{but } \frac{\delta M}{\delta x} = \text{rate of change of B.M.} = \text{shear} = F \text{ (say).}$$

Hence the maximum intensity of shearing stress f

$$= \text{1st moment of area ECE}' \times \frac{F}{I} \times \frac{I}{EE'}$$

or, as it is usually written,

$$f = \frac{FS\bar{y}}{bI}$$

where S = an area such as CEE' and \bar{y} = distance of its centroid from the neutral axis.

Example 15.—Find the maximum intensity of shearing stress, when the section is circular, of radius r (see Fig. 114).

For this section

$$I = \frac{\pi}{4} r^4.$$

Applying the rule proved above:—

$$\text{the maximum intensity} = \frac{F}{2rI} \int_0^r by dy \quad \begin{array}{l} \text{since } 2r \text{ corresponds to EE}' \\ \text{in Example 14.} \end{array}$$

$$= \frac{F}{2rI} \int_0^r 2(r^2 - y^2)^{\frac{1}{2}} y dy$$

$$= \frac{F}{rI} \int_0^r u^{\frac{1}{2}} \frac{du}{-2} \quad \left\{ \begin{array}{l} \text{where } u = r^2 - y^2 \\ \frac{du}{dy} = -2y \end{array} \right\}$$

$$= -\frac{F}{2rI} \left(\frac{2}{3} (r^2 - y^2)^{\frac{3}{2}} \right)$$

$$= \frac{F \times 4}{2r\pi r^4} \times \frac{2}{3} r^3 = \frac{4}{3} \cdot \frac{1}{\pi r^2}$$

$$= \frac{4}{3} \times \text{mean intensity.}$$

Example 16.—A uniformly tapered cantilever of circular cross section is built in at one end and is loaded at the other. The diam. at the loaded end is D ins. and the taper is t ins. per in. of length. Find an expression for the distance of the most highly stressed section from the free end of the beam due to bending moment only. Neglect the weight of the cantilever.

Let l be the length in ins. and W the load at the free end. Consider a section distant x ins. from the free end; then the diam. here is $D-tx$, and the bending moment Wx .

Also the value of I for the section considered is

$$\frac{\pi}{64} (\text{diam.})^4 = \frac{\pi}{64} (D-tx)^4.$$

$$\begin{aligned}\text{Hence the skin stress } f &= \frac{My}{I} = Wx \left(\frac{D-tx}{2} \right) \times \frac{\frac{64}{\pi(D-tx)^4}}{} \\ &= \frac{32xW}{\pi(D-tx)^3} \\ &= \frac{K}{\frac{D^3 - 3D^2tx + 3Dt^2x^2 - t^3x^3}{x}} \text{ where } K = \frac{32W}{\pi} \text{ (a constant),}\end{aligned}$$

and f is a maximum when the denominator is a minimum.

Let $N = \text{denominator}$

$$= D^3x^{-1} - 3D^2t + 3Dt^2x - t^3x^2$$

$$\text{then } \frac{dN}{dx} = -\frac{D^3}{x^2} + 3Dt^2 - 2t^3x$$

$$\text{and } \frac{dN}{dx} = 0 \text{ when } 2t^3x^3 - 3Dt^2x^2 + D^3 = 0$$

$$\text{i. e., when } 2t^3x^3 - 2Dt^2x^2 - Dt^2x^2 + D^3 = 0$$

$$2t^2x^2(tx-D) - D(t^2x^2 - D^2) = 0$$

$$(tx-D)(2t^2x^2 - Dtx - D^2) = 0$$

$$(tx-D)(2tx+D)(tx-D) = 0$$

$$\text{i. e., when } x = \frac{D}{t} \text{ or } -\frac{D}{2t}.$$

Thus the stress is maximum at a section distant $\frac{D}{t}$ ins. from the free end.

Example 17.—To find the deflection of the muzzle of a gun.

This is an instructive example on the determination of the deflection of a cantilever whose section varies.

The muzzle is divided into a number of elementary discs, the volumes of these found (and hence the weights) so that the curve of loads can be plotted. Integration of this curve gives the curve of shear, and integration of the curve of shear gives the B.M. diagram.

The values of I must next be calculated for each disc, and a new curve plotted with ordinates equal to $\frac{B.M.}{I}$: then double integration of this gives the deflected form.

It is necessary to use the ordinates of this curve to find, first the time of the fundamental oscillation and thence the upward velocity due to the deflection.

Call the deflection at any section y , and the load or weight of the small disc w .

Find the sum of all products like wy^2 and also find the sum of all products like wy .

(Suitable tabulation will facilitate matters.)

Then T (time of oscillation)

$$= 2\pi \sqrt{\sum w_y}$$

If Y = maximum deflection, assuming the motion to be S.H.M., then the upward velocity v is obtained from

$$vT = 2\pi Y$$

$$\text{or } v = \frac{2\pi Y}{T}.$$

Examples on Applied Electricity.

Example 18.—Arrange n electric cells partly in series and partly in parallel to obtain the maximum current from them through an external resistance R . (Let the internal resistance of each cell = r , and let the E.M.F. of each cell = v .)

Suppose the mixed circuit is as shown in Fig. 115, i.e., with x cells per row and therefore $\frac{n}{x}$ rows.

Then the total E.M.F. of 1 row = xv and total internal resistance of 1 row = xr ,

but as there are $\frac{n}{x}$ rows, the total internal

resistance is $\frac{n}{x}$ that of 1 row, i.e., the total internal resistance = $\frac{rx^2}{n}$; but the E.M.F. is

unaltered: in reality the effect being that of one large cell, the area being greater and thus the resistance less.

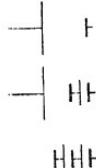


FIG. 115.—Maximum Current from Electric Cells.

$$\text{Hence the current } C = \frac{\text{total E.M.F.}}{\text{total resistance}} = \frac{Av}{\frac{rx^2}{n} + R}$$

$$= \frac{rx}{\frac{n}{x} + R}$$

and C is maximum when the denominator is a minimum.

Let D = the denominator, then

$$\frac{dD}{dx} = \frac{r}{n} - \frac{R}{x^2} \text{ and } \frac{dD}{dx} = 0 \text{ when } R = \frac{rx^2}{n},$$

i. e., external = internal resistance.

Example 19.—To find an expression for the time of discharge of an electric condenser of capacity K , discharging through a constant resistance R .

Let v = potential difference between the coatings at any time t .

Then, by Ohm's law, the current $C = \frac{v}{R}$.

But the current is given by the rate of diminution of the quantity q and $q = Kv$.

$$\text{Hence } C = -\frac{dq}{dt} = -\frac{dKv}{dt} = -K\frac{dv}{dt}$$

$$\text{and thus } \frac{v}{R} = -K\frac{dv}{dt}.$$

If V_1 = the difference of potential at the start, i. e., at $t = 0$, and V_2 = the difference of potential at the end of T secs,

Separating the variables and integrating,

$$-\int_{V_1}^{V_2} \frac{dv}{v} = \frac{1}{KR} \int_0^T dt$$

$$\text{whence } \log \frac{V_1}{V_2} : = \frac{T}{KR}$$

$$\text{or } \frac{V_1}{V_2} = e^{\frac{T}{KR}}$$

$$\frac{V_1}{V_2} = e^{-\frac{T}{KR}}$$

or the time taken to lower the voltage from

$$V_1 \text{ to } V_2 = KR \log \left| \frac{V_1}{V_2} \right|$$

Example 20.—If R = the electric resistance of a circuit, L = its self-inductance, C = the current flowing and V = the voltage, then

$$V = RC + L \frac{dC}{dt}$$

Solve this equation for the cases when $V=0$, $C=C_0 \sin qt$ and $V=V_0 \sin qt$.

For the case of a steady current $V=RC$ since L is zero, and this corresponds to the equation of uniform motion in mechanics, whilst the equation $V=RC+L\frac{dC}{dt}$ may be compared with that for accelerated motion, V being the force. Thus the second term of the equation may be regarded as one expressing the "inertia" or "reluctance to change," and since the current may vary according to various laws, the rate of change $\frac{dC}{dt}$ can have a variety of values.

Dealing with the cases suggested:—

$$(1) V=0, \text{ then } 0=RC+L\frac{dC}{dt}$$

$$\text{or } RC=-L\frac{dC}{dt}$$

and this equation is solved by separating the variables and integrating.

$$\text{Thus } \int \frac{dC}{C} = -\frac{R}{L} \int dt$$

$$\text{whence } -\frac{Rt}{L} = \log_e C + \log_e A = \log_e AC$$

$$\text{and } AC = e^{-\frac{Rt}{L}}, \text{ } A \text{ being a constant.}$$

$$(2) \text{ If } C=C_0 \sin qt$$

$$\text{then } \frac{dC}{dt} = qC_0 \cos qt.$$

$$\begin{aligned} V &= RC_0 \sin qt + LqC_0 \cos qt \\ &= C_0 \sqrt{R^2 + L^2 q^2} \sin \left(qt + \tan^{-1} \frac{Lq}{R} \right). \end{aligned}$$

$$(3) \text{ If } V=V_0 \sin qt$$

$$\text{then } V_0 \sin qt = RC + L\frac{dC}{dt}$$

$$\text{i.e., } V_0 \sin qt = (R+LD)C$$

$$\text{where } D = \frac{d}{dt}$$

$$\text{Hence } C = \frac{V_0 \sin qt}{R+LD}$$

and, using Theorem 2 of p. 288,

$$C = \frac{V_0}{\sqrt{R^2 + L^2 q^2}} \sin \left(qt - \tan^{-1} \frac{Lq}{R} \right).$$

To this must be added the solution of $0=RC+L\frac{dC}{dt}$, viz., $C=Ke^{-\frac{Rt}{L}}$;

hence the complete solution is

$$C = Ke^{-\frac{Rt}{L}} + \frac{V_0}{\sqrt{R^2 + L^2 q^2}} \sin \left(qt - \tan^{-1} \frac{Lq}{R} \right)$$

Example 21.—To find expressions for the potential and the current at any points along a long uniform conductor.

At a distance x from the "home" end let the steady potential to the ground = E and the steady current be i .

Let the resistance of 1 unit of length of the conductor = r and let the leakage of 1 unit of length of the insulation = l .

Consider a small length of conductor δx .

Its resistance = $r\delta x$ and the leakage = $l\delta x$.

$$\text{Hence the drop in potential} = i \times r\delta x \dots \dots \dots \dots \quad (1)$$

$$\text{and the drop in the current} = E \times l\delta x \dots \dots \dots \dots \quad (2)$$

$$\text{i.e., from (1)} \quad \frac{\delta E}{\delta x} = -ir\delta x \quad (1)$$

$$\text{or} \quad \frac{\delta E}{\delta x} = -ir \dots \dots \dots \dots \quad (3)$$

$$\text{and from (2)} \quad \frac{\delta i}{\delta x} = -El\delta x$$

$$\text{or} \quad \frac{\delta i}{\delta x} = -El \dots \dots \dots \dots \quad (4)$$

Writing (3) and (4) in their limiting forms

$$\frac{dE}{dx} = -ir, \quad \frac{di}{dx} = -El.$$

$$\text{Differentiating,} \quad \frac{d^2E}{dx^2} = \frac{d}{dx}(-ir) = -r \frac{di}{dx} = rEl \dots \dots \dots \quad (5)$$

$$\text{and} \quad \frac{d^2i}{dx^2} = \frac{d}{dx}(-El) = -l \frac{dE}{dx} = ril \dots \dots \dots \quad (6)$$

To solve these equations, let $D = \frac{d}{dx}$

then

$$D^2 E = rEl$$

i.e.,

$$D^2 = rl$$

$$D = \pm \sqrt{rl}.$$

$$\therefore \frac{dE}{dx} = \sqrt{rl}E \text{ or } \frac{dE}{dx} = -\sqrt{rl}E.$$

Separating the variables,

$$\frac{dE}{E} = \sqrt{rl}dx \text{ or } \frac{dE}{E} = -\sqrt{rl}dx.$$

Integrating,

$$\log E = \sqrt{rl}x + C_1 \text{ or } \log E = -\sqrt{rl}x + C_2$$

$$\text{i.e.,} \quad E = A_1 e^{\sqrt{rl}x} + A_2 e^{-\sqrt{rl}x}$$

or, if the constants are suitably chosen,

$$E = A \cosh \sqrt{rl}x + B \sinh \sqrt{rl}x.$$

In like manner, $i = C \cosh \sqrt{rl} x + D \sinh \sqrt{rl} x$.

When $x = L$

$$E = A \cosh \sqrt{rl} L + B \sinh \sqrt{rl} L.$$

When $x = 0$

$$E = A$$

and hence the constants can be found.

Examples on Strengths of Materials.

Example 22.—To find the shape assumed by a chain loaded with its own weight only; the weight per foot being w . To find also expressions for the length of arc and the tension at any point.

Let s = the length of the arc AB (Fig. 116): then the weight of this portion = ws .

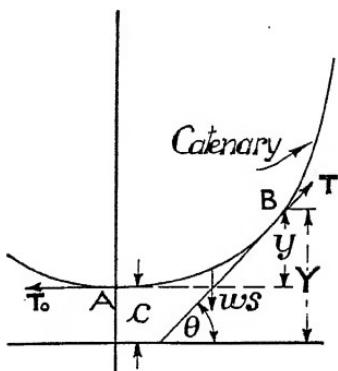


FIG. 116.

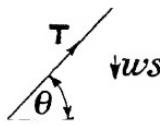


FIG. 117.

Draw the triangle of forces for the three forces T , T_0 and ws (Fig. 117).

Let it be assumed that T_0 (the horizontal tension) = wc , where c is some constant.

Then, from Figs. 116 and 117

$$\frac{dy}{dx} = \tan \theta = \frac{ws}{T_0} = \frac{ws}{wc} = \frac{s}{c}.$$

Now, as proved on p. 201,

$$\frac{ds}{dy} = \sqrt{1 + \left(\frac{dx}{dy}\right)^2} = \sqrt{1 + \frac{c^2}{s^2}} = \frac{\sqrt{s^2 + c^2}}{s}$$

$$\frac{s ds}{\sqrt{c^2 + s^2}} = dy \quad (1)$$

MATHEMATICS FOR ENGINEERS

To integrate the left-hand side, let $u = c^2 + s^2$

$$\text{then } \frac{du}{ds} = 2s$$

$$\text{and } \int \frac{s ds}{\sqrt{c^2 + s^2}} - \int \frac{s du}{2s u} = u^{\frac{1}{2}} = \sqrt{c^2 + s^2}.$$

Thus, by integration of equation (1),

$$\sqrt{c^2 + s^2} = y + C_1.$$

Now at the point A (Fig. 116) $s = 0$ and $y = 0$

$$\text{hence } \sqrt{c^2} = C_1 \text{ or } C_1 = c.$$

$$\text{Thus } \sqrt{c^2 + s^2} = y + c.$$

$$\begin{aligned} \text{Squaring} \quad & c^2 + s^2 = y^2 + c^2 + 2yc \\ \text{or} \quad & s^2 = y^2 + 2yc \quad \text{and} \quad s = \sqrt{y^2 + 2yc} \end{aligned}$$

$$\text{but as proved above } \frac{s}{c} = \frac{dy}{dx} \text{ or } s = c \frac{dy}{dx}$$

$$\text{hence } c \frac{dy}{dx} = \sqrt{y^2 + 2yc}.$$

Separating the variables

$$\frac{dy}{\sqrt{y^2 + 2yc}} = \frac{dx}{c}$$

$$\text{i.e., } \frac{dy}{\sqrt{y^2 + 2yc + c^2 - c^2}} = \frac{dx}{c} \quad \text{or} \quad \frac{dy}{\sqrt{(y+c)^2 - c^2}} = \frac{dx}{c}.$$

$$\text{Integrating } \int \frac{dy}{\sqrt{(y+c)^2 - c^2}} = \int \frac{dx}{c}$$

and this integral is of the type discussed on p. 151; the result being

$$\log \left(\frac{y+c + \sqrt{y^2 + 2yc}}{c} \right) = \frac{x}{c} + C_2.$$

Now $x = 0$ when $y = 0$, x being measured from the vertical axis through A, and thus $\log \left(\frac{c}{c} \right) = C_2$ or $C_2 = 0$.

$$\text{Thus } \frac{x}{c} = \log \left(\frac{y+c + \sqrt{y^2 + 2yc}}{c} \right)$$

or in the exponential form

$$ce^{\frac{x}{c}} = y + c + \sqrt{y^2 + 2yc}.$$

$$\text{Isolating the surd } ce^{\frac{x}{c}} - (y+c) = \sqrt{y^2 + 2yc}.$$

$$\text{Squaring } c^2 e^{\frac{2x}{c}} + y^2 + c^2 + 2yc - 2(y+c) ce^{\frac{x}{c}} = y^2 + 2yc$$

$$\text{or } c^2 e^{\frac{2x}{c}} - 2ce^{\frac{x}{c}} (y+c) + c^2 = 0.$$

Dividing through by ce^c

$$ce^c + ce^{-\frac{x}{c}} = 2(y+c),$$

$$\text{i.e., } (y+c) = \frac{c}{2} (e^{\frac{x}{c}} + e^{-\frac{x}{c}}).$$

If now the axis of x be shifted downwards a distance c , then the new ordinate $Y = y+c$ and $Y = \frac{c}{2} (e^{\frac{x}{c}} + e^{-\frac{x}{c}}) = c \cosh \frac{x}{c}$.

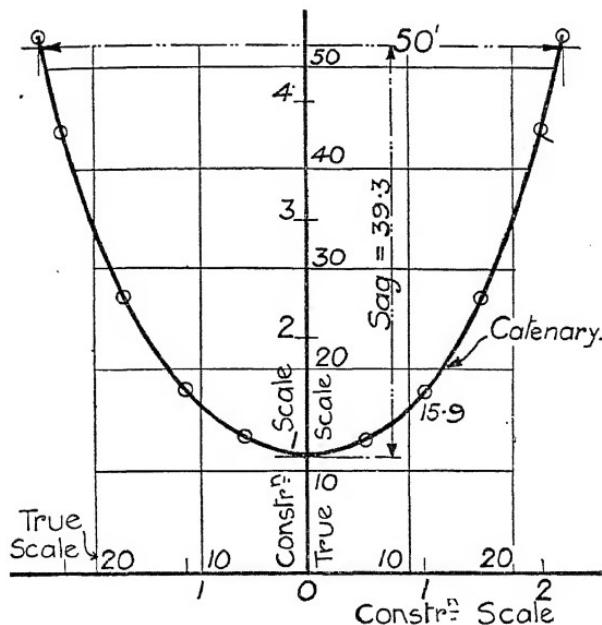


FIG. 118.—Catenary Form of a Cable.

$$\text{Again, since } Y = y+c \quad \frac{dY}{dx} = \frac{d(y+c)}{dx} = \frac{dy}{dx}$$

$$\text{and also} \quad \frac{d}{dx} c \cosh \frac{x}{c} = \frac{c}{c} \sinh \frac{x}{c} = \sinh \frac{x}{c}.$$

$$\text{Then} \quad \frac{dy}{dx} = \sinh \frac{x}{c}$$

but it has already been proved that

$$\frac{dy}{dx} = \frac{s}{c}$$

$$\text{hence} \quad \frac{s}{c} = \sinh \frac{x}{c} \quad \text{or} \quad s = c \sinh \frac{x}{c}.$$

MATHEMATICS FOR ENGINEERS

To find the tension T at any point

$$\begin{aligned} T^2 &= w^2 s^2 + w^2 c^2 \quad \text{from Fig. 117} \\ &= w^2 (s^2 + c^2) \\ &= w^2 (c + y)^2 = w^2 Y^2 \end{aligned}$$

or

$$T = wY.$$

Thus the form taken by the chain is that for which the equation is

$$m \quad Y = c \cosh \left(\frac{y}{c} \right) \quad \text{the equation of the catenary: the}$$

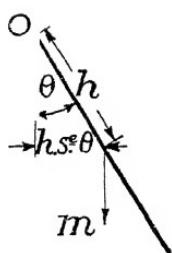


FIG. 119.

length of arc is given by $s = c \sinh \frac{y}{c}$, and the tension at any point is measured by the product of the ordinate at that point and the weight per foot of the chain.

Fig. 118 shows the catenary for a cable weighing 3.5 lbs. per foot and strained to a tension of 40 lbs. weight, and the method of calculation for the construction of this curve is explained on p. 358 of Part I.

The tension at 10 ft. from the centre = 3.5×15.9
= 55.6 lbs. weight, since the ordinate there is 15.9.

Example 23.—To find the time of oscillation of a compound pendulum swinging through small arcs.

Let I be the moment of inertia of the pendulum about an axis, through the point of suspension O (Fig. 119), and let h = the distance of the C. of G. from the point of suspension.

Then the couple acting, to produce the angular acceleration, = moment of inertia \times angular acceleration.

[Compare the rule for linear motion, Force = mass \times acceleration.]

Now the angular velocity $= \frac{d\theta}{dt}$

and hence the angular acceleration

$$= \frac{d^2\theta}{dt^2}.$$

Thus the couple acting = $I \frac{d^2\theta}{dt^2}$

and this couple is opposed by one whose arm is $h \sin \theta$, as is seen in the figure.

Thus $I \frac{d^2\theta}{dt^2} = -mh \sin \theta = -mh\theta$

since θ is supposed to be small, and consequently $\sin \theta = \theta$

or $\frac{d^2\theta}{dt^2} = -\frac{m}{I}\theta = -\omega^2\theta \quad \text{if} \quad \omega^2 = \frac{m}{I}$

and $\frac{d^2\theta}{dt^2} + \omega^2\theta = 0.$

This equation is of the type dealt with in *Case (3)*, p. 283, and the solution is $\theta = A \sin(\omega t + B)$.

The period of this function is $\frac{2\pi}{\omega}$; also the couple for angular displacement $\theta = mh\theta$; hence the couple for unit angular displacement (denoted by μ) = mh .

$$\text{Hence } t = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{I}{mh}} = 2\pi \sqrt{\frac{I}{\mu}}.$$

$$\text{or } t = 2\pi \sqrt{\frac{I}{\mu g}} \text{ if engineers' units are used.}$$

This might be written in the easily remembered form,

$$t = 2\pi \sqrt{\frac{I}{\text{unit moment of inertia per unit twist}}}.$$

If this formula is to be used in the determination of the modulus of rigidity of a sample of wire by means of torsional oscillations, h must be replaced by l , the length of the wire.

If f = skin stress, T = torque, and C = modulus of rigidity, d = dia. of wire; then

$$\theta = \frac{2fl}{Cd} \text{ and } T = \frac{\pi}{16} f d^3$$

$$\text{whence } \frac{32Tl}{\pi d^4 C}$$

$$\text{but } \mu = \frac{\pi d^4 C}{32l}$$

$$\text{and } t = 2\pi \sqrt{\frac{I}{\mu g}} \\ = 2\pi \sqrt{\frac{32lI}{\pi d^4 C g}}$$

$$\text{hence } C = \frac{128\pi l I}{g d^4 t^2} \text{ and thus } C \text{ can be determined.}$$

As regards the units, if l is in feet, I is in lbs. ft.², t in secs., and d in feet,

$$\text{then } C = \frac{\text{feet} \times \text{lbs.} \times \text{ft.}^2 \times \text{sec.}^2}{\text{feet} \times \text{ft.}^4 \times \text{sec.}^2}$$

$$= \frac{\text{lbs.}}{\text{ft.}^2}, \text{ i. e., } C \text{ is in lbs. per sq. foot.}$$

If I is in lbs. ins.² and d is in ins., then C will be in lbs. per sq. in.

Example 24.—To find formulæ giving the radial and hoop stresses in thick cylinders subjected to internal stress.

We may attack this problem by either of two methods:—

Method 1.—In (a) Fig. 120 let the outside radius = r_1 and the inside radius = r_0 ; also let the internal pressure be p , and the crushing stress at right angles to the radii, or the hoop stress, = q .

It is rather easier to consider the stress on the outside to be greater than that on the inside: thus for an annulus of radius r and thickness δr , we take the internal stress as p and the external stress as $p + \delta p$.

Considering the element RS of the annulus (subtending an angle of $\delta\theta$ at the centre), and dealing with the radial forces,

$$\begin{aligned}\text{Total radial force} &= (p + \delta p) \times \text{outer arc} - p \times \text{inner arc} \\ &= (p + \delta p) \times (r + \delta r)\delta\theta - p r \delta\theta \\ &= (pr + p\delta r + r\delta p + \delta p \cdot \delta r - pr) \delta\theta \\ &= (\delta p \delta r + r \delta p + \delta p \cdot \delta r) \delta\theta\end{aligned}$$

(for a unit length of the cylinder).

This is balanced by two forces each $q \delta r \cdot \delta\theta$, for

$$\frac{z}{q \delta r} = \sin \frac{\theta}{2} = \frac{\theta}{2} \text{ nearly} \quad [(b) \text{ Fig. 120}]$$

$$\text{i.e.,} \quad z = q \delta r.$$

z being the radial force.

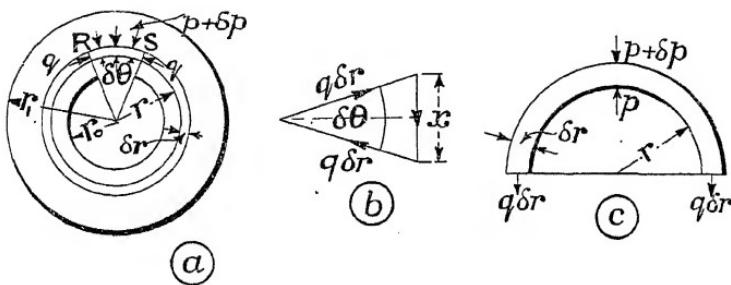


FIG. 120.—Stresses in Thick Cylinders.

$$\text{Thus} \quad .(p \delta r + r \delta p + \delta p \cdot \delta r) \delta\theta = q \delta r \cdot \delta\theta$$

or, when δr is very small,

$$p dr + r dp = q dr.$$

Assume each longitudinal fibre to lengthen the same amount due to the secondary strains.

Then if σ = Poisson's ratio and E = Young's modulus for the material,

$$\text{the extension due to } p \text{ will be } \frac{p}{E} \times \frac{1}{\sigma}$$

$$\text{and the extension due to } q \text{ will be } \frac{q}{E} \times \frac{1}{\sigma}$$

then, since the total extension is to be constant,

$$(p + q) \frac{1}{\sigma E} = \text{constant},$$

$p + q = 2A$, say, for σ and E are constants.

$$\begin{aligned} \text{Hence } r dp + p dr &= q dr \\ &= (2A - p) dr \\ \text{i.e., } r dp &= 2(A - p) dr. \end{aligned}$$

Separating the variables and integrating,

$$\begin{aligned} \int \frac{dp}{2(A-p)} &= \int \frac{dr}{r} \\ \text{i.e., } -\frac{1}{2} \log(A-p) + \log C &= \log r \\ \text{or } r &= \frac{C}{(A-p)^{\frac{1}{2}}} \\ (A-p)^{\frac{1}{2}} &= \frac{C}{r} \\ A-p &= \frac{C^2}{r^2} \\ \text{or } p &= A + \frac{B}{r^2} \end{aligned}$$

but

$$p + q = 2A$$

and hence

$$q = A - \frac{B}{r^2}$$

The constants A and B are found from the conditions stated in any example.

Method 2.—According to this scheme q is taken as a tensile stress.

By the thin cylinder theory;—consider the equilibrium of the half elementary ring of unit length [(c) Fig. 120].

$$\text{Then } (p \times 2r) - (p + \delta p) 2(r + \delta r) = 2q \delta r$$

$$\text{whence } q dr = -p dr - r dp.$$

From this point the work is as before except that $2A$ is written for $p - q$ and not for $p + q$ as in *Method 1.*

Example 25.—To find expressions for the stresses in Thick Spherical Shells.

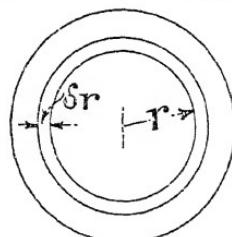


FIG. 121.

Let p = the radial pressure, q = the hoop tension.

Take an elementary shell at radius r , the thickness being δr (Fig. 121).

$$\text{Then } \pi r^2 p - \pi (r + \delta r)^2 (p + \delta p) = 2\pi r q \delta r.$$

$$\pi r^2 p - \pi r^2 p - \pi p (\delta r)^2 - 2\pi r \delta r p - \pi r^2 \delta p - \pi \delta p (\delta r)^2 - 2\pi r \delta r \cdot \delta p = 2\pi r \delta r q.$$

When δr is very small this equation reduces to

$$-2p \delta r - r \delta p = 2q \delta r$$

and hence

$$2q = -2p - r \frac{dp}{dr}.$$

Assuming the volumetric strain to be the same everywhere,

$$2l_y + l_x = C$$

where l_y = the circumferential strain, and thus $2l_y$ = the superficial strain, and l_x = the radial strain,

then it follows that

$$\frac{2q}{\sigma E} - \frac{p}{\sigma E} = C$$

$$i.e., \quad 2q - p = \text{Constant} = 3A \text{ (say).}$$

Now

$$2q = -2p - r \frac{dp}{dr}$$

$$\therefore \quad 3A + p = -2p - r \frac{dp}{dr}$$

$$i.e., \quad 3(A + p) = -r \frac{dp}{dr}.$$

Separating the variables and integrating,

$$\int -\frac{dr}{r} = \int \frac{dp}{3(A + p)}$$

$$i.e., \quad -\log r = \frac{I}{3} \log (A + p) + \log C_1$$

$$\text{whence } (A + p)^{\frac{I}{3}} = \frac{C_1 r}{C_1 r}$$

or

$$A + p = \frac{C_1^{\frac{3}{I}} r^3}{C_1}$$

$$i.e., \quad p = \frac{I}{C_1^{\frac{3}{I}} r^3} - A = \frac{2B}{r^3} - A \text{ (say).}$$

Also

$$2q = 3A + p$$

$$= 3A + \frac{2B}{r^3} - A = 2A + \frac{2B}{r^3}$$

$$i.e., \quad q = \frac{B}{r^3} + A.$$

Euler's Formulae for Loaded Struts.

Example 26.—To obtain a formula giving the buckling load for a strut of length L and moment of inertia I.

Applying the ordinary rule

$$\frac{M}{I} = E \frac{d^2y}{dx^2}$$

Bending moment at $Q = M = -Py$ [(a) Fig. 122]

$$\therefore IE \frac{d^2y}{dx^2} = -Py$$

$$i.e., \frac{d^2y}{dx^2} = -\frac{P}{IE}y.$$

$$\text{Let } \frac{P}{IE} = \omega^2$$

$$\text{then } \frac{d^2y}{dx^2} + \omega^2y = 0$$

and the solution of this equation is, according to Case (3), p. 283,

$$y = A \sin (\omega x + B).$$

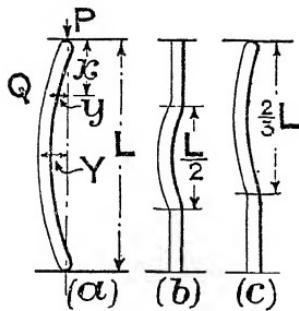


FIG. 122.

The various conditions of end fixing give rise to the following solutions:—

Case of ends rounded.—When $x = 0, y = 0$

$$\text{then } 0 = A \sin (0+B) \quad \text{and } A \text{ is not zero}$$

$$\text{so that } B = 0.$$

$$\text{When } x = \frac{\omega L}{2}, y = Y \quad [(a) \text{Fig. 122}]$$

$$i.e., Y = A \sin \frac{\omega L}{2}$$

Obviously Y is the amplitude, i.e., $A = Y$

$$1 = \sin \frac{\omega L}{2}.$$

Thus we may write $\sin \frac{\omega L}{2} = \sin \frac{\pi}{2}$ ($\frac{\pi}{2}$ being the simplest angle having its sine = 1)

$$\text{whence } \omega L = \pi$$

$$\text{and } \frac{P}{IE} \times L = \pi$$

$$\text{or } P = \frac{\pi^2 IE}{L^2}.$$

Case of both ends fixed.—The form taken by the column is as at (b) Fig. 121. The half-period of the curve is evidently $\frac{L}{2}$ in this case.

$$\text{But the period} = \frac{2\pi}{\omega}.$$

$$L = \frac{2\pi}{\omega} = \sqrt{\frac{P}{IE}}$$

$$\text{whence } P = \frac{4\pi^2 IE}{L^2}.$$

Case of one end fixed.—The form taken by the column is as at (c) Fig. 122. The half-period in this case is $\frac{2}{3}L$, but, as before proved, the period is given by $\frac{2\pi}{\omega}$.

$$\text{Hence } \frac{4}{3}L = \frac{2\pi}{\omega}$$

$$\text{or } L = \frac{3\pi}{2\omega}.$$

$$\text{Now } \omega = \sqrt{\frac{P}{IE}}$$

$$\therefore L^2 = \frac{9\pi^2 IE}{4P}$$

$$\text{or } P = \frac{9\pi^2 IE}{4L^2}.$$

Tension in Belt passing round a Pulley.

Example 27.—To compare the tensions T_1 and T_2 at the ends of a belt passing round a pulley; the coefficient of friction between the belt and pulley being μ , and the angle of lap being θ radians.

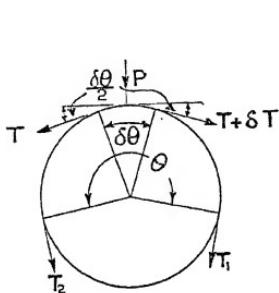


FIG. 123.

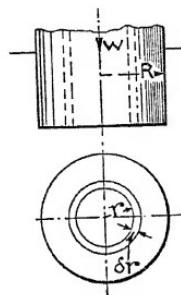


FIG. 124.

Consider a small element of belt subtending an angle of $\delta\theta$ at the centre of the pulley (see Fig. 123): then the tensions at the ends are respectively $T+\delta T$ and T .

Resolving the forces horizontally

$$(T + \delta T) \cos \frac{\delta\theta}{2} - T \cos \frac{\delta\theta}{2} = \mu P$$

$$\text{i. e.,} \quad \delta T \cos \frac{\delta\theta}{2} = \mu P$$

$$\text{or in the limit} \quad dT = \mu P \quad \dots \quad (1)$$

$$\text{for } \cos \frac{\delta\theta}{2} \rightarrow \cos 0, \text{ i. e., 1.}$$

Resolving the forces vertically,

$$P = (T + \delta T + T) \sin \frac{\delta\theta}{2}$$

$$= 2T \sin \frac{\delta\theta}{2} + \delta T \sin \frac{\delta\theta}{2}$$

$$= 2T \frac{\delta\theta}{2} + \delta T \frac{\delta\theta}{2} \quad (\text{for } \sin \frac{\delta\theta}{2} = \frac{\delta\theta}{2} \text{ when the angle is small})$$

$$\text{In the limit} \quad P = T d\theta. \quad \dots \quad (2)$$

Then, combining equations (1) and (2),

$$dT = \mu T d\theta$$

$$\text{Separating the variables, } \int_{T_2}^{T_1} \frac{dT}{T} = \mu \int_0^\theta d\theta$$

$$\text{Integrating,} \quad \log_e \frac{T_1}{T_2} = \mu \theta$$

$$\text{or} \quad \frac{T_1}{T_2} = e^{\mu \theta}$$

Friction in a Footstep Bearing.

Example 28.—To find the moment of the friction force in a footstep bearing; the coefficient of friction being μ , R = radius of journal and W = total load.

(a) Assume that the pressure is uniform over the bottom surface, i. e., $W = \pi R^2 p$, where p is the intensity of the pressure.

Take an annulus at radius r , and of thickness δr (Fig. 124).

$$\text{Area of the annulus} = 2\pi r \delta r$$

$$\text{Pressure on the annulus} = 2\pi r \delta r p$$

$$\text{Friction force on the annulus} = 2\pi r \delta r \mu p$$

and hence the moment of the friction force on the annulus

$$= 2\pi r \delta r \mu p \times r$$

and the total moment of the friction force

$$\begin{aligned} &= \int_0^R \mu p 2\pi r^2 dr \\ &= 2\pi\mu p \frac{R^3}{3} \\ &= \frac{2}{3}\pi\mu R^3 \cdot \frac{W}{\pi R^2} \\ &= \frac{2}{3}R \times \mu W \end{aligned}$$

i.e., the moment is the same as it would be if the whole load were supposed concentrated at a distance of two-thirds of the radius from the centre.

(b) Assume that the intensity of pressure varies inversely as the velocity,

$$i.e., \quad p = K \times \frac{I}{v}$$

$$\text{the velocity at radius } r = v_r = 2\pi nr$$

$$\text{so that} \quad p = K \times \frac{I}{2\pi nr} = \frac{m}{r} \text{ (say).}$$

Then the pressure intensity on an annulus distant r from the centre

$$= p = \frac{m}{r}$$

and the total pressure on the annulus

$$= 2\pi r \delta r \times \frac{m}{r}$$

$$= 2\pi m \delta r$$

$$\text{also the friction force} \quad = \mu \times \text{this pressure.}$$

Hence the moment of the friction force on the annulus

$$= 2\pi m \mu r \delta r$$

and the total moment of the friction force

$$= \int_0^R 2\pi \mu m r dr$$

$$= \frac{2\pi \mu m R^2}{2}$$

$$\text{Now the total load } W = \int_0^R \text{intensity} \times \text{area}$$

$$= \int_0^R p \times 2\pi r dr$$

$$= \int_0^R \frac{2\pi r dr \times m}{r}$$

$$= 2\pi m R.$$

Hence the moment of the friction force

$$= 2\pi mR \times \frac{\mu R}{2}$$

$$= \mu W \times \frac{R}{2}$$

i.e., the effective radius is now $\frac{1}{2}$ and not $\frac{2}{3}$, as in Case (a).

Example 29.—To find an expression for the moment of the friction force for a Schiele Pivot.

Assume that the pressure is the same all over the rubbing surface, that the wear is uniform and that the normal wear is proportional to the pressure p and to the speed v .

Referring to Fig. 125, δn = normal wear $\propto p v$, i.e., $2\pi n r p$, and thus $\delta n \propto p r$ or $\delta n = K p r$.

Let the tangent at the point P make the angle θ with the axis, then if t = length of tangent, $t \sin \theta = r$.

Now $\delta h = \text{vertical drop} = \frac{\delta n}{\sin \theta}$

or $\delta n = \delta h \sin \theta$

Also $\delta n = K p r = K p t \sin \theta$

whence $\delta h = K p t$.

Now δh is constant, p and K are constant; hence t must be constant and the curve is that known as a tractrix (i.e., the length of the tangent from the axis to any point on the curve is a constant).

To find the moment of the friction force:—

On a small element of surface, the friction force

$$= 2\pi r \delta s \times p \times \mu$$

and the moment of the friction force

$$= 2\pi r \delta s \mu p \times r.$$

Now $\delta r = \delta s \sin \theta$.

Hence the total moment of the friction force

$$\begin{aligned} &= \int_{R_1}^{R_2} 2\pi \mu p r \frac{dr}{\sin \theta} t \sin \theta \\ &= 2\pi \mu p t \times \frac{1}{2}(R_1^2 - R_2^2) \end{aligned}$$

but $p = \frac{W}{\pi(R_1^2 - R_2^2)}$

Hence the total moment of the friction force = $\mu W t$.

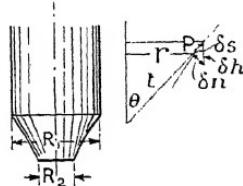


FIG. 125.

Examples on Hydraulics.

Example 30.—To find the time to empty a tank, of area A sq. ft., through an orifice of area a sq. ft., the coefficient of discharge being C_d .

If the height of the water above the orifice at any time is h , then the velocity of discharge $= v = \sqrt{2gh}$.

Hence the quantity per sec. $= C_d av$

and the quantity in time $\delta t = C_d av\delta t$.

This flow will result in a lowering of the level in the tank by an amount δh , so that the volume taken from the tank in time $\delta t = A \delta h$.

Hence $A \delta h = C_d a \sqrt{2g} h \delta t$.

Here we have a simple differential equation to solve, and separating the variables and integrating

$$\int_0^t dt = \int_{h_1}^{h_2} \frac{Adh}{C_d a \sqrt{2g} h^{\frac{1}{2}}} \quad \text{where } h_2 = \text{initial height}$$

$$h_1 = \text{final height}$$

$$t = \frac{A}{a} \times \frac{1}{C_d \sqrt{2g}} \times 2 \left\{ \sqrt{h_2} - \sqrt{h_1} \right\}$$

$$\frac{2A}{C_d a \sqrt{2g}} \left\{ h_2^{\frac{1}{2}} - h_1^{\frac{1}{2}} \right\}.$$

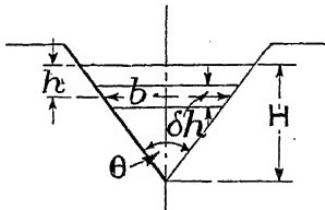


FIG. 126.—Triangular Notch.

If $h_1 = 0$, then the time to completely empty the tank

$$= \frac{2A\sqrt{h}}{C_d a \sqrt{2g}}.$$

Example 31.—To gauge the flow of water by measurements with a triangular notch.

Let the height at the notch be H , and consider a small element of width b , thickness δh , and height above the apex of the notch $(H-h)$.

From Fig. 126, $\frac{b}{2} = (H-h) \tan \frac{\theta}{2}$ where θ = the angle of the notch,

$$\text{whence } b = 2(H-h) \tan \frac{\theta}{2}.$$

Now the area of the element = $b \delta h$

and the velocity of water at that height = $\sqrt{2g} \times \text{height} = \sqrt{2gh}$.

Hence the actual quantity flowing = $C_d \times 2(H-h) \tan \frac{\theta}{2} \times \sqrt{2g} h^{\frac{1}{2}} \delta h$
and the total quantity flowing for the height H

$$\begin{aligned} &= \int_0^H 2\sqrt{2g} C_d \tan \frac{\theta}{2} (H-h)^{\frac{1}{2}} h^{\frac{1}{2}} dh \\ &= 2\sqrt{2g} C_d \tan \frac{\theta}{2} \int_0^H (Hh^{\frac{1}{2}} - h^{\frac{3}{2}}) dh \\ &= 2\sqrt{2g} C_d \tan \frac{\theta}{2} \left(\frac{2}{3} H^{\frac{5}{2}} - \frac{2}{5} H^{\frac{3}{2}} \right) \\ &= \frac{8}{15} \sqrt{2g} C_d \tan \frac{\theta}{2} H^{\frac{3}{2}}. \end{aligned}$$

If $\theta = 90^\circ$ (a common case), $\tan \frac{\theta}{2} = 1$,

and then the discharge = $\frac{8}{15} \sqrt{2g} C_d H^{\frac{3}{2}} = 2.66 H^{\frac{3}{2}}$ if $C_d = .62$.

Example 32.—To estimate the friction on a wheel disc revolving in a fluid.

Let the friction per sq. ft. = $f v^x$ and let the disc (of inside radius R_2 and outside radius R_1) revolve at n revs. per sec.

The velocity of an annulus at radius $r = 2\pi n r$

and thus the friction force per sq. ft. on this annulus
 $= (2\pi n r)^x f$.

Hence the moment of the friction force on the annulus

$$\begin{aligned} &= f (2\pi n r)^x \times 2\pi n \delta r \times r \\ &= f \times (2\pi)^{x+1} n^{x+1} r^{x+2} \delta r \end{aligned}$$

and the total moment of the friction force on one side of the disc = M

$$\begin{aligned} &= \int_{R_2}^{R_1} f \times (2\pi)^{x+1} n^{x+1} r^{x+2} dr \\ &= \frac{f \times (2\pi)^{x+1} \times n}{x+3} [R_1^{x+3} - R_2^{x+3}]. \end{aligned}$$

The total moment (*i. e.*, on the two sides) = 2M

$$\text{and H.P. lost in friction} \quad = \frac{4\pi n M}{550}.$$

If

$$x = 2$$

$$\begin{aligned} M &= \frac{f \times (2\pi)^3 \times n^2}{5} [R_1^5 - R_2^5] \\ &= 49.6 f n^2 [R_1^5 - R_2^5]. \end{aligned}$$

Example 33.—To establish a general rule for determining the depth of the Centre of Pressure of a section below the S.W.S.L. (still water surface level).

Suppose the plate (representing a section) is placed as shown in Fig. 127. Consider a small element of area δa , distant x from OY, the vertical distance being h .

Let \bar{X} = distance of the C. of G. from OY,

\bar{x} = distance of the C. of P. from OY,

and let \bar{H} and \bar{h} be the corresponding vertical distances.

Let P = total pressure and A = total area,

k = swing radius about OY,

and ρ = weight of 1 cu. ft. of water.

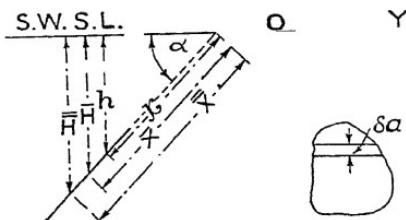


FIG. 127.—Centre of Pressure.

The whole pressure on the element

$$\begin{aligned} &= \text{intensity of pressure} \times \text{area} = \rho h \times \delta a \\ &= \rho x \sin a \delta a. \end{aligned}$$

Whole pressure on surface = $\Sigma \rho x \sin a \delta a$ approx.

or $\int \rho x \sin a da$ actually,

$$\begin{aligned} i.e., \quad P &= \rho \sin a \times \int x da \\ &= \rho \sin a \times \text{1st moment of area about OY} \\ &= \rho \sin a \times A \bar{X}, \end{aligned}$$

but $\bar{X} \sin a = \bar{H}$.

$$P = \rho \bar{H} A.$$

To find the position of the C. of P., take moments about OY.

$$\begin{aligned} \text{Then } P \times \bar{X} &= \Sigma \text{moments of the pressures on the elements} \\ &= \Sigma \rho \sin a x \delta a \times x \\ &= \rho \sin a \Sigma x^2 \delta a \text{ approx.} \\ &= \rho \sin a \int x^2 da \text{ actually} \\ &= \rho \sin a \times \text{2nd moment about OY} \\ &= \rho \sin a \times A k^2. \end{aligned}$$

Now

$$P = \rho \bar{H} A$$

so that

$$\rho \bar{H} A \bar{\bar{X}} = \rho \sin \alpha \Delta k^2,$$

i. e.,

$$\bar{H} \bar{\bar{X}} = \sin \alpha \cdot k^2$$

but

$$\bar{H} = \bar{X} \sin \alpha$$

hence

$$\bar{X} \bar{\bar{X}} = k^2.$$

Thus if \bar{X} is known, $\bar{\bar{X}}$ can be calculated.If the body is not symmetrical, then $\bar{\bar{Y}}$ (the distance of the C. of P. from OX) must be found by taking moments about OX.In a great number of cases $\alpha = 90^\circ$, so that $\sin \alpha = 1$, and thus

$$\bar{H} \times \bar{\bar{H}} = k^2.$$

Example 34.—A triangular plate is placed with its base along the S.W.S.L., the plate being vertical. Find the depth of the centre of pressure below the surface.

$$\text{For this section, } I \text{ about S.W.S.L.} = \frac{1}{12} b h^3$$

and thus

$$k^2 = \frac{\frac{1}{12} b h^3}{\frac{1}{2} b h} = \frac{h^2}{6}$$

also

$$\bar{H} = \frac{1}{3} h.$$

Hence

$$\bar{\bar{H}} = \frac{k^2}{\bar{H}} = \frac{h^2 \times 3}{6 \times h} = \frac{h}{2}$$

Example 35.—A circular plate has its upper edge along the S.W.S.L. Find the depth of its Centre of Pressure below the S.W.S.L.

For a circle,

$$I_{\text{diam.}} = \frac{\pi}{64} d^4$$

and thus

$$k^2 \text{ about diam.} = \frac{\frac{\pi}{64} d^4}{\frac{\pi}{4} d^2} = \frac{d^2}{16}$$

and hence, by the parallel axis theorem,

$$k^2 \text{ about S.W.S.L.} = \frac{d^2}{16} + \left(\frac{d}{2}\right)^2 = \frac{5d^2}{16}$$

also

$$\bar{H} = \frac{d}{2}$$

Hence

$$\bar{\bar{H}} = \frac{k^2}{\bar{H}} = \frac{\frac{5d^2}{16}}{\frac{d}{2}} = \underline{\underline{\frac{5d}{8}}}$$

Example 36.—Forced vortex (*i. e.*, water in a tube rotated round a vertical axis). To find the form taken by the surface of the water.

Let the rotation be at n R.P.S.

Consider an element at P (Fig. 128).

Then $\tan \theta = \text{the slope of the curve taken} = \frac{dy}{dh}$

and also $\tan \theta = \frac{\text{vertical force}}{\text{horizontal force}} = \frac{\text{weight of particle}}{\text{centrifugal force on particle}}$

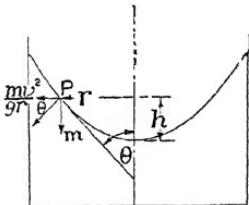


FIG. 128.—Forced Vortex.

$$= \frac{m \times g r}{m v^2}$$

$$= \frac{g r}{v^2}$$

$$= \frac{g r}{(2\pi n r)^2}$$

$$= \frac{g}{4\pi^2 n^2 r}$$

$$\text{thus } \frac{dy}{dh} = \frac{g}{4\pi^2 n^2 r}$$

Separating the variables

$$4\pi^2 n^2 r dr = g dh.$$

Integrating

$$\frac{4\pi^2 n^2 r^2}{2} = gh.$$

$$h = \frac{2\pi^2 n^2}{g} \times r^2.$$

Now $\frac{2\pi^2 n^2}{g}$ is a constant, and thus

$h = \text{constant} \times r^2$, this being the equation of a parabola.

Hence the surface of the liquid will be that of a paraboloid of revolution.

An Example from Surveying.

Example 37.—Prove that a cubic parabola is a suitable “transition” curve.

In order that the full curvature of a railway curve may be approached gradually, a curve known as a transition curve is interposed between the straight and the curve. It must be so designed that the radius of curvature varies inversely as the distance from the starting point (on the straight, because there the radius is infinite).

As before proved,

$$\frac{1}{R} = \frac{d^2 y}{dx^2}$$

or more exactly

$$\frac{d^2 y}{dx^2} = \frac{1}{\left(1 + \left(\frac{dy}{dx}\right)^2\right)^{\frac{3}{2}}}$$

For the cubic parabola we may assume an equation

$$y = px^3,$$

where x is the distance from the straight, along a tangent, and y is the offset there (obviously p must be very small).

If $y = px^3$, $\frac{dy}{dx} = 3px^2$, $\frac{d^2y}{dx^2} = 6px$.

Hence $\frac{I}{R} = \frac{6px}{(1+9p^2x^4)} = 6px(1+9p^2x^4)^{-\frac{1}{2}}$
 $= 6px(1-13.5p^2x^6)$

as a first approximation, or $\frac{I}{R} = 6px$ nearly (for p^3 is very small).

Hence $\frac{I}{R} = 6px$ or $R = \frac{I}{6p} \times \frac{1}{x} = \frac{K}{x}$

or $R \propto \frac{1}{x}$.

Exercises 23.

1. A cylindrical tank is kept full of water by a supply. Show that the time required to discharge a quantity of water, equal to the capacity of the tank, through an orifice in the bottom equals half the time required to empty the tank when the supply is cut off.

A tank 10 ft. high and 6 ft. diam. is filled with water. Find the theoretical time of discharge through an 8" diam. orifice in the bottom.

2. A tank empties through a long pipe discharging into the air. If the head lost in the pipe is written $h_l = \frac{Kv^2}{2g}$, show that K can be found from the expression,

$$t_1 - t_2 = 2 \frac{A}{\pi} \sqrt{\frac{1+K}{2g}} (h_1^{\frac{1}{2}} - h_2^{\frac{1}{2}})$$

where h_1 is the level of the water in the tank at the time t_1 and h_2 is the level of the water in the tank at the time t_2 measured from the centre of the discharge end of the pipe.

A = area of cross section of the tank.

a = area of cross section of the pipe.

An experiment with a tank 15.6 sq. ft. in cross section and a 4" diam. pipe gave the following results:

Time, t mins.	Level in tank, h .
0	38.35
1	32.84
2	27.82
3	23.19
4	19.02

Find the value of K for the pipe.

3. Use the following table to obtain $\frac{dP}{dT}$ and thence find the volume of 1 lb. of steam at 160 lbs. absolute pressure per sq. in.

Absolute press. (lbs. per sq. in.)	159	160	161
	363.1	363.6	364.1

The latent heat of 1 lb. of steam at 160 lbs. per sq. in. pressure is 858.8 B.Th.U.

4. Find the "fixing moments" for a beam built in at its ends and 40 feet long, when it carries loads of 8 tons and 12 tons, acting 15 feet and 30 feet respectively from one end.

5. A tank of constant cross section has two circular orifices, each 2" diam., in one of its vertical sides, one of which is 20 ft. above the bottom of the tank and the other 8 ft.

Find the time required to lower the water from 30 ft. down to 15 ft. above the bottom of the tank.

Cross section of the tank = 12 sq. ft.

Coefficient of discharge = .62.

6. A hemispherical tank 12 ft. in diam. is emptied through a hole 8" diam. at the bottom. Assuming that the coefficient of discharge is .6, find the time required to lower the level of the water surface from 6 ft. to 4 ft.

7. A vertical shaft having a conical bearing is 9" in diam. and carries a load of $3\frac{1}{2}$ tons; the angle of the cone is 120° and the coefficient of friction is .025. Find the horse power lost in friction when the shaft is making 140 revolutions per minute.

Assume that the intensity of pressure is uniform.

8. A circular plate, 5 ft. diam., is immersed in water, its greatest and least depths below the surface being 6 ft. and 3 ft. respectively; find

(a) the total pressure on one face of the plate,

(b) the position of the centre of pressure.

9. An annular plate is submerged in water in such a position that the minimum depth of immersion is 4 ft. and the maximum depth of immersion is 8 ft. If the external diam. of the plate is 8 ft. and the internal diam. 4 ft., determine the total pressure on one face of the plate and the position of the centre of pressure.

10. One pound of steam at 100 lbs. per sq. in. absol. (vol. = 4.45 cu. ft.) is admitted to a cylinder and is then expanded to a ratio of 5, according to the law $Pv^{1.06} = C$; it is then exhausted at constant pressure.

Find the net work done on the piston.

11. Find the loss of head h in a length l of pipe the diameter of which varies uniformly, being given that

$$H = \frac{4fLv^2}{2gd}, \text{ and } v = \frac{4Q}{\pi d^2}.$$

{Let diam. at distance x from entry end = $d_e + Kx$

where d_e = diam. at entry}.

12. Taking the friction of a brass surface in a fluid as .22 lb. per sq. ft. for a velocity of 10 f.p.s. and as proportional to $v^{1.9}$, find the horse power lost in friction on two sides of a brass disc 30" external and 15" internal diam. running at 500 r.p.m.

13. A rectangular plate 2 ft. wide by 5 ft. deep is immersed in water at an inclination of 40° to the vertical. Find the depth of the centre of pressure, if the top of the plate is 6 ft. below the level of the water.

CHAPTER XI

HARMONIC ANALYSIS

Fourier's Theorem relates to periodic functions, of which many examples are found in both electrical and mechanical engineering theory and practice: it states that any periodic function can be expressed as the sum of a number of sine functions, of different amplitudes, phases and periods. Thus, however irregular the curve representing the function may be, so long as its ordinates repeat themselves after the same interval of time or space, it is possible to resolve it into a number of sine curves, the ordinates of which when added together give the ordinates of the primitive curve. This resolution of a curve into its component sine curves is known as *Harmonic Analysis*; and in view of its importance, the simpler and most direct methods employed for the analysis are here treated in great detail.

Expressed in mathematical symbols, Fourier's theorem reads

$$y = f(t) = A_0 + B \sin(qt + c_1) + C \sin(2qt + c_2) + \dots$$

or $y = A_0 + A_1 \sin qt + A_2 \sin 2qt + A_3 \sin 3qt + \dots$
 $+ B_1 \cos qt + B_2 \cos 2qt + B_3 \cos 3qt + \dots$

the latter form being equivalent to the first, since

$$A_1 \sin qt + B_1 \cos qt = B \sin(qt + c_1)$$

provided that B and c_1 are suitably chosen.

For the purposes of the analysis the expression may appear simpler if we write θ in place of qt .

Thus

$$y = A_0 + A_1 \sin \theta + A_2 \sin 2\theta + A_3 \sin 3\theta + \dots$$
 $+ B_1 \cos \theta + B_2 \cos 2\theta + B_3 \cos 3\theta + \dots$

Of the various methods given, three are here selected and explained, these being easy to understand and to apply.

Dealing with the three processes in turn, viz., (a) by calculation, (b) by a graphical interpretation of method (a), and (c) by superposition, we commence with the study of method (a).

Method (a): Analysis by Calculation.—Before actually proceeding to detail the scheme of working, it is well to verify the following statements.

$\int_0^{2\pi} \cos \theta = 0$, this being self-evident, since the area under a cosine curve is zero, provided that the full period is considered.

$$\int_0^{2\pi} \cos m\theta \cos n\theta d\theta = 0 \quad \dots \dots \dots \dots \dots \quad (1)$$

for

$$\cos m\theta \cos n\theta = \frac{1}{2}[\cos(m+n)\theta + \cos(m-n)\theta]$$

and hence

$$\begin{aligned} \int_0^{2\pi} \cos m\theta \cos n\theta d\theta &= \frac{1}{2} \int_0^{2\pi} \cos(m+n)\theta d\theta + \frac{1}{2} \int_0^{2\pi} \cos(m-n)\theta d\theta \\ &= 0+0 \end{aligned}$$

(for both are cosine curves over the full period or a multiple of the full period).

$$\begin{aligned} \int_0^{2\pi} \cos m\theta \sin n\theta d\theta &= \frac{1}{2} \int_0^{2\pi} \sin(m+n)\theta d\theta - \frac{1}{2} \int_0^{2\pi} \sin(m-n)\theta d\theta \\ &= 0 \quad \dots \dots \dots \dots \quad (2) \end{aligned}$$

$$\begin{aligned} \int_0^{2\pi} \cos^2 \theta d\theta &= \frac{1}{2} \int_0^{2\pi} \cos 2\theta d\theta + \frac{1}{2} \int_0^{2\pi} d\theta \\ &= 0 + \frac{1}{2}(2\pi - 0) = \pi \quad \dots \dots \dots \quad (3) \end{aligned}$$

$$\begin{aligned} \int_0^{2\pi} \sin m\theta \sin n\theta d\theta &= \frac{1}{2} \int_0^{2\pi} \cos(m-n)\theta d\theta - \frac{1}{2} \int_0^{2\pi} \cos(m+n)\theta d\theta \\ &= \frac{1}{2}\{0-0\} = 0 \quad \dots \dots \dots \quad (4) \end{aligned}$$

and

$$\begin{aligned} \int_0^{2\pi} \sin^2 \theta d\theta &= \frac{1}{2} \int_0^{2\pi} d\theta - \frac{1}{2} \int_0^{2\pi} \cos 2\theta d\theta \\ &= \frac{1}{2}\{2\pi - 0\} - 0 \\ &= \pi \quad \dots \dots \dots \quad (5) \end{aligned}$$

To proceed with the analysis:—

We are told that

$$\begin{aligned} y &= A_0 + A_1 \cos \theta + A_2 \cos 2\theta + A_3 \cos 3\theta + \dots \\ &\quad + B_1 \sin \theta + B_2 \sin 2\theta + B_3 \sin 3\theta + \dots \end{aligned}$$

and we wish to find the values of the coefficients $A_0, A_1 \dots, B_1, B_2$, etc.

If we integrate throughout (with the limits 0 and 2π), every term on the right-hand side, except the first, will vanish,

$$\text{i.e., } \int_0^{2\pi} y d\theta = A_0 \int_0^{2\pi} d\theta + 0 + 0 + \dots$$

$$\text{or } \int_0^{2\pi} y d\theta = A_0 \times (2\pi - 0)$$

$$\text{whence } A_0 = \frac{1}{2\pi - 0} \int_0^{2\pi} y d\theta$$

= the mean value of y (Cf. p. 183)

so that A_0 is found by averaging the ordinates; but in the majority of cases an inspection will show that A_0 is zero.

To find A_1 :—multiply throughout by its coefficient, viz., $\cos \theta$, and integrate, then

$$\begin{aligned} \int_0^{2\pi} y \cos \theta d\theta &= \int_0^{2\pi} A_0 \cos \theta d\theta + \int_0^{2\pi} A_1 \cos^2 \theta d\theta + \int_0^{2\pi} A_2 \cos \theta \cos 2\theta d\theta + \dots \\ &\quad + \int_0^{2\pi} B_1 \cos \theta \sin \theta d\theta + \int_0^{2\pi} B_2 \cos \theta \sin 2\theta d\theta + \dots \end{aligned}$$

$$\text{or } \int_0^{2\pi} y \cos \theta d\theta = 0 + \pi A_1 + 0 + 0.$$

+ 0 + 0 ... [from (3), (2) and (1)]

$$\text{whence } A_1 = \frac{2}{2\pi} \int_0^{2\pi} y \cos \theta d\theta$$

= twice the mean value of ($y \cos \theta$)

i.e., a certain number of values of y must be taken, each being multiplied by the cosine of the angle for which y is the ordinate, the average of these found, and the result multiplied by 2.

The values of A_2 , A_3 , etc., may be found in like manner by multiplying through by $\cos 2\theta$, $\cos 3\theta$, etc., in order, and performing the integration as above.

To find B_1 :—multiply throughout by its coefficient, viz., $\sin \theta$, and integrate, then

$$\begin{aligned} \int_0^{2\pi} y \sin \theta d\theta &= \int_0^{2\pi} A_0 \sin \theta d\theta + \int_0^{2\pi} A_1 \sin \theta \cos \theta d\theta + \int_0^{2\pi} A_2 \sin \theta \cos 2\theta d\theta + \dots \\ &\quad + \int_0^{2\pi} B_1 \sin^2 \theta d\theta + \int_0^{2\pi} B_2 \sin \theta \sin 2\theta d\theta + \dots \\ &= 0 + \pi B_1 \quad [\text{from (2), (4) and (5)}] \end{aligned}$$

$$\therefore B_1 = \frac{2}{2\pi} \int_0^{2\pi} y \sin \theta d\theta = 2 \times \text{mean value of } (y \sin \theta)$$

so that the values of B_1 , B_2 , B_3 , etc., may be found.

Actually, the approximate values of the coefficients A_1 , A_2 , B_1 , B_2 , etc., are found by dividing the base into ten or eight divisions and averaging the mid-ordinates for these divisions. To determine the *absolute* values, an infinite number of ordinates would be necessary, so that the degree of accuracy obtainable is greater as the number of ordinates is increased.

The work is made clearer by suitable tabulation, as will be seen from the following example.

Example 1.—Resolve the curve ABCD (Fig. 129) into its component curves: it being understood that no higher harmonic than the first occurs.

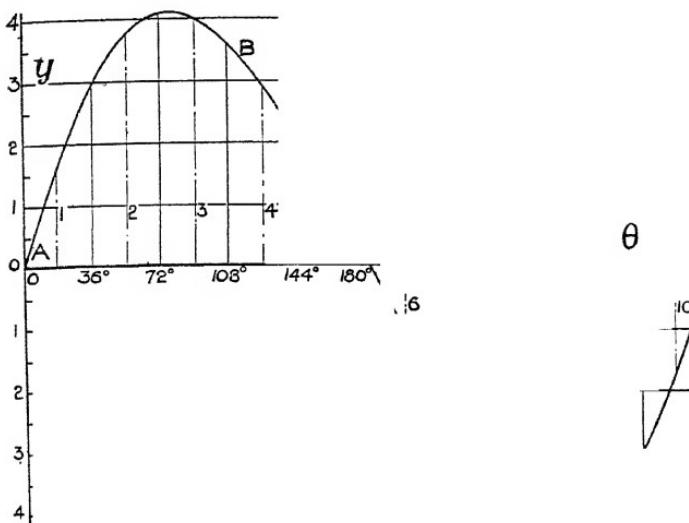


FIG. 129.—Harmonic Analysis.

[The term containing θ is spoken of as the fundamental, and that containing 2θ as the first harmonic.]

$$\text{Thus } y = A_0 + B \sin(\theta + c_1) + C \sin(2\theta + c_2)$$

$$\text{or } y = A_0 + A_1 \cos \theta + A_2 \cos 2\theta + B_1 \sin \theta + B_2 \sin 2\theta$$

will represent the function in this case.

A glance at the figure will show that the curve is symmetrical about the axis of θ ; thus we observe that the average ordinate = 0, or $A_0 = 0$.

Divide the base into 10 equal parts, erect the mid-ordinates and tabulate the values as follows:—

(a)	(b)	(c)	(d)	(e)	(f)	(g)
Ordinate No.	y	θ	$\sin \theta$	$\cos \theta$	$\sin 2\theta$	$\cos 2\theta$
1	1.56	18°	.309	.951	.588	.809
2	3.75	54°	.809	.588	.951	-.309
3	4	90°	1	0	0	-1
4	2.91	126°	-.809	-.588	-.951	-.309
5	1.13	162°	.309	-.951	-.588	.809
6	-1.13	198°	-.309	-.951	.588	.809
7	-2.91	234°	-.809	-.588	.951	-.309
8	-4	270°	-1	0	0	-1
9	-3.75	306°	-.809	.588	-.951	-.309
10	-1.56	342°	-.309	.951	-.588	.809

Then $A_0 = \text{mean value of } y = 0$.

$A_1 = 2 \times \text{mean value of } (y \cos \theta)$.

To obtain the values of $y \cos \theta$, corresponding figures in columns (b) and (e) must be multiplied.

Then $A_1 = \frac{2}{10} \left[.951(1.56 - 1.13 + 1.13 - 1.56) + .588(3.75 - 2.91) \right]$

Similarly, $B_1 = \frac{2}{10} \times \text{sum of the products of columns (b) and (d)}$
 $= \frac{2}{10} \left[.309(1.56 + 1.13 + 1.13 + 1.56) + 1(4+4) \right]$
 $= \frac{2}{10} \left[+.809(3.75 + 2.91 + 2.91 + 3.75) \right]$
 $= 2 \times 20.43 = 4.086$

$A_2 = \frac{2}{10} \times \text{sum of products of columns (b) and (g)}$
 $= \frac{2}{10} \left[.809(1.56 + 1.13 - 1.13 - 1.56) + 1(-4+4) \right]$
 $= \frac{2}{10} \left[+.309(-3.75 - 2.91 + 2.91 + 3.75) \right]$
 $= 0$

$B_2 = \frac{2}{10} \times \text{sum of products of columns (b) and (f)}$
 $= \frac{2}{10} \left[.588(1.56 - 1.13 - 1.13 + 1.56) + .951(3.75 - 2.91) \right]$
 $= \frac{2}{10} \left[-2.91 + 3.75 \right]$
 $= 2 \times 2.104 = 4.21$

Hence $y = (0 \times \cos \theta) + (0 \times \cos 2\theta) + (4.09 \sin \theta) + (4.21 \sin 2\theta)$
or $y = 4.09 \sin \theta + 4.21 \sin 2\theta$ (the cosine terms being absent).

Analysis by Method (b): The Graphical Interpretation of (a) (due to Professor Harrison).—To employ this method we must take at least twice as many ordinates as the largest, multiple

of θ ; thus if we suppose that the second harmonic is the highest occurring we might take 6 ordinates as the minimum, although it would be better if 8 or 10 were taken.

The method can best be illustrated by applying it to an example.

Example 2.—Resolve the curve ABC [(a) Fig. 130] into its com-

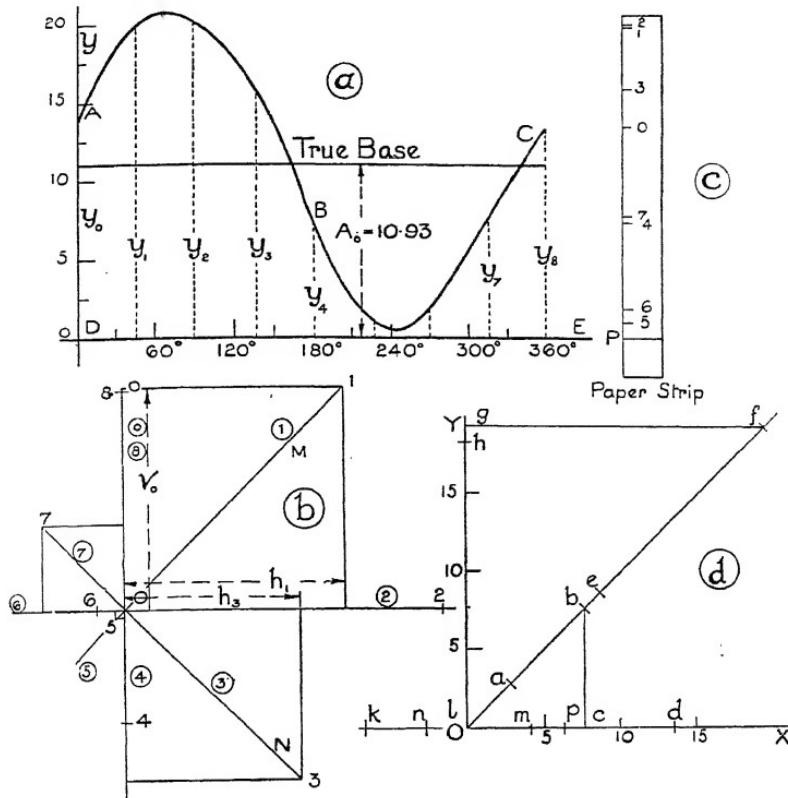


FIG. 130.

ponent curves (the second being the highest harmonic); *i.e.*, find the values of the constants in the equation

$$y = A_0 + A_1 \cos \theta + A_2 \cos 2\theta + A_3 \cos 3\theta + B_1 \sin \theta + B_2 \sin 2\theta + B_3 \sin 3\theta.$$

To arrange that all the ordinates shall be positive, take a base line DE entirely below the curve. Divide the base into 8 equal divisions and number the ordinates y_0, y_1, y_2, \dots . The angular intervals are thus 45° , since a full period corresponds to 360° .

Draw a new figure [(b) Fig. 130], the lines OM and ON making 45° with the principal axes; number these lines:—o, i, 8, as shown in the figure. Along line o set off a distance equal to y_0 , along line i set off a distance equal to y_1 and so on. Drop perpendiculars from the points o, i, etc., on to the principal axes, calling the projections on these axes h_0 (this particular projection being zero), h_1 h_8 , and $v_0, v_1 \dots v_7$ respectively.

Then to find A₁ and B₁:

As already proved

$$\begin{aligned}A_1 &= \frac{2}{3}(\Sigma y \cos \theta) = \frac{1}{2}[y_0 - y_4 + (y_1 - y_3 - y_5 + y_7) \cos 45^\circ + (y_2 - y_6) \cos 90^\circ; \\&\quad = \frac{1}{4}\{v_0 - v_4 + v_1 - v_3 - v_5 + v_7\},\end{aligned}$$

and similarly $B_1 = \frac{1}{4}\{h_1 + h_3 - h_5 - h_7 + h_2 - h_6\}$

i.e., the lengths $v_0 \dots v_7$, and $h_1 \dots h_7$, can be read off from the figure and then the values of A₁ and B₁ are calculated as above.

In this example

$v_0 = 13.7$	$h_0 = 0$
$v_1 = 14$	$h_1 = 14$
$v_2 = 0$	$h_2 = 20.4$
$v_3 = 11$	$h_3 = 11$
$v_4 = 7.3$	$h_4 = 0$
$v_5 = 5$	$h_5 = 5$
$v_6 = 0$	$h_6 = 1.5$
$v_7 = 5.4$	$h_7 = 5.4$

$$\therefore A_1 = \frac{1}{4} \times 14.3 = 3.58$$

$$\text{and } B_1 = \frac{1}{4} \times 3.8 = 9.5$$

By the aid of a strip of paper a great amount of this arithmetical work might be obviated, the procedure being as follows:—

Mark off along the edge of a strip of paper lengths to represent the various ordinates of the original curve, viz., y_0, y_1 , etc., and number the points so obtained o, i, 2 8 as shown at (c) Fig. 130.

Thus P₀ = y_0 , P₄ = y_4 and so on.

We have seen that in order to find the value of A₁ it is necessary to evaluate $y \cos \theta$ for the various angles; i.e., we must find the values of $y_1 \cos 45^\circ, y_2 \cos 90^\circ, y_3 \cos 135^\circ$ and so on.

Now $y_3 \cos 135^\circ = y_3 \times -\cos 45^\circ = -y_3 \cos 45^\circ$, so that the one line, viz., that at 45° , serves also for 135° provided that the ordinate is stepped off in a negative direction. Thus, for example,

$y_1 \cos \theta + y_3 \cos 3\theta = y_1 \cos 45^\circ - y_3 \cos 45^\circ = \cos 45^\circ(y_1 - y_3)$ and the value of this expression depends upon the difference between the lengths on the strip P_i and P₃, or the distance 3 to i.

Evidently, then, the work is shortened by grouping the ordinates in pairs to give differences; thus

$$y_1 - y_3 = P_i - P_3 = i \text{ to } 3 \text{ on the strip}$$

$$y_7 - y_5 = P_7 - P_5 = 5 \text{ to } 7 \text{ on the strip}$$

and so on for other pairs of ordinates.

Having found these differences, we multiply by $\cos 45^\circ$, by setting these lengths along the line Og in (d) Fig. 130 and then projecting to the horizontal axis OX ; the resultant of these projections being the value of $4A_1$.

Thus in (d) Fig. 130 :—Make $Oa = 1$ to 3 (on the strip) and $ab = 5$ to 7.

Drop bc perpendicular to OX . Then $Oc = (y_1 - y_3 - y_5 + y_7) \cos 45^\circ$.

Step off $cd = 0$ to 4 (*i.e.*, $y_0 - y_4$), then measure Od ; this is the value of $+A_1$, since $Od = Oc + cd = (y_1 - y_3 - y_5 + y_7) \cos 45^\circ + (y_0 - y_4)$.

$$Od = 13.7$$

$$A_1 = 3.43$$

∴

For the value of B_1 the strip must be used according to the following plan. A line is drawn at 45° [(d) Fig. 130] and distances marked off along it as follows

$Oe = 1$ to 7 on the strip, $ef = 3$ to 5 on the strip.

(for $4B_1 = (y_0 + y_4) \sin 0^\circ + (y_1 + y_3 - y_5 - y_7) \sin 45^\circ + (y_2 - y_6) \sin 90^\circ$)

A perpendicular to OY gives the point g . To Og must be added a distance = 2 to 6 on the strip, but to avoid extending the diagram this distance is set off from O giving the length Oh .

Thus $Og = 19.5$, $Oh = 18.2$, the sum = 37.7.

Then $4B_1 = 37.7$

and $B_1 = 9.43$.

To find the values of A_2 and B_2 :—The terms containing 2θ , *i.e.*, 90° , will now occur and so there will be no lines at 45° .

$$\begin{aligned} A_2 &= \frac{2}{8} \{y_0 \cos 0^\circ + y_1 \cos 90^\circ + y_2 \cos 180^\circ + \dots + y_7 \cos 630^\circ\} \\ &= \frac{1}{4} \{y_0 - y_2 + y_4 - y_6\}. \end{aligned}$$

$$\text{Similarly } B_2 = \frac{1}{4} \{y_1 - y_3 + y_5 - y_7\}.$$

Hence set off

$Ok = 0$ to 2, *i.e.*, $(y_0 - y_2)$ and $kl = 4$ to 6, *i.e.*, $(y_4 - y_6)$ along OX

and the resultant is

$$Ol = -8.$$

Hence $4A_2 = -8$

and $A_2 = -2$.

Set off

$Om = 1$ to 3, *i.e.*, $(y_1 - y_3)$ and $mn = 5$ to 7, *i.e.*, $(y_5 - y_7)$ along OX

and the resultant is

$$On = -2.6$$

Hence $4B_2 = -2.6$

and $B_2 = -0.65$.

To find the values of A_3 and B_3 :

$$\begin{aligned} A_3 &= \frac{2}{8} \{y_0 \cos 0^\circ + y_1 \cos 135^\circ + y_2 \cos 270^\circ + y_3 \cos 405^\circ + y_4 \cos 540^\circ\} \\ &\quad + y_5 \cos 675^\circ + y_6 \cos 810^\circ + y_7 \cos 945^\circ \end{aligned}$$

$$= \frac{1}{4} \{y_0 - y_4 + (y_3 - y_1 + y_5 - y_7) \cos 45^\circ\}.$$

Set off $O\dot{p} = 0$ to 4 on the strip, along OX,

and $Ob = (y_1 - y_3 - y_5 + y_7)$ (which has already been done when finding A_1).

Project b to c on OX; then $Oc = -(y_3 - y_1 + y_5 - y_7) \cos 45^\circ$.

$$\text{Hence } c\dot{p} = 4A_3$$

$$\text{but } c\dot{p} = -1 \cdot 3$$

$$\text{and thus } A_3 = -1 \cdot 33.$$

To find B_3 :

$$B_3 = \frac{1}{4} \left\{ \begin{array}{l} y_0 \sin 0^\circ + y_1 \sin 135^\circ + y_2 \sin 270^\circ + y_3 \sin 405^\circ + y_4 \sin 540^\circ \\ + y_5 \sin 675^\circ + y_6 \sin 810^\circ + y_7 \sin 945^\circ \end{array} \right\}$$

$$= \frac{1}{4} \{ y_6 - y_2 + (y_1 + y_3 - y_5 - y_7) \sin 45^\circ \}.$$

Set off $O\dot{h} = 6$ to 2 along OY.

$O\dot{f} = (y_1 + y_3 - y_5 - y_7)$ (which has already been done when finding B_1).

Project f to g on OY,

$$\text{then } g\dot{h} = 4B_3$$

$$\text{but } g\dot{h} = 1 \cdot 2$$

$$\text{Hence } B_3 = 1 \cdot 3$$

$$\text{Also } \frac{\frac{1}{2}y_0 + y_1 + y_2 + y_3 + y_4 + y_5 + y_6 + y_7 + \frac{1}{2}y_8}{8} = A_0$$

(using the trapezoidal rule given on p. 307, Part I),

$$\text{i.e., } A_0 = \frac{6 \cdot 75 + 19 \cdot 8 + 20 \cdot 4 + 16 + 7 \cdot 3 + 9 + 1 \cdot 9 + 7 \cdot 6 + 6 \cdot 75}{8}$$

$$= \frac{87 \cdot 4}{8} = 10 \cdot 93.$$

$$\therefore y = 10 \cdot 93 + 3 \cdot 43 \cos \theta + 9 \cdot 43 \sin \theta - 2 \cos 2\theta$$

$$- 6 \cdot 5 \sin 2\theta - 3 \cdot 33 \cos 3\theta + 1 \cdot 3 \sin 3\theta.$$

There should be no difficulty in the understanding of this method if method (a) is first carefully studied. All that this

method (b) adds is the multiplication of lengths by the cosines or sines of angles by regarding the products as projections on fixed axes (i.e., if $OA = R$ (Fig. 131) and the angle $AOB = 30^\circ$, then $OB = OA \cos 30^\circ = R \cos 30^\circ$, and $OC = OA \sin 30^\circ = R \sin 30^\circ$).

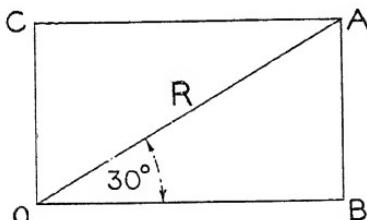


FIG. 131.

The beauty of the method consists in the use of the paper for the grouping together of pairs of ordinates which have to be multiplied by the same quantity.

In the example just discussed, the angular intervals were taken as 45° , this choice being made as a matter of great convenience, since $\cos 45^\circ = \sin 45^\circ$ and projections may thus be made on either a horizontal or a vertical axis.

For greater accuracy, more ordinates should be taken, and then care must be observed as to the axis on which the projections are made. Thus if the angular intervals were taken as 18° , say, the lines corresponding to OM, ON and Of in (b) and (d) Fig. 130 would be drawn making angles of 18° with the horizontal axis; then for the values of A_1, A_2 , etc., the projections along OX would be measured, whilst the values of B_1, B_2 , etc., would be determined from the projections on OY.

Method (c): Analysis by Superposition.—This method is much used in alternating current work, for the problems of which it is specially suited. It is not difficult to employ, nor to understand, although the proof of the method is long and is in consequence not treated here.

In order to present the method in as clear a fashion as possible, the rules of procedure are here set out in place of a detailed explanation.

The method is as follows; the case of a curve containing the second as the highest harmonic being treated, although the process can readily be extended if necessary:—

(1) Divide the curve into two equal parts and superpose the second part upon the first, using dividers and paying attention to the signs. If the resultant curve approximates to a sine curve there is no need to further subdivide. (This gives terms containing $2\theta, 4\theta, 6\theta$, etc., but if this curve is a sine curve, probably only terms containing 2θ occur.)

Put in a base line for this new curve (by estimation); then the height of this from the original base line = $2A_0$.

(2) Divide the original curve into three equal parts and superpose (first, the second on the first, and then to this result add the third).

(This gives the terms containing $3\theta, 6\theta, 9\theta$, etc.)

The height of the base line of the resulting curve from the original base line = $3A_0$. (The two values of A_0 may be compared, and of course they should be alike; but if not, take the average of these and draw a new base line distant A_0 from the original; this line we shall speak of as the true base line.)

(3) Subtract corresponding ordinates of the 2θ curve (divided by 2) and the 3θ curve (divided by 3), paying attention to the

signs, from the ordinates of the original curve ; the resultant curve is approximately a sine curve symmetrical about the true base line.

To calculate the values of the constants, if

$$y = A_0 + A_1 \sin(\theta + c_1) \\ + A_2 \sin(2\theta + c_2)$$

A_0 is already found.

Select two convenient values of θ and work from the ordinates of the θ curve to find A_1 and c_1 ; proceed similarly, using the 2θ curve to find A_2 and c_2 .

Note that in alternating current work only terms of the order $\theta, 3\theta, 5\theta$, etc., occur, so that the curve would need to be divided into 3, 5, etc., equal divisions and the parts superposed. There is thus no need to divide into 2, 4, etc., equal parts; also it is evident that the value of A_0 must be zero.

Example 3.—The curve ABCD, Fig. 132, gives by its ordinates the displacement of a valve actuated by a Gooch Link Motion.

It is required to find the constants in the equation

$$y = A_0 + A_1 \sin(\theta + c_1) \\ + A_2 \sin(2\theta + c_2) \text{ etc.}$$

The original curve is divided into two equal parts, the second being placed over the first, with the result that Curve 2 is obtained.

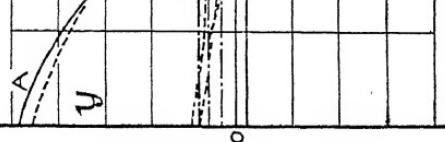


FIG. 132.

The estimated base line for this is B_2 ; the height of B_2 above the original base line being .29, i.e.,

the height of the true base line is $\frac{.29}{2}$ or .145 unit. This base line can now be put in, and is indicated as the true base line.

By division into 3 and 4 equal parts and superposition the curves 3 and 4 respectively are obtained.

B_3 , the base line for 3, is at a height of .43; this figure divided by 3 gives .143, which agrees well with our former result.

Curve 2 really represents the first harmonic with double amplitude; therefore we subtract ordinates of Curve 2 (to half scale, i. e., we use proportional compasses) from the corresponding ordinates of the original curve.

Similarly we subtract $\frac{1}{2}$ of the ordinates of Curve 3 from the original curve, and since those for Curve 4 are too small to be taken into account, the net result is Curve 1, which represents the fundamental, and is a sine curve symmetrical about the true base line.

To find the constants A_1 and c_1 in the equation

$$y_1 = A_1 \sin(\theta + c_1).$$

When $\theta = 0$, $y_1 = 2.175$ (measured from the true base line to Curve 1).

$$\text{At } \theta = 90^\circ, y_1 = 0.$$

$$\therefore c_1 = 90^\circ \text{ or } \frac{\pi}{2}.$$

$$\text{At } 180^\circ \quad y_1 = -2.135,$$

$$\text{i. e., } A_1 = \text{the mean of } 2.175 \text{ and } -2.135, \text{ i. e., } 2.15.$$

$$\therefore y = 2.15 \sin(\theta + 90^\circ) \\ = 2.15 \cos \theta.$$

To find A_2 and c_2 .

The amplitude of Curve 2 is $\frac{.29}{2}$, i. e., .145.

$$\therefore A_2 = .145,$$

and since the curve has its maximum ordinate when $\theta = 0$ we have again $c_2 = 90$, or the curve is a cosine curve.

$$\text{Hence } y_2 = .145 \cos 2\theta.$$

Beyond this first harmonic we need not proceed as the amplitudes of Curves 3 and 4 are exceedingly small.

$$\text{Hence } y = y_1 + y_2 \\ = 2.15 \cos \theta + .145 \cos 2\theta.$$

This method of superposition is to be recommended in cases of A.C. work, as one can so readily tell by its aid which harmonics are present. If the actual constants in the equation are required it may be easier to proceed according to method (a) or method (b).

Exercises 24.—On Harmonic Analysis.

1. Show how to analyse approximately the displacement x of a point in a mechanism on the assumption that it may be represented by a limited series of sine and cosine terms, and obtain general expressions for the values of the coefficients in the series

$$x = \sum_1^n (A_n \cos n\theta + B_n \sin n\theta) + A_0$$

where $n = 3$ and θ is the angular displacement of an actuating crank which revolves uniformly. Apply your results to obtain the values of the coefficients for the values of x and θ given in the accompanying table, where the linear displacement of a point in a mechanism is given for the corresponding angular displacement of a uniformly revolving crank.

Angular displacement of crank in degrees.	0	60	90	120	180	240	300
x (in ins.)	1.11	.43	.83	1.65	3.67	4.15	2.93

2. A part of a machine has an oscillating motion. The displacements y at times t are as in the table.

t	.02	.04	.06	.08	.1	.12	.14	.16	.18	.2
y	.64	1.13	1.34	.95	0	-1.92	-1.33	-1.16	-1.66	0

Find the constants in the equation

$$y = A \sin (10\pi t + a_1) + B \sin (20\pi t + a_2).$$

3. Analyse the curve which results when the following values are plotted.

45	90	135	180	225	270	315	360
21.5	31.25	11.25		30	26.5	0	

4. The values of the primary E.M.F. of a transformer at different points in the cycle are as follows (θ being written in place of pt for reasons of simplicity).

θ	0	30	60	90	120	150	180	210	240	270	300	330	360
E	70	886	1293	1400	1307	814	-70	-886	-1293	-1400	-1307	-814	70

If θ and E are connected by the equation

$$E = A \sin \theta + B \sin 3\theta + C \cos \theta + D \cos 3\theta$$

find the values of the constants A, B, C and D.

CHAPTER XII

THE SOLUTION OF SPHERICAL TRIANGLES

THE curvature of the earth's surface is not an appreciable factor in the calculations following a small survey, and is therefore not regarded, but when the lengths of the boundaries of the survey are great, as in the case of a "major triangulation," the effect of the curvature must be allowed for, if precision is desired. It is therefore necessary to use *Spherical Trigonometry* in place of the more familiar *Plane Trigonometry*, and accordingly a very brief chapter is inserted here, dealing mainly with the solution of spherical triangles.

Definitions of Terms used.—The earth may be considered as a sphere of radius 20,890,172 feet, this being the mean radius.

A *great circle* on a sphere is a circle traced by the intersection of the sphere by a plane passing through its centre; if the plane does not pass through the centre of the sphere, its intersection with the sphere is called a *small circle*. Thus all meridians are great circles, whilst parallels of latitude, except for the equator parallel, are all small circles.

A straight line on the earth's surface is in reality a portion of a great circle; hence a parallel of latitude is not a straight line, or, in other words, a movement due East or West is not a movement along a straight line.

A triangle set out on the earth's surface with straight sides is what is termed a "spherical triangle," its sides being arcs of great circles. The lengths of these sides might be measured according to the usual rules, viz., in miles, furlongs, etc., but it is more usual to measure them by the sizes of the angles subtended by them at the centre of the sphere. In this connection it is convenient to remember that an arc of one nautical mile (6076 feet) subtends an angle of 1' at the centre of the earth; hence a length of 80 nautical miles would be spoken of as a side of $80'$, i.e., $1^{\circ}20'$.

In Fig. 133 is shown the difference between great and small circles; and AB, BC and CA being portions of great circles form a

spherical triangle (shown cross hatched). The length BA would be expressed by the magnitude of the angle BOA.

A spherical triangle ABC is shown in Fig. 134, O being the centre of the sphere. The arc AB is proportional to the angle AOB, and therefore, instead of speaking of AB as a length, it is quite legitimate to represent it by $\angle AOB$.

c would thus stand for $\angle AOB$, b for $\angle COA$, and a for $\angle COB$. As regards the angles of the triangle, the angle between CA and AB is that between the planes AOC and AOB and is, therefore, the angle between the tangents AD and AE. Spherical triangles should be regarded as the most general form of plane triangles; for if the radius of the sphere becomes infinite the spherical triangle becomes a plane triangle.

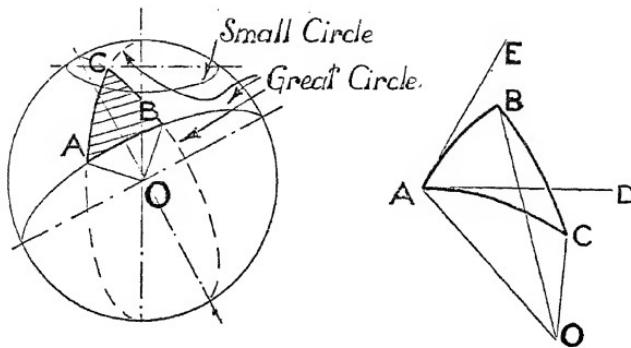


FIG. 133.

Spherical Triangles.

FIG. 134.

Many rules with which we are familiar in connection with plane triangles hold also for spherical triangles, as, for example, "Any two sides of a triangle are greater than the third," or, again, "If two triangles have two sides and the included angle of the one respectively equal to two sides and the included angle of the other, the triangles are equal in all respects"; "The greater side of every triangle is subtended by the greater angle."

There is one important difference between the rule for a plane triangle and a corresponding rule for a spherical triangle: viz., whilst the three angles of a plane triangle add up to 180° the sum of those in a spherical triangle always exceeds 180° , the sum in fact lying between 180° and 540° ; and the difference between the sum of the three angles and 180° is known as the "*spherical excess*."

The magnitude of this can be found from the rule

$$\text{spherical excess} = \frac{360^\circ \times \text{area of triangle}}{2\pi r^2}$$

($2\pi r^2$ being the area of the surface of the hemisphere).

This spherical excess is a small quantity for the cases likely to be considered in connection with surveys.

E.g., consider the case of an equilateral triangle of side 68 miles.

$$r = 20,900,000 \text{ ft. approx.} = 3960 \text{ miles.}$$

The area of the triangle is about 2000 sq. miles.

Then the spherical excess

$$= \frac{360 \times 60 \times 2000}{2\pi \times 3960 \times 3960} \text{ minutes} = .437 \text{ minute.}$$

A good approximation for the spherical excess of a triangle on the earth's surface is:

$$\text{spherical excess (seconds)} = \frac{\text{area of spherical triangle in sq. miles}}{78}.$$

Solution of Spherical Triangles.—The most widely used rule in connection with the solution of plane triangles is the “*sine*” rule which states that the sides are proportional to the sines of the angles opposite. In the case of spherical triangles this becomes modified and reads—“The sines of the angles are proportional to the sines of the sides opposite.”

Therefore, adopting the notation of Fig. 134,

$$\frac{\sin a}{\sin A} = \frac{\sin b}{\sin B} = \frac{\sin c}{\sin C} \quad (1)$$

it being remembered that $\sin a$ is really $\sin \angle BOC$, etc.

Other rules are

$$\sin \frac{A}{2} = \sqrt{\frac{\sin(s-b) \sin(s-c)}{\sin b \sin c}} \quad (2)$$

$$\cos \frac{A}{2} = \sqrt{\frac{\sin s \sin(s-a)}{\sin b \sin c}} \quad (3)$$

$$\tan \frac{A}{2} = \sqrt{\frac{\sin(s-b) \sin(s-c)}{\sin s \sin(s-a)}} \quad (4)$$

and corresponding forms for $\frac{B}{2}$ and $\frac{C}{2}$, obtained by writing

the letters one on in the proper sequence, $a \ b \ c \ a$.

s in these formulæ = $\frac{a+b+c}{2}$ and is, therefore, an angle

(in plane trigonometry, $s = \frac{a+b+c}{2}$, but is a length).

It is of interest to compare these with the corresponding rules in connection with plane triangles, which are

$$\sin \frac{A}{2} = \sqrt{\frac{(s-b)(s-c)}{bc}}$$

$$\cos \frac{A}{2} = \sqrt{\frac{s(s-a)}{bc}}$$

$$\tan \frac{A}{2} = \sqrt{\frac{(s-b)(s-c)}{s(s-a)}}$$

It will be seen that, as in the previous case, sides occurring in the formulæ of plane trigonometry are replaced by their sines in the corresponding formulæ of spherical trigonometry.

Other rules are:—

$$\cos a = \frac{\cos A + \cos B \cos C}{\sin B \sin C} \quad \dots \dots \quad (5)$$

$$\cos A = \frac{\cos a - \cos b \cos c}{\sin b \sin c} \quad \dots \dots \quad (6)$$

$$\cot A \sin B = \cot a \sin c - \cos B \cos c \quad \dots \dots \quad (7)$$

$$\tan \frac{A+B}{2} = \frac{\cos \frac{(a-b)}{2}}{\cos \left(\frac{(a+b)}{2} \right)} \cot \frac{C}{2} \quad \dots \dots \quad (8)$$

$$\tan \frac{A-B}{2} = \frac{\sin \frac{(a-b)}{2}}{\sin \left(\frac{(a+b)}{2} \right)} \cot \frac{C}{2} \quad \dots \dots \quad (9)$$

Solution of Right Angled Spherical Triangles.—In the case of a right angled spherical triangle these rules can be put into somewhat simpler forms.

Assume that the triangle is right angled at C.

$$C = 90^\circ, \therefore \cos C = 0, \text{ and } \sin C = 1.$$

$$\text{From (6)} \qquad \cos C = \frac{\cos c - \cos a \cos b}{\sin a \sin b}$$

$$\text{but} \qquad \cos C = 0,$$

$$\therefore \cos c - \cos a \cos b = 0,$$

$$\text{i.e.} \qquad \cos c = \cos a \cos b \quad \dots \dots \quad (10)$$

Also $\cos A = \frac{\cos a - \cos b \cos c}{\sin b \sin c}$ from (6)

$$= \frac{\cos c - \cos b \cos c}{\cos b \sin b \sin c} \quad \text{from (10)}$$

$$= \frac{\cos c}{\sin c} \times \frac{1}{\sin b \cos b} - \frac{\cos b}{\sin b} \times \frac{\cos c}{\sin c}$$

$$= \frac{1}{\tan c} \left(\frac{1}{\sin b \cos b} - \frac{\cos b}{\sin b} \right)$$

$$= \cot c \left(\frac{1 - \cos^2 b}{\sin b \cos b} \right) = \frac{\cot c \times \sin^2 b}{\sin b \cos b}$$

$$= \cot c \times \frac{\sin b}{\cos b}$$

$$= \cot c \times \tan b$$

or $\tan b \times \tan(90 - c)$

i. e., $\cos A = \tan b \tan(90 - c)$
 also $\cos B = \tan a \tan(90 - c)$ (11).

Again $\cos A = \frac{\cos a - \cos b \cos c}{\sin b \sin c}$

$$\frac{\cos a - \cos^2 c}{\sin b \sin c} \quad \text{from (10)}$$

$$\frac{\cos^2 a - \cos^2 c}{\cos a \sin b \sin c} \quad \text{or} \quad \frac{\sin^2 c - \sin^2 a}{\cos a \sin b \sin c} \quad (12)$$

And from (1) $\sin A = \frac{\sin a}{\sin c}$ (13)

[In plane trigonometry $\sin A = \frac{a}{c}$.]

Napier's Rules of Circular Parts.—The equations (10), (11) and (13) and their modifications may be easily remembered by Napier's two rules of circular parts, which may almost be regarded as a mnemonic.

For the application of these two rules the five parts of the spherical triangle, other than the right angle at C, are regarded as $a, b, (90 - A), (90 - c)$, and $(90 - B)$ respectively, the complements of A, c and B being taken instead of the values A, c and B in order that the two rules may embrace all the cases.

These five parts are written in the five sectors of a circle in the order in which they occur in a triangle: thus in Fig. 135, commencing from the side a and making the circuit of the triangle in the direction indicated, the parts in turn are a b A (for which we write $90-A$), c (for which is written $90-c$) and B (for which is written $90-B$). These parts are set out as shown in Fig. 136.

Then Napier's rules state:—

Sine of the middle part = product of tangents of adjacent parts.

Sine of the middle part = product of cosines of opposite parts.

The terms *middle*, *adjacent* and *opposite* have reference to the mutual position of the parts in Fig. 136. Thus if b is selected as the middle part, the adjacent parts are those in immediate contact

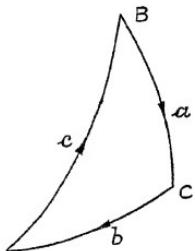


FIG. 135.

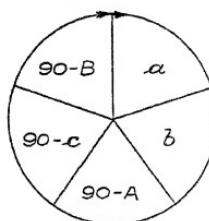


FIG. 136.

with b , viz., α and $(90-A)$, whilst $(90-c)$ and $(90-B)$ are the opposite parts.

$$\text{Hence } \sin b = \tan \alpha \times \tan (90-A) = \tan \alpha \cot A$$

$$\sin b = \cos (90-B) \times \cos (90-c) = \sin B \sin c$$

$$\text{or } \sin B = \frac{\sin b}{\sin c}. \quad (\text{Cf. equation (13); p. 359.)}$$

Again, if $(90-B)$ is selected as the middle part, the adjacent parts are $(90-c)$ and α , and the opposite parts are $(90-A)$ and b .

$$\text{Hence } \sin (90-B) = \tan (90-c) \tan \alpha$$

$$\text{or } \cos B = \tan (90-c) \tan \alpha \quad (\text{cf. equation (11), p. 359}),$$

$$\text{and } \sin (90-B) = \cos (90-A) \cos b$$

$$\text{or } \cos B = \sin A \cos b.$$

These rules, being composed of products and quotients only, lend themselves well to logarithmic computation.

The Ambiguous Case in the Solution of Spherical Triangles.—In the solution of a plane triangle, if two sides and the angle opposite the shorter of these is given, there is the possibility

of two solutions of the problem ; the best test for which, as pointed out in Chap. VI, Part I, being the drawing to scale.

A similar difficulty occurs in the solution of spherical triangles, when two sides and the angle opposite one of them is given.

E. g., let a b and B be the given parts.

Then from equation (1), p. 357.

$$\frac{\sin A}{\sin a} = \frac{\sin B}{\sin b}$$

or $\sin A = \frac{\sin a \sin B}{\sin b}$

Now $\sin A = \sin (180 - A)$ and thus the right-hand side of this last equation may be the value of either a particular angle or its supplement.

Without going into the proof it may be stated that there will be one solution only if the side opposite the given angle has a value between the other given side and its supplement. Thus in the case in which a b and B are given, there will be one solution only if b lies between a and $(180 - a)$.

If b is not between a and $(180 - a)$, then the test must be applied that the greater angle must be opposite the greater side : thus for the case of a b and B given, if $a > b$ then A must be $> B$. The possible cases may be best illustrated by numerical examples, a b and B being regarded as the given parts throughout.

(a) Given $a = 144^\circ 40'$, $b = 87^\circ 37'$, $B = 11^\circ 9'$ to find A .

Using equation (1) of p. 357

$$\sin A = \frac{\sin a \sin B}{\sin b} = \frac{\sin 144^\circ 40' \times \sin 11^\circ 9'}{\sin 87^\circ 37'}$$

$$\begin{aligned} \text{and } \log \sin A &= \log \sin 144^\circ 40' + \log \sin 11^\circ 9' - \log \sin 87^\circ 37' \\ &= \bar{1} \cdot 7622 + \bar{1} \cdot 2864 - \bar{1} \cdot 9996 \\ &= \bar{1} \cdot 0490 \end{aligned}$$

so that it is possible that $A =$ either $6^\circ 26'$ or $173^\circ 34'$.

Now $a > b$ and therefore A must be $> B$, and this condition is only satisfied if $A = 173^\circ 34'$, since $6^\circ 26'$ is not $> 11^\circ 9'$.

It will be noted that the case chosen is that in which b , viz., $87^\circ 37'$, lies between a , i.e., $144^\circ 40'$, and $(180 - a)$, i.e., $35^\circ 20'$, and therefore only one solution is expected.

(b) $b = 44^\circ 35'$, $a = 55^\circ 10'$ and $B = 38^\circ 46'$.

Here b does not lie between a and $(180 - a)$, so that two solutions are possible.

As before

$$\begin{aligned}\log \sin A &= \log \sin a + \log \sin B - \log \sin b \\&= \log \sin 55^\circ 10' + \log \sin 38^\circ 46' - \log \sin 44^\circ 35' \\&= 1.9142 + 1.7966 - 1.8463 = 1.8645 \\&= \log \sin 47^\circ 3'\end{aligned}$$

so that possible values of A are $47^\circ 3'$ and $132^\circ 57'$ and we must test each of these values.

Now $a > b$, and hence A must be $> B$; but $47^\circ 3'$ and $132^\circ 57'$ are both $> 38^\circ 46'$, so that we have two triangles satisfying the conditions, and for complete solution the two values of A, C and c must be determined.

Example 1.—In a spherical triangle ABC, having given $a = 30^\circ$, $b = 40^\circ$, $C = 70^\circ$, find A and B.

Given also that

$$\left\{ \begin{array}{l} L \sin 5^\circ = 8.9402960 \\ L \sin 35^\circ = 9.7585913 \\ L \cos 5^\circ = 9.9983442 \\ L \cos 35^\circ = 9.9133645 \end{array} \right. \quad \left\{ \begin{array}{l} L \tan 12^\circ 14' 38'' = 9.3364779 \\ L \tan 60^\circ 4' 3'' = 10.2397529 \end{array} \right.$$

In this case two sides and the included angle are given; we therefore use equations (8) and (9).

$$\begin{aligned}\tan \frac{A+B}{2} &= \frac{\cos \left(\frac{a-b}{2} \right)}{\cos \left(\frac{a+b}{2} \right)} \cot \frac{C}{2} && \text{from (8)} \\&= \frac{\cos 5^\circ}{\cos 35^\circ} \cot 35^\circ && \left\{ \begin{array}{l} \text{for } \cos -5^\circ \\ = \cos +5^\circ \end{array} \right\} \\&= \frac{\cos 5^\circ}{\cos 35^\circ} \times \frac{\cos 35^\circ}{\sin 35^\circ} = \frac{\cos 5^\circ}{\sin 35^\circ}\end{aligned}$$

Taking logs of both sides

$$L \tan \frac{A+B}{2} = L \cos 5^\circ - L \sin 35^\circ + 10$$

(or, alternatively, $\log \tan \frac{A+B}{2} = \log \cos 5^\circ - \log \sin 35^\circ$)

$$\begin{aligned}L \tan \frac{A+B}{2} &= \frac{10.9983442}{9.7585913} \\&= \frac{10.9983442}{10.2397529} \\&= L \tan 60^\circ 4' 3''\end{aligned}$$

$$A+B = 60^\circ 4' 3''$$

$$A+B = 120^\circ 8' 6''$$

(a)

From equation (9)

$$\tan \frac{A-B}{2} = \frac{\sin \left(\frac{a-b}{2} \right)}{\sin \left(\frac{a+b}{2} \right)} \cot \frac{C}{2}$$

$$\tan \frac{A-B}{2} = -\frac{\sin 5^\circ}{\sin 35^\circ} \frac{\cos 35^\circ}{\sin 35^\circ}$$

$$\tan \frac{B-A}{2} = \frac{\sin 5^\circ \times \cos 35^\circ}{\sin^2 35^\circ}$$

taking logs throughout.

$$\begin{aligned} L \tan \frac{B-A}{2} &= L \sin 5^\circ + L \cos 35^\circ - 2L \sin 35^\circ + 10 \\ &\quad \underline{18.9402960} \\ &\quad \underline{9.9133645} \\ &= 28.8536605 \\ &\quad \underline{19.5171826} \\ &\quad \underline{9.3364779} \\ &= L \tan 12^\circ 14' 38'' \\ \therefore B-A &= 24^\circ 29' 16'' \dots \end{aligned} \tag{b}$$

By adding (a) and (b)

$$2B = 144^\circ 37' 22''$$

\therefore

$$B = 72^\circ 18' 41''$$

and

$$A = \underline{120^\circ 8' 6''} - 72^\circ 18' 41'' = 47^\circ 49' 25''.$$

[Note that

$$\begin{aligned} A+B+C &= 47^\circ 49' 25'' + 72^\circ 18' 41'' + 70^\circ \\ &= 190^\circ 8' 6'' \end{aligned}$$

so that the spherical excess = $10^\circ 8' 6''$.]

Example 2.—Solve the spherical triangle ABC, having given

$$c = 91^\circ 18', \quad a = 72^\circ 27', \quad \text{and} \quad C = 90^\circ.$$

In this case the triangle is right angled, and therefore rules (10) to (13) may be used.

To find A:—

$$\text{From equation (13), p. 359, } \sin A = \frac{\sin a}{\sin c}.$$

$$\begin{aligned} \therefore L \sin A &= L \sin a - L \sin c + 10 \\ &= L \sin 72^\circ 27' - L \sin 91^\circ 18' + 10 \\ &= \underline{19.97930} \\ &= \underline{9.99989} \\ &= \underline{9.97941} \\ &= L \sin 72^\circ 29' 45''. \\ \therefore A &= 72^\circ 29' 45''. \end{aligned}$$

To find b :—

From equation (10), p. 358,

$$\cos c = \cos a \cos b$$

$$\text{whence} \quad \cos b = \frac{\cos c}{\cos a}$$

$$\therefore \cos b = \frac{\cos 91^\circ 18'}{\cos 72^\circ 27'} = \frac{-\cos 7^\circ 42'}{\cos 72^\circ 27'}$$

$$\text{or} \quad \cos(180 - b) = -\cos b = \frac{\cos 88^\circ 42'}{\cos 72^\circ 27'}$$

Hence we shall work to find the supplement of b .

Taking logs *

$$\begin{aligned} \log \cos(180 - b) &= \log \cos 88^\circ 42' - \log \cos 72^\circ 27' \\ &= \frac{2.35578}{1.47934} \\ &\quad - \frac{2.87644}{1.47934} \\ &= \log \cos 85^\circ 41' 7''. \\ \therefore 180 - b &= 85^\circ 41' 7'' \\ \therefore b &= 94^\circ 18' 53''. \end{aligned}$$

* It is rather easier to work in terms of the logs in preference to the logarithmic ratios. One must remember, however, that the $L \sin A = \log \sin A + 10$, so that if a $L \sin A$ reading is 9.97941 , then the reading for $\log \sin A$ would be 1.97941 . If the logarithmic ratios are used the addition of the 10 must not be overlooked.

To find B :—

From equation (11), p. 359,

$$\cos B = \tan a \tan(90^\circ - c)$$

$$\text{i.e., } \cos(180^\circ - B) = \tan a \tan(c - 90^\circ) = \tan 72^\circ 27' \times \tan 1^\circ 18'$$

$$\therefore \log \cos(180 - B) = \log \tan 72^\circ 27' + \log \tan 1^\circ 18'$$

$$\begin{aligned} &= \frac{49996}{2.35590} \\ &= \frac{2.85586}{1.47934} \\ &= \log \cos 85^\circ 53' 6''. \end{aligned}$$

$$\therefore 180 - B = 85^\circ 53' 6''$$

$$\therefore B = 94^\circ 6' 54''$$

Hence, grouping our results,

$$\begin{array}{ll} a = 72^\circ 27' & A = 72^\circ 29' 45' \\ b = 94^\circ 18' 53'' & B = 94^\circ 6' 54'' \\ c = 91^\circ 18' & C = 90^\circ \end{array}$$

Example 3.—At a point A, in latitude 50° N., a straight line is ranged out which runs due E. at A. This straight line is prolonged for

60 nautical miles to B. Find the latitude of B, and if it be desired to travel due N. from B so as to meet the 50° parallel again at C, find the angle ABC at which we must set out and also the distance EC.

In Fig. 137 let A be the point on latitude 50° N. and ABD be a great circle passing through A: thus AB is a straight line running due E. from A. Let NB be the meridian through B, and NA that through A.

The sides NA, AB and BN are straight lines, because they are parts of great circles and therefore they together form a spherical triangle.

In this triangle we know the side AB (its value being $60'$, for 1 nautical mile subtends an angle of $1'$ at the centre); the angle at A (90°); and the side NA (90° —latitude, i.e., 40°).

Thus two sides and the included angle are given and we require to solve the triangle; hence we use rule (10), p. 358,

from which

$$\cos NB = \cos NA \cos AB$$

$$= \cos 40^{\circ} \cos 60'$$

or

$$\begin{aligned}\log \cos NB &= \log \cos 40^{\circ} + \log \cos 1' \\ &= 7.88425 + 7.99993 \\ &= 7.88418\end{aligned}$$

i. e.,

$$NB = 40^{\circ} 0' 38''$$

or the latitude of B is

$$90^{\circ} - 40^{\circ} 0' 38'' = 49^{\circ} 59' 22''.$$

Now C is at the same latitude as A, so that BC is $38''$, corresponding to $\frac{38}{60}$ nautical miles; i. e., BC = $.633$ nautical mile.

To find the angle ABC, we use rule (13), p. 359.

$$\sin \angle ABC = \frac{\sin NA}{\sin NB} = \frac{\sin 40^{\circ}}{\sin 40^{\circ} 0' 38''}$$

$$\therefore \log \sin \angle ABC = \log \sin 40^{\circ} - \log \sin 40^{\circ} 0' 38'' \\ = 7.90807 - 7.90817 \\ = 7.99990$$

$$\text{whence } \angle ABC = 88^{\circ} 45'.$$

For the surveyor, spherical trigonometry has an important application in questions relating to spherical astronomy. Thus in the determination of the latitude of a place by observation to a star, the calculations necessary involve the solution of a spherical triangle. This triangle is indicated in Fig. 139, the sides AB, BC

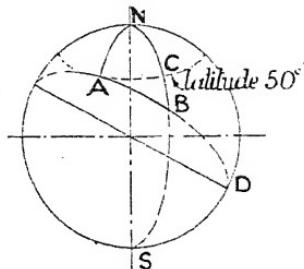


FIG. 137.

and CA representing the co-latitude of the place, *i.e.*, $(90^\circ - \text{latitude})$, $(90^\circ - \text{declination})$ and $(90^\circ - \text{altitude})$ respectively; whilst the angles A, B and C measure respectively the azimuth, the hour angle and the parallactic angle.

The terms just mentioned are defined as follows:—

Fig. 138 represents a section of the celestial sphere at the meridian through the point of observation O. RDT is the celestial equator, CEX is the horizon, Z is the zenith of the point of observation, *i.e.*, the point on the celestial sphere directly above O, and S marks the position of the heavenly body to which observa-

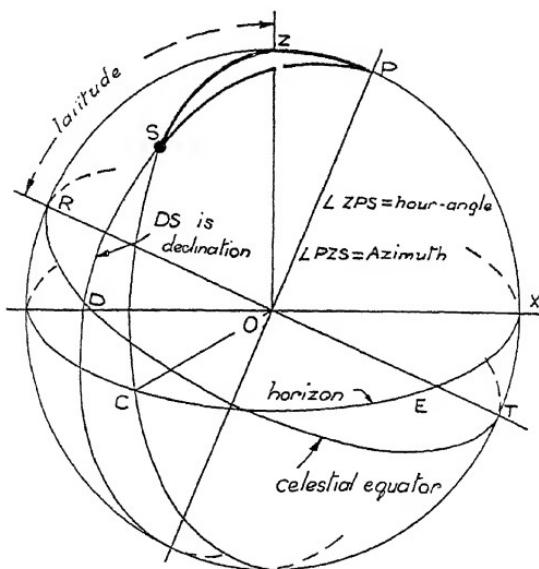


FIG. 138.—Determination of Latitude.

tions are made. Also PSD, ZSC, RDT and CEX are portions of great circles.

The *altitude* of a heavenly body is the arc of a great circle passing through the zenith of the point of observation and the heavenly body; the arc being that intercepted between the body and the horizon. We may thus compare the altitude in astronomy with the angle of elevation in surveying. Referring to Fig. 138, ZSC is the great circle passing through Z and S, and SC is the altitude. ZS, which is the complement of SC, is called the *zenith distance*.

The *azimuth* of a heavenly body is the angle between the meridian plane through the point of observation and the vertical plane passing through the body. It can be compared with the "bearing" of plane trigonometry. In Fig. 138, the angle PZS is the azimuth of S.

The *hour angle* of a heavenly body is the angle at the pole, between the meridian plane through the point of observation and the great circle through the pole and the body.

Thus, in the figure, P is the pole, and PSD is the great circle passing through P and S; this being known as the "declination circle." Then $\angle ZPS$ = the hour angle of S, and it is usually expressed in terms of time rather than in degrees.

The *declination* of a heavenly body is the arc of the declination

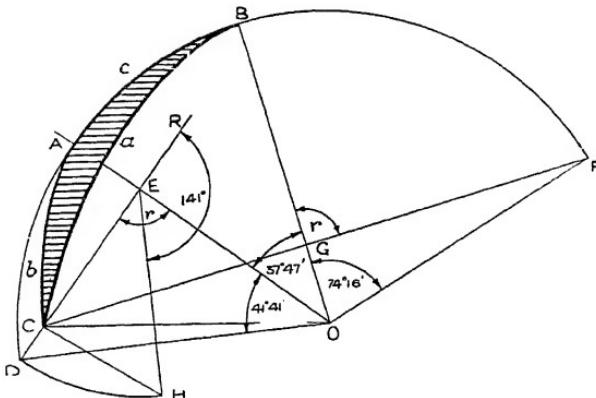


FIG. 139.

circle intercepted between the celestial equator and the heavenly body: thus DS is the declination of S.

The method of calculation can be best explained by working through a numerical example; and in order to ensure a clear conception of the problem, it is treated both graphically and analytically.

Example 4.—At a certain time at a place in latitude $52^{\circ} 13'$ N. the altitude of the Sun was found to be $48^{\circ} 19'$ and its declination was $15^{\circ} 44'$ N. Determine the azimuth.

As explained before, a spherical triangle can be constructed with sides as follows: $a = 90 - \text{declination} = 74^{\circ} 16'$, $b = 90 - \text{altitude} = 41^{\circ} 41'$, and $c = \text{co-latitude} = 37^{\circ} 47'$. Then the angle A is the azimuth (Fig. 139).

Graphic construction.—With any convenient radius OD describe an arc of a circle DABF. Draw OA, OB and OF, making the angle DOA = $b = 41^\circ 41'$, $\angle AOB = c = 37^\circ 47'$, and $\angle BOF = a = 74^\circ 16'$. Draw DCE at right angles to OA, and FGC at right angles to OB, intersecting at the point C. Note that C lies outside the triangle AOB. With centre E and radius ED construct the arc of a circle DH; draw CH perpendicular to DE to meet this arc at H and join EH. Then the angle REH is the value of the required angle A, and is found to be in the neighbourhood of 141° . [If C had fallen the other side of OA, the angle CEH would have been measured.]

The actual spherical triangle ABC is formed by the circular arc BA and the elliptical arcs AC and BC.

Proof of the construction—The side b is such that it subtends an angle of $41^\circ 41'$ at the centre of the sphere. Thus DA measures the actual length of b , but does not represent it in its true position. In like manner BF gives the length of a , but again does not give its position on the sphere.

Let the circular sector OAD be rotated about OA as axis, and the sector OBF about OB as axis, and let the rotation of both be continued until they have a common radius OC, i.e., OC is the intersection of the two revolving planes. Then evidently C is the third angular point of the spherical triangle ABC, since the given conditions concerning the lengths of the sides are satisfied by its position.

We observe that in this case the rotation of OBF has to be continued beyond OA, from which fact we gather that the angle at A must be obtuse. The line OA is in the plane of the paper, and taking a section along DE and turning this down to the plane of the paper, we observe that the actual height of C above the paper is CH. Thus EH is a line on the plane OAC, also ER is a line in the plane AOB, both lines being perpendicular to the line of intersection, and the angle REH therefore measures the inclination of the plane AOC to the plane AOB, this angle being by definition the angle A of the spherical triangle ABC.

By calculation.—Here we have the three sides given, and we wish to find an angle which may be done by use of equation (4), p. 357, viz.,

$$\tan \frac{A}{2} = \sqrt{\frac{\sin(s-b) \sin(s-c)}{\sin s \sin(s-a)}}.$$

$$\text{Now } s = \frac{a+b+c}{2} = \frac{74^\circ 16' + 41^\circ 41' + 37^\circ 47'}{2} = \frac{153^\circ 44'}{2} = 76^\circ 52',$$

$$\text{so that } s-a = 76^\circ 52' - 74^\circ 16' = 2^\circ 36'$$

$$s-b = 76^\circ 52' - 41^\circ 41' = 35^\circ 11'$$

$$s-c = 76^\circ 52' - 37^\circ 47' = 39^\circ 5'.$$

$$\text{Hence } \tan \frac{A}{2} = \sqrt{\frac{\sin 35^\circ 11' \times \sin 39^\circ 5'}{\sin 76^\circ 52' \times \sin 2^\circ 36'}}.$$

$$\text{and } \log \tan \frac{A}{2} = \frac{1}{2} \left[(\log \sin 35^\circ 11' + \log \sin 39^\circ 5') - (\log \sin 76^\circ 52' + \log \sin 2^\circ 36') \right]$$

$$= \frac{1}{2} \times \frac{1.76057 - 1.79965}{1.56022} - \left(\frac{1.98849}{2.65670} - \frac{1.64519}{2.64519} \right)$$

$$= \frac{1}{2} \times .91503 = .45752$$

thus $\frac{A}{2} = 70^\circ 46' 30''$

and $A = 141^\circ 33'$.

Exercises 25.—On the Solution of Spherical Triangles.

(4-figure log tables only have been used in the solution of these problems.)

In Nos. 1 to 6, solve the spherical triangle ABC, when

1. $a = 50^\circ$ $C = 90^\circ$ $b = 32^\circ 17'$.
2. $C = 90^\circ$ $a = 45^\circ 43'$. $A = 61^\circ 15'$.
3. $a = 72^\circ 14'$, $b = 43^\circ 47'$, $c = 29^\circ 33'$. Find also the value of B by the graphic method explained on p. 368.
4. $b = 52^\circ 5'$ $a = 58^\circ 25'$ $C = 64^\circ$.
5. $b = 27^\circ 13'$ $c = 51^\circ 18'$ $C = 85^\circ 9'$ and the spherical excess is $2^\circ 14'$.
6. $c = 79^\circ 49'$ $b = 28^\circ 5'$ $B = 15^\circ 18'$
7. If the sun's altitude is $17^\circ 58'$, its declination is $28^\circ 16'$ N., and its azimuth is N. $65^\circ 43'$ W., find the latitude of the place of observation.
8. The spherical excess of a triangle on the earth's surface is $1^\circ 15'$: taking the earth as a sphere of radius 3,960 miles, find the area of the triangle in square miles.
9. Given that the azimuth of the sun is 10° , and its zenith distance is $24^\circ 50'$ when its declination is $22^\circ 15'$, find the latitude of the place and also the hour angle.

CHAPTER XIII

MATHEMATICAL PROBABILITY AND THEOREM OF LEAST SQUARES

WHEN extremely accurate results are desired, these results being derived from a series of observations, the possibility of error in each or all of the observations must be considered. The correct result, or what is termed "the most probable result," is usually found by combining the mean of the observations with "the probable error of the mean." The work that is to follow is concerned primarily with the establishment of a rule enabling us to find this probable error; and as a preliminary investigation, a few simple rules of probability will be discussed.

Supposing that an event is likely to happen 5 times and to fail 7 times, then the probability that it will happen on any specified occasion is $\frac{5}{12}$, whilst its probability of failing is $\frac{7}{12}$, because, considered over a great range, it only happens 5 times out of 12. It is important to note the significance of the phrase "*considered over a great range*"; we could not say with truth that the event was bound to happen 5 times out of the first 12, 10 times out of the first 24, and so on; it might be doubtful whether it would happen 50 times out of 120. If, however, say, 12,000 opportunities offered, it would be fairly correct to say that the happenings would be 5,000 and the failures 7,000, for when a large number of occasions were considered, all "freaks" would be eliminated.

To take another illustration:—the probability that a man will score 90 per cent. of the full score or over on a target is $\frac{6}{11}$ indicates that he is rather more likely to score 90 per cent. than not (in the proportion 6 to 5) if he fires a great number of shots.

In general terms, if an event may happen in a ways and fail in b ways, and all these are equally likely to occur, then the probability of its happening is $\frac{a}{a+b}$, and of its failing $\frac{b}{a+b}$; and if

$a = b$, then it is as likely to happen as not, *i.e.*, its probability of either happening or failing is $\frac{1}{2}$.

Note. Probability of happening $= \frac{a}{a+b} \times \frac{a+b}{b} = \frac{a}{b}$,

i.e., the odds are a to b for the event, or b to a against it, the first form being used if $a > b$ and *vice versa*.

E.g., if the odds are 10 to 1 against an event, the probability of its happening $= \frac{1}{1+10} = \frac{1}{11}$; or it will probably happen once only out of eleven attempts.

Exclusive Events.—Let us now consider the case of two exclusive events, viz., the case in which the happenings do not concur.

Suppose the probability of the happening of the first event $= \frac{a}{a+b}$ and the probability of the happening of the second event $= \frac{A}{A+B}$. Then for purposes of comparison each of these fractions may be expressed with the same denominator: if this common denominator is c , write the fractions as $\frac{a_1}{c}$ and $\frac{a_2}{c}$ respectively.

Now out of c equally likely ways the first event may happen in a_1 ways and the second in a_2 ways, and since the two events are exclusive, *i.e.*, the happenings of the one do not coincide with the happenings of the other, the two events together may happen in $a_1 + a_2$ ways.

Hence the probability that one or the other will happen is $\frac{a_1+a_2}{c}$, which may be written in the form $\frac{a_1}{c} + \frac{a_2}{c}$, *i.e.*, as the sum of the separate probabilities.

E.g., suppose that one event happens once out of 8 times, and a second event happens three times out of 17, and that there is no possibility of the two events happening together; then, the common denominator of 8 and 17 being 136, the first event happens 17 times out of 136 and the second event happens 24 times out of 136, and hence, either the one or the other happens 41 times out of each 136.

Probability of the Happening together of Two Independent Events.—Suppose that one event is likely to happen once out of every 6 times, whilst another is likely to happen twice out of every 17 times; then the probability that the two will happen together must be smaller than the probability of the

happening of either—in fact, it must be the product of the separate probabilities; *i.e.*, the probability of the two events happening together $= \frac{1}{6} \times \frac{2}{17} = \frac{1}{51}$ or $\frac{1}{51}$; or out of every 10,200 times the first will probably happen 1,700 times, the second will probably happen 1,200 times, whilst the two would happen *together* 200 times only.

Probability of Error.—Bearing in mind these fundamental theorems, we can proceed to a study of the question of probability of error; making particular reference to its application in precision surveying.

It will be admitted that, for any well-made series of observations, the following assumptions may be regarded as reasonable:—

- (1) That small errors are more likely to occur frequently than large errors, and hence extremely large errors never occur.
- (2) That positive and negative errors are equally likely, *i.e.*, we are as likely to give a result that is .001 too high as one that is .001 too low.

Hence the probability of the occurrence of an error of a given magnitude, which is denoted by

$$\frac{\text{the number of errors of that magnitude}}{\text{total number of errors}}$$

depends in some way upon the magnitude of that error. Our first idea, therefore, might be that the probability of the occurrence of an error of magnitude x could be expressed as some linear function of x . It will be seen, however, that this is not in accordance with assumption (2); for assumption (2) demands that if a curve be plotted, the ordinates showing probabilities and the abscissæ indicating errors, it must be symmetrical about the y axis. The function must therefore be of an even power of x , and taking the simplest even power we say that y (the probability of occurrence of an error of magnitude x) $= f(x^2)$.

Now, from assumption (1) we note that the coefficient of x^2 must be negative, because y must decrease as x increases.

The probability of an error of magnitude x being included in the range x to $x + \delta x$ must thus depend on x^2 , and also on the range δx ; hence it would be reasonable to say that it $= f(x^2)\delta x$, because the greater the range the more is the chance of happening increased. Therefore, the probability that an error of magnitude x falls

between any assigned limits, $-a$ and $+a$, must be the sum of the probability $f(x^2)\delta x$ extended over the range $-a$ to $+a$,

$$\text{i.e., } P = \int_{-a}^a f(x^2)dx$$

this being the probability that the error does not exceed a .

Hence the probability that the error may have any value whatever (i.e., the probability is 1) must be expressed by

$$\int_{-\infty}^{+\infty} f(x^2)dx,$$

for the range is unlimited, so that

$$\int_{-\infty}^{\infty} f(x^2)dx \text{ must} = 1.$$

It has been proved by Lord Kelvin that $f(x^2)$ must be such that

$$f(x^2) \times f(y^2) = f(x^2 + y^2)$$

$$\text{and since } e^{x^2} \times e^{y^2} = e^{x^2 + y^2}$$

$$\text{and } e^{kx^2} \times e^{ky^2} = e^{k(x^2 + y^2)}$$

this condition will be satisfied if

$$f(x^2) = Ae^{kx^2} \text{ or } Ae^{-\frac{x^2}{h^2}}$$

the minus sign being inserted in accordance with assumption I on p. 372; and the coefficient k being written as $\frac{1}{h^2}$ for the reason that is explained later.

A value can now be found for the constant A.

$$\text{It is known that } \int_{-\infty}^{\infty} f(x^2)dx = 1,$$

$$\text{hence } A \int_{-\infty}^{+\infty} e^{-\frac{x^2}{h^2}}dx = 1.$$

Now it has already been proved (see p. 163) that

$$\int_0^{\infty} e^{-x^2}dx = \frac{\sqrt{\pi}}{2}$$

$$\text{and } \int_0^{\infty} e^{-\frac{x^2}{h^2}}dx = h\sqrt{\pi}$$

$$-\frac{x^2}{h^2}dx = 2 \int_0^{\infty} e^{-\frac{x^2}{h^2}}dx = h\sqrt{\pi}$$

hence

$$A \times h\sqrt{\pi} = 1,$$

or

$$A = \frac{1}{h\sqrt{\pi}}.$$

Thus

$$y = f(x^2) = \frac{1}{h\sqrt{\pi}} e^{-\frac{x^2}{h^2}}$$

the law being known as the Normal Error Law.

The curve representing this equation is called the probability curve and also Gauss's Error curve. Two such curves are plotted in Fig. 140, to show the effect of the variation of the parameter h . In the one case $h = .2$, and for the second curve $h = .5$; and it will be noticed on comparing the curves that for the smaller value of h the probability of the occurrence of *small errors* is greater, *i.e.*, the set of observations for which $h = .2$ would be more nearly correct than that for which $h = .5$.

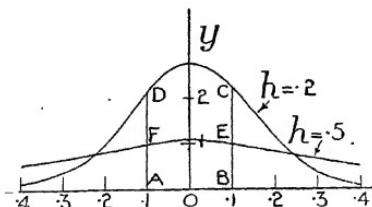


FIG. 140.

It will be seen that the curve is in agreement with the axioms stated on p. 372; for the probability of error is greatest when the error is least, the probability of a large error is very small, and there is as much likelihood of an error of $+2$, say, as of -2 .

The probability that the error does not exceed ± 1 is given by the area ABCD in the one case, and ABEF in the other.

Theorem of Least Squares.—If a number of observations are made upon a quantity, and the errors in each of these noted, *i.e.*, as nearly as can be estimated; then from a knowledge of these errors it is possible to find the most probable or likely value of the quantity.

Let n observations be taken and let the errors be x_1, x_2, \dots, x_n : also suppose that all the measurements are equally good, *i.e.*, the "fineness" of reading is the same throughout; h in the formulæ above being a measure of the fineness.

The probability of the error x_1 being within a certain range δx

will be the probability of an error of magnitude x_1 multiplied by the range δx , i.e., $P_1 = \delta x \times y_1$

$$= \delta x \times \frac{1}{h\sqrt{\pi}} e^{-\frac{x_1^2}{h^2}}$$

and for error x_2 $P_2 = \delta x \times \frac{1}{h\sqrt{\pi}} e^{-\frac{x_2^2}{h^2}}$, and so on.

Now x_1 x_2 etc. are quite independent, so that the probability of all the errors falling within the range δx will be the product of the separate probabilities, i.e.,

$$\begin{aligned} P &= P_1 \times P_2 \times \dots P_n \\ &= \frac{\delta x}{h\sqrt{\pi}} e^{-\frac{x_1^2}{h^2}} \times \frac{\delta x}{h\sqrt{\pi}} e^{-\frac{x_2^2}{h^2}} \times \dots \\ &= \frac{(\delta x)^n}{(h\sqrt{\pi})^n} \left[e^{-\left(\frac{x_1^2}{h^2} + \frac{x_2^2}{h^2} + \frac{x_3^2}{h^2} + \dots\right)} \right] \\ &= K e^{-\frac{1}{h^2}(\Sigma x^2)}. \end{aligned}$$

We have thus obtained an expression which gives us the probability of all the errors falling within a certain range. We might say that this range was ± 1 , for instance, or ± 0.5 . Evidently if all the errors were kept within the range -0.5 to $+0.5$ the calculated result would be a nearer approximation to the truth than if the range were double the amount stated.

Our object then is to find when the probability of a small error (δx may be reduced as we please) is greatest, i.e., to find when P is a maximum.

$$\text{Now } P = K e^{-\frac{1}{h^2}(\Sigma x^2)} = \frac{K}{\frac{1}{h^2}(\Sigma x^2)}$$

and the smaller the denominator is made, the larger will P become. But the only variable in the denominator is Σx^2 , and hence, in order that P may have its maximum value, Σx^2 must be the least possible. Hence the most probable value of the quantity to be determined is that which makes the sum of the squares of the errors the least.

The fact can now be established that the arithmetic mean of the observed values is the most probable value of the quantity,

Thus, if n observations are made,

let $a_1 a_2 a_3 \dots a_n$ be the respective observations

a the A.M. of these values

\bar{a} the value most probably correct

then $(a_1 - \bar{a})$ $(a_2 - \bar{a})$ etc. are known as *residual errors*.

Now the probability of making this system of errors

$$= P$$

$$= Ae^{-\frac{1}{h^2}[\Sigma(a_i - \bar{a})^2]}$$

or

$$P = Ae^{-\frac{1}{h^2}(a_1^2 + \bar{a}^2 - 2a_1\bar{a} + a_2^2 + \bar{a}^2 - 2a_2\bar{a} + \dots)}$$

$$= Ae^{-\frac{1}{h^2}[\Sigma a_i^2 + n\bar{a}^2 - 2\bar{a}(\Sigma a_i)]}$$

To differentiate P with regard to \bar{a} , put $u = \Sigma a_i^2 + n\bar{a}^2 - 2\bar{a}\Sigma a_i$

so that

$$\frac{du}{d\bar{a}} = 0 + 2n\bar{a} - 2\Sigma a_i$$

Then

$$P = Ae^{-\frac{1}{h^2}}$$

$$\frac{dP}{d\bar{a}} = \frac{dP}{du} \times \frac{du}{d\bar{a}}$$

$$= -\frac{A}{h^2}e^{-\frac{u}{h^2}} \times (2n\bar{a} - 2\Sigma a_i)$$

and

$$\frac{dP}{d\bar{a}} = 0 \text{ if } 2n\bar{a} - 2\Sigma a_i = 0$$

$$\text{or if } \bar{a} = \frac{1}{n}\Sigma a_i$$

but $\frac{1}{n}\Sigma a_i = a$ = A.M. of the observations

and hence $\bar{a} = a$

or the most probable value is the A.M. of the observations.

Again, if x is the error of the A.M. and $x_1 x_2 x_3$ etc. are the respective errors of the observations,

$$x = \frac{1}{n}(x_1 + x_2 + x_3 + \dots + x_n).$$

By squaring

$$\begin{aligned} x^2 &= \frac{1}{n^2}(x_1^2 + x_2^2 + x_3^2 + \dots + x_n^2 + 2x_1x_2 + 2x_1x_3 + \dots \\ &\quad + 2x_2x_3 + \dots) \end{aligned}$$

$$= \frac{1}{n^2}(\Sigma x_1^2) + \frac{2}{n^2}(\Sigma x_1x_2)$$

then, since it is assumed that all the observations are equally good, and that positive and negative errors are equally likely to occur,

$$x_1^2 = x_2^2 = x_3^2 = \dots = \mu^2 \text{ and } \sum x_i x_j = 0,$$

for all the errors are small and their products, two at a time, are still smaller.

Also

$$x^2 = \frac{1}{n^2} (n\mu^2) = \frac{\mu^2}{n}$$

or

$$x = \frac{\mu}{\sqrt{n}}$$

or the probable error of the A.M. = $\frac{\text{probable error of a single observation}}{\sqrt{n}}$,

and thus, other things being equal, the possibility of a large error in the final result is greatly reduced by taking a great number of observations. Also in a set of well-made observations, if a sufficient number are made, the arithmetic mean cannot differ from any of the observations to any very great extent, and accordingly the residual errors and the actual errors are very nearly alike.

We are now in a position to summarise the results of the investigation so far as we have pursued it; thus

(a) The arithmetic mean of the series of observations, which are supposed to have been made with equal care, is the most probable value of the quantity.

(b) The sum of the squares of the residual errors must be the least.

(c) The probable error of the A.M. is equal to the probable error of a single observation divided by the square root of the number of observations.

Example 1.—Seven observations of a certain quantity, all made with equal care, were 12, 11, 14, 12, 11.2, 11.7, and 12.1.

Find the most probable value of the quantity.

$$\text{The most probable value} = \text{A.M.} = \frac{84}{7} = 12,$$

and it can readily be shown, by actual calculation, that this value makes the sum of the squares of the residual errors the least.

The residual errors are

$$(12 - 12), (11 - 12), (14 - 12), (12 - 12), (11.2 - 12), (11.7 - 12)$$

$$\text{and } (12.1 - 12) \text{ or } 0, -1, 2, 0, -0.8, -0.3, +0.1$$

$$\text{and } \Sigma \text{ squares of residual errors} = 0 + 1 + 4 + 0 + 0.64 + 0.09 + 0.01$$

$$= 5.74.$$

To test whether this is the least, let us suppose that the most probable value is 11.5; then the residual errors are: .5, -.5, 2.5, .5, -3, .2 and .6 respectively.

$$\Sigma \text{ squares} = .25 + .25 + 6.25 + .25 + .09 + .04 + .36 = 7.49.$$

Similarly, if we assume, say, 12.2 as the most probable value,

$$\begin{aligned}\Sigma (\text{residual error})^2 &= (.2)^2 + (1.2)^2 + (1.8)^2 + (.2)^2 + (1)^2 + (.5)^2 + (.1)^2 \\ &= .04 + 1.44 + 3.24 + .04 + 1 + .25 + .01 \\ &= 6.02\end{aligned}$$

both of which totals exceed 5.74.

To find the Probable Error of the Arithmetic Mean.—

Let r = the probable error of any one of the observations; then if this is an "average" error, i.e., if errors greater are as likely to occur as errors smaller, the probability that the error is less than r is $\frac{1}{2}$.

Now, the probability that an error lies within the range $-r$ to $+r$

$$\begin{aligned}\text{is } \int_{-\sqrt{\pi}}^{+\sqrt{\pi}} e^{-\frac{r^2}{h^2}} dr &= \frac{2}{h\sqrt{\pi}} \int_0^r e^{-\frac{r^2}{h^2}} dr \\ &= \frac{2h}{h\sqrt{\pi}} \int_0^{\frac{r}{h}} e^{-\frac{r^2}{h^2}} dr\end{aligned}$$

(for $dr = hd\left(\frac{r}{h}\right)$ and the limits are now those for $\frac{r}{h}$ and not those for r).

There must be some connection between the amount of error and the fineness of measurement, i.e., between r and h , and this we must now find.

If $X = \frac{r}{h}$

$$\frac{2}{\sqrt{\pi}} \int_0^{\frac{r}{h}} e^{-\frac{r^2}{h^2}} d\left(\frac{r}{h}\right) = \frac{2}{\sqrt{\pi}} \int_0^X e^{-x^2} dx$$

and we see from the above statement that the value of this integral is to be $\frac{1}{2}$.

$$\text{Now } e^x = 1 + x + \frac{x^2}{2} + \frac{x^3}{6} +$$

$$\text{and thus } e^{-x^2} = 1 - X^2 + \frac{X^4}{2} - \frac{X^6}{6} +$$

and if X^2 is small we may perform the integration by way of expansion in series: if X^2 is not small the value of the integral would be read from probability tables which give the values of the integral $\frac{2}{\sqrt{\pi}} \int_0^X e^{-x^2} dx$: these tables being given in the *Transactions of the Royal Society of Edinburgh*, Vol. xxxix. For the present

application of the integral, however, X is a small quantity, and a sufficiently correct result is obtained by expanding in a series and calculating from a few terms in this series.

Thus

$$\begin{aligned} \frac{2}{\sqrt{\pi}} \int_0^{\frac{r}{h}-X^2} dX &= \frac{2}{\sqrt{\pi}} \left(\int_0^{\frac{r}{h}} \left(1 - X^2 + \frac{X^4}{3} - \frac{X^6}{10} + \dots \right) dX \right) \\ &= \frac{2}{\sqrt{\pi}} \left(X - \frac{X^3}{3} + \frac{X^5}{10} - \frac{X^7}{42} + \dots \right)_0^{\frac{r}{h}} \\ &= \frac{2}{\sqrt{\pi}} \left(\frac{r}{h} - \frac{r^3}{3h^3} + \frac{r^5}{10h^5} - \frac{r^7}{42h^7} + \dots \right) \end{aligned}$$

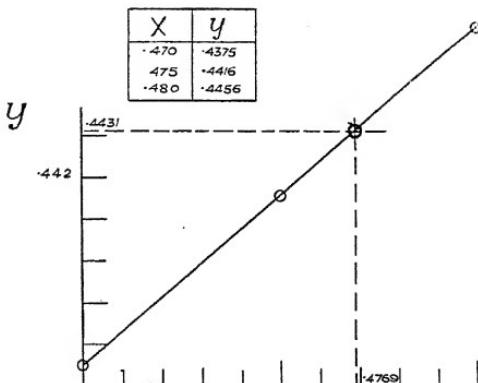


FIG. 141.

Hence $\frac{1}{2} = \frac{2}{\sqrt{\pi}} \left(\frac{r}{h} - \frac{r^3}{3h^3} + \frac{r^5}{10h^5} - \frac{r^7}{42h^7} + \dots \right)$

and this equation may be written

$$\frac{\sqrt{\pi}}{4} = \left(\frac{r}{h} - \frac{r^3}{3h^3} + \frac{r^5}{10h^5} - \frac{r^7}{42h^7} + \dots \right)$$

or if for $\frac{r}{h}$ we again write X

$$\cdot4431 = X - \frac{X^3}{3} + \frac{X^5}{10} - \frac{X^7}{42} + \text{terms which are very small.}$$

By selecting values of X and plotting, the solution of this equation is found, the final plotting being represented in Fig. 141, where it is seen that the solution is $X = \cdot4769$.

Thus $\frac{r}{h} = .4769$ or $r = .4769h$.

[If solved to a greater degree of accuracy, the value of $\frac{r}{h}$ is found to be $.47696h$, and this figure will be used in the work that follows.]

Again, if n equally good measurements have been made, each will have what is termed a *weight* of unity, *i.e.*, none is better or worse than any other, and when working towards the result to be deduced from the measurements, equal consideration must be paid to each measurement; also the A.M. is said to have a weight of n since on the average n observations of equal weight must be made to give a result as true as the A.M.

Knowing that $r_m = \frac{r}{\sqrt{n}}$

where r_m = probable error of the A.M.

and r = probable error of any observation

and also $\frac{\text{weight of A.M.}}{\text{weight of one observation}} = \frac{n}{1}$

which we can write as $\frac{w_m}{w} = \frac{n}{1}$

we can link up w_m and w with r_m and r ,

for $\frac{r_m^2}{r^2} = \frac{1}{n} = \frac{w}{w_m}$

or the weight varies inversely as the square of the probable error.

Thus the determination of the probable error, whilst a useful guide to the accuracy of the one set of observations, is more useful in fixing the relative weights that must be given to different sets of observations.

Thus, if three sets of observations have been made on a certain length with the results that the probable errors of the A.M. are 1.423 , $.917$, and 1.614 respectively; then the weights to be given to these sets are

$$\frac{1}{(1.423)^2} \quad \frac{1}{(.917)^2} \quad \frac{1}{(1.614)^2} \quad \text{respectively}$$

or $.494 \quad 1.19 \quad .384$.

Then in assessing for the final result, by far the most reliance would be placed on the second set of observations, less on the first, and least on the third set; this fact being well illustrated by

Fig. 142, the resultant weight being nearer to the weight 1.19 than to either of the other weights.

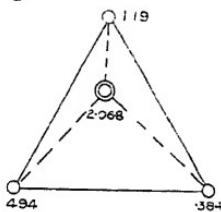


FIG. 142.

To return to the object of this paragraph :—

If x_1, x_2, x_3, \dots are the actual errors of observation, then the probability that each falls within the small range δx is

$$P_1 = \frac{1}{h\sqrt{\pi}} e^{-\left(\frac{x_1}{h}\right)^2} \delta x \quad P_2 = \frac{1}{h\sqrt{\pi}} e^{-\left(\frac{x_2}{h}\right)^2} (\delta x) \text{ etc.,}$$

and the probability that they all fall within this range at the same time will be less than either of the separate probabilities; it will actually be the product of these.

Thus $P = P_1 \times P_2 \times \dots$

$$\begin{aligned} &= \frac{1}{h\sqrt{\pi}} e^{-\left(\frac{x_1}{h}\right)^2} \delta x \times \frac{1}{h\sqrt{\pi}} e^{-\left(\frac{x_2}{h}\right)^2} \delta x \times \dots \\ &= \frac{(\delta x)^n}{h^n \pi^{\frac{n}{2}}} e^{-\frac{1}{h^2}(x_1^2 + x_2^2 + \dots)} \end{aligned}$$

We wish to find for what value of h P has its greatest value: hence differentiate P with respect to h .

$$\begin{aligned} P &= \frac{K}{h^n} \times e^{-\frac{1}{h^2}(\sum x_i^2)} \quad \text{where } K = \frac{(\delta x)^n}{\pi^{\frac{n}{2}}} \\ K &\quad = u \times v \\ \text{and } \frac{du}{dh} &= K \times -nh^{-n-1} = -nKh^{-(n+1)} \end{aligned}$$

$$v = e^{-\frac{1}{h^2}(\sum x_i^2)} \quad \text{or if } w = \frac{1}{h^2}(\sum x_i^2) \quad v = e^{-w}$$

$$\text{and thus } \frac{dw}{dh} = (\sum x_i^2) \times -2h^{-3}$$

$$\begin{aligned} \text{Also } \frac{dv}{dh} &= \frac{dv}{dw} \times \frac{dw}{dh} \\ &= \frac{de^{-w}}{dw} \times \frac{dw}{dh} = -e^{-\frac{1}{h^2}(\sum x_i^2)} \times -\frac{2(\sum x_i^2)}{h^3} \end{aligned}$$

Then

$$\begin{aligned} \frac{dP}{dh} &= v \frac{du}{dh} + u \frac{dv}{dh} \\ &= \left(e^{-\frac{1}{h^2}(\Sigma x_1^2)} \times -nKh^{-(n+1)} \right) + \left(\frac{K}{h^n} \times 2e^{-\frac{1}{h^2}(\Sigma x_1^2)} \times \frac{(\Sigma x_1)^2}{h^3} \right) \\ &= Ke^{-\frac{1}{h^2}(\Sigma x_1^2)} \left[-nh^{-(n+1)} + 2h^{-(n+3)}(\Sigma x_1^2) \right] \end{aligned}$$

and $\frac{dP}{dh} = 0$ if $nh^{-(n+1)} = 2h^{-(n+3)}(\Sigma x_1^2)$

i.e., if $h^2 = \frac{2\Sigma x_1^2}{n}$

$$\text{or } h = 1.414 \sqrt{\frac{\Sigma x_1^2}{n}}$$

Now it has already been proved that $r = .47696h$

$$\begin{aligned} \text{so that } r &= .47696 \sqrt{2} \sqrt{\frac{(\Sigma x_1^2)}{n}} \\ &= .6745 \sqrt{\frac{(\Sigma x_1^2)}{n}}. \end{aligned}$$

Also we have previously stated that the sum of the squares of the actual errors differs very little from the sum of the squares of residual errors; this being true if a great number of observations are taken. The difference in the two sums may be expressed rather more accurately by the relation

$$\Sigma x_1^2 = \frac{n}{n-1} \sum (\text{residual error})^2.$$

Hence if for $\sum (\text{residual error})^2$ we write $\sum (r_e^2)$

$$r = .6745 \sqrt{\frac{(\Sigma r_e^2)}{n-1}}$$

$$\text{and } r_m = \frac{r}{\sqrt{n}} = .6745 \sqrt{\frac{(\Sigma r_e^2)}{n(n-1)}}.$$

Applying these results to *Example 1* on p. 377,

$$\Sigma r_e^2 = 5.74$$

$$n = 7$$

$$\text{then } r = .6745 \sqrt{\frac{5.74}{6}} = .656$$

$$r_m = .6745 \sqrt{\frac{5.74}{7 \times 6}} = .2475$$

$$\text{also } h = \sqrt{\frac{2n \sum r_e^2}{(n-1) \times n}} = \sqrt{\frac{2 \times 5.74}{6}} = 1.38$$

i. e., h has a very high value; and this would be expected, for the "fineness" of reading, as judged by the results, is not at all good (one error being as much as 2 in 12).

Example 2.—In a chain survey four measurements of a base line gave 867·35, 867·51, 867·28 and 867·62 links respectively. Find the best length and the probable error in this length.

The best result is the A.M. of these, i. e.,

$$\begin{array}{r} 867.35 + 867.51 + 867.28 + 867.62 \\ \hline 4 \\ = 867.44 \text{ links} \end{array}$$

and whilst this is the best result it contains a probable error.

Probable error in A.M.

$$\begin{aligned} &= r_n = .6745 \sqrt{\frac{\Sigma r_e^2}{n(n-1)}} \\ &= .6745 \sqrt{\frac{(-.09)^2 + (.07)^2 + (-.16)^2 + (.18)^2}{4 \times 3}} \\ &= .6745 \sqrt{\frac{.071}{12}} \\ &= .0517 \end{aligned}$$

i. e., the base line measurement (867·44) is subject to an error of .0517 link, and as this result could not be bettered it would be unnecessary to repeat this portion of the survey.

The probable error in any one observation would be

$$r = .6745 \quad : = .103,$$

so that there is a decided gain in accuracy obtained by increasing the number of observations. (Cf. "repetition," when working with the theodolite.)

It is of interest to find h for this example.

$$h = \sqrt{\frac{2 \times .071}{3}} = .2176$$

and as this is a small quantity we are confirmed in our conclusion that the observations were well made.

Example 3.—The mean values of the three angles of a spherical triangle were calculated from the actual observations to be $75^\circ 40' 21.6''$, $39^\circ 11' 47.3''$, and $65^\circ 7' 56.2''$; and these values were subject to probable errors $2.9''$, $3.6''$, and $4.3''$ respectively. From a knowledge

of the area of the triangle, the spherical excess of the triangle was found to be $3\cdot3''$. Make the necessary adjustments to the angles to satisfy this condition.

The actual spherical excess

$$\begin{aligned} &= (75^\circ 40' 21\cdot6'' + 39^\circ 11' 47\cdot3'' + 65^\circ 7' 56\cdot2'') - 180^\circ \\ &= 5\cdot1''. \end{aligned}$$

There is thus ($5\ 1-3\cdot3$) to be divided among the angles, according to the respective weights; and these weights are in the proportion

$$\begin{array}{ccc} 2\cdot9^2 & 3\cdot6 & 4\cdot3^2 \\ \text{or} & 8\cdot41 & 12\cdot96 & 18\cdot49, \end{array}$$

the sum of the weights being $39\cdot86$.

Hence the corrections to be applied are $\frac{8\cdot41}{39\cdot86} \times 1\cdot8$, $\frac{12\cdot96}{39\cdot86} \times 1\cdot8$, and $\frac{18\cdot49}{39\cdot86} \times 1\cdot8$ to the respective angles; all these corrections being subtracted, since the observed angles give a spherical excess greater than should actually be the case.

These corrections are $\cdot380$, $\cdot585$, and $\cdot835$.

Hence the true angles are $(75^\circ 40' 21\cdot6'' - \cdot38'')$, $(39^\circ 11' 47\cdot3'' - \cdot59'')$ and $(65^\circ 7' 56\cdot2'' - \cdot84'')$,

$$\text{or } \underline{75^\circ 40' 21\cdot22''}, \underline{39^\circ 11' 46\cdot71''} \text{ and } \underline{65^\circ 7' 55\cdot36''}.$$

Example 4.—Measurements of an angle in a traverse survey were made by two different observers, with the following results:—

Readings by A.	Readings by B.
$76^\circ 50' 20''$	$76^\circ 50' 55''$
$76^\circ 50' 50''$	$76^\circ 50' 35''$
$76^\circ 50' 30''$	$76^\circ 51' 15''$
$76^\circ 51' 10''$	$76^\circ 51' 20''$
$76^\circ 50' 30''$	$76^\circ 51' 0''$
$76^\circ 51' 0''$	$76^\circ 50' 45''$
$76^\circ 50' 40''$	$76^\circ 50' 25''$
$76^\circ 50' 30''$	$76^\circ 50' 40''$

Compare the two results from the point of accuracy, and find the most probable value of the angle.

We must first find the arithmetic mean of each set of observations, and then, by subtracting this from each reading, we determine the residual errors.

$$\begin{array}{ll} \text{The A.M. of set A} & = 76^\circ 50' 41\cdot25'' \\ \text{and A.M. of set B} & = 76^\circ 50' 51\cdot88''. \end{array}$$

Since the differences are of seconds only, we need not concern ourselves for the present with the degrees and minutes; and thus the table of residual errors and their squares becomes

Residual Error.	(Residual Error) ² .	Residual Error.	(Residual Error) ² .
-21.25	451.4	+ 3.12	9.7
+ 8.75	76.6	-16.88	284.9
-11.25	126.6	+23.12	534.6
+28.75	826.8	+28.12	790.7
-11.25	126.6	+ 8.12	66.0
+18.75	351.6	- 6.88	47.3
- 1.25	1.6	-26.88	722.4
-11.25	126.6	-11.88	141.2
sum	0	2087.8	2596.8

In case A $r_m = .6745 \sqrt{\frac{2087.8}{8 \times 7}} = 4.119.$

In case B $r_m = .6745 \sqrt{\frac{2596.8}{8 \times 7}} = 4.594.$

Then the $\frac{\text{weight of observations by A}}{\text{weight of observations by B}} = \frac{(4.594)^2}{(4.119)^2} = \frac{1.244}{1}$

Thus A's readings can be relied on before those of B; the former being roughly $1\frac{1}{2}$ times as good as the latter.

The most probable value of the angle, taking into account the two sets of readings, will be obtained by the calculation of the "weighted mean," i.e., the mean of the two arithmetic means already found, determined with due regard to the respective weights to be given to A's readings and B's readings.

Dealing only with the seconds, the most probable value

$$= \frac{(41.25 \times 1.244) + (51.88 \times 1)}{1 + 1.244}$$

$$\frac{51.31 + 51.}{2.244} \cdot \frac{103.19}{2.244} = 46 \text{ seconds.}$$

Hence the most probable value of the angle = $76^{\circ} 50' 46''$.

Application of the Principle of Least Squares to the Determination of Laws.—If corresponding values of two variables
C C

x and y are given, and it is thought that the relation between them is $y = a + bx$ the values of a and b can be found from a plotting of y against x . This method necessitates the careful selection of the best straight line for the plotted points, and, in cases in which the values to be plotted are obtained from experimental results, it is often difficult to decide which is really the best line. The most probable law can, however, be found without any plotting, and with great accuracy, by a process based upon the principle of least squares.

The most probable law is that which makes the sum of the squares of the differences between the values of y calculated from the equation and the given values of y the least. Thus, if $y = a + bx$ is the form of equation desired, the most probable values of a and b are those found from the fact that $\Sigma(y - y_c)^2$ must be the least; y_c being the calculated value of y .

Now $y_c = a + bx$, so that $\Sigma(y - a - bx)^2$ must be a minimum.

Again, $\Sigma(y - a - bx)^2$ depends upon both a and b , so that it is a minimum if

$$\frac{\partial}{\partial a} \Sigma(y - a - bx)^2 = 0 \quad [b \text{ being constant}]$$

$$\text{and} \quad \frac{\partial}{\partial b} \Sigma(y - a - bx)^2 = 0 \quad [a \text{ being constant}]$$

$$\frac{\partial}{\partial a} \Sigma(y - a - bx)^2 = 0 \quad \text{if } \frac{\partial \Sigma(y - a - bx)^2}{\partial(y - a - bx)} \times \frac{\partial(y - a - bx)}{\partial a} = 0$$

$$\text{i.e. if} \quad 2\Sigma(y - a - bx) \times -1 = 0$$

$$\text{if} \quad \Sigma y - na - b\Sigma x = 0$$

$$\text{or if} \quad \Sigma y = na + b\Sigma x \dots \dots \dots \quad (1)$$

where n is the number of sets of values and consequently the number of times that a occurs when calculating the differences.

$$\text{In like manner} \quad \frac{\partial}{\partial b} \Sigma(y - a - bx)^2 = 0$$

$$\text{if} \quad 2\Sigma(y - a - bx) \times -x = 0$$

$$\text{i.e. if} \quad \Sigma xy - a\Sigma x - b\Sigma x^2 = 0$$

$$\text{or} \quad \Sigma xy = a\Sigma x + b\Sigma x^2 \dots \dots \dots \quad (2)$$

so that two equations can be formed from the given values of x and y , and the values of a and b found therefrom.

Example 5.—In a test on two metallic filament lamps connected in parallel the following values of the volts V and the resistance R were obtained :—

V	54	60	65	70	75	80	85	90	105
R	108	109	114	118	123	127	131	134	146

Find the most probable law connecting R and V in the form

$$R = a + bV.$$

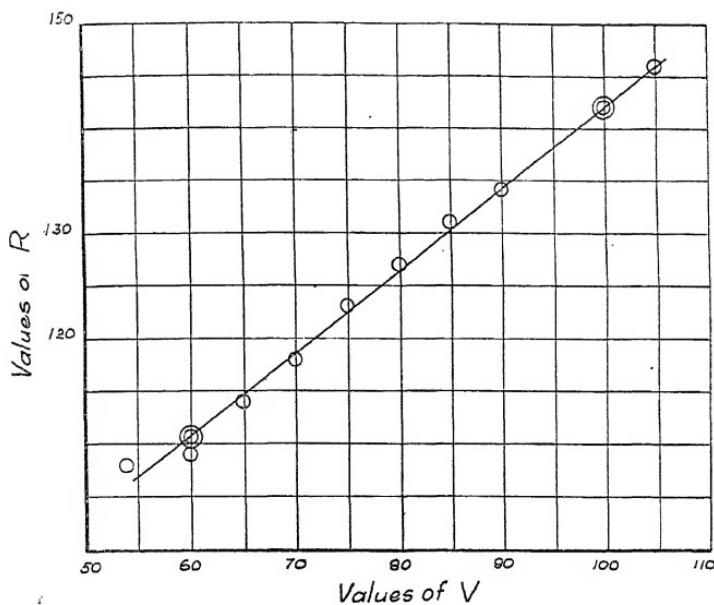


FIG. 143.

In Fig. 143 R is plotted against V and a line is drawn which seems to fit the points well. Selecting two convenient points on the line, and substituting the values in the equation, we have

$$142 = 100b + a$$

$$111 = 60b + a$$

$$\text{whence } 31 = 40b \quad \text{and} \quad b = .775$$

$$\text{and} \quad a = 142 - 77.5 = 64.5$$

or the equation obtained from the graph is $R = 64.5 + .775V$.

We cannot be certain that this is the most accurate equation for the values as given; to obtain this we proceed as follows:—

V	54	60	65	70	75	80	85	90	105	$\Sigma V = 624$
R	108	109	114	118	123	127	131	134	146	$\Sigma R = 1110$
VR	5832	6540	7410	8260	9225	10160	11135	12060	15330	$\Sigma VR = 85952$
V^2	2916	3600	4225	4900	5625	6400	7225	8100	11025	$\Sigma V^2 = 54016$

also $n = 9$, hence

$$1110 = 9a + 684b \quad \dots \dots \dots \dots \quad (1)$$

$$85952 = 684a + 54016b \quad \dots \dots \dots \dots \quad (2)$$

Multiplying (1) by 76 and subtracting

$$85952 = 684a + 54016b$$

$$84360 = 684a + 51984b$$

$$1592 = 2032b$$

or

$$b = .7835$$

and, by substitution in equation (1)

$$1110 = 9a + 535.98$$

$$a = 63.78.$$

Hence the most probable law for the given values is

$$R = 63.78 + .7835V.$$

We may test this result by calculating values of R from it, and comparing with the values of R calculated from $R = 64.5 + .775V$, thus:—

V	54	60	65	70	75	80	85	90	105	—
R_g	106.35	111	114.875	118.75	122.625	126.5	130.375	134.25	145.375	—
R_e	106.089	110.79	114.7075	118.625	122.5425	126.46	130.3775	134.295	146.0475	—
$R - R_g$	1.65	— 2	— .875	— .75	*375	*5	*625	— .25	*125	$\Sigma = -.6$
$R - R_e$	1.911	— 1.79	— .7075	— .625	*4575	*54	*6225	— .295	— .0475	$\Sigma = .066$
$(R - R_g)^2$	2.7225	4	.7656	.5625	.1406	.25	.3906	.0625	.0156	$\Sigma = 8.9059$
$(R - R_e)^2$	3.6519	3.2041	.5006	.3906	.2093	.2916	.3875	.0870	.0023	$\Sigma = 8.7249$

$$\text{where } R_g = 64.5 + .775V \text{ and } R_e = 63.78 + .7835V.$$

It is seen that both $\Sigma(R - R_e)$ is less than $(R - R_g)$ and $\Sigma(R - R_e)^2$ is less than $\Sigma(R - R_g)^2$, the differences being small, which indicates

that the choice of the line can be made with reasonable accuracy even in cases where the points are somewhat off the line.

When the values of y and x are connected by an equation of the form $y = a + bx + cx^2$ the points lie on, or about, a curve, and it is more difficult to fit a curve to a series of points than to find the best straight line for them. In cases where great accuracy is desired, it is the better plan to use the method of this paragraph, although the calculation is wearisome.

To find the most probable values of a , b and c , it is necessary to equate to zero the partial derivatives of $\Sigma(y - a - bx - cx^2)^2$ with respect to a , b and c respectively.

By so doing the three equations obtained are :—

$$\Sigma y = na + b\Sigma x + c\Sigma x^2$$

$$\Sigma xy = a\Sigma x + b\Sigma x^2 + c\Sigma x^3$$

$$\Sigma x^2y = a\Sigma x^2 + b\Sigma x^3 + c\Sigma x^4$$

and consequently Σx , Σx^2 , Σx^3 , Σx^4 , Σy , Σxy and Σx^2y must be found.

Example 6.—If $y = a + bx + cx^2$ and corresponding values of y and x are

x	0	2	5	10
y	4	7	6.4	-6

find the most probable values of a , b and c .

The table of values reads :—

x	0	2	5	10	$\Sigma = 17$
y	4	7	6.4	-6	$\Sigma = 11.4$
xy	0	14	32	-60	$\Sigma = -14$
x^2	0	4	25	100	$\Sigma = 129$
x^2y	0	28	160	-600	$\Sigma = -412$
x^3	0	8	125	1000	$\Sigma = 1133$
x^4	0	16	625	10000	$\Sigma = 10641$

from which the equations are formed,

$$\begin{aligned} 11.4 &= 4a + 17b + 129c \\ - 14 &= 17a + 129b + 1133c \\ - 412 &= 129b + 1133c + 10641 \end{aligned}$$

and the solutions of these equations are

$$a = 4.0771, \quad b = 1.9794, \quad c = - .2989$$

so that the best law for the given values is

$$y = 4.0771 + 1.9794x - .2989x^2.$$

Exercises 26.—On the Calculations of Errors of Measurements.

1. One surveying party measured a certain base line as 6 chains 42.7 links, 6 chains 53.5 links, 6 chains 46.4 links, and 6 chains 41.9 links; and a second party measured the same line as 6 chains 38.4 links, 6 chains 39.7 links, 6 chains 46.9 links, and 6 chains 43 links. State which of the two parties is the more dependable, and find the most probable length of the line.

2. Plot the probability curve $y = \frac{1}{h\sqrt{\pi}} e^{-\frac{x^2}{h^2}}$ the value of h being 14.14, and find the probability that an error lies within the limits -6 and $+6$.

3. The following are the values of the determination of the azimuth of Allen from Sears, Texas, the results of a U.S. Coast and Geodetic Survey; the values of the seconds only being stated after the first reading: 98° 6' 41.5", 42.8, 43.4, 43.1, 39.7, 42.7, 41.6, 43.3, 40.0, 45.0, 43.3 and 40.7. Find the A.M., the probable error of a single observation and the probable error of the mean.

4. Find the weighted mean of the following observations: 95.8, 96.9, 97.2, 95.4, 95.7, 97.1, 96.5, 96.7 and 97; the probable errors in the measurements being .2, .4, .1, .9, .7, 1.2, .8, .3 and 1.5 respectively.

5. Find the most probable relation between the twisting moment T and the angle of twist α for the following case :—

α	0	.34	.67	1	1.35	1.7	2.05
T	0	1200	2400	3600	4800	6000	7200

6. Calculate the probable error r of a single observation, taking the figures in Example 1, p. 377, but using Peters' formula

$$r = \frac{.8453}{\sqrt{n(n-1)}} \Sigma [\text{residuals (without reference to sign)}].$$

ANSWERS TO EXERCISES

Exercises 1

3. $E = \text{constant} \times \frac{dZ}{dt}$

4. $V = RC + L \frac{dC}{dt}$

 5. -11.03 cms. per sec. : 1.07 secs. from start 6. $.336$ ton

 11. 5.65 12. Middle of May : middle of October

 15. Loading is $.2$ ton per foot run 16. $.966$: $\frac{d \sin \theta}{d \theta} = \cos \theta$

 17. $.42$ ton per foot 21. 6.3

Exercises 2

1. $4x^3$

2. -128

3. $-2h$

4. $27x^8$

5. $-\frac{75}{x^6}$

6. $-\frac{18.75}{x^{1.23}}$

7. $32.6x^{.72}$

8. $\frac{.0086}{x^{.84}}$

9. $31.8x^{10.68}$

10. $-\frac{1.11}{x^{1.1}}$

11. $-\frac{.982}{x^{2.3}}$

12. $.62x^{8.3}$

13. $45x^2 - 44.8x^{1.8} + \frac{21}{x^4}$

14. 0

15. $-\frac{.19a^2b^{1.75}}{x^{1.5}}$

16. -347

17. $.71v^{3.84} + \frac{.84}{v^{4.36}} + \frac{1.29}{v^{4.44}} - \frac{.525}{v^{5.2}} - \frac{12.48}{v^{5.16}}$

18. 10.74

19. $.25p$

20. $.073$

21. $1 - a - \frac{2}{3}bP^{-\frac{1}{3}}$

22. $w\left(\frac{xy}{l} + \frac{xy^2}{l^2} - \frac{y^3}{l}\right) - x$

23. $.289l$

24. $\frac{w}{yl}(xy + ny^2 - xl)$

25. $h = \frac{d}{l} \sqrt{1 + \frac{l}{d}}$

26. $-2(p + q)$

27. 7.85

28. $w\left(\frac{ry}{l} - x\right)$

29. 9.6

30. -7333

Exercises 3

1. Sub-normal = 466 ; sub-tangent = 1 2. 25.7

3. $y = .0256x$; (x is distance from centre): $.64$

4. $p = -15.5v + 142.5$ 5. $M = \frac{W}{2} \left(\frac{l}{2} - x \right)$: $S = -\frac{W}{2}$: $L = 0$

6. $M = \frac{w}{2} \left(\frac{l^2}{4} - x^2 \right)$: $S = -wx$: $L = -w$

7. $M = W(l - x)$: $S = -W$: $L = 0$

8. Sub-tangent = $\frac{81a^2}{5b^2}$: sub-normal = $5b^2$

9. 3

10. $\frac{x}{2EI}(wl - wx - 2P)$

Exercises 4

- $$1. -5e^{-5x} \quad 2. 6 \cdot 15e^{4 \cdot 1x} \quad 3. -\frac{189}{e^{7x}} \quad 4. 1 \cdot 423 (4 \cdot 15)^x$$
- $$5. 4 \cdot 33 (8 \cdot 72)^{2x} \quad 6. 9e^{9x} - 35e^{-7x} \quad 7. 5 \cdot 44x^{1 \cdot 718} \quad 8. 9 \cdot 7 (2)^x$$
- $$9. 10 \cdot 25e^{25x} - \frac{3 \cdot 04}{x^{1 \cdot 8x}} \quad 10. 16e^{5 \cdot 1x} - 47 \cdot 25x^{8 \cdot 45} + 3 \cdot 39 (3 \cdot 1)^{3x}$$
- $$11. 12 \cdot 6e^{4 \cdot 2x} \quad 12. \frac{1}{x} \quad 13. \frac{15}{5x - 4} \quad 14. \frac{4 \cdot 343}{x}$$
- $$15. \frac{4ac}{4ax + 5b} \quad 16. -1 \cdot 8e^{-2x} - \frac{1}{x} - \frac{2 \cdot 46}{x^{1 \cdot 43}}$$
- $$17. \frac{1}{x} + \frac{3}{3x - 4 \cdot 7} \text{ or } \frac{6x - 4 \cdot 7}{x(3x - 4 \cdot 7)} \quad [\text{Use the rule } \log AB = \log A + \log B]$$
- $$18. \frac{5}{5x + 4} + \frac{1}{3x - 2} + \frac{1}{7 - 4x} \quad 19. 3e^{3x} + 8 \sinh 2x - \frac{738}{x}$$
- $$20. \frac{2}{x} - \frac{3 \cdot 5}{x^{1 \cdot 7}} - 1 \cdot 057 (1 \cdot 8)^x \quad 21. 0 \quad 22. 1 \cdot 052 \quad 23. \frac{2 \cdot 84}{0 \cdot 04u - 18}$$
- $$24. \frac{4343}{t} \quad 25. 2T \quad 26. \frac{C_0 R}{L} e^{-\frac{Rt}{L}} \quad 27. \frac{1 \cdot 587}{1 \cdot 8u - 7}$$
- $$28. \frac{5}{4} \sinh \frac{x}{4} : \frac{p}{q} \cosh \frac{y}{q} \quad 29. lxE \quad 30. \frac{p_1}{p_0} \quad 31. b$$
- $$32. 0 \quad 33. 0 \quad 34. \frac{B}{x} + C - \frac{D}{x^2}$$

Exercises 5

- $$1. -5 \cdot 3 \cos(4 - 5 \cdot 3x) \quad 2. -16 \cdot 32 \sin 5 \cdot 1x \quad 3. \cdot 48 \sec^2(3x + 9)$$
- $$4. \cdot 914 \cos(425x - 1 \cdot 25) \quad 5. -40 \operatorname{cosec}^2 x \quad 6. -\frac{5 \cdot 05 \sin(0 \cdot 05 - 117x)}{\cos^2(0 \cdot 05 - 117x)}$$
- $$7. gbc \sin(d - gx) \quad 8. -20 \sin 5x - 14 \cos(2x - 5)$$
- $$9. 4 \cdot 4 \cos 8 \cdot 8x + 8 \cos 1 \cdot 6x \quad [\text{Use the rule: } 2 \sin A \cos B = \sin(A + B) + \sin(A - B)]$$
- $$10. -6 \cdot 74 \sin 6 \cdot 2x - 3 \cdot 04 \sin 2 \cdot 8x$$
- $$11. 4 \cdot 52 \left\{ \frac{1}{q-p} \sin(px - qx + 2c) + \frac{1}{p+q} \sin(px + qx) \right\}$$
- $$12. 5 \sin 2x. \quad \{\text{Use the rule: } \cos 2A = 1 - 2 \sin^2 A\} \quad 13. -1 \cdot 195 \sin 6x$$
- $$14. 0 \quad 15. 5 \cdot 16x^{72} - \frac{15 \cdot 42}{3x - 4 \cdot 1} - 0 \cdot 0273 \cos(4 \cdot 31 - 1 \cdot 195x) + 24 \cdot 93$$
- $$16. \cdot 1056 \cos 0 \cdot 015x - 0 \cdot 0529 \sin(6 \cdot 1 - 2 \cdot 3x) + 7 \cdot 4 \sec^2(4x - 0 \cdot 07)$$
- $$17. \text{Velocity} = 37 \cdot 7 \sin 31 \cdot 4t - 56 \cdot 56 \cos 31 \cdot 4t; \quad \text{acceleration} = 1184 \cos 31 \cdot 4t + 1777 \sin 31 \cdot 4t$$
- $$18. \text{Acceleration} = -0 \cdot 0289g; \quad \text{S.H.M.} \quad 19. -1 \cdot 162$$
- $$20. \text{Sine curve (i.e., second derived curve).}$$
- $$21. 0 \quad \left\{ \text{Treat as a constant the portion } \frac{Bl}{8 \left(\frac{EI\pi^2}{l^2} - F \right)} \right\}$$
- $$22. \frac{dE}{dt} = 1500p \cos pt + 300p \cos 3pt + 42p \sin pt - 84p \sin 3pt$$

Exercises 6

1. $2 \cos 2x \cdot e^{\sin 2x}$
2. $\frac{2}{v}$
3. $-2 \sin 2t$
4. $24x^2 \cdot \cos x^3$
5. $3 \cdot 14 (10x + 7) \sec^2(5x^2 + 7x - 2)$
6. $3 \log a \cdot \cos 3x \cdot a^{\frac{x}{3}}$
7. $1 \cdot 85x^{85} \cdot e^{x^{1.85}}$
8. $\frac{4343(7 - 27x^2)}{3 + 7x - 9x^3}$
9. $-5 \sin(\log s^5)$
10. cosec x
11. $\frac{\sec^2 \theta}{\sec^2 \phi \cos \alpha}$
12. $\frac{\sin \theta}{1 + \cos \theta} \quad \left(\frac{dy}{dx} = \frac{dy}{d\theta} \times \frac{d\theta}{dx} \right)$
13. $\left(\frac{d \log h}{d \log V} \right) = \text{slope of curve} = \frac{d \log h}{dh} \times \frac{dh}{dV} \times \frac{dV}{d \log V}$
15. 1.08 ft. per min. : 377 ft. per min.
16. 0.0332 lb. : 0.0102 d
19. $7 \operatorname{cosec} 7t + 45t^2$
20. $\frac{\text{Ful}}{\text{EA}}$
21. $56^\circ 19'$
22. $53^\circ 7'$
24. $\frac{144t^2}{6t^3 - 37}$

Exercises 7

1. $x(2 \sin 3x + 3x \cos 3x)$
2. $2x^{2.4}(1 + 3.4 \log 5x)$
3. $e^{9x} \left(9 \log_{10} 9x + \frac{4343}{x} \right)$
4. $-\frac{4}{x^5 \cos(3 \cdot 1 - 2.07x)} \left\{ \frac{2.07}{\cos(3 \cdot 1 - 2.07x)} + \frac{5 \sin(3 \cdot 1 - 2.07x)}{x} \right\}$
5. $-\{2.575 \sin(5.15x + 4) + 625 \sin(1.25x - 4)\}$ or
 $-\{3.2 \sin 3.2x \cos(1.95x + 4) + 1.95 \cos 3.2x \sin(1.95x + 4)\}$
6. $\sec^2 2x \{2 \cos(5 - 3x) + 1.5 \sin(5 - 3x) \sin 4x\}$ or
 $3 \tan 2x \sin(5 - 3x) + 2 \sec^2 2x \cos(5 - 3x)$
7. $12.8x^{6.6} \{ \cos(3 + 8x) + 2 - 5x \sin(3 + 8x) \}$
8. $27(5)^{3x} \left\{ 4.83 \log x + \frac{1}{x} \right\}$
9. $(1 + \log x) e^{x \log x}$
10. $5x^2 e^{4x}$
11. $30e^{5x+2} (5x+4)(5x+2)$
12. $50 \cdot 4 \left(\frac{\tan 1.25x}{x} + \frac{\log x}{8 \cos^2 1.25x} \right)$
13. o
14. $-5e^{-10t}$
15. o
16. $12600 \sin(14t - 116)$
17. $6t \{5 \sin(4 - .8t) - 2t \cos(4 - .8t)\}$
18. $4t^{2.7} (3.7 \cos 3t - 3t \sin 3t)$

Exercises 8

- $\frac{5x^2(3 - 7x)}{e^{7x-5}}$
2. $\frac{7}{\cos(2 - 7x)} \left\{ \frac{1}{7x-2} - \log(2 - 7x) \tan(2 - 7x) \right\}$
- $\frac{20}{\sqrt{49 - 16x^2}}$
4. $-\frac{b}{\sqrt{d^4 - b^2x^2}}$
5. $-\frac{5.46(5)^{2.2x}}{e^{9x-4}}$
- $\frac{1.8}{4^{1.8x}} (\sinh 1.8x - 1.386 \cosh 1.8x)$ or $-\frac{9}{4^{1.8x}} (2.386e^{-1.8x} + 3.86e^{1.8x})$
8. $\frac{63x \cos^{-1} 3x - 21\sqrt{1 - 9x^2}}{(1 - 9x^2)^{\frac{3}{2}}}$
- $\frac{wb(ab - 2bx + x^2 \cot B)}{2(b - x \cot B)^2}$
10. $\frac{-}{(a^2 + x^2)^{\frac{3}{2}}}$

$$11. \frac{56x^3 - 111lx^2 + 72l^2x - 14l^3}{(3l - 4x)^2}$$

$$12. \frac{e^{\sin(1.2x+1.7)}}{\log(8x^2-7x+3)} \times$$

$$\left\{ 1.2 \cos(1.2x+1.7) \log(8x^2-7x+3) + \frac{7-16x}{8x^2-7x+3} \right\}$$

$$13. \operatorname{sech}^2 x$$

$$14. \frac{6.55(\sin \theta - \theta \cos \theta)}{\theta^{\frac{3}{2}}(\theta - \sin \theta)}$$

$$15. \frac{66.2(\theta - \sin \theta)^{\frac{1}{2}}(2\theta - 3\theta \cos \theta + \sin \theta)}{\theta^{\frac{3}{2}}}$$

$$16. \frac{1}{1-y^4}$$

$$17. r\omega^2 \left[\cos \theta + \frac{\sin^4 \theta - 2m^2 \sin^2 \theta + m^2}{(m^2 - \sin^2 \theta)^{\frac{3}{2}}} \right] : r\omega^2 \left(1 + \frac{1}{m} \right)$$

$$18. \frac{d\phi}{dt} = \frac{\omega \cos \theta}{\sqrt{m^2 - \sin^2 \theta}} : \frac{d^2\phi}{dt^2} = \frac{\omega^2 \sin \theta (1 - m^2)}{(m^2 - \sin^2 \theta)^{\frac{3}{2}}}$$

$$19. \frac{w \tan^2 \theta - q}{(p - q) \sin^2 \theta} : \pm \sqrt{\frac{q}{w}} \quad 20. \frac{w}{2(3l-2x)^2} (3l^3 + 24x^2l - 18xl^2 - 8x^3)$$

$$21. \frac{5}{t^4} \left\{ \frac{5t}{5t-8} - 3 \log(5t-8) \right\}$$

Exercises 9

$$1. \sqrt{r_1^2 b^2 + r_2^2 a^2}$$

$$2. 7.52x^5 e^{2y} : 75.2e^{2y} x^3$$

$$3. \frac{5e^{4t}}{5p-3} - t^2 : 5 \cdot 2t^{4-2} - 2pt + 4e^{4t} \cdot \log(5p-3)$$

$$4. 10(4-u)(9-4u)(3+8u)^2$$

$$6. 8(1.7+x)(1.7+x)^3$$

$$7. -\frac{3x^2 + 18x + 31}{(x^2 + 6x + 5)^3}$$

$$8. \frac{v}{c\tau} \left(\frac{dp}{dt} - \frac{p}{\tau} \cdot \frac{dt}{d\tau} \right)$$

Exercises 10

$$1. 75^\circ$$

$$2. 17.1$$

$$3. \frac{l}{2} : \frac{\omega l^2}{8}$$

$$4. 577l : 12SWl$$

$$5. .5$$

$$6. -2.25 : \text{minimum}$$

$$7. .278 : \text{maximum}$$

$$8. \text{maximum at } x = -5 : \text{point of inflection at } x = -2$$

$$9. 2 \text{ rows of } 8 \\ \text{minimum at } x = 1$$

$$10. \text{base} = 3.652 \text{ ft. : height} = 1.826 \text{ ft.}$$

$$11. 2.1 : \text{minimum}$$

$$12. \frac{l-y}{2} \quad 13. 4968 : f632 \quad 14. \text{width} = \text{height} = 8.4'$$

$$16. x = .289l$$

$$15. 15.2 \text{ knots : } f956, f948, f957$$

$$17. h = 6.34 \text{ ft. : } d = 12.68 \text{ ft.} \quad 18. \text{base} = 4": \text{height} = 5"$$

$$19. \text{depth} = 3 \times \text{breadth.} \quad 20. \frac{ry}{l}$$

$$21. 6 \quad 22. .866 r$$

$$23. v : \frac{v}{3} : \frac{8}{27}$$

$$24. u = .5v$$

$$25. 135^\circ \text{ or } 315^\circ$$

26. $d = l$ 27. $l = 2.065r$ 28. $20.15 : -45$ 29. 0 or $20^\circ 56'$
 30. height = 8.1 ft. : base = 6.72 ft. 31. $x = .4l$
 32. $\tan^{-1} \left(\frac{-2\mu + \sqrt{2(\mu^2 + 1)}}{1 - \mu^2} \right)$ 33. $l = \sqrt{\frac{6f}{K\rho n^2}}$
 34. maximum at $x = 0$: points of inflection at $x = \pm \frac{h}{\sqrt{2}}$
 35. $\sqrt{P_1 P_3}$ 36. $\sqrt{\frac{d}{4}(4l+d)}$ 37. $1 + \sqrt{\frac{K}{1+K}}$
 38. .58 (Let $r = \frac{r^2}{P_1}$ and find $\frac{dW^2}{dr}$) 39. 3 units 40. $x = \frac{l-y}{y}$
 41. $T_f = \frac{1}{3}T_m$ 42. maximum at $x = -2$
 minimum at $x = 4$ and at $x = -2.5$
 points of inflection when $x = -2.26$ and 1.92
 43. $x = \sqrt{R_1 R_2} : p_x$ (maximum) = $\frac{w\omega^2}{8gm} (3m+1)(R_1 - R_2)^2$
 44. $d = \sqrt{\frac{D^6}{8fl}}$ 46. $83^\circ 1'$ or $276^\circ 59'$

Exercises 11

1. .006 2. 2.5% too low 3. .0264 4. -2.45
 5. 2.66 6. decrease of .00135 7. .03 link; .237 link
 8. $1 + x \log a + \frac{(x \log a)^2}{1.2} + \frac{(x \log a)^3}{1.2.3} + \dots$
 9. 2214.2525 10. .536

Exercises 12

2. 152 5. 240; 205; 64
 6. 621,000 ft. lbs. : potential energy = 240,000 :
 kinetic energy = 381,000: 987,000 ft. lbs.
 7. 480 9. 238,000 10. 3006 12. $1.526x^{2.62} + C$
 13. $70.15x + C$ 14. $-\frac{1.5}{x^2} + C$ 15. $\frac{x^{2-n}}{2-n} + C$ 16. $1.43e^{.7x} + C$
 17. $.1x^{10} - 10 \log x + 14x + C$ 18. $3.32x^{1.04} - 2.5x^2 + C$
 19. $1.074x^{3.718} + \frac{1}{4}ex + C$ 20. $1.33e^{9x-5} + C$
 21. $6.54e^{2.4x-1.2} + C$ 22. $.689x + C$ 23. $\frac{.71bx^{1.41}}{x} + C$
 24. $3.025x^{84} - 8.2 \log x - 2.71e^{-2.6x} + 1.13x + C$,
 25. $-.0234e^{-10.2x} + C$ 26. $1.96e^{.51x} - 1.297x^{.77} + .674x^{3.04} + C$
 27. $.797 \cos \theta x^{1.18} - 2.2e^{.8x-14} + C$ 28. $\frac{1}{6}v^6 + C$ 29. $-\frac{1}{3u^3} + C$
 30. $35t + C$ 31. $\frac{1}{5}e^{5x-4} + C$ 32. $-5.88pv + C$
 33. $20.2(2)^x + C$ 34. $-\frac{4}{x} + 2.5x^2 + 4.25x^4 - 8x + C$
 35. $.885(3.1)^t + C$ 36. $-\frac{5.67}{e^{3p}} + C$

$$37. \frac{e^{4t}}{4} - \frac{e^{-5t}}{5} - 2.718t + C$$

$$38. 16 \cdot 1t^2 + C \quad 39. \frac{175}{x^8} + C$$

40. Write the equation in the form $\frac{dp}{p} = -n \frac{dv}{v}$ and then integrate:

$$pv^n = C$$

Exercises 13

$$1. -\frac{3}{4} \cos 4x + C$$

$$3. -49 \tan(3 - \frac{1}{2}x) + C$$

$$5. -1854e^{5.4x} - \frac{5}{a} \cos(b + ax) + C$$

$$7. 713 \cos(2(16x - 4.5)) + C$$

$$8. 12.85e^{-7x} - \frac{868}{x^4} + 1.83 \log \cos x + C$$

$$9. -9.95 \cos\left(\frac{3x - 2.8}{7}\right) + 0.022 \sin 9x - 1.46x^{2.74} + .455(3)^{2x+5} + C$$

$$10. 2x - 787 \cos\left(\frac{\pi}{4} - 3.7x\right) + 7.55 \cot\frac{3\pi x}{5} + C$$

$$11. v = 7 \cos(7t - 26) + C; s = -\frac{a}{49}$$

$$12. \frac{dx}{d\theta} = 4\pi^2 n^2 r \left(\sin \theta + \frac{\sin 2\theta}{2m} \right) + C; x = -4\pi^2 n^2 r \left(\cos \theta + \frac{\cos 2\theta}{4m} \right) + C$$

$$13. 311(5^{2p}) - 139 \sin(3.7 - 7.2p) + C$$

$$14. -19.5 \cos 6t - 4.9 \sin 6t + C$$

Exercises 14

$$1. \cdot 1825$$

$$2. \cdot 345$$

$$3. 1.7$$

$$4. \cdot 561$$

$$5. \cdot 0626$$

$$6. 1.218 \times 10^7$$

$$7. 2.62$$

$$8. \cdot 1589$$

$$9. \frac{2I}{\tau}$$

$$10. 616B_{\max}$$

$$11. -\frac{1}{2} \left\{ \frac{\cos(a+b)t}{a+b} + \frac{\cos(a-b)t}{a-b} \right\};$$

$$12. \frac{v_1 r_1^2}{2g} \left\{ \frac{1}{R_1^2} - \frac{1}{R_2^2} \right\}$$

$$13. P = \frac{wl}{8}; y = \frac{w}{8EI} \left\{ \frac{lx^3}{2} - \frac{x^4}{3} - \frac{l^3 x}{6} \right\}$$

$$14. \frac{w}{24EI} \{x^4 - 4l^3x + 3l^4\}$$

$$15. \frac{w}{24EI} \left\{ \frac{l^2 x^2}{2} - x^4 - \frac{l^4}{16} \right\}$$

$$16. \frac{l^5}{30}$$

$$17. \cdot 2046l^4$$

$$18. \frac{1 - \sin \phi}{1 + \sin \phi} \cdot \frac{wh^2}{2}$$

$$19. 26.24 \text{ (Limits must first be found); } \frac{2}{3}$$

$$20. 334$$

$$21. y = \cdot 736x^{3.4} + 5 \log x + 3x - 3.25$$

$$22. 1.087.$$

$$23. \frac{N}{al} (e^{al} - 1)$$

$$24. \frac{2\pi wV_1^2(R_1^3 - R_2^3)}{3R_1^2}$$

$$25. -\frac{v}{8}$$

$$26. H = \frac{wl^2}{96r}$$

$$27. 240$$

$$28. 2.906$$

$$29. \frac{8.92}{l^2} \sqrt{\frac{EI}{w}}$$

$$30. 49.82$$

$$31. \frac{\tau dl \rho s^3}{12l\mu}$$

$$32. \cdot 8596CA_1lh$$

$$33. \frac{\pi fa^4}{8\mu}$$

$$34. \frac{l}{5} \left[\log\left(\frac{x_1}{x}\right)^2 + \frac{\pi y}{x} \right]$$

$$35. 283.3 \text{ sq. units}$$

$$36. 1.487$$

Exercises 15

1. $-158 \log \frac{C(x - 1.583)}{(x + 1.583)}$ 2. $\frac{1}{3\sqrt{6}} \tan^{-1} \frac{x+1}{\sqrt{6}} + C$
 3. $\log(9x^2 - 18x + 17)^{\frac{1}{18}} + C$ 4. -1919
 5. 605 {Let $u = 6 - h$ } 6. $y\sqrt{75 - y^2} + 75 \sin^{-1} 1.154y + C$
 7. -106 8. $\frac{1}{3} \sin 12t + 4t + C$ 9. $-\frac{1}{5} \cot 5x + C$
 10. $\frac{WR^3}{EI} \left(\frac{1}{\pi} - \frac{1}{4} \right)$ or $\frac{0.0683 WR^3}{EI}$
 11. $-8 \log \cos 5t + C$ {Let $u = \cos 5t$ } 12. $x \sin^{-1} x + \sqrt{1 - x^2} + C$
 13. $-\frac{1}{3} \sqrt{(a^2 - x^2)^3} + C$ 14. $\frac{5e^{2x}}{13} \{3 \sin 2x - 2 \cos 2x\}$
 15. $\tan^{-1} x + \frac{x}{1+x^2} + C$ {Let $u = \tan^{-1} x$ } 16. 0.81
 17. $\frac{1}{3} \sin^3 \theta$ 18. $\frac{0.253fQ^2}{k} \left[\frac{1}{d^4} - \frac{1}{(d+kl)^4} \right]$
 19. 183 secs.: {Rationalise denominator of right hand side by multiplying top and bottom by $\sqrt{h+12} - \sqrt{h}$; then integrate, making the substitution $u = h + 12.$ }
 20. $\frac{2}{\sqrt{\pi}} \left(t - \frac{t^3}{3} + \frac{t^5}{10} - \frac{t^7}{42} + \dots \right)$ 21. $\frac{4F}{3\pi r^2}$. (Put $u = r^2 - y^2$)
 22. $\frac{t^3}{12} + \frac{t\sqrt{t^2 - 4}}{8} - \frac{1}{2} \cosh^{-1} \frac{t}{2} + C$ 23. $\frac{35\pi}{256}$ 24. 1.749
 25. $\frac{16}{315}$ 26. $0.1R^3$
 27. $(.5x + 1.25) \sqrt{21 - 5x - x^2} + 13.63 \sin^{-1} \left(\frac{x+2.5}{5.22} \right) + C$
 28. $F = 2\pi k\sigma \left(\frac{z}{\sqrt{a^2 + z^2}} - 1 \right)$

Exercises 16

1. 41.59 2. 1.718 3. 10.85 4. $.688$ 5. 4.5
 6. 23.05 7. 1.348 ft. candles. 8. 0 9. 1294
 10. 273 11. 205 lbs.

Exercises 17

1. 14.14 2. $.6215$ 3. 2.4 4. $.1165$ 5. $.833$ 6. 1.194
 7. R.M.S. = $.509$; $\frac{\text{R.M.S.}}{\text{M.V.}} = 1.11$ 8. $\frac{3.32\sqrt{E_1^2 + E_3^2}}{3E_1 + E_3}$
 9. $\frac{\text{Sinusoidal}}{\text{triangular}} = .816$ 10. 5.01 11. $9.86''$ 12. $\frac{3}{256}$ 13. $.14$

Exercises 18

1. 1450 cu. yds.
2. 5977 lbs.
3. 1070
4. $4\pi r^2$
5. $a = 3.036, b = .1423; 1617$
6. $\frac{K\pi D^2 l^2}{8}$ or Vol. $\times \frac{Kl}{2}$
7. 524 {limits are 5 and 10}
8. 271.6
9. 1.2 lbs.
10. true = 76.62: (a) 75.41 : 1.58 % low (b) 77.73 : 1.45 % high
- (c) 76.60 : correct
11. 60.9 ft.
12. 1011 lbs.

Exercises 19

1. $\frac{h}{2}$ height from vertex
2. area = 7200 sq. ft.: centroid is 158' from forward end
3. 3.84 lbs.; 4" 4. 10 ft. from top
5. $\bar{x} = \bar{y} = 1.7$ (taking the centre as origin) 6. 771; 2.25
7. (0, .95) 8. 2.35" from AB 9. 1.055" 10. .935"
11. .877" 12. 1.02" 13. 2.68" i.e., 1.34*t*
14. 5.12 ft. from O 15. 30880 lbs. 16. 18432 lbs.: 3.534 ft.
17. 9 units. 18. 5.1 ins. 19. 2.35 ins.
20. (a) 17 lbs. (b) $1\frac{3}{4}$ " 21. 1.48 ins. 22. $\frac{2}{3}h$ 23. $\frac{4}{3}h$

Exercises 20

1. $.655l$
2. 17.11 ins.: 785 lbs. ins.²
3. C. of G. is 1125" distant from centre of large circle: 2.68"
4. 16.6 ins.⁴
5. (a) $.408h$; (b) $.707h$
6. $I_{AB} = 80.7$ ins.⁴: $k_{AB} = 3.04"$ 7. 29.1" 8. 377
9. 9.86 10. 7.35
11. $.2887d$. (Divide into strips by planes perpendicular to the axis and sum the polar moments of these)
12. $\frac{\text{IE of circular}}{\text{IE of square}} = \frac{3}{\pi} = .956$ 13. 33.3 inch units
14. 11613: 17.04
15. $I_{NN} = 169.4$: $k_{NN} = 2.44$: $I_{AB} = 570$: $k_{AB} = 4.47$
16. NN is 3.99" from bottom of lower flange: $I_{NN} = 461$: $k_{NN} = 3.77$
17. 5.04" 18. 2.023": .444 19. 2.74"
20. (a) 13.9 (b) 31.1 (c) 1.48" (d) 1.82" 21. .28
22. mass $\left(R^2 + \frac{3r^2}{4} \right)$ 23. .5*b*

Exercises 21

3. 5.23
4. $\rho = 2r \sin \theta$: the sine curve
6. 892
7. 5.01

Exercises 22

1. $y = 1.67x^3 - 2.4x - 12.8z$
2. $s = 8.05t^2 - 23.06t + 14.09$
3. $y = Ae^{8x} - \frac{5}{8}$
4. $y = 8.35 - 6.18e^{-1.044x}$
5. $y = \frac{W}{48\text{IE}} (6lx - 4x^3 - l^3)$ $\frac{dy}{dx} = 0$ when $x = 0$; $y = 0$ when $x = \frac{l}{2}$

$$6. K = \frac{wl^2}{12} : y = \frac{w}{24EI} \left(\frac{l^2x^2}{2} - x^4 - \frac{l^4}{16} \right)$$

$$7. \log \left(\frac{T_2 - t}{T_1 - t} \right) = \frac{\pi r l D}{as(r + r)} \quad 8. v = \frac{p}{8l\mu} (s^2 - x^2)$$

$$9. \log \left(\frac{\tau_1 - \theta}{\tau_s - \theta} \right) = \frac{\pi Q D l}{ws} \quad 10. \frac{\pi Q D l}{ws} :$$

$$11. H = \frac{2\pi Kl(\tau_1 - \tau_2)}{\log \frac{r_2}{r_1}} \quad 12. \theta = A \sin \left(\sqrt{\frac{m}{I}} t + c \right)$$

$$13. p = A + \frac{B}{r^2} \quad 14. p = \frac{b}{x^3} - a \quad 16. \log \frac{z}{C} + \frac{w\omega^2 x^4}{2gf} = 0$$

$$17. y = A_1 e^{10x} + A_2 e^{7x} : y = A_1 e^{10x} + A_2 e^{7x} + I$$

$$18. s = A_1 e^{9.33t} + A_2 e^{-9.33t} \quad 19. s = A \sin(9.33t + B)$$

$$20. KR \log \frac{v_1}{v_2} \quad 21. C = C_0 A e^{-\frac{Rt}{L}} \quad 22. C = \frac{V_0 \sin(qt - \tan^{-1} \frac{Lq}{R})}{\sqrt{R^2 + L^2 q^2}}$$

$$23. x = a \log \frac{y + a + \sqrt{y^2 + 2ay}}{a} \text{ or } ae^{\frac{x}{a}} = y + a + \sqrt{y^2 + 2ay}$$

(Separate the variables and use the $\int \frac{dx}{x^2 - a^2}$ form)

$$24. x = A \sin \left(\sqrt{\frac{a}{SM^2}} t + c \right) + pS \quad 25. y = \frac{Y \sin \sqrt{\frac{P}{IE}} x}{\sin \sqrt{\frac{P}{IE}} L}$$

$$26. nt = \log \left(\frac{x + \sqrt{x^2 - a^2}}{a} \right) : 1945 \quad 27. x = 833e^{-7.485t} \sin 12t$$

$$28. x = Ae^{-3t} \sin(6.32t + c) + 0.026a \sin(5t - \tan^{-1} 1.25)$$

$$29. V = A_1 e^{\sqrt{\frac{r_1}{r_2}} x} + A_2 e^{-\sqrt{\frac{r_1}{r_2}} x}$$

$$30. Pv^n = C$$

$$31. \theta = \theta_a + e^{-kt} (\theta_0 - \theta_a) \quad 32. \theta = -53.63e^{-1.16t} + 5.83e^{-10.66t} + 48.8$$

$$33. y = A_1 e^{j\alpha x} + A_2 e^{-j\alpha x} + A_3 e^{j\beta x} + A_4 e^{-j\beta x} - \frac{g}{\omega^2}$$

$$\text{where } a = \sqrt{F + \sqrt{F^2 + \frac{4\rho}{\sigma} \omega^2 EI}}$$

$$\text{and } b = \sqrt{F - \sqrt{F^2 + \frac{4\rho}{g} \omega^2 EI}}$$

$$\text{or } y = B_1 e^{cx} + B_2 e^{-cx} + B_3 \sin \phi x + B_4 \cos \phi x - \frac{g}{\omega^2}$$

$$34. v = \frac{g \cos \alpha}{k} (1 - e^{-kt})$$

Exercises 23

1. 103 secs. if coefficient of discharge is taken as .62 2. 7.37
 3. 2.83 cu. ft. 4. 69.5 : 95.5 (Draw in the "simply supported" bending moment diagram and work on the Goodman plan, see page 313)
 5. Find the time to lower to level of upper orifice (183 secs.) with both orifices open; then the time for the further lowering of 5 ft., through the one orifice (180 secs.). Total time = 363 secs. Note that
- $$\frac{I}{\sqrt{h+12} + \sqrt{h}} - \frac{\sqrt{h+12} - \sqrt{h}}{12} \quad 6. 57.7 \text{ secs.} \quad 7. 1.4$$
8. 5500 lbs. 4.71 ft. below S.W.S.L. 14100 lbs.: 6.65' below S.W.S.L. 10. 761 11. $\frac{0253fQ^2}{K} \left(\frac{I}{d_e^4} - \frac{I}{(d_e + Kl)^4} \right)$ (Hint, let $u = d_e + Kl$) 12. 1.23 13. Vertical depth = 8.07 ft.

Exercises 24

1. $x = 2.31 - 1.231 \cos \theta - 1.55 \sin \theta - 1.16 \cos 2\theta - 0.022 \sin 2\theta - 0.004 \cos 3\theta - 0.04 \sin 3\theta$
 2. $A = 1.29$, $a_1 = 0$, $B = 1.4$, $a_2 = \pi$
 3. $y = 16.97 + 6.49 \cos x + 0.02 \sin x - 12.66 \cos 2x - 1.46 \sin 2x - 1.75 \cos 3x - 7 \sin 3x$
 4. $E = 1500 \sin \theta + 100 \sin 3\theta + 42 \cos \theta + 28 \cos 3\theta$

Exercises 25

1. $B = 39^\circ 31'$; $A = 65^\circ 51'$; $c = 57^\circ 5'$
 2. $c = 54^\circ 44\frac{1}{2}'$; $b = 34^\circ 14'$; $B = 43^\circ 32\frac{1}{2}'$
 3. $A = 161^\circ 8'$; $B = 13^\circ 35'$; $C = 9^\circ 38'$
 4. $A = 76^\circ 36'$; $B = 64^\circ 8'$; $c = 52^\circ$
 5. $B = 35^\circ 43' 40''$; $A = 61^\circ 21' 20''$; $a = 43^\circ 25' 23''$
 6. $C = 33^\circ 29'$ or $146^\circ 31'$
 $a = 103^\circ 28'$ or $55^\circ 28'$
 $A = 146^\circ 58'$ or $27^\circ 30'$ 7. $55^\circ 10'$ 8. 342,200
 9. Latitude = $43^\circ 54'$; hour angle = $4^\circ 31.3'$

Exercises 26

1. 2nd set better than 1st set in the proportion 1.943 to 1: 6 chns.
 43.4 links. 2. Just under 1. 3. $98^\circ 6' 42.26''$: $r_m = 307''$, $r = 1.062''$
 4. 96.93 5. $T = 26.71 + 35.18\alpha$ 6. .5479

MATHEMATICAL TABLES

TABLE I.—TRIGONOMETRICAL RATIOS

Angle.		Chord.	Sine.	Tangent.	Co-tangent.	Cosine.			
Degrees.	Radians.								
0°	0	0	0	0	∞	1	1.414	1.5708	90°
1	.0175	.017	.0175	.0175	57.2900	.9998	1.402	1.5533	89
2	.0349	.035	.0349	.0349	28.6363	.9994	1.389	1.5359	88
3	.0524	.052	.0523	.0524	19.0811	.9986	1.377	1.5184	87
4	.0698	.070	.0698	.0699	14.3007	.9976	1.364	1.5010	86
5	.0873	.087	.0872	.0875	11.4301	.9962	1.351	1.4835	85
6	.1047	.105	.1045	.1051	9.5144	.9945	1.338	1.4661	84
7	.1222	.122	.1219	.1228	8.1443	.9925	1.325	1.4486	83
8	.1396	.140	.1392	.1405	7.1514	.9903	1.312	1.4312	82
9	.1571	.157	.1564	.1584	6.3138	.9877	1.299	1.4137	81
10	.1745	.174	.1736	.1763	5.6713	.9848	1.286	1.3963	80
11	.1920	.192	.1908	.1944	5.1446	.9816	1.272	1.3788	79
12	.2094	.209	.2079	.2126	4.7046	.9781	1.259	1.3614	78
13	.2269	.226	.2250	.2309	4.3315	.9744	1.245	1.3439	77
14	.2443	.244	.2419	.2493	4.0108	.9703	1.231	1.3265	76
15	.2618	.261	.2588	.2679	3.7321	.9659	1.218	1.3090	75
16	.2793	.278	.2756	.2867	3.4874	.9613	1.204	1.2915	74
17	.2967	.296	.2924	.3057	3.2709	.9563	1.190	1.2741	73
18	.3142	.313	.3090	.3349	3.0777	.9511	1.176	1.2566	72
19	.3316	.330	.3256	.3443	2.9042	.9455	1.161	1.2392	71
20	.3491	.347	.3420	.3640	2.7475	.9397	1.147	1.2217	70
21	.3665	.364	.3584	.3839	2.6051	.9336	1.133	1.2043	69
22	.3840	.382	.3746	.4040	2.4751	.9272	1.118	1.1868	68
23	.4014	.399	.3907	.4245	2.3559	.9205	1.104	1.1694	67
24	.4189	.416	.4067	.4452	2.2460	.9135	1.089	1.1519	66
25	.4363	.433	.4226	.4663	2.1445	.9063	1.075	1.1345	65
26	.4538	.450	.4384	.4877	2.0503	.8988	1.060	1.1170	64
27	.4712	.467	.4540	.5095	1.9626	.8910	1.045	1.0996	63
28	.4887	.484	.4695	.5317	1.8807	.8839	1.030	1.0821	62
29	.5061	.501	.4848	.5543	1.8040	.8746	1.015	1.0647	61
30	.5236	.518	.5000	.5774	1.7321	.8660	1.000	1.0472	60
31	.5411	.534	.5150	.6009	1.6643	.8572	.985	1.0297	59
32	.5585	.551	.5299	.6249	1.6003	.8480	.970	1.0123	58
33	.5760	.568	.5446	.6494	1.5399	.8387	.954	.9948	57
34	.5934	.585	.5592	.6745	1.4826	.8290	.939	.9774	56
35	.6109	.601	.5736	.7002	1.4281	.8192	.923	.9599	55
36	.6283	.618	.5878	.7265	1.3764	.8090	.908	.9425	54
37	.6458	.635	.6018	.7536	1.3270	.7986	.892	.9250	53
38	.6632	.651	.6157	.7813	1.2799	.7880	.877	.9076	52
39	.6807	.668	.6293	.8098	1.2349	.7771	.861	.8901	51
40	.6981	.684	.6428	.8391	1.1918	.7660	.845	.8727	50
41	.7156	.700	.6561	.8693	1.1504	.7547	.829	.8552	49
42	.7330	.717	.6691	.9004	1.1106	.7431	.813	.8378	48
43	.7505	.733	.6820	.9325	1.0724	.7314	.797	.8203	47
44	.7679	.749	.6947	.9657	1.0355	.7193	.781	.8029	46
45°	.7854	.765	.7071	1.0000	1.0000	.7071	.765	.7854	45°
			Cosine	Co-tangent	Tangent	Sine	Chord	Radians	Degrees
									Angle

MATHEMATICAL TABLES

TABLE II.—LOGARITHMS

	0	1	2	3	4	5	6	7	8	9	1	2	3	4	5	6	7	8	9
10	0000	0043	0086	0128	0170	0212	0253	0294	0334	0374	4	9	13	17	21	26	30	34	38
											4	8	12	16	20	24	28	32	37
11	0414	0453	0492	0531	0569	0607	0645	0682	0719	0755	4	8	12	15	19	23	27	31	35
											4	7	11	15	19	22	26	30	33
12	0792	0833	0874	0899	0934	0969	1004	1038	1072	1106	3	7	11	14	18	21	25	29	32
											3	7	10	14	17	20	24	27	31
13	1139	1173	1206	1239	1271	1303	1335	1367	1399	1430	3	7	10	13	16	20	23	26	30
											3	7	10	12	16	19	22	25	29
14	1461	1492	1523	1553	1584	1614	1644	1673	1703	1732	3	6	9	12	15	18	21	24	28
											3	6	9	12	15	17	20	23	26
15	1761	1790	1818	1847	1875	1903	1931	1959	1987	2014	3	6	9	11	14	17	20	23	26
											3	5	8	11	14	16	19	22	25
16	2041	2063	2095	2123	2148	2175	2201	2227	2253	2279	3	5	8	11	14	16	19	22	24
											3	5	8	10	13	15	18	21	23
17	2304	2330	2355	2380	2405	2430	2455	2480	2504	2529	3	5	8	10	13	15	18	20	23
											2	5	7	10	12	15	17	19	22
18	2553	2577	2601	2623	2648	2672	2695	2718	2742	2765	2	5	7	9	12	14	16	18	21
											2	5	7	9	11	14	16	18	21
19	2738	2810	2833	2856	2878	2900	2923	2945	2967	2989	2	4	7	9	11	13	16	18	20
											2	4	6	8	11	13	15	17	19
20	3010	3032	3054	3075	3096	3118	3139	3160	3181	3201	2	4	6	8	11	13	15	17	19
21	3292	3313	3333	3354	3374	3394	3415	3435	3455	3475	2	4	6	8	10	12	14	16	18
22	3424	3444	3464	3484	3504	3524	3544	3564	3584	3604	2	4	6	8	10	12	14	16	17
23	3447	3467	3487	3507	3527	3547	3567	3587	3607	3627	2	4	6	7	9	11	13	15	17
24	3517	3537	3557	3577	3597	3617	3637	3657	3677	3697	2	4	5	7	9	11	12	14	16
25	3979	3997	4014	4031	4048	4065	4082	4099	4116	4133	2	3	5	7	9	10	12	14	15
26	4150	4166	4183	4200	4216	4232	4249	4265	4281	4298	2	3	5	7	8	10	11	13	15
27	4314	4330	4346	4362	4378	4393	4409	4425	4440	4456	2	3	5	6	8	9	11	13	14
28	4472	4487	4502	4518	4533	4548	4564	4579	4594	4609	2	3	5	6	8	9	11	12	14
29	4624	4639	4654	4669	4683	4698	4713	4728	4742	4757	1	3	4	6	7	9	10	12	13
30	4771	4786	4800	4814	4829	4843	4857	4871	4886	4900	1	3	4	6	7	9	10	11	13
31	4914	4928	4942	4955	4969	4983	4997	5011	5024	5038	1	3	4	6	7	8	10	11	12
32	5051	5065	5079	5093	5105	5119	5132	5145	5159	5172	1	3	4	5	7	8	9	11	12
33	5185	5198	5211	5224	5237	5250	5263	5276	5289	5302	1	3	4	5	6	8	9	10	12
34	5315	5328	5340	5353	5366	5378	5391	5403	5416	5428	1	3	4	5	6	8	9	10	11
35	5441	5455	5465	5478	5490	5502	5514	5527	5539	5551	1	2	4	5	6	7	9	10	11
36	5563	5575	5587	5599	5611	5623	5635	5647	5658	5670	1	2	4	5	6	7	8	10	11
37	5632	5644	5657	5670	5671	5679	5740	5752	5763	5776	1	2	3	5	6	7	8	9	10
38	5798	5809	5821	5832	5843	5855	5866	5877	5888	5899	1	2	3	5	6	7	8	9	10
39	5911	5922	5933	5944	5955	5966	5977	5988	5999	6010	1	2	3	4	5	7	8	9	10
40	6021	6031	6042	6053	6061	6075	6085	6096	6107	6117	1	2	3	4	5	6	8	9	10
41	6128	6138	6149	6160	6170	6180	6191	6201	6212	6222	1	2	3	4	5	6	7	8	9
42	6232	6243	6253	6263	6274	6284	6294	6304	6314	6325	1	2	3	4	5	6	7	8	9
43	6335	6345	6355	6365	6375	6385	6395	6405	6415	6425	1	2	3	4	5	6	7	8	9
44	6435	6444	6454	6464	6474	6484	6493	6503	6513	6522	1	2	3	4	5	6	7	8	9
45	6532	6542	6551	6561	6571	6580	6590	6599	6609	6618	1	2	3	4	5	6	7	8	9
46	6628	6637	6646	6656	6665	6675	6684	6693	6702	6712	1	2	3	4	5	6	7	8	9
47	6721	6730	6739	6749	6758	6767	6776	6785	6794	6803	1	2	3	4	5	6	7	8	9
48	6812	6821	6830	6839	6848	6857	6866	6875	6884	6893	1	2	3	4	5	6	7	8	9
49	6902	6911	6920	6928	6937	6946	6955	6964	6972	6981	1	2	3	4	4	5	6	7	8
50	6990	6998	7007	7016	7024	7033	7042	7050	7059	7067	1	2	3	3	4	5	6	7	8

TABLE II. (*contd.*)

	0	1	2	3	4	5	6	7	8	9	1	2	3	4	5	6	7	8	9
51	7076	7084	7093	7101	7110	7118	7126	7135	7143	7152	1	2	3	3	4	5	6	7	8
52	7160	7168	7177	7185	7193	7202	7210	7218	7226	7235	1	2	2	3	4	5	6	7	7
53	7243	7251	7259	7267	7275	7284	7292	7300	7308	7316	1	2	2	3	4	5	6	6	7
54	7324	7332	7340	7348	7356	7364	7372	7380	7388	7396	1	2	2	3	4	5	6	6	7
55	7404	7412	7419	7427	7435	7443	7451	7459	7466	7474	1	2	2	3	4	5	5	6	7
56	7482	7490	7497	7505	7513	7520	7528	7536	7543	7551	1	2	2	3	4	5	5	6	7
57	7569	7566	7574	7582	7589	7597	7604	7612	7619	7627	1	2	2	3	4	5	5	6	7
58	7634	7642	7649	7657	7664	7672	7679	7686	7694	7701	1	1	2	3	4	5	5	6	7
59	7709	7716	7723	7731	7738	7745	7752	7760	7767	7774	1	1	2	3	4	5	5	6	7
60	7782	7789	7796	7803	7810	7818	7825	7832	7839	7846	1	1	2	3	4	4	5	6	6
61	7853	7860	7868	7875	7882	7889	7896	7903	7910	7917	1	1	2	3	4	4	5	6	6
62	7924	7931	7938	7945	7952	7959	7966	7973	7980	7987	1	1	2	3	3	4	5	6	6
63	7948	8000	8007	8014	8021	8028	8035	8041	8048	8055	1	1	2	3	3	4	5	5	6
64	8062	8069	8075	8082	8089	8096	8102	8109	8116	8122	1	1	2	3	3	4	5	5	6
65	8129	8136	8142	8149	8156	8162	8169	8176	8182	8189	1	1	2	3	3	4	5	5	6
66	8195	8202	8209	8215	8222	8228	8235	8241	8248	8254	1	1	2	3	3	4	5	5	6
67	8261	8267	8274	8281	8287	8293	8299	8306	8312	8319	1	1	2	3	3	4	5	5	6
68	8325	8331	8338	8344	8351	8357	8363	8370	8376	8382	1	1	2	3	3	4	5	5	6
69	8388	8395	8401	8407	8414	8420	8426	8432	8439	8445	1	1	2	3	3	4	4	5	6
70	8451	8457	8463	8470	8476	8482	8488	8494	8500	8506	1	1	2	2	3	4	4	5	6
71	8513	8519	8525	8531	8537	8543	8549	8555	8561	8567	1	1	2	2	3	4	4	5	5
72	8573	8579	8585	8591	8597	8603	8609	8615	8621	8627	1	1	2	2	3	4	4	5	5
73	8633	8639	8645	8651	8657	8663	8669	8675	8681	8686	1	1	2	2	3	4	4	5	5
74	8692	8698	8704	8710	8716	8722	8727	8733	8739	8745	1	1	2	2	3	4	4	5	5
75	8751	8756	8762	8768	8774	8779	8785	8791	8797	8802	1	1	2	2	3	3	4	5	5
76	8808	8814	8820	8825	8831	8837	8842	8848	8854	8859	1	1	2	2	3	3	4	5	5
77	8865	8871	8876	8882	8888	8893	8899	8904	8910	8915	1	1	2	2	3	3	4	4	5
78	8921	8927	8932	8938	8943	8949	8954	8960	8965	8971	1	1	2	2	3	3	4	4	5
79	8976	8982	8987	8993	8998	9004	9009	9015	9020	9025	1	1	2	2	3	3	4	4	5
80	9031	9036	9042	9047	9053	9058	9063	9069	9074	9079	1	1	2	2	3	3	4	4	5
81	9085	9090	9096	9101	9106	9112	9117	9122	9128	9133	1	1	2	2	3	3	4	4	5
82	9138	9143	9149	9154	9159	9165	9170	9175	9180	9186	1	1	2	2	3	3	4	4	5
83	9191	9196	9201	9206	9212	9217	9222	9227	9232	9238	1	1	2	2	3	3	4	4	5
84	9243	9248	9253	9258	9263	9269	9274	9279	9284	9289	1	1	2	2	3	3	4	4	5
85	9294	9299	9304	9309	9315	9320	9325	9330	9335	9340	1	1	2	2	3	3	4	4	5
86	9345	9350	9355	9360	9365	9370	9375	9380	9385	9390	1	1	2	2	3	3	4	4	5
87	9395	9400	9405	9410	9415	9420	9425	9430	9435	9440	0	1	1	2	2	3	3	4	4
88	9445	9450	9455	9460	9465	9470	9474	9479	9484	9489	0	1	1	2	2	3	3	4	4
89	9494	9499	9504	9509	9513	9518	9523	9528	9533	9538	0	1	1	2	2	3	3	4	4
90	9542	9547	9552	9557	9562	9566	9571	9576	9581	9586	0	1	1	2	2	3	3	4	4
91	9590	9595	9600	9605	9609	9614	9619	9624	9628	9633	0	1	1	2	2	3	3	4	4
92	9638	9643	9647	9652	9657	9661	9666	9671	9675	9680	0	1	1	2	2	3	3	4	4
93	9685	9689	9694	9699	9703	9708	9713	9717	9722	9727	0	1	1	2	2	3	3	4	4
94	9731	9736	9741	9745	9750	9754	9759	9763	9768	9773	0	1	1	2	2	3	3	4	4
95	9777	9782	9786	9791	9795	9800	9805	9809	9814	9818	0	1	1	2	2	3	3	4	4
96	9823	9827	9832	9836	9841	9845	9850	9854	9859	9863	0	1	1	2	2	3	3	4	4
97	9868	9872	9877	9881	9886	9890	9894	9899	9903	9908	0	1	1	2	2	3	3	4	4
98	9912	9917	9921	9926	9930	9934	9939	9943	9948	9952	0	1	1	2	2	3	3	4	4
99	9956	9961	9965	9969	9974	9978	9983	9987	9991	9996	0	1	1	2	2	3	3	4	4

MATHEMATICAL TABLES

TABLE III.—ANTILOGARITHMS

	0	1	2	3	4	5	6	7	8	9	1	2	3	4	5	6	7	8	9
-00	1000	1002	1005	1007	1009	1012	1014	1016	1019	1021	0	0	1	1	1	1	2	2	2
-01	1023	1026	1028	1030	1033	1035	1038	1040	1042	1045	0	0	1	1	1	1	2	2	2
-02	1047	1050	1052	1054	1057	1059	1062	1064	1067	1069	0	0	1	1	1	1	2	2	2
-03	1072	1074	1076	1079	1081	1084	1086	1089	1091	1094	0	0	1	1	1	1	2	2	2
-04	1096	1099	1102	1104	1107	1109	1112	1114	1117	1119	0	1	1	1	1	1	2	2	2
-05	1122	1125	1127	1130	1132	1135	1138	1140	1143	1146	0	1	1	1	1	1	2	2	2
-06	1145	1151	1153	1156	1159	1161	1164	1167	1169	1172	0	1	1	1	1	1	2	2	2
-07	1175	1178	1180	1183	1186	1189	1191	1194	1197	1199	0	1	1	1	1	1	2	2	2
-08	1202	1205	1208	1211	1213	1218	1219	1222	1225	1227	0	1	1	1	1	1	2	2	3
-09	1230	1233	1236	1239	1242	1245	1247	1250	1253	1256	0	1	1	1	1	1	2	2	3
-10	1250	1262	1265	1268	1271	1274	1276	1279	1282	1285	0	1	1	1	1	1	2	2	3
-11	1288	1291	1294	1297	1300	1303	1306	1309	1312	1315	0	1	1	1	1	1	2	2	3
-12	1312	1321	1324	1327	1330	1334	1337	1340	1343	1346	0	1	1	1	1	1	2	2	3
-13	1349	1352	1355	1358	1361	1365	1368	1371	1374	1377	0	1	1	1	1	1	2	2	3
-14	1380	1384	1384	1387	1390	1393	1396	1400	1403	1406	0	1	1	1	1	1	2	2	3
-15	1413	1416	1419	1422	1426	1429	1432	1435	1439	1442	0	1	1	1	1	1	2	2	3
-16	1445	1449	1452	1455	1459	1462	1466	1469	1472	1476	0	1	1	1	1	1	2	2	3
-17	1479	1483	1486	1489	1493	1496	1500	1503	1507	1510	0	1	1	1	1	1	2	2	3
-18	1514	1517	1521	1524	1528	1531	1535	1538	1542	1545	0	1	1	1	1	1	2	2	3
-19	1549	1550	1556	1560	1563	1567	1570	1574	1578	1581	0	1	1	1	1	1	2	2	3
-20	1585	1589	1592	1596	1600	1603	1607	1611	1614	1618	0	1	1	1	1	1	2	2	3
-21	1622	1626	1629	1633	1637	1641	1644	1648	1652	1656	0	1	1	1	1	1	2	2	3
-22	1660	1663	1667	1671	1675	1679	1683	1687	1690	1694	0	1	1	1	1	1	2	2	3
-23	1698	1703	1706	1710	1714	1718	1722	1726	1730	1734	0	1	1	1	1	1	2	2	3
-24	1738	1742	1746	1750	1754	1758	1762	1766	1770	1774	0	1	1	1	1	1	2	2	3
-25	1778	1782	1786	1791	1795	1799	1803	1807	1811	1815	0	1	1	1	1	1	2	2	3
-26	1820	1824	1828	1832	1837	1841	1845	1849	1854	1855	0	1	1	1	1	1	2	2	3
-27	1862	1866	1871	1875	1879	1884	1888	1892	1897	1901	0	1	1	1	1	1	2	2	3
-28	1905	1910	1914	1919	1923	1928	1932	1936	1941	1945	0	1	1	1	1	1	2	2	3
-29	1950	1954	1959	1963	1968	1972	1977	1982	1986	1991	0	1	1	1	1	1	2	2	3
-30	1995	2000	2004	2009	2014	2018	2023	2028	2032	2037	0	1	1	1	1	1	2	2	3
-31	2042	2046	2051	2056	2061	2065	2070	2075	2080	2084	0	1	1	1	1	1	2	2	3
-32	2099	2094	2099	2104	2109	2113	2118	2123	2128	2133	0	1	1	1	1	1	2	2	3
-33	2138	2143	2148	2153	2158	2163	2168	2173	2178	2183	0	1	1	1	1	1	2	2	3
-34	2188	2193	2193	2203	2208	2213	2218	2223	2228	2234	1	1	2	2	3	3	4	4	5
-35	2239	2244	2249	2254	2259	2265	2270	2275	2280	2286	1	1	2	2	3	3	4	4	5
-36	2291	2296	2301	2307	2312	2317	2323	2328	2333	2339	1	1	2	2	3	3	4	4	5
-37	2344	2350	2355	2360	2366	2371	2377	2382	2388	2393	1	1	2	2	3	3	4	4	5
-38	2399	2404	2410	2415	2421	2427	2432	2438	2443	2449	1	1	2	2	3	3	4	4	5
-39	2455	2460	2466	2472	2477	2483	2489	2495	2500	2506	1	1	2	2	3	3	4	4	5
-40	2512	2518	2523	2529	2535	2541	2547	2553	2559	2564	1	1	2	2	3	3	4	4	5
-41	2570	2576	2582	2588	2594	2600	2606	2612	2618	2624	1	1	2	2	3	3	4	4	5
-42	2630	2636	2642	2649	2655	2661	2667	2673	2679	2685	1	1	2	2	3	3	4	4	5
-43	2692	2698	2704	2710	2716	2723	2729	2735	2742	2748	1	1	2	3	3	3	4	4	5
-44	2754	2761	2767	2773	2780	2786	2793	2799	2805	2812	1	1	2	3	3	3	4	4	5
-45	2818	2825	2831	2838	2844	2851	2858	2864	2871	2877	1	1	2	3	3	3	4	4	5
-46	2884	2891	2897	2904	2911	2917	2924	2931	2938	2944	1	1	2	3	3	3	4	4	5
-47	2951	2958	2965	2972	2979	2985	2992	2999	3006	3013	1	1	2	3	3	3	4	4	5
-48	3020	3027	3034	3041	3048	3055	3062	3069	3076	3083	1	1	2	3	3	3	4	4	5
-49	3090	3097	3105	3112	3119	3126	3133	3141	3148	3155	1	1	2	3	3	3	4	4	5

MATHEMATICAL TABLES

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TABLE III. (*contd.*)

	0	1	2	3	4	5	6	7	8	9	1	2	3	4	5	6	7	8	9
-50	3162	3170	3177	3184	3192	3199	3206	3214	3221	3228	1	1	2	3	4	4	5	6	7
-51	3236	3243	3251	3258	3266	3273	3281	3289	3296	3304	1	2	2	3	4	5	5	6	7
-52	3311	3319	3327	3334	3342	3350	3357	3365	3373	3381	1	2	2	3	4	5	5	6	7
-53	3388	3396	3404	3412	3420	3428	3436	3443	3451	3459	1	2	2	3	4	5	6	6	7
-54	3467	3475	3483	3491	3499	3508	3516	3524	3532	3540	1	2	2	3	4	5	6	6	7
-55	3548	3556	3565	3573	3581	3589	3597	3606	3614	3622	1	2	2	3	4	5	6	7	7
-56	3681	3689	3648	3666	3684	3673	3681	3690	3698	3707	1	2	3	3	4	5	6	7	8
-57	3715	3724	3733	3741	3750	3758	3767	3776	3784	3793	1	2	3	3	4	5	6	7	8
-58	3802	3811	3819	3828	3837	3846	3855	3864	3873	3882	1	2	3	4	4	5	6	7	8
-59	3890	3899	3908	3917	3926	3936	3945	3954	3963	3972	1	2	3	4	5	5	6	7	8
-60	3981	3990	3999	4009	4018	4027	4036	4046	4055	4064	1	2	3	4	5	6	6	7	8
-61	4074	4083	4093	4102	4111	4121	4130	4140	4150	4159	1	2	3	4	5	6	7	8	9
-62	4169	4178	4188	4198	4207	4217	4227	4236	4246	4256	1	2	3	4	5	6	7	8	9
-63	4286	4276	4285	4295	4305	4315	4325	4335	4345	4355	1	2	3	4	5	6	7	8	9
-64	4385	4375	4385	4395	4408	4416	4426	4436	4446	4457	1	2	3	4	5	6	7	8	9
-65	4467	4477	4487	4498	4508	4519	4529	4539	4550	4560	1	2	3	4	5	6	7	8	9
-66	4571	4581	4592	4603	4613	4624	4634	4645	4656	4667	1	2	3	4	5	6	7	9	10
-67	4677	4684	4693	4710	4721	4732	4742	4753	4764	4775	1	2	3	4	5	7	8	9	10
-68	4786	4797	4808	4819	4831	4842	4853	4864	4875	4887	1	2	3	4	6	7	8	9	10
-69	4898	4909	4920	4932	4943	4955	4966	4977	4989	5000	1	2	3	5	6	7	8	9	10
-70	5012	5023	5035	5047	5058	5070	5082	5093	5105	5117	1	2	4	5	6	7	8	9	11
-71	5129	5140	5152	5164	5176	5188	5200	5212	5224	5236	1	2	4	5	6	7	8	10	11
-72	5248	5260	5272	5284	5297	5309	5321	5333	5346	5358	1	2	4	5	6	7	9	10	11
-73	5370	5383	5395	5408	5420	5433	5445	5458	5470	5483	1	3	4	5	6	8	9	10	11
-74	5495	5508	5521	5534	5546	5559	5572	5585	5598	5610	1	3	4	5	6	8	9	10	12
-75	5623	5636	5649	5662	5675	5689	5702	5715	5728	5741	1	3	4	5	7	8	9	10	12
-76	5754	5763	5781	5794	5808	5821	5834	5848	5861	5873	1	3	4	5	7	8	9	11	12
-77	5888	5902	5916	5929	5943	5957	5970	5984	5998	6012	1	3	4	5	7	8	10	11	12
-78	6026	6039	6053	6067	6081	6095	6108	6124	6138	6152	1	3	4	6	7	8	10	11	13
-79	6166	6180	6194	6209	6223	6237	6252	6266	6281	6295	1	3	4	6	7	9	10	11	13
-80	6310	6324	6330	6353	6388	6388	6397	6413	6427	6442	1	3	4	6	7	9	10	12	13
-81	6457	6471	6486	6501	6516	6531	6548	6561	6577	6592	2	3	5	6	8	9	11	12	14
-82	6607	6622	6637	6653	6668	6683	6699	6714	6730	6745	2	3	5	6	8	9	11	12	14
-83	6761	6776	6793	6808	6823	6839	6855	6871	6887	6902	2	3	5	6	8	9	11	13	14
-84	6918	6934	6950	6968	6982	6998	7015	7031	7047	7063	2	3	5	6	8	10	11	13	15
-85	7079	7096	7112	7129	7145	7161	7178	7194	7211	7228	2	3	5	7	8	10	12	13	15
-86	7244	7261	7278	7295	7311	7328	7345	7362	7379	7396	2	3	5	7	8	10	12	13	15
-87	7413	7430	7447	7464	7482	7499	7516	7534	7551	7568	2	3	5	7	9	10	12	14	16
-88	7586	7603	7621	7638	7656	7674	7691	7709	7727	7745	2	4	5	7	9	11	12	14	16
-89	7762	7780	7793	7810	7834	7852	7870	7889	7907	7925	2	4	5	7	9	11	13	14	16
-90	7943	7962	7980	7998	8017	8035	8054	8072	8091	8110	2	4	6	7	9	11	13	15	17
-91	8128	8147	8166	8185	8204	8222	8241	8260	8279	8299	2	4	6	8	9	11	13	15	17
-92	8318	8337	8356	8375	8395	8414	8433	8453	8472	8492	2	4	6	8	10	12	14	15	17
-93	8511	8531	8551	8570	8590	8610	8630	8650	8670	8690	2	4	6	8	10	12	14	16	18
-94	8710	8730	8750	8770	8790	8810	8831	8851	8872	8892	2	4	6	8	10	12	14	16	18
-95	8913	8933	8954	8974	8995	9016	9036	9057	9078	9099	2	4	6	8	10	12	15	17	19
-96	9120	9141	9162	9183	9204	9226	9247	9268	9290	9311	2	4	7	8	11	13	15	17	19
-97	9333	9354	9376	9397	9419	9441	9462	9484	9508	9528	2	4	7	9	11	13	15	17	20
-98	9550	9573	9594	9616	9638	9661	9683	9705	9727	9750	2	4	7	9	11	13	18	18	20
-99	9772	9795	9817	9840	9863	9886	9908	9931	9954	9977	2	5	7	9	11	14	16	18	20

TABLE IV.—NAPIERIAN, NATURAL, OR HYPERBOLIC LOGARITHMS

MATHEMATICAL TABLES

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TABLE IV (*contd.*)

MATHEMATICAL TABLES

TABLE V.—NATURAL SINES.

Degree.	Natural Sines.										Mean Differences.				
	0°.0	0°.1	0°.2	0°.3	0°.4	0°.5	0°.6	0°.7	0°.8	0°.9	1'	2'	3'	4'	5'
0	.0000	.0017	.0035	.0052	.0070	.0087	.0105	.0122	.0140	.0157	3	6	9	12	15
1	.0175	.0192	.0209	.0227	.0244	.0262	.0279	.0297	.0314	.0332	3	6	9	12	15
2	.0349	.0366	.0384	.0401	.0419	.0436	.0454	.0471	.0488	.0506	3	6	9	12	15
3	.0523	.0541	.0558	.0576	.0593	.0610	.0628	.0645	.0663	.0680	3	6	9	12	15
4	.0698	.0715	.0732	.0750	.0767	.0785	.0802	.0819	.0837	.0854	3	6	9	12	14
5	.0872	.0889	.0906	.0924	.0941	.0958	.0976	.0993	.1011	.1028	3	6	9	12	14
6	.1045	.1063	.1080	.1097	.1115	.1132	.1149	.1167	.1184	.1201	3	6	9	12	14
7	.1219	.1236	.1253	.1271	.1288	.1305	.1323	.1340	.1357	.1374	3	6	9	12	14
8	.1392	.1409	.1426	.1444	.1461	.1478	.1495	.1513	.1530	.1547	3	6	9	12	14
9	.1564	.1582	.1599	.1616	.1633	.1650	.1668	.1685	.1702	.1719	3	6	9	12	14
10	.1736	.1754	.1771	.1788	.1805	.1822	.1840	.1857	.1874	.1891	3	6	9	11	14
11	.1908	.1925	.1942	.1959	.1977	.1994	.2011	.2028	.2045	.2062	3	6	9	11	14
12	.2079	.2096	.2113	.2130	.2147	.2164	.2181	.2198	.2215	.2233	3	6	9	11	14
13	.2250	.2267	.2284	.2300	.2317	.2334	.2351	.2368	.2385	.2402	3	6	8	11	14
14	.2419	.2436	.2453	.2470	.2487	.2504	.2521	.2538	.2554	.2571	3	6	8	11	14
15	.2588	.2605	.2622	.2639	.2656	.2672	.2689	.2706	.2723	.2740	3	6	8	11	14
16	.2756	.2773	.2790	.2807	.2823	.2840	.2857	.2874	.2890	.2907	3	6	8	11	14
17	.2924	.2940	.2957	.2974	.2990	.3007	.3024	.3040	.3057	.3074	3	6	8	11	14
18	.3090	.3107	.3123	.3140	.3156	.3173	.3190	.3206	.3223	.3239	3	6	8	11	14
19	.3256	.3272	.3289	.3305	.3322	.3338	.3355	.3371	.3387	.3404	3	5	8	11	14
20	.3420	.3437	.3453	.3469	.3486	.3502	.3518	.3535	.3551	.3567	3	5	8	11	14
21	.3584	.3600	.3616	.3633	.3649	.3665	.3681	.3697	.3714	.3730	3	5	8	11	14
22	.3746	.3762	.3778	.3795	.3811	.3827	.3843	.3859	.3875	.3891	3	5	8	11	14
23	.3907	.3923	.3939	.3955	.3971	.3987	.4003	.4019	.4035	.4051	3	5	8	11	14
24	.4067	.4083	.4099	.4115	.4131	.4147	.4163	.4179	.4195	.4210	3	5	8	11	13
25	.4226	.4242	.4258	.4274	.4289	.4305	.4321	.4337	.4352	.4368	3	5	8	11	13
26	.4384	.4399	.4415	.4431	.4446	.4462	.4478	.4493	.4509	.4524	3	5	8	10	13
27	.4540	.4555	.4571	.4586	.4602	.4617	.4633	.4648	.4664	.4679	3	5	8	10	13
28	.4695	.4710	.4726	.4741	.4756	.4772	.4787	.4802	.4818	.4833	3	5	8	10	13
29	.4848	.4863	.4879	.4894	.4909	.4924	.4939	.4955	.4970	.4985	3	5	8	10	13
30	.5000	.5015	.5030	.5045	.5060	.5075	.5090	.5105	.5120	.5135	3	5	8	10	13
31	.5150	.5165	.5180	.5195	.5210	.5225	.5240	.5255	.5270	.5284	2	5	7	10	12
32	.5299	.5314	.5329	.5344	.5358	.5373	.5388	.5402	.5417	.5432	2	5	7	10	12
33	.5446	.5461	.5476	.5490	.5505	.5519	.5534	.5548	.5563	.5577	2	5	7	10	12
34	.5592	.5606	.5621	.5635	.5650	.5664	.5678	.5693	.5707	.5721	2	5	7	10	12
35	.5736	.5750	.5764	.5779	.5793	.5807	.5821	.5835	.5850	.5864	2	5	7	9	12
36	.5878	.5892	.5906	.5920	.5934	.5948	.5962	.5976	.5990	.6004	2	5	7	9	12
37	.6018	.6032	.6046	.6060	.6074	.6088	.6101	.6115	.6129	.6143	2	5	7	9	12
38	.6157	.6170	.6184	.6198	.6211	.6225	.6239	.6252	.6266	.6280	2	5	7	9	11
39	.6293	.6307	.6320	.6334	.6347	.6361	.6374	.6388	.6401	.6414	2	4	7	9	11
40	.6428	.6441	.6455	.6468	.6481	.6494	.6508	.6521	.6534	.6547	2	4	7	9	11
41	.6561	.6574	.6587	.6600	.6613	.6626	.6639	.6652	.6665	.6678	2	4	7	9	11
42	.6691	.6704	.6717	.6730	.6743	.6756	.6769	.6782	.6794	.6807	2	4	6	9	11
43	.6820	.6833	.6845	.6858	.6871	.6884	.6896	.6909	.6921	.6934	2	4	6	8	11
44	.6947	.6959	.6972	.6984	.6997	.7009	.7022	.7034	.7046	.7059	2	4	6	8	10
45	.7071	.7083	.7096	.7108	.7120	.7133	.7145	.7157	.7169	.7181	2	4	6	8	10

TABLE V. (*contd.*)

MATHEMATICAL TABLES

TABLE VI.—NATURAL COSINES

0'	6'	12'	18'	24'	30'	36'	42'	48'	54'	Mean Differences.	
0°.0	0°.1	0°.2	0°.3	0°.4	0°.5	0°.6	0°.7	0°.8	0°.9	1' 2' 3' 4' 5'	
1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	0 0 0 0 0	
	9998	9997	9997	9997	9996	9996	9995	9995	9995	0 0 0 0 0	
·9994	9993	9992	9991	9990	9990	9989	9988	9987	9987	0 0 1 1 0	
·9986	9985	9984	9983	982	9983	9982	9979	9978	9977	0 1 1 1 1	
·9976	9974	9973	9972	9971	9969	9968	9966	9965	9963	0 1 1 1 1	
·9962	9960	9959	9957	9956	9954	9952	9951	9949	9947	1 1 2	
·9945	9943	9942	9940	9938	9936	9934	9932	9930	9928	1 1 2	
·9925	9923	9921	9919	9917	9914	9912	9910	9907	9905	1 2 2	
·9903	9900	9898	9895	9893	9890	9885	9882	9880	9878	1 2 2	
·9877	9874	9871	9869	9866	9863	9860	9857	9854	9851	1 2 2	
10	·9848	9845	9842	9839	9836	9833	9829	9826	9823	9820	
·9816	9813	9810	9806	9803	9799	9796	9792	9789	9785	1 2	
·9781	9778	9774	9770	9767	9763	9759	9755	9751	9748	1 2 3 3	
·9744	9749	9736	9732	9728	9724	9720	9715	9711	9707	1 2 3 3	
·9703	9699	9694	9690	9686	9681	9677	9673	9668	9664	1 2 3 4	
15	·9659	9655	9650	9646	9641	9636	963	9627	9622	9617	2 2 3 4
16	·9613	9608	9603	9598	9593	9588	9583	9578	9573	9568	2 2 3 .
17	·9563	9558	9553	9548	9542	9537	9532	9527	9521	9516	2 3 3 4
18	·9511	9505	9500	9494	9489	9483	9478	9472	9466	9461	2 3 4 5
19	·9455	9449	9444	9438	9432	9426	9421	9415	9409	9403	2 3 4 5
20	·9397	9391	9385	9379	9373	9367	9361	9354	9348	9342	2 3 4 5
21	·9336	9330	9323	9317	9311	9304	9298	9291	9285	9278	2 3 4 5
22	·9272	9265	9259	9252	9245	9239	9232	9225	9219	9212	2 3 4 6
23	·9205	9198	9191	9184	9178	9171	9164	9157	9150	9143	2 3 5 6
24	·9135	9128	9121	9114	9107	9100	9092	9085	9078	9070	2 4 5 6
25	·9063	9056	9048	9041	9033	9026	9018	9011	9003	8996	3 4 5 6
26		8980	8973	8965	8957	8949	8942	8934	8926	8918	3 4 5 6
27	·8910	8902	8894	8886	8879	8862	8854	8846			3 4 5 7
28	·8829	8821	8813	8805	8796	8788	8780	8771	8763	8755	3 4 6 7
29	·8746	8738	8729	8721	8712	8704	8695	8686	8678	8669	3 4 6 7
30	·8660	8652	8643	8634	8625	8616	8607	8599	8590	8581	3 4 6 7
31	·8572	8563	8554	8545	8536	8526	8517	8508	8499	8490	2 3 5 6 8
32	·8480	8471	8462	8453	8443	8434	8425	8415	8406	8396	2 3 5 6
33	·8387	8377	8358	8348	8339	8329	8320	8310	8300	8300	2 3 5 6 8
34	·8290	8281	8271	8261	8251	8241	8231	8221	8211	8202	2 3 5 7
35	·8192	8181	8171	8161	8151	8141	8131	8121	8111	8100	2 3 5 7
36	·8090	8080	8070	8059	8049	8039	8028	8018	8007	7997	2 3 5 7 9
37	·7986	7976	7965	7955	7944	7934	7923	7912	7902	7891	2 4 5 7 9
38	·7880	7869	7859	7848	7837	7826	7815	7804	7793	7782	2 4 5 7 9
39	·7771	7760	7749	7738	7727	7716	7705	7694	7683	7672	2 4 6 7 9
40	·7660	7649	7638	7627	7615	7604	7593	7583	7570	7559	2 4 6 8 9
41	·7547	7536	7524	7513	7501	7490	7478	7466	7455	7443	2 4 6 8 10
42	·7431	7420	7408	7396	7385	7373	7361	7349	7337	7325	2 4 6 8 10
43	·7314	7302	7290	7278	7266	7254	7242	7230	7218	7206	2 4 6 8 10
44	·7193	7181	7169	7157	7145	7133	7120	7108	7096	7083	2 4 6 8 10
45	·7071	7059	7046	7034	7022	7009	6997	6984	6972	6959	2 4 6 8 10

MATHEMATICAL TABLES

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TABLE VI (*contd.*)

MATHEMATICAL TABLES

TABLE VII.—NATURAL TANGENTS.

Degree.	0'	6'	12'	18'	24'	30'	36'	42'	48'	54'	Mean Differences.				
	0°.0	0°.1	0°.2	0°.3	0°.4	0°.5	0°.6	0°.7	0°.8	0°.9	1'	2'	3'	4'	5'
0	.0000	.0017	.0035	.0052	.0070	.0087	.0105	.0122	.0140	.0157	3	6	9	12	15
1	.0175	.0192	.0209	.0227	.0244	.0262	.0279	.0297	.0314	.0332	3	6	9	12	15
2	.0349	.0367	.0384	.0402	.0419	.0437	.0454	.0472	.0489	.0507	3	6	9	12	15
3	.0524	.0542	.0559	.0577	.0594	.0612	.0629	.0647	.0664	.0682	3	6	9	12	15
4	.0699	.0717	.0734	.0752	.0769	.0787	.0805	.0822	.0840	.0857	3	6	9	12	15
5	.0875	.0892	.0910	.0928	.0945	.0963	.0981	.0998	.1016	.1033	3	6	9	12	15
6	.1051	.1069	.1086	.1104	.1122	.1139	.1157	.1175	.1192	.1210	3	6	9	12	15
7	.1228	.1246	.1263	.1281	.1299	.1317	.1334	.1352	.1370	.1388	3	6	9	12	15
8	.1405	.1423	.1441	.1459	.1477	.1495	.1512	.1530	.1548	.1566	3	6	9	12	15
9	.1584	.1602	.1620	.1638	.1655	.1673	.1691	.1709	.1727	.1745	3	6	9	12	15
10	.1763	.1781	.1799	.1817	.1835	.1853	.1871	.1890	.1908	.1926	3	6	9	12	15
11	.1944	.1962	.1980	.1998	.2016	.2035	.2053	.2071	.2089	.2107	3	6	9	12	15
12	.2126	.2144	.2162	.2180	.2199	.2217	.2235	.2254	.2272	.2290	3	6	9	12	15
13	.2309	.2327	.2345	.2364	.2382	.2401	.2419	.2438	.2456	.2475	3	6	9	12	15
14	.2493	.2512	.2530	.2549	.2568	.2586	.2605	.2623	.2642	.2661	3	6	9	12	15
15	.2679	.2698	.2717	.2736	.2754	.2773	.2792	.2811	.2830	.2849	3	6	9	13	16
16	.2867	.2886	.2905	.2924	.2943	.2962	.2981	.3000	.3019	.3038	3	6	9	13	16
17	.3057	.3076	.3096	.3115	.3134	.3153	.3172	.3191	.3211	.3230	3	6	10	13	16
18	.3249	.3269	.3288	.3307	.3327	.3346	.3365	.3385	.3404	.3424	3	6	10	13	16
19	.3443	.3463	.3482	.3502	.3522	.3541	.3561	.3581	.3600	.3620	3	7	10	13	16
20	.3640	.3659	.3679	.3699	.3719	.3739	.3759	.3779	.3799	.3819	3	7	10	13	17
21	.3839	.3859	.3879	.3899	.3919	.3939	.3959	.3979	.4000	.4020	3	7	10	13	17
22	.4040	.4061	.4081	.4101	.4122	.4142	.4163	.4183	.4204	.4224	3	7	10	14	17
23	.4245	.4265	.4286	.4307	.4327	.4348	.4369	.4390	.4411	.4431	3	7	10	14	18
24	.4452	.4473	.4494	.4515	.4536	.4557	.4578	.4599	.4621	.4642	4	7	11	14	18
25	.4663	.4684	.4706	.4727	.4748	.4770	.4791	.4813	.4834	.4856	4	7	11	14	18
26	.4877	.4899	.4921	.4942	.4964	.4986	.5008	.5029	.5051	.5073	4	7	11	15	18
27	.5095	.5117	.5139	.5161	.5184	.5206	.5228	.5250	.5272	.5295	4	7	11	15	18
28	.5317	.5349	.5362	.5384	.5407	.5430	.5452	.5475	.5498	.5520	4	8	11	15	19
29	.5543	.5566	.5589	.5612	.5635	.5658	.5681	.5704	.5727	.5750	4	8	12	15	19
30	.5774	.5797	.5820	.5844	.5867	.5890	.5914	.5938	.5961	.5985	4	8	12	16	20
31	.6009	.6032	.6056	.6080	.6104	.6128	.6152	.6176	.6200	.6224	4	8	12	16	20
32	.6249	.6273	.6297	.6322	.6346	.6371	.6395	.6420	.6445	.6469	4	8	12	16	20
33	.6494	.6519	.6544	.6569	.6594	.6619	.6644	.6669	.6694	.6720	4	8	13	17	21
34	.6745	.6771	.6796	.6822	.6847	.6873	.6899	.6924	.6950	.6976	4	9	13	17	21
35	.7002	.7028	.7054	.7080	.7107	.7133	.7159	.7186	.7212	.7239	4	9	13	18	22
36	.7265	.7292	.7319	.7346	.7373	.7400	.7427	.7454	.7481	.7508	5	9	14	18	23
37	.7536	.7563	.7590	.7618	.7646	.7673	.7701	.7729	.7757	.7785	5	9	14	18	23
38	.7813	.7841	.7869	.7898	.7926	.7954	.7983	.8012	.8040	.8069	5	9	14	19	24
39	.8098	.8127	.8156	.8185	.8214	.8243	.8273	.8302	.8332	.8361	5	10	15	20	24
40	.8391	.8421	.8451	.8481	.8511	.8541	.8571	.8601	.8632	.8662	5	10	15	20	25
41	.8693	.8724	.8754	.8785	.8816	.8847	.8878	.8910	.8941	.8972	5	10	16	21	26
42	.9004	.9036	.9067	.9099	.9131	.9163	.9195	.9228	.9260	.9293	5	11	16	21	27
43	.9325	.9358	.9391	.9424	.9457	.9490	.9523	.9556	.9590	.9623	6	11	17	22	28
44	.9657	.9691	.9725	.9759	.9793	.9827	.9861	.9896	.9930	.9965	6	11	17	23	29
45	1.0000	0.035	0.070	0.105	0.141	0.176	0.212	0.247	0.283	0.319	6	12	18	24	30

TABLE VII. (*contd.*)

Degree.	Mean Differences.														
	0'	6'	12'	18'	24'	30'	36'	42'	48'	54'	1'	2'	3'	4'	5'
0°.0	0°.1	0°.2	0°.3	0°.4	0°.5	0°.6	0°.7	0°.8	0°.9						
45	1.0000	0.035	0.070	0.105	0.141	0.176	0.212	0.247	0.283	0.319	6	12	18	24	30
46	1.0355	0.0392	0.0428	0.0464	0.0501	0.0538	0.0575	0.0612	0.0649	0.0686	6	12	18	25	31
47	1.0724	0.0761	0.0799	0.0837	0.0875	0.0913	0.0951	0.0990	0.1028	0.1067	6	13	19	25	32
48	1.1106	1.145	1.184	1.224	1.263	1.303	1.343	1.383	1.423	1.463	7	13	20	27	33
49	1.1504	1.144	1.185	1.262	1.667	1.708	1.750	1.792	1.833	1.875	7	14	21	28	34
50	1.1918	1.160	2.002	2.045	2.088	2.131	2.174	2.218	2.261	2.305	7	14	22	29	36
51	1.2349	2.393	2.437	2.482	2.527	2.572	2.617	2.662	2.708	2.753	8	15	23	30	38
52	1.2799	2.846	2.892	2.938	2.985	3.032	3.079	3.127	3.175	3.222	8	16	24	31	39
53	1.3270	3.319	3.367	3.416	3.465	3.514	3.564	3.613	3.663	3.713	8	16	25	33	41
54	1.3764	3.814	3.865	3.916	3.968	4.019	4.071	4.124	4.176	4.229	9	17	26	34	43
55	1.4281	4.335	4.388	4.442	4.496	4.550	4.605	4.659	4.715	4.770	9	18	27	36	45
56	1.4826	4.882	4.938	4.994	5.051	5.108	5.166	5.224	5.282	5.340	10	19	29	38	48
57	1.5399	5.458	5.517	5.577	5.637	5.697	5.757	5.818	5.880	5.941	10	20	30	40	50
58	1.6003	6.066	6.128	6.191	6.255	6.319	6.383	6.447	6.512	6.577	11	21	32	43	53
59	1.6643	6.709	6.775	6.842	6.909	6.977	7.045	7.113	7.182	7.251	11	23	34	45	56
60	1.7321	7.391	7.461	7.532	7.603	7.675	7.747	7.820	7.893	7.966	12	24	36	48	60
61	1.8040	8.115	8.190	8.265	8.341	8.418	8.495	8.572	8.650	8.728	13	26	38	51	64
62	1.8807	8.887	8.967	9.047	9.128	9.210	9.292	9.375	9.458	9.542	14	27	41	55	68
63	1.9626	9.711	9.797	9.883	9.970	1.005	1.045	1.023	1.033	1.0413	15	29	44	58	73
64	2.0503	1.0594	1.0686	1.0778	1.0872	1.0965	1.1060	1.1155	1.1251	1.1348	16	31	47	63	78
65	2.1445	1.543	1.642	1.742	1.842	1.943	2.045	2.148	2.251	2.355	17	34	51	68	85
66	2.2460	2.566	2.673	2.781	2.889	2.998	3.109	3.220	3.332	3.445	18	37	55	73	92
67	2.3559	3.673	3.789	3.906	4.023	4.142	4.262	4.383	4.504	4.627	20	40	60	79	99
68	2.4751	4.876	5.002	5.129	5.257	5.386	5.517	5.649	5.782	5.916	22	43	65	87	108
69	2.6051	6.187	6.325	6.464	6.605	6.746	6.889	7.034	7.179	7.326	24	47	71	95	119
70	2.7475	7.625	7.776	7.929	8.083	8.239	8.397	8.556	8.716	8.878	26	52	78	104	131
71	2.9042	9.208	9.375	9.544	9.714	9.887	1.0061	1.0237	1.0415	1.0595	29	58	87	116	145
72	3.0777	1.061	1.146	1.334	1.524	1.716	1.910	2.106	2.305	2.506	32	64	96	129	161
73	3.2709	2.914	3.122	3.332	3.544	3.759	3.977	4.197	4.420	4.646	36	72	108	144	180
74	3.4874	5.105	5.339	5.576	5.816	6.059	6.305	6.554	6.806	7.062	41	81	122	163	204
75	3.7321	7.583	7.848	8.118	8.391	8.667	8.947	9.232	9.520	9.812	46	93	139	186	232
76	4.0108	0.048	0.0713	1.022	1.335	1.653	1.976	2.303	2.635	2.972					
77	4.3315	3.662	4.015	4.374	4.737	5.107	5.483	5.864	6.232	6.646					
78	4.7046	7.453	7.867	8.288	8.716	9.152	9.594	1.0445	1.054	1.0970					
79	5.1446	1.929	2.422	2.924	3.435	3.955	4.486	5.026	5.578	6.140					
80	5.6713	7.297	7.894	8.502	9.124	9.758	1.0405	1.066	1.1742	1.2432					
81	6.3138	3.859	4.596	5.350	6.122	6.912	7.720	8.548	9.395	1.0264	Mean differences are no longer sufficiently accurate, since the differences vary considerably along each line.				
82	7.1154	2.066	3.002	3.962	4.947	5.958	6.996	8.062	9.158	1.0285					
83	8.1443	2.636	3.863	5.126	6.427	7.769	9.152	1.0579	2.052	3.372					
84	9.514	9.677	9.845	10.02	10.20	10.39	10.58	10.78	10.99	11.20					
85	11.43	11.66	11.91	12.16	12.43	12.71	13.00	13.30	13.62	13.95					
86	14.30	14.67	15.06	15.46	15.89	16.35	16.83	17.34	17.89	18.46					
87	19.08	19.74	20.45	21.20	22.02	22.90	23.86	24.90	26.03	27.27					
88	28.64	30.14	31.82	33.69	35.80	38.19	40.92	44.07	47.74	52.08					
89	57.29	63.66	71.62	81.85	95.49	114.6	143.2	191.0	286.5	573.0					
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TABLE VIII.—LOGARITHMIC SINES.

Degrees.	Mean Differences.										1°.0	2°.0	3°.0	4°.0	5°.0
	0°.0	6°.0	12°.0	18°.0	24°.0	30°.0	36°.0	42°.0	48°.0	54°.0					
0	-∞	32419	5429	7190	8439	9408	6200	6870	1450	1961					
1	22419	2832	3210	3558	3880	4179	4459	4723	4971	5206					
2	5428	5040	5842	6035	6220	6397	6567	6731	6889	7041					
3	7188	7330	7468	7602	7731	7857	7979	8098	8213	8326					
4	8436	8543	8647	8749	8849	8946	9042	9135	9226	9315	16 32 48 64 80				
5	9403	9489	9573	9655	9736	9816	9894	9970	6046	6120	13 26 39 52 65				
6	10192	0264	0334	0403	0472	0539	0605	0670	0734	0797	11 22 33 44 55				
7	0859	0920	0981	1040	1099	1157	1214	1271	1326	1381	10 19 29 38 48				
8	1436	1489	1542	1594	1646	1697	1747	1797	1847	1895	8 17 25 34 42				
9	1943	1991	2038	2085	2131	2176	2221	2266	2310	2353	8 15 23 30 38				
10	2397	2439	2482	2524	2565	2606	2647	2687	2727	2767	7 14 20 27 34				
11	2806	2845	2883	2921	2959	2997	3034	3070	3107	3143	6 12 19 25 31				
12	3179	3214	3250	3284	3319	3353	3387	3421	3455	3488	6 11 17 23 28				
13	3521	3554	3586	3618	3650	3682	3713	3745	3775	3806	5 11 16 21 26				
14	3837	3867	3897	3927	3957	3986	4015	4044	4073	4102	5 10 15 20 24				
15	4130	4158	4186	4214	4242	4269	4296	4323	4350	4377	5 9 14 18 23				
16	4403	4430	4456	4482	4508	4533	4559	4584	4609	4634	4 9 13 17 21				
17	4659	4684	4709	4733	4757	4781	4805	4829	4853	4876	4 8 12 16 20				
18	4900	4923	4946	4969	4992	5015	5037	5060	5082	5104	4 8 11 15 19				
19	5126	5148	5170	5192	5213	5235	5256	5278	5299	5320	4 7 11 14 18				
20	5341	5361	5382	5402	5433	5443	5463	5484	5504	5523	3 7 10 14 17				
21	5543	5563	5583	5602	5621	5641	5660	5679	5698	5717	3 6 10 13 16				
22	5736	5754	5773	5792	5810	5828	5847	5865	5883	5901	3 6 9 12 15				
23	5919	5937	5954	5972	5990	6007	6024	6042	6059	6076	3 6 9 12 15				
24	6093	6110	6127	6144	6161	6177	6194	6210	6227	6243	3 6 8 11 14				
25	6259	6276	6292	6308	6324	6340	6356	6371	6387	6403	3 5 8 11 13				
26	6418	6434	6449	6465	6480	6495	6510	6526	6541	6556	3 5 8 10 13				
27	6570	6585	6600	6615	6629	6644	6659	6673	6687	6702	2 5 7 10 12				
28	6716	6730	6744	6759	6773	6787	6801	6814	6828	6842	2 5 7 9 12				
29	6856	6869	6883	6896	6910	6923	6937	6950	6963	6977	2 4 7 9 11				
30	6990	7003	7016	7029	7042	7055	7068	7080	7093	7106	2 4 6 9 11				
31	7118	7131	7144	7156	7168	7181	7193	7205	7218	7230	2 4 6 8 10				
32	7242	7254	7266	7278	7290	7302	7314	7326	7338	7349	2 4 6 8 10				
33	7361	7373	7384	7396	7407	7419	7430	7442	7453	7464	2 4 6 7 9				
34	7476	7487	7498	7509	7520	7531	7542	7553	7564	7575	2 4 5 7 9				
35	7586	7597	7607	7618	7629	7640	7650	7661	7671	7682	2 4 5 7 9				
36	7692	7703	7713	7723	7734	7744	7754	7764	7774	7785	2 3 5 7 9				
37	7795	7805	7815	7825	7835	7844	7854	7864	7874	7884	2 3 5 7 8				
38	7893	7903	7913	7922	7932	7941	7951	7960	7970	7979	2 3 5 6 8				
39	7989	7998	8007	8017	8026	8035	8044	8053	8063	8072	2 3 5 6 7				
40	8081	8090	8099	8109	8117	8125	8134	8143	8152	8161	1 3 4 6 7				
41	8169	8178	8187	8195	8204	8213	8221	8230	8238	8247	1 3 4 6 7				
42	8255	8264	8272	8280	8289	8297	8305	8313	8322	8330	1 3 4 6 7				
43	8338	8346	8354	8362	8370	8378	8386	8394	8402	8410	1 3 4 5 6				
44	8418	8426	8433	8441	8449	8457	8464	8472	8480	8487	1 3 4 5 6				
45	8495	8502	8510	8517	8525	8532	8540	8547	8555	8562	1 2 4 5 6				

TABLE VIII. (contd.)

Degree.	0'	6'	12'	18'	24'	30'	36'	42'	48'	54'	Mean Differences.				
	0°.0	0°.1	0°.2	0°.3	0°.4	0°.5	0°.6	0°.7	0°.8	0°.9	1'	2'	3'	4'	5'
45	8495	8502	8510	8517	8525	8532	8540	8547	8555	8562	I	2	4	5	6
46	-8509	8577	8584	8591	8598	8606	9613	8620	8627	8634	I	2	4	5	6
47	-8641	8648	8655	8662	8669	8676	8683	8690	8697	8704	I	2	3	5	6
48	-8711	8718	8724	8731	8738	8745	8751	8758	8765	8771	I	2	3	4	6
49	-8778	8784	8791	8797	8804	8810	8817	8823	8830	8836	I	2	3	4	5
50	-8843	8849	8855	8862	8868	8874	8880	8887	8893	8899	I	2	3	4	5
51	-8905	8911	8917	8923	8929	8935	8941	8947	8953	8959	I	2	3	4	5
52	-8905	8971	8977	8983	8989	8995	9000	9006	9012	9018	I	2	3	4	5
53	-9023	9029	9035	9041	9046	9052	9057	9063	9069	9074	I	2	3	4	5
54	-9080	9085	9091	9096	9101	9107	9112	9118	9123	9128	I	2	3	4	5
55	-9134	9139	9144	9149	9155	9160	9165	9170	9175	9181	I	2	3	3	4
56	-9186	9191	9196	9201	9206	9211	9216	9221	9226	9231	I	2	3	3	4
57	-9236	9241	9246	9251	9255	9260	9265	9270	9275	9279	I	2	2	3	4
58	-9284	9289	9294	9298	9303	9308	9312	9317	9322	9326	I	2	2	3	4
59	-9331	9335	9340	9344	9349	9353	9358	9362	9367	9371	I	1	2	3	4
60	-9375	9380	9384	9388	9393	9397	9401	9406	9410	9414	I	1	2	3	4
61	-9418	9422	9427	9431	9435	9439	9443	9447	9451	9455	I	1	2	3	3
62	-9459	9463	9467	9471	9475	9479	9483	9487	9491	9495	I	1	2	3	3
63	-9499	9503	9507	9510	9514	9518	9522	9525	9529	9533	I	1	2	3	3
64	-9537	9540	9544	9548	9551	9555	9558	9562	9566	9569	I	1	2	2	3
65	-9573	9576	9580	9583	9587	9590	9594	9597	9601	9604	I	1	2	2	3
66	-9607	9611	9614	9617	9621	9624	9627	9631	9634	9637	I	1	2	2	3
67	-9640	9643	9647	9650	9653	9656	9659	9662	9665	9669	I	1	2	2	3
68	-9672	9675	9678	9681	9684	9687	9690	9693	9696	9699	O	1	1	2	2
69	-9702	9704	9707	9710	9713	9716	9719	9722	9724	9727	O	1	1	2	2
70	-9730	9733	9735	9738	9741	9743	9746	9749	9751	9754	O	1	1	2	2
71	-9757	9759	9762	9764	9767	9770	9772	9775	9777	9780	O	1	1	2	2
72	-9782	9785	9787	9789	9792	9794	9797	9799	9801	9804	O	1	1	2	2
73	-9806	9808	9811	9813	9815	9817	9820	9822	9824	9826	O	1	1	2	2
74	-9823	9831	9833	9835	9837	9839	9841	9843	9845	9847	O	1	1	1	2
75	-9849	9851	9853	9855	9857	9859	9861	9863	9865	9867	O	1	1	1	2
76	-9869	9871	9873	9875	9876	9878	9880	9882	9884	9885	O	1	1	1	2
77	-9887	9889	9891	9892	9894	9896	9897	9899	9901	9902	O	1	1	1	1
78	-9904	9906	9907	9909	9910	9912	9913	9915	9916	9918	O	1	1	1	1
79	-9919	9921	9922	9924	9925	9927	9928	9929	9931	9932	O	0	1	1	1
80	-9934	9935	9936	9937	9939	9940	9941	9943	9944	9945	O	0	1	1	1
81	-9946	9947	9949	9950	9951	9952	9953	9954	9955	9956	O	0	1	1	1
82	-9958	9959	9960	9961	9962	9963	9964	9965	9966	9967	O	0	1	1	1
83	-9968	9968	9969	9970	9971	9972	9973	9974	9975	9975	O	0	0	1	1
84	-9976	9977	9978	9978	9979	9980	9981	9981	9982	9983	O	0	0	0	1
85	-9983	9984	9985	9985	9986	9987	9987	9988	9988	9989	O	0	0	0	0
86	-9989	9990	9990	9991	9991	9992	9992	9993	9993	9994	O	0	0	0	0
87	-9994	9994	9995	9995	9996	9996	9996	9996	9997	9997	O	0	0	0	0
88	-9997	9998	9998	9998	9998	9999	9999	9999	9999	9999	O	0	0	0	0
89	-9999	9999	9999	0000	0000	0000	0000	0000	0000	0000	O	0	0	0	0
90	0.0000										O	0	0	0	0

TABLE IX.—LOGARITHMIC COSINES

Degree.	Mean Differences.														
	0'	8'	12'	18'	24'	30'	36'	42'	48'	54'	1'	2'	3'	4'	5'
0°.0	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000	0°.0000
0	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
1	1.9999	9999	9999	9999	9999	9999	9998	9998	9998	9998	9998	9998	9998	9998	9998
2	2.9997	9997	9997	9996	9996	9996	9995	9995	9995	9995	9994	9994	9994	9994	9994
3	3.9994	9994	9993	9993	9992	9992	9991	9991	9990	9990	9990	9990	9990	9990	9990
4	4.9989	9989	9988	9988	9987	9987	9986	9985	9985	9984	9984	9984	9984	9984	9984
5	5.9983	9983	9982	9981	9981	9980	9979	9978	9978	9977	9977	9977	9977	9977	9977
6	6.9976	9975	9975	9974	9973	9972	9971	9970	9969	9968	9968	9968	9968	9968	9968
7	7.9968	9967	9966	9965	9964	9963	9962	9961	9960	9959	9959	9959	9959	9959	9959
8	8.9958	9956	9955	9954	9953	9952	9951	9950	9949	9947	9947	9947	9947	9947	9947
9	9.9946	9945	9944	9943	9941	9940	9939	9937	9935	9935	9935	9935	9935	9935	9935
10	10.9934	9932	9931	9929	9928	9927	9925	9924	9922	9921	9921	9921	9921	9921	9921
11	11.9919	9918	9916	9915	9913	9912	9910	9909	9907	9906	9906	9906	9906	9906	9906
12	12.9904	9902	9901	9899	9897	9896	9894	9892	9891	9889	9889	9889	9889	9889	9889
13	13.9887	9885	9884	9882	9880	9878	9876	9875	9873	9871	9871	9871	9871	9871	9871
14	14.9869	9867	9865	9863	9861	9859	9857	9855	9853	9851	9851	9851	9851	9851	9851
15	15.9849	9847	9845	9843	9841	9839	9837	9835	9833	9831	9831	9831	9831	9831	9831
16	16.9828	9826	9824	9822	9820	9817	9815	9813	9811	9808	9808	9808	9808	9808	9808
17	17.9806	9804	9801	9799	9797	9794	9792	9789	9787	9785	9785	9785	9785	9785	9785
18	18.9782	9780	9777	9775	9773	9770	9767	9764	9762	9759	9759	9759	9759	9759	9759
19	19.9757	9754	9751	9749	9746	9743	9741	9738	9735	9733	9733	9733	9733	9733	9733
20	20.9730	9727	9724	9722	9719	9716	9713	9710	9707	9704	9704	9704	9704	9704	9704
21	21.9702	9699	9696	9693	9690	9687	9684	9681	9678	9675	9675	9675	9675	9675	9675
22	22.9672	9669	9666	9662	9659	9656	9653	9650	9647	9643	9643	9643	9643	9643	9643
23	23.9640	9637	9634	9631	9627	9624	9621	9617	9614	9611	9611	9611	9611	9611	9611
24	24.9607	9604	9601	9597	9594	9590	9587	9583	9580	9576	9576	9576	9576	9576	9576
25	25.9573	9569	9566	9562	9558	9555	9551	9548	9544	9540	9540	9540	9540	9540	9540
26	26.9537	9533	9529	9525	9522	9518	9514	9510	9507	9503	9503	9503	9503	9503	9503
27	27.9499	9495	9491	9487	9483	9479	9475	9471	9467	9463	9463	9463	9463	9463	9463
28	28.9459	9455	9451	9447	9443	9439	9435	9431	9427	9422	9422	9422	9422	9422	9422
29	29.9418	9414	9410	9406	9401	9397	9393	9388	9384	9380	9380	9380	9380	9380	9380
30	30.9375	9367	9367	9362	9358	9353	9349	9344	9340	9335	9335	9335	9335	9335	9335
31	31.9331	9326	9322	9317	9312	9308	9303	9298	9294	9289	9289	9289	9289	9289	9289
32	32.9284	9279	9275	9270	9265	9260	9255	9251	9246	9241	9241	9241	9241	9241	9241
33	33.9236	9231	9226	9221	9216	9211	9206	9201	9196	9191	9191	9191	9191	9191	9191
34	34.9186	9181	9175	9170	9165	9160	9155	9149	9144	9139	9139	9139	9139	9139	9139
35	35.9134	9128	9123	9118	9112	9107	9101	9096	9091	9085	9085	9085	9085	9085	9085
36	36.9080	9074	9069	9063	9057	9052	9046	9041	9035	9029	9029	9029	9029	9029	9029
37	37.9023	9018	9012	9006	9000	8995	8989	8983	8977	8971	8971	8971	8971	8971	8971
38	38.8965	8959	8955	8947	8941	8935	8929	8923	8917	8911	8911	8911	8911	8911	8911
39	39.8905	8899	8893	8887	8880	8874	8868	8862	8855	8849	8849	8849	8849	8849	8849
40	40.8843	8836	8830	8823	8817	8810	8804	8797	8791	8784	8784	8784	8784	8784	8784
41	41.8778	8771	8765	8758	8751	8745	8738	8731	8724	8718	8718	8718	8718	8718	8718
42	42.8711	8704	8697	8690	8683	8676	8669	8662	8655	8648	8648	8648	8648	8648	8648
43	43.8641	8634	8627	8620	8613	8606	8598	8591	8584	8577	8577	8577	8577	8577	8577
44	44.8569	8562	8555	8547	8540	8532	8525	8517	8510	8502	8502	8502	8502	8502	8502
45	45.8495	8487	8480	8472	8464	8457	8449	8441	8433	8426	8426	8426	8426	8426	8426

MATHEMATICAL TABLES

TABLE IX.—LOGARITHMIC COSINES

Degrees.	0'	8'	12'	18'	24'	30'	36'	42'	48'	54'	Mean Differences.				
	0°.0	0°.1	0°.2	0°.3	0°.4	0°.5	0°.6	0°.7	0°.8	0°.9	1'	2'	3'	4'	5'
0	0.0000	0000	0000	0000	0000	0000	0000	0000	0000	09999	0	0	0	0	0
1	1.9999	9999	9999	9999	9999	9999	9998	9998	9998	9998	0	0	0	0	0
2	1.9997	9997	9997	9996	9996	9996	9996	9995	9995	9995	0	0	0	0	0
3	1.9994	9994	9993	9993	9992	9992	9991	9991	9990	9990	0	0	0	0	0
4	1.9989	9989	9988	9988	9987	9987	9986	9985	9985	9984	0	0	0	0	3
5	1.9983	9983	9982	9981	9981	9980	9979	9978	9978	9977	0	0	0	0	1
6	1.9976	9975	9975	9974	9973	9972	9971	9970	9969	9968	0	0	0	1	1
7	1.9968	9967	9966	9965	9964	9963	9962	9961	9960	9959	0	0	1	1	1
8	1.9958	9956	9955	9954	9953	9952	9951	9950	9949	9947	0	0	1	1	1
9	1.9946	9945	9944	9943	9941	9940	9939	9937	9936	9935	0	0	1	1	1
10	1.9934	9932	9931	9929	9928	9927	9925	9924	9924	9921	0	0	1	1	1
11	1.9919	9918	9916	9915	9913	9912	9910	9909	9907	9906	0	1	1	1	1
12	1.9904	9902	9901	9899	9897	9896	9894	9892	9891	9889	0	1	1	1	1
13	1.9887	9885	9884	9882	9880	9878	9876	9875	9873	9871	0	1	1	1	2
14	1.9869	9867	9865	9863	9861	9859	9857	9855	9853	9851	0	1	1	1	2
15	1.9849	9847	9845	9843	9841	9839	9837	9835	9833	9831	0	1	1	1	2
16	1.9828	9826	9824	9822	9820	9817	9815	9813	9811	9808	0	1	1	2	2
17	1.9806	9804	9801	9799	9797	9794	9792	9789	9787	9785	0	1	1	2	2
18	1.9782	9780	9777	9775	9772	9770	9767	9764	9762	9759	0	1	1	2	2
19	1.9757	9754	9751	9749	9746	9743	9741	9738	9735	9733	0	1	1	2	2
20	1.9730	9727	9724	9722	9719	9716	9713	9710	9707	9704	0	1	1	2	2
21	1.9702	9699	9696	9693	9690	9687	9684	9681	9678	9675	0	1	1	2	2
22	1.9672	9669	9666	9662	9659	9656	9653	9650	9647	9643	1	1	2	2	3
23	1.9640	9637	9634	9631	9627	9624	9621	9617	9614	9611	1	1	2	2	3
24	1.9607	9604	9601	9597	9594	9590	9587	9583	9580	9576	1	1	2	2	3
25	1.9573	9569	9566	9562	9558	9555	9551	9548	9544	9540	1	1	2	2	3
26	1.9537	9533	9529	9525	9522	9518	9514	9510	9507	9503	1	1	2	3	3
27	1.9499	9495	9491	9487	9483	9479	9475	9471	9467	9463	1	1	2	3	3
28	1.9459	9455	9451	9447	9443	9439	9435	9431	9427	9422	1	1	2	3	3
29	1.9418	9414	9410	9406	9401	9397	9393	9388	9384	9380	1	1	2	3	4
30	1.9375	9371	9367	9362	9358	9353	9349	9344	9340	9335	1	1	2	3	4
31	1.9331	9326	9322	9317	9312	9308	9303	9298	9294	9289	1	2	2	3	4
32	1.9284	9279	9275	9270	9265	9260	9255	9251	9246	9241	1	2	2	3	4
33	1.9236	9231	9226	9221	9216	9211	9206	9201	9196	9191	1	2	3	3	4
34	1.9186	9181	9175	9170	9165	9160	9155	9149	9144	9139	1	2	3	3	4
35	1.9134	9128	9123	9118	9112	9107	9101	9096	9091	9085	1	2	3	4	5
36	1.9080	9074	9069	9063	9057	9052	9046	9041	9035	9029	1	2	3	4	5
37	1.9023	9018	9012	9006	9000	8995	8989	8983	8977	8971	1	2	3	4	5
38	1.8965	8959	8953	8947	8941	8935	8929	8923	8917	8911	1	2	3	4	5
39	1.8905	8899	8893	8887	8880	8874	8868	8862	8855	8849	1	2	3	4	5
40	1.8843	8836	8830	8823	8817	8810	8804	8797	8791	8784	1	2	3	4	5
41	1.8778	8771	8765	8758	8751	8745	8738	8731	8724	8718	1	2	3	5	6
42	1.8711	8704	8697	8690	8683	8676	8669	8662	8655	8648	1	2	3	5	6
43	1.8641	8634	8627	8620	8613	8606	8598	8591	8584	8577	1	2	4	5	6
44	1.8569	8562	8555	8547	8540	8532	8525	8517	8510	8502	1	2	4	5	6
45	1.8495	8487	8480	8472	8464	8457	8449	8441	8433	8426	1	3	4	5	6

MATHEMATICAL TABLES

TABLE X.—LOGARITHMIC TANGENTS.

Degree.	0'	6'	12'	18'	24'	30'	36'	42'	48'	54'	Mean Differences.	Degree.	0'	
	0° 0	0° 1	0° 2	0° 3	0° 4	0° 5	0° 6	0° 7	0° 8	0° 9	1' 2' 3' 4' 5'		0°	
0	-∞	3°24'19	5429	7190	8439	9409	0200	0870	1450	1962			45°	.00
1	2°24'19	2833	3211	3559	3881	4181	4461	4725	4973	5208			46°	.01
2	5°54'31	5643	5845	6038	6223	6401	6571	6736	6894	7046			47°	.03
3	7°19'4	7337	7475	7609	7739	7865	7988	8107	8223	8336			48°	.04
4	8°44'6	8554	8659	8762	8862	8960	9056	9150	9241	9331	16 32 48 64 81	49°	.06	
5	9°42'0	9506	9501	9674	9756	9836	9915	9992	0068	0143	13 26 40 53 66	50°	.07	
6	1°02'16	0289	0360	0430	0499	0567	0633	0699	0764	0828	II 22 34 45 56	51°	.09	
7	0°89'1	0954	1015	1076	1135	1194	1252	1310	1367	1423	10 20 29 39 49	52°	.10	
8	1°47'8	1533	1587	1640	1693	1745	1797	1848	1888	1948	9 17 26 35 45	53°	.12	
9	1°99'7	2046	2094	2142	2189	2236	2282	2328	2374	2419	8 16 23 31 39	54°	.13	
10	2°46'3	2507	2551	2594	2637	2680	2722	2764	2805	2846	7 14 21 28 35	55°	.14	
11	2°88'7	2927	2967	3006	3046	3085	3123	3162	3200	3237	6 13 19 26 34	56°	.15	
12	3°27'5	3312	3349	3385	3422	3458	3493	3529	3564	3599	6 12 18 24 30	57°	.16	
13	3°36'4	3668	3702	3736	3770	3804	3837	3870	3903	3935	6 11 17 22 28	58°	.20	
14	3°39'8	4000	4032	4064	4095	4127	4158	4189	4220	4250	5 10 16 21 29	59°	.21	
15	4°28'1	4311	4341	4371	4400	4430	4459	4488	4517	4546	5 10 15 20 28	60°	.22	
16	4°57'5	4603	4632	4660	4688	4716	4744	4771	4799	4826	5 9 14 19 23	61°	.2	
17	4°48'3	4880	4907	4934	4961	4987	5014	5040	5066	5092	4 9 13 18 21	62°	.2	
18	5°11'8	5143	5169	5195	5220	5245	5270	5295	5320	5345	4 8 13 17 21	63°	.2	
19	5°37'0	5394	5419	5443	5467	5491	5516	5539	5563	5587	4 8 12 16 20	64°	.3	
20	5°56'11	5634	5658	5681	5704	5727	5750	5773	5796	5819	4 8 12 15 19	65°	.3	
21	5°58'42	5864	5887	5909	5932	5954	5976	5998	6020	6042	4 7 11 15 19	66°	.3	
22	6°06'4	6086	6108	6129	6151	6172	6194	6215	6236	6257	4 7 11 14 19	67°	.	
23	6°27'9	6300	6321	6341	6362	6383	6404	6424	6445	6465	3 7 10 14 19	68°	.	
24	6°48'6	6506	6527	6547	6567	6587	6607	6627	6647	6667	3 7 10 13 19	69°	.	
25	6°68'7	6706	6726	6746	6765	6785	6804	6824	6843	6863	3 7 10 13 19	70°	.	
26	6°88'2	6901	6920	6939	6958	6977	6996	7015	7034	7053	3 6 9 13 19	71°	.	
27	7°07'2	7090	7109	7128	7146	7165	7183	7202	7220	7238	3 6 9 12 19	72°	.	
28	7°25'7	7275	7293	7311	7330	7348	7366	7384	7402	7420	3 6 9 12 19	73°	.	
29	7°43'8	7455	7473	7491	7509	7526	7544	7562	7579	7597	3 6 9 12 19	74°	.	
30	7°61'4	7632	7649	7667	7684	7701	7719	7736	7753	7771	3 6 9 12 19	75°	.	
31	7°77'8	7805	7822	7839	7856	7873	7890	7907	7924	7941	3 6 9 11 14	76°	.	
32	7°95'8	7975	7992	8008	8025	8042	8059	8075	8092	8109	3 6 8 11 14	77°	.	
33	8°12'5	8142	8158	8175	8191	8208	8224	8241	8257	8274	3 5 8 11 14	78°	.	
34	8°20'2	8306	8323	8339	8355	8371	8388	8404	8420	8436	3 5 8 11 14	79°	.	
35	8°34'52	8468	8484	8501	8517	8533	8549	8565	8581	8597	3 5 8 11 14	80°	.	
36	8°61'3	8629	8644	8660	8676	8692	8708	8724	8740	8755	3 5 8 11 14	81°	.	
37	8°77'1	8787	8803	8818	8834	8850	8865	8881	8897	8912	3 5 8 10 13	82°	.	
38	8°92'8	8944	8959	8975	8990	9006	9022	9037	9053	9068	3 5 8 10 13	83°	.	
39	9°08'4	9099	9115	9130	9146	9161	9176	9192	9207	9223	3 5 8 10 13	84°	.	
40	9°25'4	9269	9284	9300	9315	9330	9346	9361	9376	9391	3 5 8 10 13	85°	.	
41	9°42'7	9422	9438	9453	9468	9483	9499	9514	9529	9543	3 5 8 10 13	86°	.	
42	9°57'5	9575	9590	9605	9621	9636	9651	9666	9681	9696	3 5 8 10 13	87°	.	
43	9°72'7	9742	9757	9773	9788	9803	9818	9833	9848	9863	3 5 8 10 13	88°	.	
44	9°89'4	9909	9909	9924	9939	9955	9970	9985	9997	9997	3 5 8 10 13	89°	.	
45	9°00'45	0045	0061	0076	0091	0106	0121	0136	0151	0166	3 5 8 10 13	90°	.	

TABLE X. (*contd.*)

MATHEMATICAL TABLES

TABLE XI.—EXPONENTIAL AND HYPERBOLIC FUNCTIONS

x	e^x	e^{-x}	$\cosh x = \frac{e^x + e^{-x}}{2}$	$\sinh x = \frac{e^x - e^{-x}}{2}$	$\tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}}$
.1	1.1052	.9048	1.0050	.1002	.0997
.2	1.2214	.8187	1.0201	.2013	.1974
.3	1.3499	.7408	1.0453	.3045	.2913
.4	1.4918	.6703	1.0811	.4108	.3799
.5	1.6487	.6065	1.1276	.5211	.4621
.6	1.8221	.5488	1.1855	.6367	.5370
.7	2.0138	.4966	1.2552	.7586	.6044
.8	2.2255	.4493	1.3374	.8881	.6640
.9	2.4596	.4066	1.4331	1.0265	.7163
1.0	2.7183	.3679	1.5431	1.1752	.7616
1.1	3.0042	.3329	1.6685	1.3357	.8005
1.2	3.3201	.3012	1.8107	1.5095	.8337
1.3	3.6693	.2725	1.9709	1.6984	.8617
1.4	4.0552	.2466	2.1509	1.9043	.8854
1.5	4.4817	.2231	2.3524	2.1293	.9051
1.6	4.9530	.2019	2.5775	2.3756	.9217
1.7	5.4739	.1827	2.8283	2.6456	.9354
1.8	6.0496	.1653	3.1075	2.9422	.9468
1.9	6.6859	.1496	3.4177	3.2682	.9563
2.0	7.3891	.1353	3.7622	3.6269	.9640
2.1	8.1662	.1225	4.1443	4.0219	.9704
2.2	9.0251	.1108	4.5679	4.4571	.9758
2.3	9.9742	.1003	5.0372	4.9370	.9801
2.4	11.0232	.0907	5.5570	5.4662	.9837
2.5	12.1825	.0821	6.1323	6.0502	.9866
2.6	13.4638	.0743	6.7690	6.6947	.9890
2.7	14.8797	.0672	7.4735	7.4063	.9910
2.8	16.4446	.0608	8.2527	8.1919	.9926
2.9	18.1741	.0550	9.1146	9.0596	.9940
3.0	20.0855	.0498	10.068	10.018	.9951
3.1	22.1980	.0450	11.122	11.076	.9959
3.2	24.5325	.0408	12.287	12.246	.9967
3.3	27.1126	.0369	13.575	13.538	.9973
3.4	29.9641	.0334	14.999	14.955	.9978
3.5	33.1155	.0302	16.573	16.543	.9982
3.6	36.5982	.0273	18.313	18.285	.9985
3.7	40.4473	.0247	20.236	20.211	.9988
3.8	44.7012	.0224	22.362	22.339	.9990
3.9	49.4024	.0202	24.711	24.691	.9992
4.0	54.5982	.0183	27.308	27.290	.9993
4.1	60.3403	.0166	30.178	30.162	.9995
4.2	66.6863	.0150	33.351	33.336	.9996
4.3	73.6998	.0136	36.857	36.843	.9996
4.4	81.4509	.0123	40.732	40.719	.9997
4.5	90.0171	.0111	45.014	45.003	.9997
4.6	99.4843	.0101	49.747	49.737	.9998
4.7	109.9472	.0091	54.978	54.969	.9998
4.8	121.5104	.0082	60.759	60.751	.9999
4.9	134.2898	.0074	67.149	67.141	.9999
5.0	148.4132	.0067	74.210	74.203	.9999

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